

Electrical grid simulation in the COLMENA framework

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1 Introduction

COLMENA is a decentralized framework that allows the coordination of multiple agents to solve complex problems. The framework is based on the concept of a colony of agents that can communicate and coordinate to solve a problem. The agents can be programmed to have different roles and behaviors. The objective of the project is to develop a test case for the COLMENA framework in the context of electrical grids using the simulation tools provided by ANDES [1](later on, potentially others). The resulting goal is to showcase the capabilities of COLMENA in the context of a decentralized electrical grid, providing useful use cases showing noticeable improvements to be derived from this architecture. The present document is an answer to Objective 1 - Development plan for the validation of the platform.

I would start by saying what the objective of the project as a whole is. You can read the technical offer inside the documentation folder. For example:

1.1 Power Grid & Service definition

We define an electrical grid as a set of nodes called buses with electrical devices attached to them. The nodes are interconnected between them through branches, traditionally, power lines and/or transformers. The devices connected to each given bus are generators, loads or others types of devices. In ANDES, each device is defined by a set of differential and algebraic equations (DAE) that define how the devices' states change over time.

Let's draw a simple network showing buses and lines between them to give

a first idea of the systems we are dealing with.

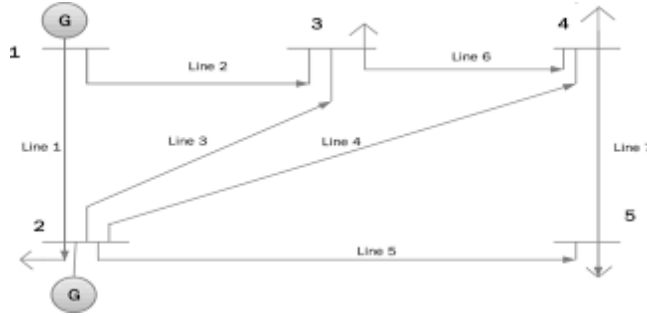


Figure 1: Power grid diagram with buses, lines and generators.

The electrical grid is defined by multiple magnitudes that define its overall state. Some of the more critical metrics that we consider are the following. The one most important to our use case is the frequency since it's linked with most other values and a drop in general, maintaining the frequency is one of the most important tasks of a grid operator.

- **Make bold each item such as below**
- **Frequency:** The frequency can be understood as a local measurement that describes the voltage at a specific bus. A device called Phasor Measurement Unit (PMU) can measure the frequency of the bus it is connected to. Maintaining the frequency at the nominal value (e.g. 50 Hz in Europe) is key for the proper functioning of the grid. Frequency values above or below this value can unbalance the grid from a power point of view or even damage certain components. It is worth mentioning that while the frequency is a local variable, it is often the case that the frequency is the same, or very similar, in all buses.
- **Something to be aware of:** is the frequency at each bus a different variable from the synchronous rotor speed? You say the two are very closely related, which is true, but I do not know if ANDES treats them separately.
- **Synchronous Generator Shaft's Speed:** Synchronous generators are device that generate power which is then inject to the grid. This is done by magnetically coupling a stator and a rotor that spins at a certain speed, ideally as close as to the nominal frequency. The value of the frequency in the grids buses and the angular speed of the rotor are closely linked and are frequently used interchangeably. In fact, generators can see a drop in their angular speed to mitigate a drop in frequency in a close bus.
- **Better to mention voltage magnitude, just to avoid confusion**

- **Voltage Magnitude(V)**: The voltage is a magnitude linked to a specific bus and also needs to be as close to the nominal value as possible. Drops in frequency can be linked to drops in voltage.
- **Power injected/consumed (kW)**: The power injected is by a generator is the amount of power the . The objective of the grid supervisor is to keep the balance of power as close to zero as possible. Raising the amount of power injected by a generator also tends to raise its synchronous speed. It's an important lever in controlling

From the various available grid measurements, I would emphasize we will focus on the frequency for these first study cases. This will make the following explanation more clear I think.

Magnitude	Unit	Description
Voltage	kV	Voltage at a bus
Generator Speed	Hz	Rotations of the shaft er second
Current	A	Current through a branch
Frequency	Hz	Frequency of the sinusoidal voltage signal at a bus
RoCof	Hz/s	Frequency's derivative
Power Injected	kW	Power injected to the grid by a generator.

