Emilio Tuosto @ GSSI

joint work with

Elvis Gerardin Konjoh Selabi Maurizio Murgia Antonio Ravara

A tutorial @ FORTE 2025, Lille

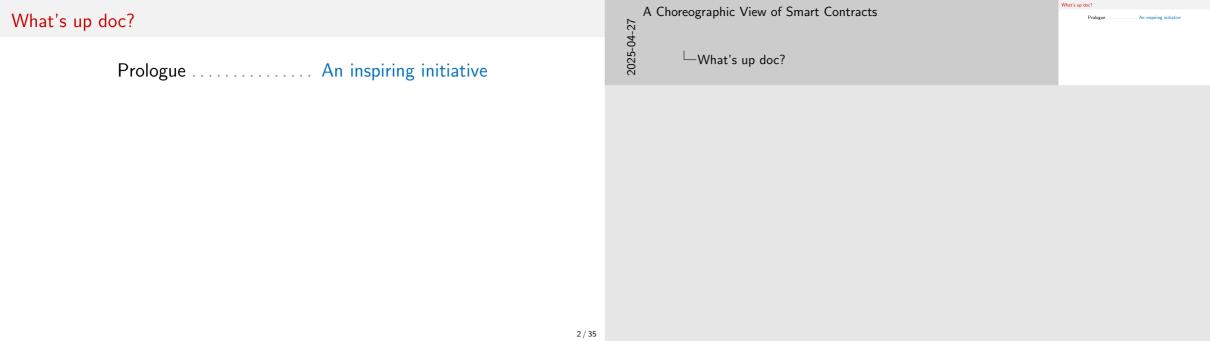
A Choreographic View of Smart Contracts

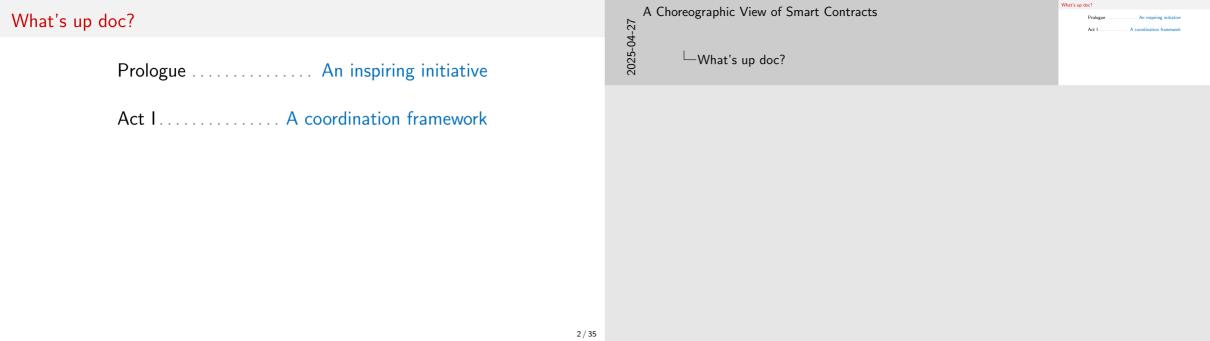
A Choreographic View of Smart Contracts

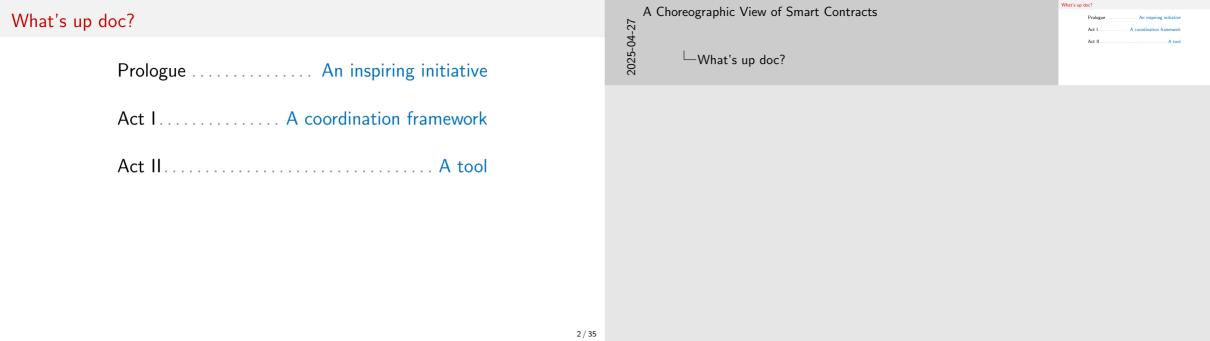
Emilio Tueste © COST

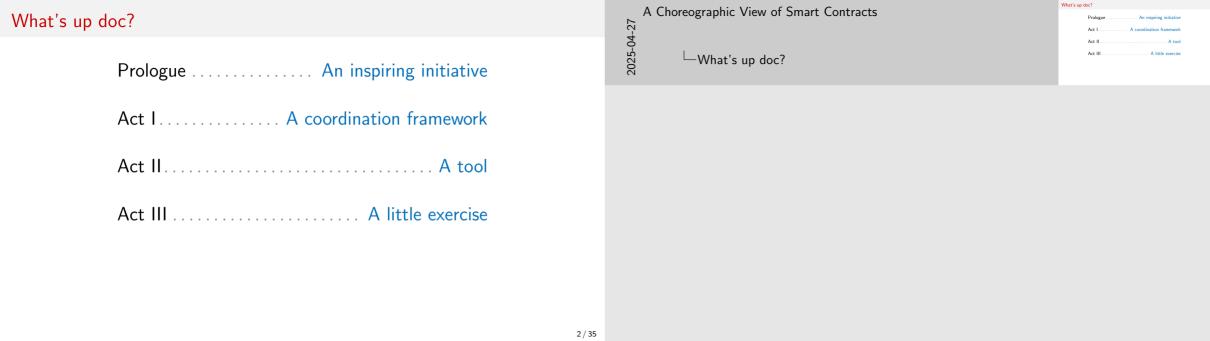
joint work with

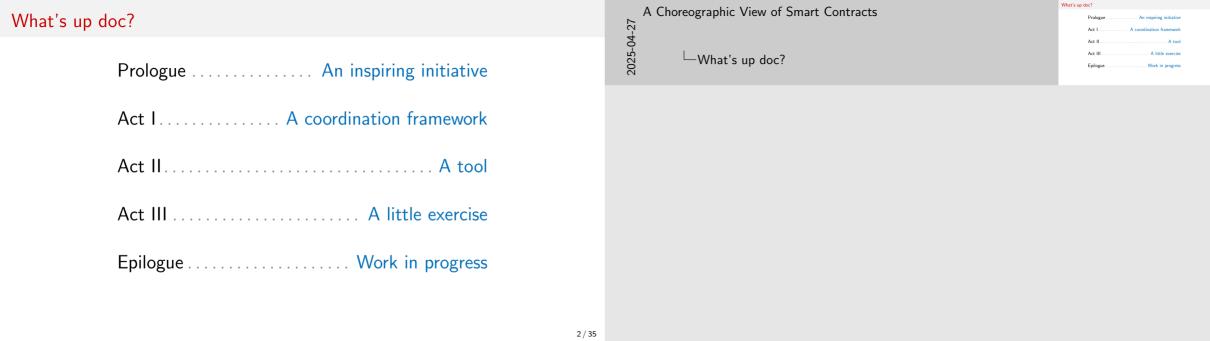
Gerarde Korjak Sdali Mauritio Morgia Antonio Revura









