An important variant A labelled transition system is a triple (5, 1, ->) where - S is a set of states - A is a set of lebels (or actions, or operations, or events, ...) (→: S →> Z AXS) transition relation - → ⊆ S×A×S sommenication longulation about what happens during the tousition posticularly handy to model communication / concoursency / distribution Exemple An FSA, M= (Q,Z, 90, S,F) is en LTS: e = 2 & s' & S(s, a) LTSM= (Sulo), Sulv), >) where s > s' = v & s'= · & sEF

$$\mathcal{L}_{M} = \left\{ a_{1} ... a_{n} \in \mathbb{Z}^{N} \mid \overline{J}_{1},...,q_{n} \mid q_{n} \xrightarrow{a_{1}} \dots q_{n-1} \xrightarrow{a_{m}} q_{n} \xrightarrow{a_{m}} q_{n} \right\}$$

Communication-based concurrency

A robotic scenario:

Some mobile robots need to manage their energy in order to accoplish their task (e.g., patrolling some premises).

- When their batteries deplete, robots look for a recharge.
- Recharges are offered by recharge stations or other robots.

We can model this behaviour using an LTS capturing the observable features we are interested in: in this case communication For instance, the behaviour of a robot seeking for a recharge is

The set of labels is the union of

- {b low, b ok}

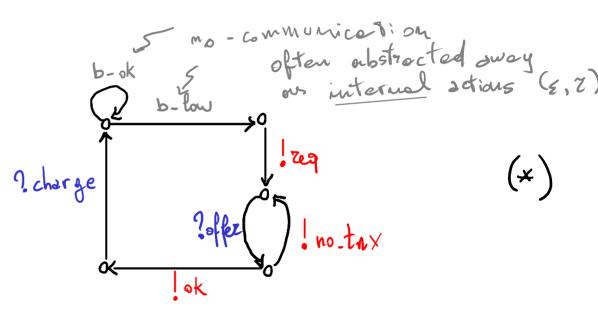
- {?charge, ?offer}

- {!req, !no tnx}

internal actions

input actions

output actions



Exercise 4

Give an LTS modelling the behaviour of a robot offering a recharge.

Reflect about the "compatibility" between your solution and the LTS (*) above

A more sophisticated example

Petri Nets

A Petri net (aka place-transition) met is a 4-tuple

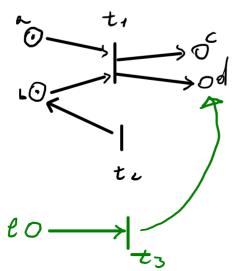
N=(P,T,F,m) where

· P is a finite set (of places)

· T is a finite set (of transitions)

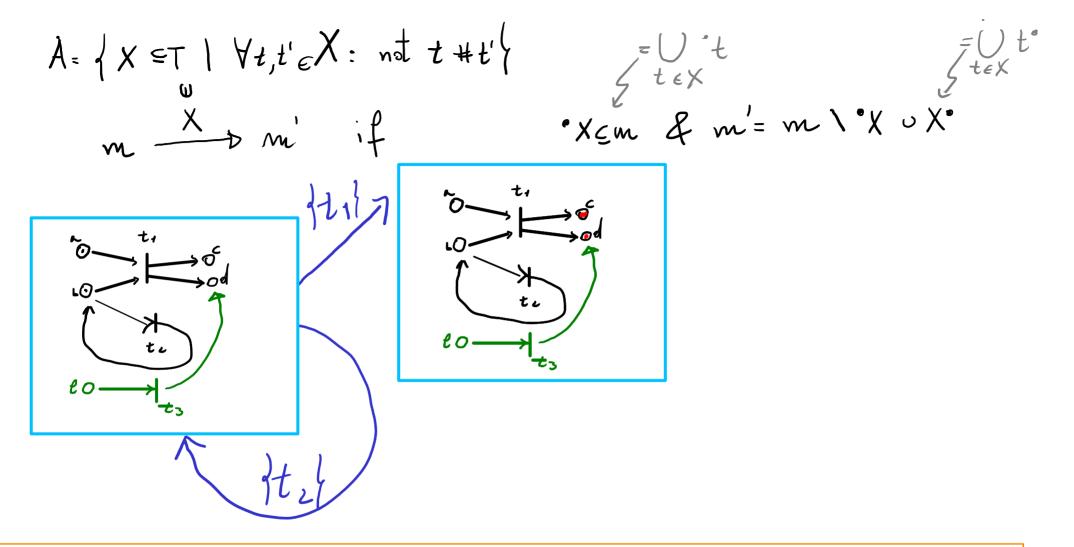
· F ∈ (PxT) v (TxP) is a (flow) relation

. mcP is the initial marking



>0 with marking m=10,64

 $t = \{p \text{ in } P \mid (p,t) \text{ in } F\}$ $t' = \{p \text{ in } P \mid (t,p) \text{ in } F\}$ $t_1 \neq t_2 \Rightarrow t_1 \neq t_2 \land t_n t_n \neq \emptyset$



Exercise 5
Give the transition system obtained from the initial marking {a,b,e}

Regular expressions

BNF. like syntex A, finite alphabet

Exist to | 1 | a | E+E | E·E | E*

and skip atomic instruct.

Dendational semanties:
$$L: E \longrightarrow 2^{A*}$$
 $L(0) = \emptyset$
 $L(1) = 1E$
 $L(a) = 1a$
 $L(a) = 1$

Exercise 6

Prove or disprove that $(a + b)^* = (a^* + b^*)^*$

Term	A	lge	br	as

assume ({f2,..., fn}.02) ar: {f2,..., fn} ~~ w SUnffiniful = \$

Term Algebra

The term elgebre on a signature I and a countible set V of variables is the smallest set Termy v s.t.

- $\forall f \in \Sigma$, $t_{1,...,t_{az(f)}} \in \text{Term}_{\Sigma,V}$: $f(t_{1,...,t_{ar(f)}}) \in \text{Term}_{\Sigma,V}$

Ty = Term, is the set of does terms

Exercise 7

Explain why in the above definition it is essential to require that Termy is the smallest set

· are either variables 02 "constants" (i.e (e [s. + ar(c) - 10)

Exercise 8

Give the term algebra for regular expressions

Transition System Specifications

"The first systematic study of TSSs may be found in [208], while the first study of TSSs with negative premises appeared in [57]." (Aceto et al.) [208] R. d. Simone, Calculabilité et Expressivité dans l'Algèbre de Processus Parallèles Meije, thèse de 3 e cycle, Univ. Paris 7, 1984. [57] B. Bloom, S. Istrail, and A. Meyer, Bisimulation can't be traced: preliminary report, in Conference Record 15th ACM Symposium on Principles of Programming Languages, San Diego, California, 1988, pp. 229–239. Preliminary version of Bisimulation can't be traced, J. Assoc. Comput. Mach., 42 (1995), pp. 232–268.