Table 1: Summary of the metric's definition

The metrics just introduced are key to defining the performance of a grid and to the frequency control response of a power grid. The objective of the frequency response is multiple. On a first time scale (primary response)[2], the control aims to take the system from a transient to a stable condition and avoiding critical values for the frequency. During the secondary response, the objective is to restore the steady state values to their nominal values. Finally, the last response's objective is to restore the the power reserves to their original value [3].

The objective of the service implemented in COLMENA will be then to aid to the frequency control response by implementing decentralized roles that can improve the performance of the control. These roles will take the form of changing set-points for certain devices, connecting or disconnecting devices such as secondary generators and others.

Additionally, we will define the different metrics in relations to their context in the grid. This means that every metric is measured in a specific context like a given area or a type of electrical device. This way we can group the values of the previously defined metrics in specific contexts such as the following and develop more specific insights.

- Local: Measurements that can be done in the same device.
- Semi-Local: Measurements that can be done in the devices connected to the same bus.
- Regional: Measurements that can be done in the devices from the same given area.
- Categorical: Measurements that can be done in the devices of the same type.
- Adjacent: Measurements that can be done in the devices that are just one connection away.

1.2 Devices

Power system simulations, such as the ones performed by the ANDES package, are organized around devices. Each device at a given time t is defined by the value's of the algebraic variables and state variables. Devices of the same type have the same variables. In the context of the frequency service control we have found the following devices that can be useful to the simulation and also present some sort of decentralized control.

For each device below, explain: its electrical purpose, if they are injections or branches in the topology, and if they can be controlled.

- Synchronous Generators: They inject power to the grid.
- Converters & distributed generations: Used to convert power from distributed generation from DC to AC, usually associated to some sort of distributed generation.
- Loads: They consume power from the grid.
- Lines: They connect different buses.
- Switches: They allow the flow of power through a Line.

In the following sections we will see how these devices fit with the service of controlling the frequency.

Synchronous Generators

Generators are devices that inject power to the grid. A synchronous generator injects the power through a rotating part that spins synchronously to the grid's

frequency. The synchronous generators in the simulation will be defined by two internal states: $\omega \in \mathbb{R}$ the angular velocity and $\theta \in \mathbb{R}$ the shaft's angular position. The generator's turbine can set the value of the power being injected by the generator's or the set point for the reference angular speed ω_{ref} . Controlling these set points is key to improve the performance of the grid and impacts the directly on the grid. The generator model used in the simulation can be consulted at [4] and [5], it also includes the governor's and the exciter's model.

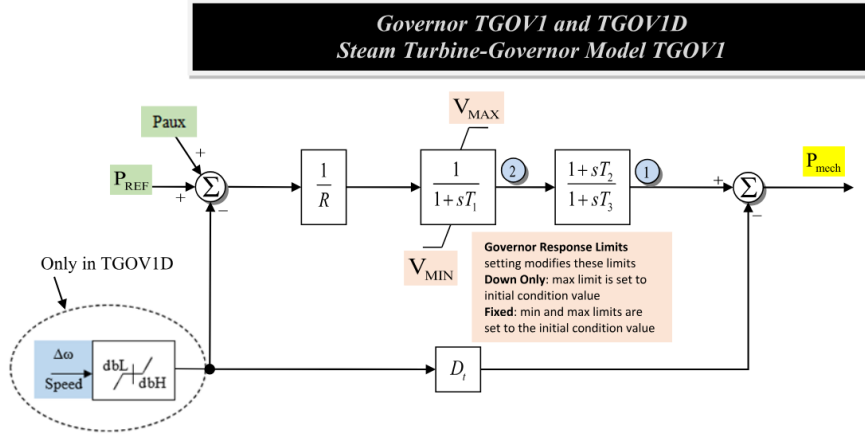


Figure 2: Block diagram of a generator's governor controlling the injected power. [4]

Converters & distributed generation

Converters can take the form of a Voltage Source Converter (VSC). A VSC is a converter (converts a DC current to AC) with some differences to classical converters. They are commonly used to track the angle of the grid at a bus and inject (or absorb) active and reactive power from an energy source. They are usually paired with DC sources of energy as a way to connect them to the grid. We consider a VSC that can operate in two modes: 'Grid following'(GFL) and 'Grid forming'(GFM).