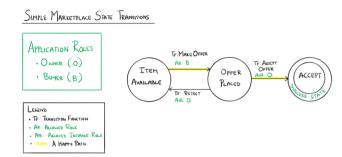


- Prologue -
- [ An inspiring initiative ]

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# A nice sketch! [5, 6]

A smart contract among Owners and Buyers



initially buyers can make offers then

either an owner can accept an offer and the protocol stops
or the offer is rejected and the protocol restarts

A Choreographic View of Smart Contracts

A nice sketch! [5, 6]

A nice sketch! [5, 6]

## What did we just see?

A smart contract looks like

a choreographic model

global specifications determine the enabled actions along the evolution of the protocol

a typestate In OOP, "can reflects how the legal operations on imperative objects can

change at runtime as their internal state changes." [2]

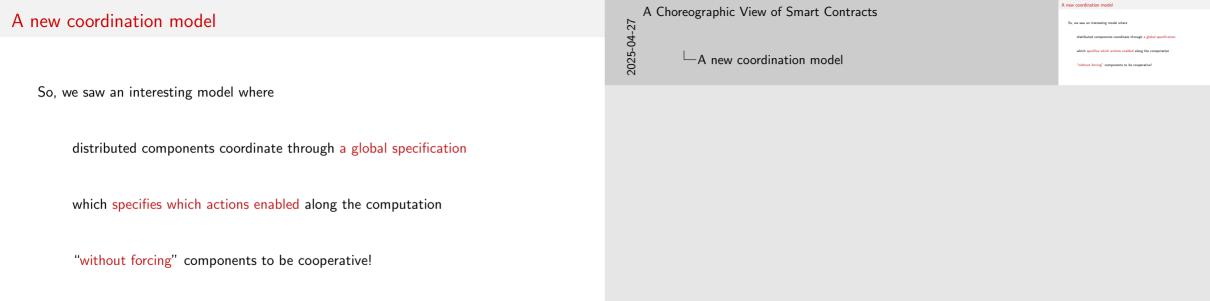
A Choreographic View of Smart Contracts

What did we just see?

A smart contract looks like

global specifications determine the enabled actions along the evolution of the

What did we just see?



# Let's look again at our sketch

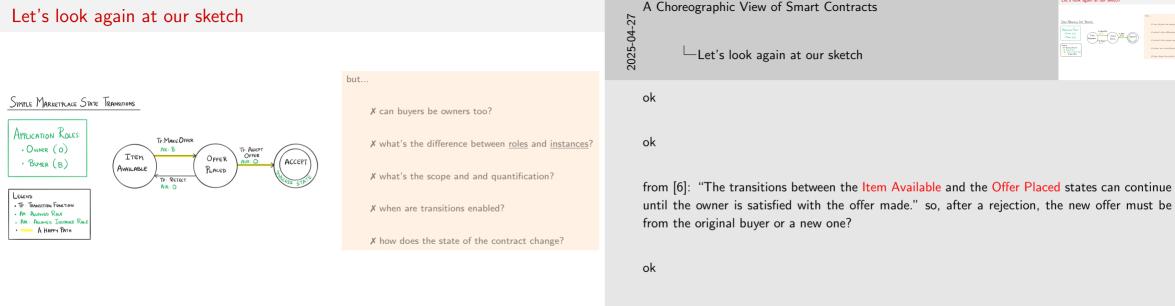
#### SIMPLE MARKETPLACE STATE TRANSITIONS APPLICATION ROLES: TF: MAKE OFFER · OWNER (O) OFFER ITEM OFFER (ACCEPT) · BUYER (B) AVAILABLE PLACED TF: REJECT LEGEND · TE : TRANSITION FUNCTION · AR: ALLOWED ROLE . AIR: ALLOWED INSTANCE ROLE · A HAPPY PATH

A Choreographic View of Smart Contracts

Let's look again at our sketch

| September | Sept

Let's look again at our sketch



Let's look again at our sketch

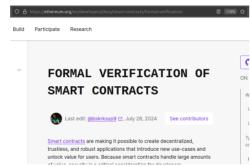
should the price of the item remain unchanged when the owner invokes the Reject?

#### ...and by the way



Bug-free programming is a difficult task and a fundamental challenge for critical systems. To this end, formal methods provide techniques to develop programs and certify their correctness.

https://medium.com/@teamtech/formal-verification-of-smart-contracts-trust-in-the-making-2745a60ce9db



https://ethereum.org/en/develo pers/docs/smart-contracts/forma l-verification/

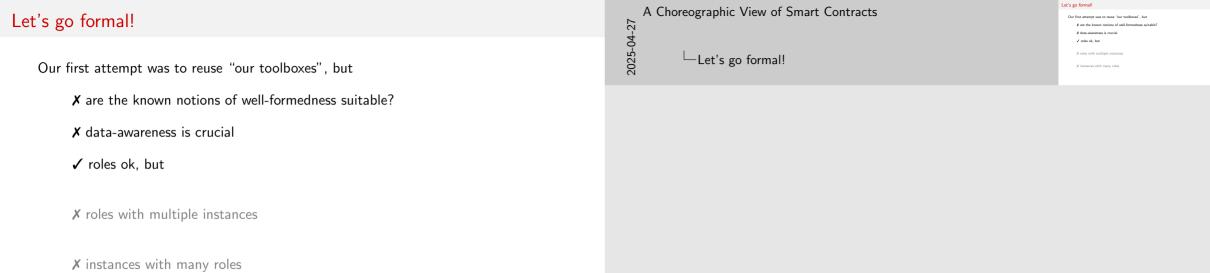
#### A Choreographic View of Smart Contracts