- **Grid Following:** In the GFL mode, the converter tracks the grid's frequency and injects a controlled power, acting as an ideal current source.
- **Grid Forming:** In the GFM mode, the converter creates its own frequency and imposes a voltage differential acting as an ideal voltage source.

In terms of control, both GFM and GFL have reference values they have

to track with controllers. The control is built with the goal of following the reference value as close as possible. For the GFL mode the reference value usually refers to the power injected, while for the GFM its the frequency or voltage. This GFM behavior is quite close to one of a typical synchronous generator. The flexibility and the different set points of this type of converter fit well with the decentralized control principle of COLMENA.

The modelling of distributed generation, modelling tools usually combines the generation considered as a DC current source and a battery that are connected to a AC-DC converter. The converter that is paired to this ensemble can control both the active and reactive power that is injected to the grid and that is stored in the battery (if present). The control of the setup is defined by the parameters $\gamma_p, \gamma_q \in [0, 1]$. These parameters define which proportion of the active and reactive power respectively and generated by the setup is injected to the grid. We can therefore define different set points for the distributed generation depending on the power injected. The power that is not injected is then saved by the battery. This can be expressed as these three different set points:

- $\gamma_p = 1$ all of the power generated is injected to the grid.
- $\gamma_p = 0$ all of the power generated is stored in the battery.
- $\gamma_p = 0.5$ half of the power generated is injected to the grid and half is stored in the battery.

To me it makes more sense to move this paragraph to the beginning of the section, as it is the first time you mention converters, and then detail the control of converters and the γ factor.

Loads

Recommendation to add a bus indicating powers flowing there, and voltages as nodal magnitudes. It will make it easier to understand for people in the BSC. A load is an electrical model that is connected to a bus and consumes a given amount of active and reactive ($P(MW), Q(Mvar)$ respectively). In the context of the frequency control service, the load device can have varying values of P and Q depending on the state of the grid. More specifically, operators can control the power consumed by enforcing load shedding which consist in reducing part of the power being used. This response can be very useful to the grid in order to adapt to drops in generation or line faults.

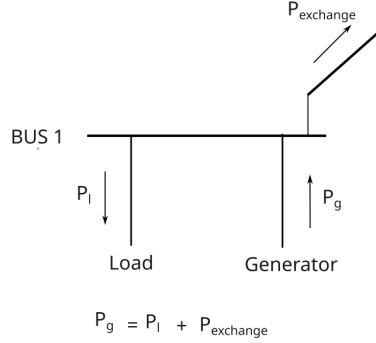


Figure 3: Bus power exchange diagram.

Switches

Switches are controllable elements that control the connection state of a Line. In this case the set states are just 'Open' or 'Closed'. In the open state no current travels directly between the buses while in the Closed state the line works at normal operation.

1.3 Andes-COLMENA Integration requirements

In this section we explain how ANDES and COLMENA will work during the simulation and how they will communicate. As a standalone, ANDES simulates the time domain response of the power grid for a pre-set amount of time. The package solves the equations numerically and returns the solution but it does not simulate the grid in real time. To enable the integration with COLMENA we modify ANDES into running for a given step-size only when the real time is greater than the simulation time in order for it to catch-up to. ANDES is run parallel to COLMENA on an independent app run on an separate device not part of COLMENA's colony of agents. Specific COLMENA Agents will periodically send requests to the ANDES App to get the simulation's information and to send changes.

From the COLMENA's side, we will define specific COLMENA-agents that will be paired with a single ANDES-device in the grid. The COLMENA-agent will have two main roles in a continuous manner. They will read their device's variables, store the values internally, and send the behavior changes in the form of new set-point and parameter changes for the paired device. These roles will be the building blocks of the COLMENA-ANDES integration.

Here one of the diagrams you had on the slides would be useful

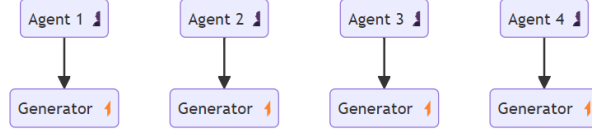


Figure 4: COMENA-Agent pairing diagram.

2 Use Case Specification

Just wondering, should we explain somewhere here the roles, the context, the channels...?

Having explained the objectives of the project, we want to chose specific scenarios that are well adapted to evaluate these objectives. In this particular case, we are looking for power grids of considerable size, and with the appropriate types of devices presented earlier such as generators and converters to facilitate the integration of distributed generators. Additionally, we would want to choose use cases in which the grid can be separated into different areas to properly implement different geographical contexts to take into account. Finally, we also consider the ease to access information and data about the modeled grid. We consider the following as interesting candidates:

- Kundur 2-area system [6]
- IEEE-118 bus test case [7]
- IEEE 300 bus test case [8]
- ACTIVSg 2000 bus test case [9]

I would add with an itemize to list the grids we are considering: Kundur, IEEE118, etc. Also, at each point indicate the source of information with a reference

For the first use case we propose first using the grid defined in the Kundur two area system [6]. This grid consists of 10 buses divided in 2 areas. Each area includes two synchronous generators. Additionally, this simulation includes a line failure at a specific time step (Line 8, at $t = 2s$). The objective of this is to showcase how the decentralized nature of COLMENA can adapt to unexpected events in the grid such as failures and avoid cascading failures in the grid.

In this specific use case the COLMENA-Agents will be paired with the different generators and monitor the values provided by the ANDES simulation. Moreover, this agents will be able to modify some of the generators values such

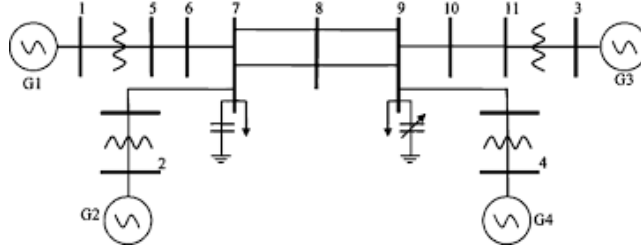


Figure 5: Kundur grid scheme. [6]

as the power injected or internal controlling parameters. The objective is to overtime include different sources of generation and the proposed GFL-GFM converters. Let's see a proof of concept of what the integration could look like. In this use case one of the COLMENA Agents is able to modify the inertia parameter of the generator 1 inside the simulation depending of the value of the generator's speed ω . By modifying the inertia what we expect to see is the generator's angular velocity ω having 2 distinct behaviors.

Operating State	KPI	Parameter M value
A	$\omega \in [1 - \varepsilon, 1 + \varepsilon]$	12
B	$\omega \notin [1 - \varepsilon, 1 + \varepsilon]$	120

Table 2: Generator set-points summary.

Once this more accessible use case is deployed, our next goal is to scale the simulation to a more extensive grid that could be able to showcase the performance of COLMENA in a more complicated environment, with more varieties of models and more complicated controls overall. The objective is to eventually run the simulation in larger grids with a larger number of agents. For this we can use other test grids such as the IEEE 118 bus case [7]. This test grid is composed by 118 buses, 54 generators and 99 Loads. Additionally, some of the generators are synchronous condensers which are essentially synchronous motors whose shaft is not connected to any mechanical load. Their main function is to provide reactive power compensation. Moreover, it uses the same models as the ones used in the previous tests cases so transferring the already developed models is feasible.

2.1 Grid's Performance & Key Performance Indicators

In the first section we have defined a set of metrics and states that are key to defining the grids state, specifically when dealing with the frequency response. These include the frequency, the angular speed of the synchronous generators