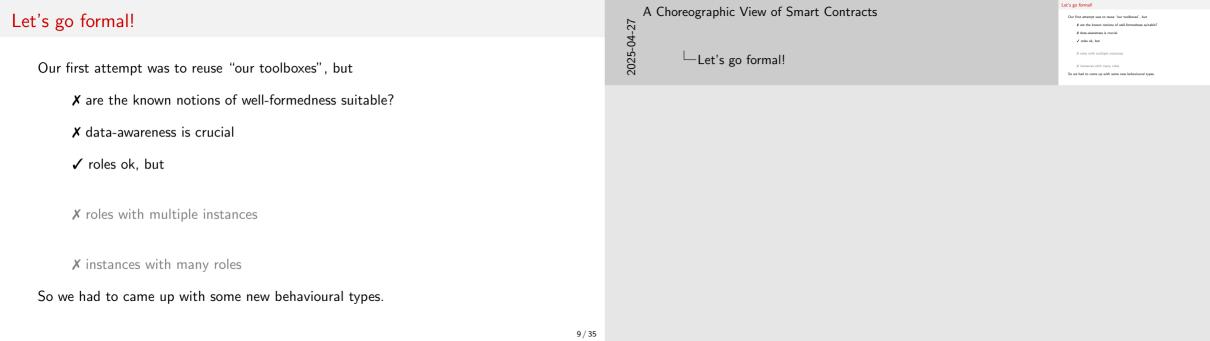


https://athereum.org/en/devel-

and by the way

\_\_\_\_ ...and by the way



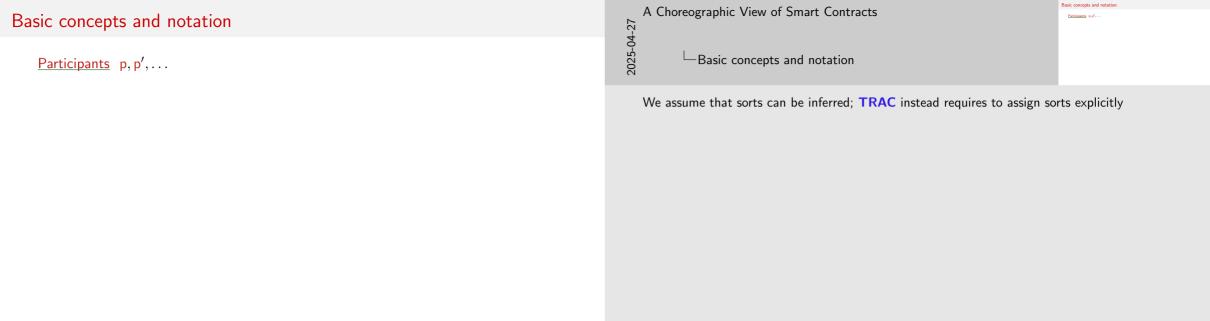


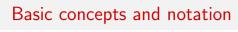
A Choreographic View of Smart Contracts

- Act I -A coordination framework

- Act I -

[ A coordination framework ]





Participants  $p, p', \dots$ 

have  $\underline{\text{roles}}$  R, R', . . .

Basic concepts and notation We assume that sorts can be inferred; TRAC instead requires to assign sorts explicitly

A Choreographic View of Smart Contracts

Basic concepts and notation

Participants p.p. have roles R,R',...

Participants  $p, p', \dots$ 

have roles  $R, R', \dots$ 

cooperate through a coordinator c

Basic concepts and notation

A Choreographic View of Smart Contracts

cooperate through a coordinator

Basic concepts and notation

 $\underline{\mathsf{Participants}} \ \ \mathsf{p},\mathsf{p'},\ldots$ 

have roles  $R, R', \dots$ 

cooperate through a coordinator c

which can be thought of as an object with "fields" and "methods":

ਲੂੰ □ Basic concepts and notation

A Choreographic View of Smart Contracts

ion

Basic concepts and notation

have roles R.R'...

```
Participants p, p', \ldots have roles R, R', \ldots cooperate through a coordinator c which can be thought of as an object with "fields" and "methods":
```

• u, v, ... represent sorted <u>state variables</u> of c (sorts include data types such as 'int', 'bool', etc. as well as participants' roles)



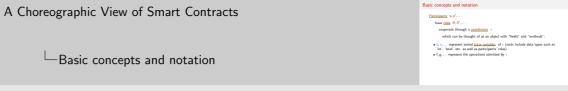
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- f.g... represent the operations admitted by c



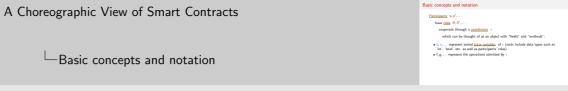
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"int" 'hool' etc. as well as narticinants' roles) Basic concepts and notation An assignment with a undates the state variable with a num expression a on function assignment) [3, 4]: B. B', ... range over finite sets of assignments where each variable

We assume that sorts can be inferred; TRAC instead requires to assign sorts explicitly Expressions are standard but for state variables occurring in rhs e must have the old \_ qualifier; this concept will be used in the definition of (progress for) well-formedness

We adapt the mechanism based on the old keyword from the Eiffel language [4] which, as explained in [3] is necessary to render assignments into logical formulae since e.g.,  $x = x+1 \iff$ False.

```
Participants p, p', \dots
```

have roles R.R'.... cooperate through a coordinator c

which can be thought of as an object with "fields" and "methods":

- u, v, ... represent sorted state variables of c (sorts include data types such as 'int', 'bool', etc. as well as participants' roles)
- f, g, ... represent the operations admitted by c

An assignment u := e updates the state variable u to a pure expression e on function parameter and state variables u or old u (representing the value of u before the assignment) [3, 4];  $B, B', \ldots$  range over finite sets of assignments where each variable can be assigned at most once

A Choreographic View of Smart Contracts

Data-Aware FSMs

 $^{2}$  for S, Oof. 1), here we just simplified the notation and adapted it to our mosts.

a participant p whose transitions are decorated with specific labels as follows

A DAFSMs c on state variables  $u_1, \ldots, u_n$  is a finite-state machine "instantiated" by a participant p whose transitions are decorated with specific labels as follows<sup>1</sup>

$$\nu \, \mathsf{p} \colon \mathsf{R} \triangleright \mathsf{start}(\mathsf{c}, \cdots, T_i \times_i, \cdots) \, \{\cdots \, \mathsf{u}_j := \underset{\bullet}{\mathsf{e}_j} \cdots \}$$

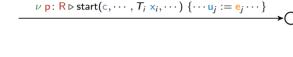
the DAFSM c is freshly created by p instantiating state variables  $u_j$  with expressions  $e_j$  on state variables and the parameters  $x_i$ 

each state variable is declared and initialises with type-consistent expressions on state variables and parameters  $\mathbf{u}_j$ 

start is a "build-in" (and pleonastic) function name

<sup>&</sup>lt;sup>1</sup>See [1, Def. 1]: here we just simplified the notation and adapted it to our needs

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the DAFSM c is freshly created by p instantiating state variables  $\mathbf{u}_j$  with expressions  $\mathbf{e}_j$  on state variables and the parameters  $\mathbf{x}_i$ 

where  $\gamma$  is a guard (ie a boolean expression) and  $\pi ::= \nu p : R \mid \text{any } p : R \mid p$  is a qualified participant calling f with parameters  $x_i$  state variables are reassigned according to B if the

invocation is successful

Data-Aware FSMs

Data-Aware FSMs

 $\gamma$  predicates over state variables and formal parameters of its transition; guards have to be satisfied for the invocation to succeed: an invocation that makes the guard false is rejected

 $\nu$  p: R specifies that p must be a fresh participant with role R any p: R qualifies p as an existing participant with role R p we refer to a participant in the scope of a binder invocations from non-suitable callers are rejected

the variables occurring in the right-hand side of assignments in B are either state variables or parameters of the invocation

See [1. Def. 1]: here we just simplified the notation and adapted it to our needs

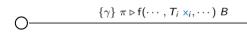
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$$\frac{\nu \mathsf{p} \colon \mathsf{R} \triangleright \mathsf{start}(\mathsf{c}, \cdots, T_i \times_i, \cdots) \left\{ \cdots \mathsf{u}_j := \mathsf{e}_j \cdots \right\}}{}$$

ables and the parameters  $x_i$ where  $\gamma$  is a guard (ie a boolean expression) and

the DAFSM c is freshly created by p instantiating

state variables  $u_i$  with expressions  $e_i$  on state vari-



 $\pi ::= \nu p: R \mid any p: R \mid p$ is a qualified participant calling f with parameters  $x_i$ state variables are reassigned according to B if the invocation is successful



accepting states are denoted as usual

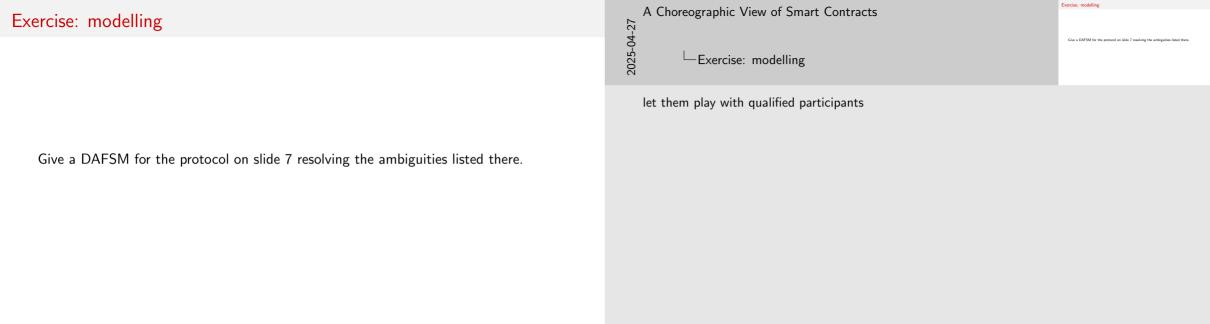


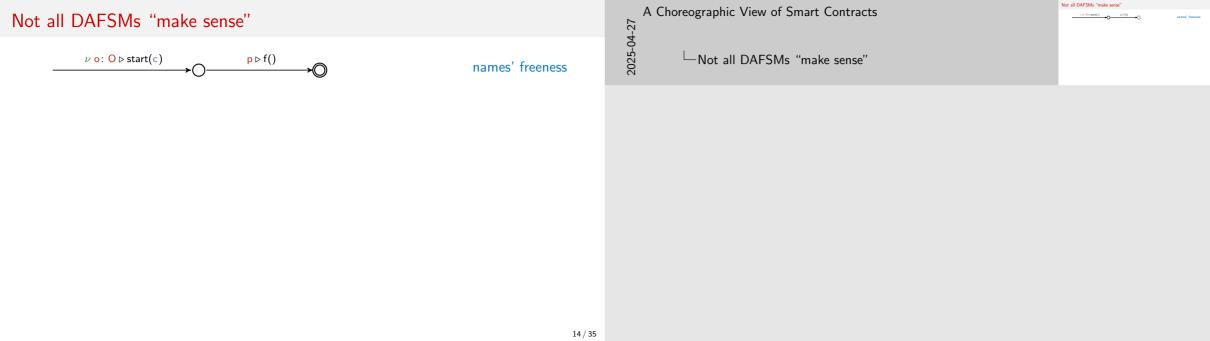


the DAFSM c is feetbly created by p instantiating state variables w with expressions of on state var



<sup>&</sup>lt;sup>1</sup>See [1, Def. 1]; here we just simplified the notation and adapted it to our needs









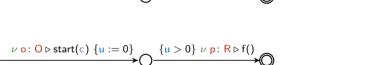
 $\nu \circ : \mathsf{O} \triangleright \mathsf{start}(\mathsf{c})$ 



any p: R⊳f()

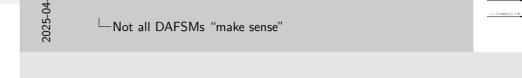








no progress



A Choreographic View of Smart Contracts

Not all DAFSMs "make sense"



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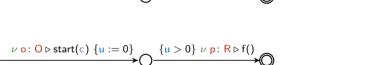
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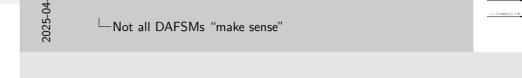








no progress



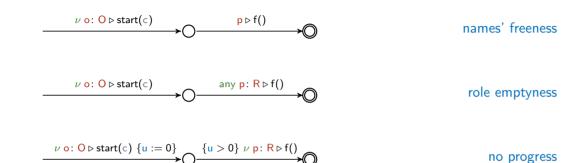
A Choreographic View of Smart Contracts

Not all DAFSMs "make sense"

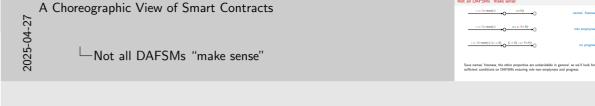


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Save names' freeness, the other properties are undecidable in general, so we'll look for sufficient conditions on DAFSMs ensuring role non-emptyness and progress.