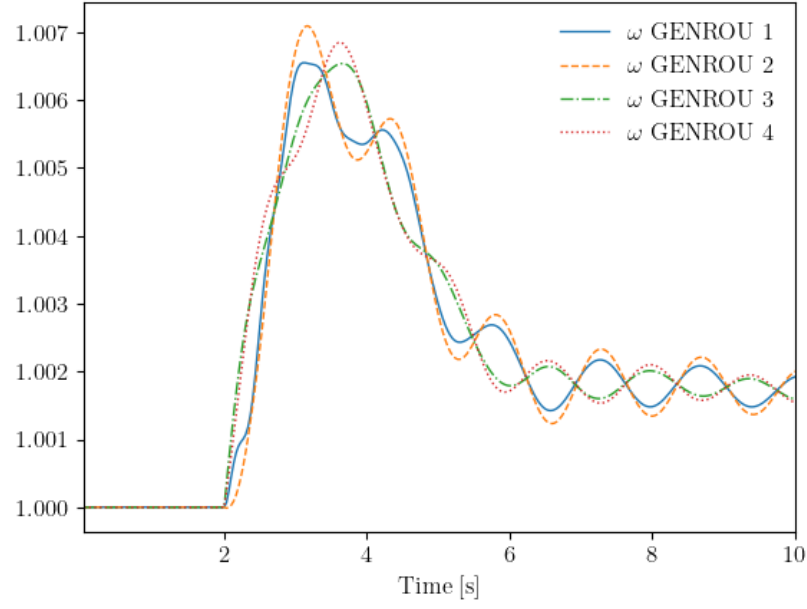


Figure 6: Time series of the distributed generator's frequency.

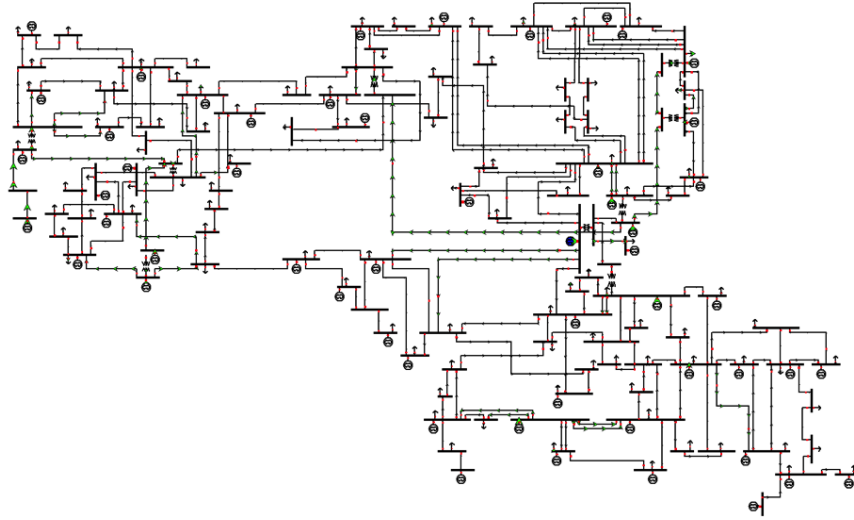


Figure 7: IEEE118 grid scheme. [7]

and others. We aim to define key performance indicators (KPI) starting from the metrics defined previously. These KPIs define the performance of the grid with respect to the frequency service control.

- Minimum and maximum of the generator's frequency.
- Minimum and maximum of the mean bus frequency in an area from the nominal frequency.
- Voltage steady state values.
- Rate of Change of Frequency (RoCoF).
- Available power reserves.
- Power Balance & regional power exchanges.
- N-1 criteria
- Economic criteria
- Power Losses

A few questions. What do you mean by steady-state values? (I mean, which magnitude? Voltages, currents...?) Also, the $N - 1$ criteria will be very hard to assess I believe. Same applies to the economic criteria as we have no information on costs for these grids. Some ideas to add: percentual power losses, maximum overloading of lines, short-circuit currents.

Yeah N-1 can be complicated.

Minimum and maximum of the generator's frequency

This KPIs is usually used with regards to the primary response in the frequency control response. The objective would be to maintain the generator's frequency ω as close to the nominal value. In moderately strong power grids a common value for this KPI would be around 0.1% around the nominal value. This is true for both the generator's frequency and the buses' frequency.

RoCoF

The Rate of Change of Frequency is the frequency's time derivative measured in a given bus. It signals sudden changes in frequency and if its close to 0 for a given amount of time it can also signal the grid reaching a steady state. Therefore the RoCoF is key to measure the performance of the grid during transients.

Available Power Reserves

The available power reserves is the amount of power that can be activated in a given amount of time in case of need but its not being used. It usually considers an horizon of 10 to 30 minutes. Additionally, we also need to consider the ramp up capabilities of these power reserves. The ramp up measured in kW/s and is the speed with which this reserve power can come online. These power reserves come in the form of battery storage and ancillary generators that can be ramped up when necessary. The grid operator usually defines minimum requirements for available power values.