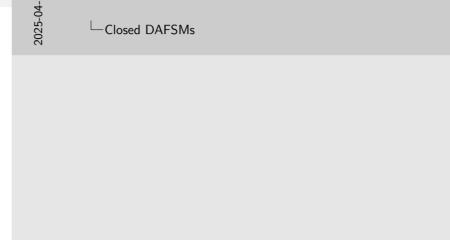


Not all DAFSMs "make sense"



Binders: parameter declarations in function call,  $\nu$  p: R, and any p: R





A Choreographic View of Smart Contracts

Closed DAFSMs

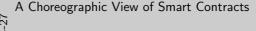
Binders: parameter declarations in function call, up: R, and any p: R

#### Closed DAFSMs

Binders: parameter declarations in function call,  $\nu$  p: R, and any p: R

p is bound in 
$$\bigcap \{\gamma\} \ \pi \triangleright f(\cdots, T_i \times_i, \cdots) \ B$$
 if, for some role R,

$$\pi = \nu$$
 p: R or  $\pi = \text{any p: R}$  or there is i s.t.  $x_i = p$  and  $T_i = R$ 



Closed DAFSMs



<u>Binders:</u> parameter declarations in function call,  $\nu p: R$ , and any p: R  $p \text{ is <u>hound in O (1) } \pi \circ f(\dots, T, v_1, \dots) \text{ B O } M$ , for some role R,  $\pi = \nu p: R \text{ or } \pi = \text{any } p: R \text{ or there is } i \text{ s.t. } v_i = p \text{ and } T_i = R$ </u>

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### Closed DAFSMs

Binders: parameter declarations in function call,  $\nu$  p: R, and any p: R

p is bound in 
$$\{\gamma\}$$
  $\pi \triangleright f(\cdots, T_i \times_i, \cdots)$   $B$  if, for some role R,  $\pi = \nu$  p: R or  $\pi = \text{any p}$ : R or there is  $i$  s.t.  $x_i = p$  and  $T_i = R$ 

The occurrence of p is bound in a path

$$\{\gamma\} p \triangleright f(\cdots) B$$

if p is bound in a transition of  $\sigma$  before  $\bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p \triangleright \cdots (\cdots, T_i \times_i, \cdots) B \longrightarrow \bigcap \{\gamma\} p 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A Choreographic View of Smart Contracts

Closed DAFSMs

Closed DAFSMS  $\frac{\lim_{\Omega \to \infty} \text{parameter declinations in function call, } v \not \in \mathbb{R}, \text{ and any } p \in \mathbb{R}$   $p \text{ is bound in } \bigcirc \underbrace{(\lambda(x)^2 - \lambda^2, x - \beta^2)^2}_{\{\lambda(x)^2 - \lambda^2, x - \beta^2\}} \bigcirc \{f \text{ for some sole } R, x - p \text{ and } T \text{ or } \text{ then in list } k_1, x_1 = p \text{ and } T_2 = R$  The occurrence of p is bound in a path  $\sigma = 0 \qquad \qquad \underbrace{(\lambda(x)^2 - k_1^2 - k_2^2)^2}_{\{\lambda(x)^2 - k_1^2 - k_2^2 - k_2^2\}} \bigcirc 0$  if p is bound in a transition of  $\sigma$  before  $0 \leq 0$ .

### Closed DAFSMs

Binders: parameter declarations in function call,  $\nu$  p: R, and any p: R

p is bound in 
$$\bigcap \{\gamma\} \ \pi \triangleright f(\cdots, T_i \times_i, \cdots) \ B$$
 if, for some role R,  $\pi = \nu \ p$ : R or  $\pi = \text{any } p$ : R or there is  $i$  s.t.  $x_i = p$  and  $T_i = R$ 

The occurrence of p is bound in a path

the DAFSM they occur on

 $\sigma = \cdots \bigcirc \qquad \qquad \{\gamma\} \ \mathsf{p} \triangleright \mathsf{f}(\cdots) \ B \qquad \qquad \cdots$ 

if p is bound in a transition of  $\sigma$  before  $\bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B 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\bigcap \{\gamma\} \ p \triangleright \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots) \ B \longrightarrow \bigcap \{\gamma\} \ p \triangleright \cap \cdots (\cdots, T_i \times_i, \cdots)$ 

A DAFSM is closed if all occurrences of participant variables are bound in the paths of

Closed DAFSMs

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The occurrence of p is bound in a path if p is bound in a transition of  $\sigma$  before  $(\gamma) \circ \cdots (\cdots, T_1 \times_1, \cdots) B$ A DAFSM is closed if all occurrences of participant variables are bound in the paths

Rinders: narameter declarations in function call, u.n. R. and any n. R.

Closed DAFSMs

# Roles non-emptyness

A transition  $\bigcap \{\gamma\} \ \pi \triangleright f(\cdots, T_i \times_i, \cdots) \ B$  if  $\pi = \nu \ p : R$  or there is i s.t.  $\times_i = p$  and  $T_i = R$  expands role R

Role R is expanded in a path

$$\sigma = \cdots \bigcirc \qquad \qquad \{\gamma\} \text{ any } \mathbf{p} \colon \mathsf{R} \triangleright \mathsf{f}(\cdots) \ B \qquad \qquad \bullet \bigcirc \cdots$$

if a transition in  $\sigma$  before  $\bigcap$   $\{\gamma\}$  any  $p: \mathbb{R} \triangleright f(\cdots) B$  expands

A DAFSM <u>expands</u> R if all its paths expand R and is <u>(strongly) empty-role free</u> if it expands all its roles

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Roles non-emptyness



following implication holds for each transition 
$$\bigcirc \qquad \qquad \overbrace{ \{\gamma\} \ \pi \triangleright \mathsf{f}(\cdots, T_i \times_i, \cdots) \ B }$$
 
$$\forall (\mathsf{u}, \mathsf{old} \ \mathsf{u})_{\mathsf{u} \in \mathcal{U}} \ \exists (\mathsf{x})_{\mathsf{x} \in \mathcal{X}} : (\gamma \{\mathsf{old} \ \mathsf{u}/\mathsf{u}\}_{\mathsf{u} \in \mathcal{U}} \ \land \ \gamma_B) \implies \gamma_{\mathsf{s}}$$

where

$$X = \{x \mid \exists i : x = x_i \text{ or } x \text{ is a parameter of an outgoing transition of s} \}$$

$$\gamma_{s} = \begin{cases} \text{the disjunction of guards of the outgoing transitions of s} & \text{is not accepting} \\ \text{True} & \text{if sotw} \end{cases}$$

$$\gamma_B = \bigwedge_{\mathbf{u} := \mathbf{e} \in B} \mathbf{u} = \mathbf{e} \wedge \bigwedge_{\mathbf{u} \notin B} \mathbf{u} = \text{old } \mathbf{u}$$
 with

$$u:=e \in B$$
  $u \notin B$   $u \notin B \iff v:=e \in B \implies u \neq v$  and old u does not occur in e

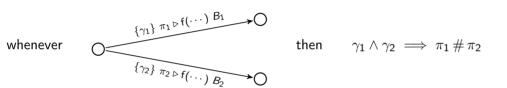
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└─ Progress

following implication holds for each transition  $\forall (u, old \ u)_{u \in U} \ \exists (x)_{s \in X} : (\gamma \{old \ u/u\}_{u \in U} \ \land \ \gamma_B) \implies \gamma$  $X = \{x \mid \exists i : x = x_i \text{ or } x \text{ is a parameter of an outgoing transition of s} \}$  $\gamma_B = \bigwedge u = \bullet \land \bigwedge u = \text{old } u$  with  $u \not\in B \iff v := \bullet \in B \implies u \neq v$  and old u does not occur in

## Determinism

# A DAFSM is deterministic if



where  $_{-}\#_{-}$  is the least binary symmetric relation s.t.

where 
$$-\#$$
 is the least binary symmetric relation s.t.  $\nu$  p: R# $\pi$  and  $\nu$  p: R# $\pi$  and  $\nu$  p: R# $\pi$  and R  $\neq$  R'  $\Longrightarrow$  any p: R# $\pi$  any p': R'

A Choreographic View of Smart Contracts ☐ Determinism

Determinism

transitions from the same source state and calling the same function

### Exercise: Determinism

The DAFSM 
$$S = \frac{\nu p : R \triangleright start(c)}{\ell_2}$$

is deterministic or not, depending on the labels  $\ell_1$  and  $\ell_2$ .

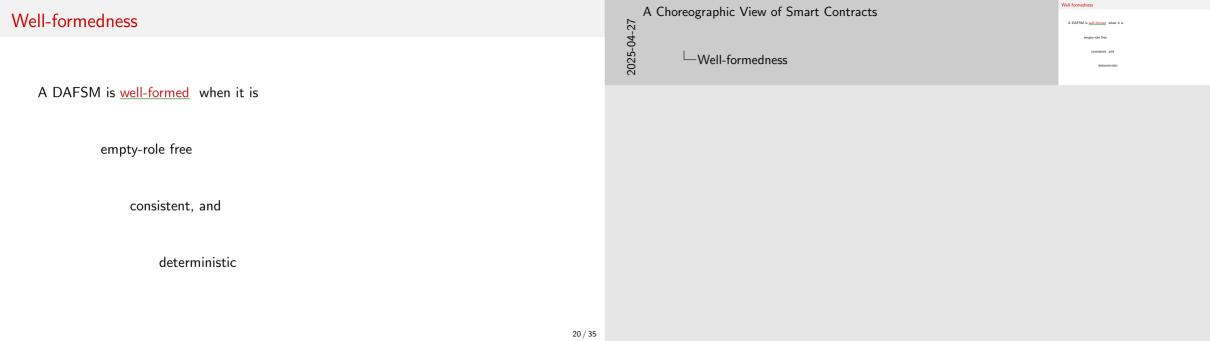
- lacksquare Is it the case that  ${\cal S}$  is not deterministic whenever  $\ell_1=\ell_2$ ?
- Find two labels  $\ell_1$  and  $\ell_2$  that make  ${\cal S}$  deterministic
- Find two labels  $\ell_1 \neq \ell_2$  that make  ${\cal S}$  non-deterministic

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Exercise: Determinism

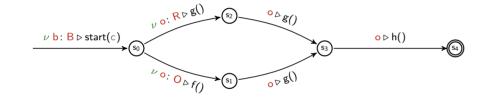


- 1. no: eg for  $\ell_1 = \ell_2 = \nu$  p: R S is deterministic
- 2.  $\ell_1 = \ell_2 = \nu$  p:  $R \triangleright f(\dots, T_i \times_i, \dots)$  make S deterministic because the next state is unambiguously determined by the caller which is fresh on both transitions
- 3.  $\ell_1 = \{x \leq 0\}$   $p \triangleright f(x : Int)$  and  $\ell_2 = \{x \geq -1\}$   $p \triangleright f(x : Int)$  make  $\mathcal S$  non-deterministic because the guards of  $\ell_1$  and of  $\ell_2$  are not disjoint therefore the next state is not determined by the caller

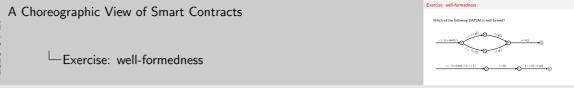


### Exercise: well-formedness

Which of the following DAFSM is well-formed?

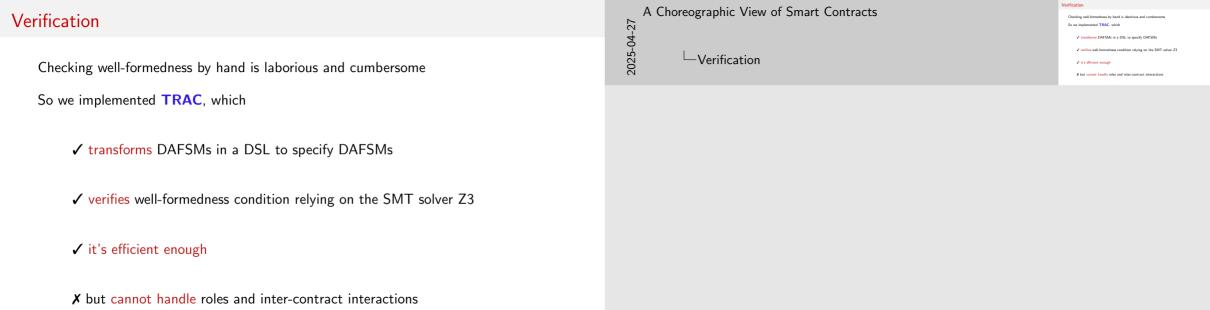


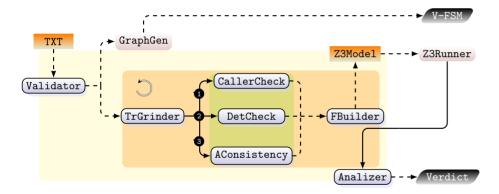




yes: o is defined on paths it occurs on and the DAFSM is deterministic.

no: the transition from  $s_0$  violates consistency since True does not imply u>0 hinting that the protocol could get stuck in state  $s_1$ . However, this never happens because u is initially set to 1 and never changed, hence the transition from  $s_1$  would be enabled when the protocol lands in  $s_1$ .

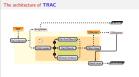




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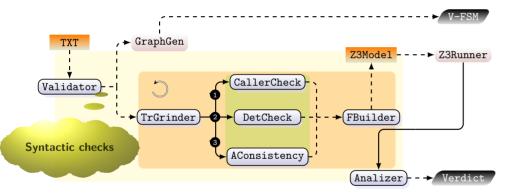
2025-04-27

☐ The architecture of **TRAC** 



the architecture of **TRAC** is compartmentalised into two principal modules: parsing and visualisation (yellow box) and

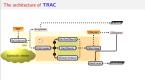
TRAC's core (orange box). The latter module implements well-formedness check (green box). Solid arrows represent calls between components while dashed arrows data IO.



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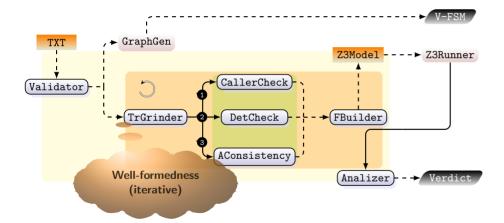
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☐ The architecture of **TRAC** 

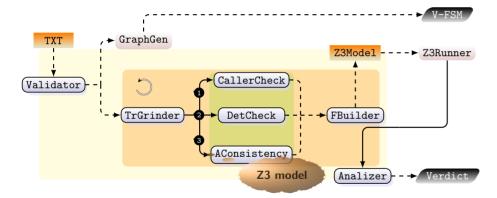


basic syntactic checks on a DSL representation of DAFSMs and transforming the input in a format that simplifies the analysis of the following phases:

- passed to GraphGen for visual representation of DAFSMs (V-FSM output)
- passed to the TrGrinder component (orange box) for well-formedness checking.

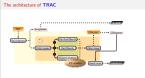




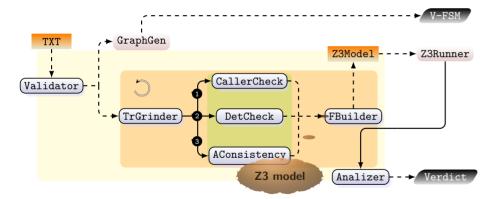


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☐ The architecture of **TRAC** 



AConsistency (arrow 3 to generate a Z3 formula which holds if, and only if, the transtion is consistent.

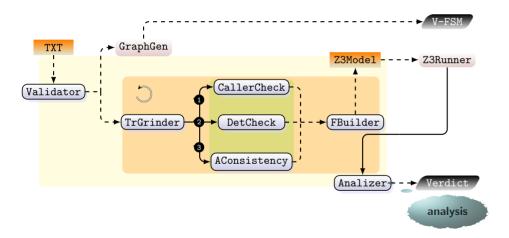


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The architecture of TRAC

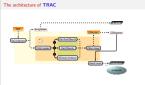
The architecture of **TRAC** 

computes the z3 f.la equivalent to the conjunction of the outputs which is then passed to a Z3 engine to check its satisfiability

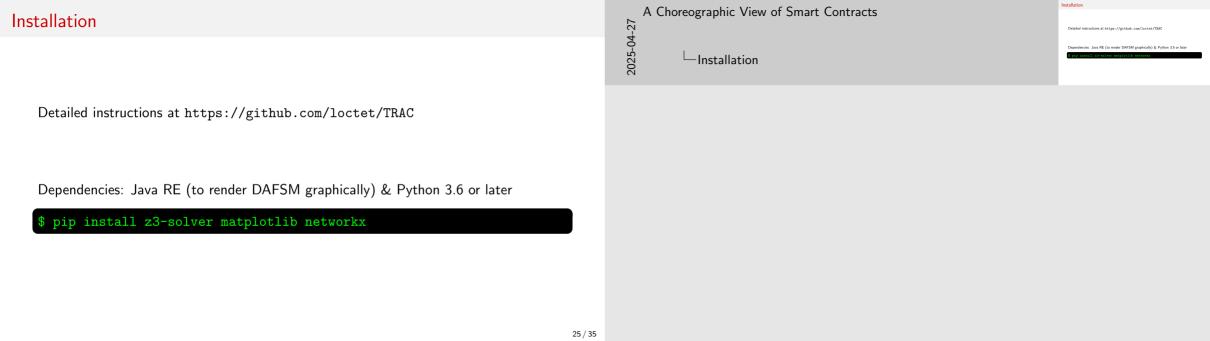


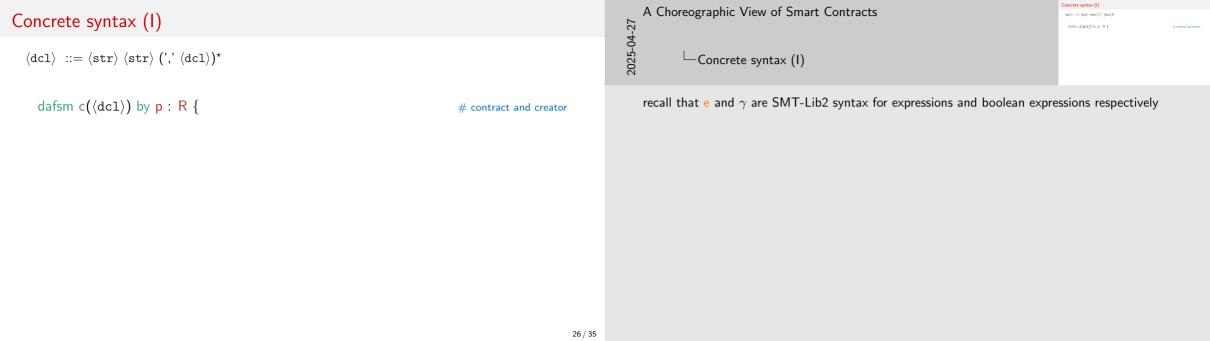
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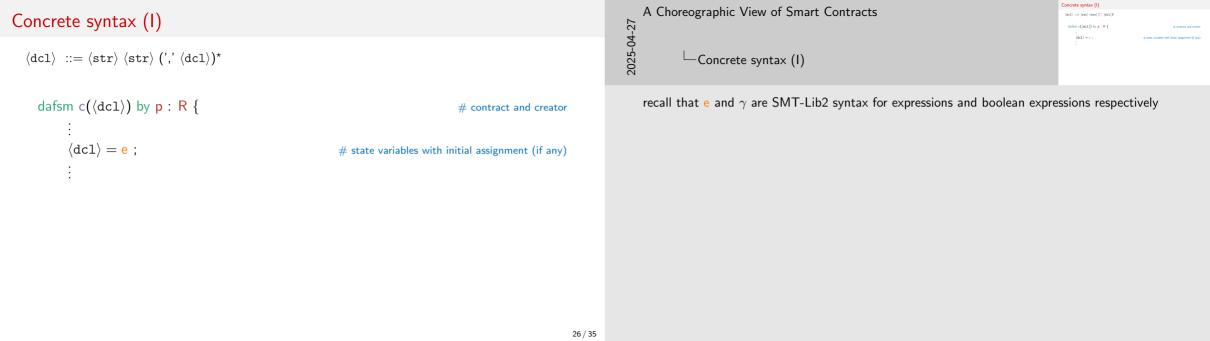
The architecture of **TRAC** 

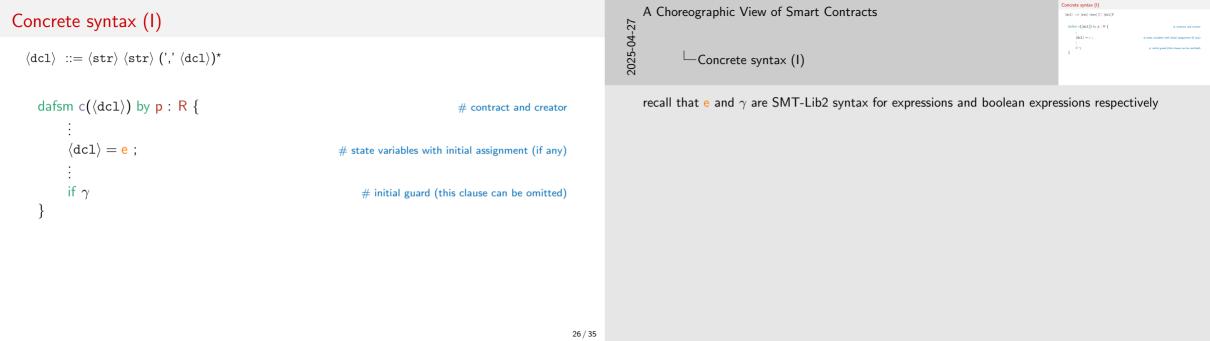


Finally, the Analizer component that diagnoses the output of Z3 and produces a Verdict which reports (if any) the violations of well-formedness of the DAFSM in input.



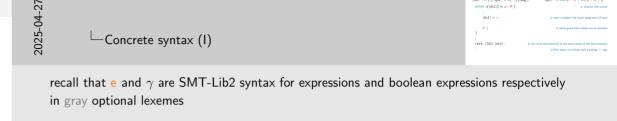






# Concrete syntax (I)

```
\langle dcl \rangle ::= \langle str \rangle \langle str \rangle (',' \langle dcl \rangle)^*
                                                                                \langle asg \rangle ::= \langle str \rangle ':=' e (';' \langle asg \rangle)^*
                                                                               \langle qlf \rangle ::= new p':' R \mid any p':' R \mid p
\langle lbl \rangle ::= \{ \gamma \} \langle qlf \rangle '>' f(\cdots) \{ \langle asg \rangle \}
   dafsm c(\langle dcl \rangle) by p : R 
                                                                                                                       # contract and creator
            \langle dc1 \rangle = e:
                                                                                      # state variables with initial assignment (if any)
           if \gamma
                                                                                            # initial guard (this clause can be omitted)
    ⟨str⟩ ⟨lbl⟩ ⟨str⟩;
                                                             # the initial state defaults to the source state of the first transition
                                                                                      # final states are strings with a trailing '+' sign
```

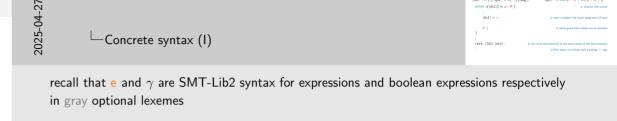


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Concrete syntax (I)

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```
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                                                             # the initial state defaults to the source state of the first transition
                                                                                      # final states are strings with a trailing '+' sign
```



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Concrete syntax (I)



Edit a .trac file for the DAFSM on slide ??.

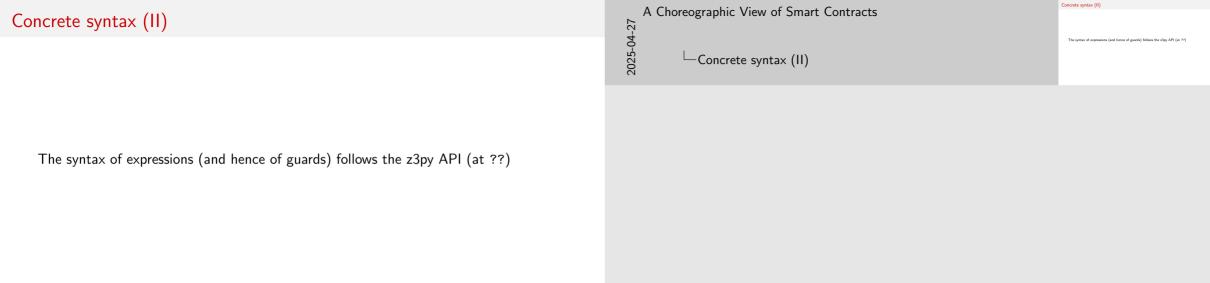
Exercise: TRAC syntax (I)

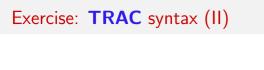
use basic\_provenance.txt ?

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Exercise: TRAC syntax (I)

Edit a strac file for the DAFSM on slide ??





Edit a .trac file for the DAFSM on slide ??.

Exercise: TRAC syntax (II)

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syntax (II)

Edit a . truc file for the DAFSM on slide ??.

Exercise: TRAC syntax (II)

- Act III -

- Act III -

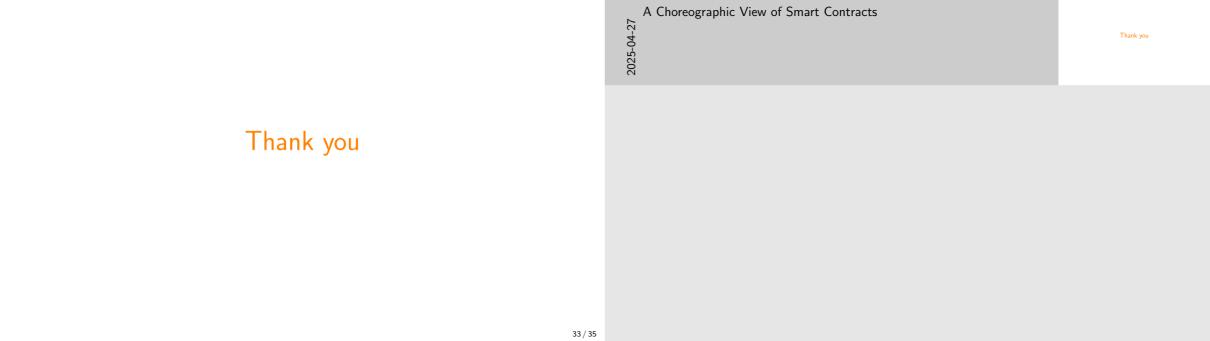
[ A little exercise ]

A Choreographic View of Smart Contracts  70-45  800  100  100  100  100  100  100  10	
https://github.com/blockchain-unica/rosetta-smart-contracts/tree/main/c	contracts/vesting

Epilogue –

[ Work in progress ]

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[1] J. Afonso. E. Konjoh Salabi, M. Murgia, A. Ravara, and E. Tousto. TRAC: A too for data-aware coordination, - (with an application to some contraction). In L. Castellania and F. Tiezzi, editors, Coordination Models and Languages - 26th IEEE Conference on COORDINATION 2024, Held as Part of the 18th World Computing Techniques, Discorber 2023, Connegon, The Mathenhands, London Conference on Distributed Computing Techniques, Discorber 2023, Connegon, The Mathenhands, June 1-722, 2024, Proceedings.

[2] R. Garcia, E. Tanter, R. Wolff, and J. Aldrich. Foundations of typestate-oriented programming. ACM Trans. Processor Lang. Syst., 28(4), Oct. 2014.

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