OK, the only thing is that it will be hard to model these reserves. Not sure how it is done in ANDES.

My, idea is to consider Storage Systems and Generators that can be connected or disconnected.

Maximum line current

The current through a line is limited by a maximum value for security purposes. If the current through a line surpasses the maximum value for a specific amount of time the line can disconnect to avoid being damaged.

Power Balance and regional power exchanges

The power balance is defined as the net power that is coming into the grid. A good performance of the grid should maintain the net power balance close to 0. Additionally, we can also look into the power balances between different areas that are interconnected and define KPI that take into account excessive reliance on these interconnections. One KPI that could be useful for taking into account these power exchanges between areas is the Area Control Error (ACE). The ACE of an area is defined as the difference between the net power exchange and the schedule power exchange with all adjacent areas. It measures if the grid is sticking to the scheduled power exchanges. A good performing grid looks to have an ACE close to 0.

To be discussed. I like the explanation on the ACE, it is a nice way to measure it. I am not so sure about the power balance concept because by Kirchhoff's first law, the balance will always be maintained. By the way, how would we compute the ACE in ANDES? I have some ideas, but what do you think?

N-1 criteria

The N-1 criterion is a standard used in power system planning and operation to ensure reliability and resilience. It specifies that a power system should be able to withstand the loss of any single element (like a generator, transformer, or transmission line) without causing a system-wide failure. New devices could be connected or scheduled by the COLMENA agents to help ensure the criterion is respected.

Correct. How would we test it? By running many simulations and assessing if we are complying with the criterion?

I forgot to tell you but a table such as the following would be nice:

Magnitude	Unit	Description
Voltage	kV	Voltage at a bus
Current	A	Current through a branch
...		

Economic criteria

Economic criteria for grid performance focuses on minimizing costs by prioritizing energy production based on the merit order. This approach ranks power sources from least to most expensive, using cheaper, typically renewable sources first to reduce overall energy costs. Efficient grid performance depends on aligning supply with demand through this ranking, ensuring that the most economical energy is produced and dispatched first while maintaining reliability.

Power Losses

Grid performance is also influenced by power losses and reactive compensation. Power losses, primarily due to resistance in transmission lines, reduce overall efficiency and increase operational costs. To mitigate these losses, reactive compensation is used, which balances reactive power in the grid, improving voltage stability and reducing strain on transmission infrastructure

2.2 Role Definitions

The envisioned integration of Andes and COLMENA places a special focus on the grid's frequency control response. For this purpose we propose a set of roles that can be taken by the COLMENA agents in order to control the grid in a

decentralized grid. The roles are explained descriptively.

Device Basic Role

The device basic role defines the basic operations needed for the agents and devices to coordinate through Andes-COLMENA. The agent that takes on this role is supposed to be paired to a single device of type generator, although we can consider this role being taken multiple times by the same agent in order to control multiple devices. In this case the device basic roles is persistent and has the following functions:

- Initializes a client that calls Andes and sets up the exchange of information.
- Stores the state and algebraic variables relative to the device it is paired up.
- Changes the parameter when it receives the message to do so through the appropriate channel.
- Changes the behaviour of the device when instructed to do so through the appropriate channel.

Taking the example of a generator device this role has the requirement of having a generator and at least these 2 channels:

- Channel Generator parameter change: where it receives both the parameter to change and the new value.
- Channel Generator measurements: where it publishes the frequency of the generator every time step.

Rotor Speed Optimizer

This role specific to an agent with requirement "generator" is activated when the rotor's speed is unusual (high value, high RoCoF) and defines the reference value for the rotor's speed ω_{ref} . This role can be subdivided into transient and steady state depending on the grid's state since it can behave differently based on the grid's state.

Rotor Speed Setter

This role specific to an agent with requirement "generator" receives a reference value of the rotor's speed ω_{ref} and modifies the generator's parameters in order to get to that value. The actions are:

- Reading the ω_{ref} continuously.
- Adapt the control strategy in Andes through a parameter change.
- Deactivate the role when the $\omega \in [\omega_{ref} - \varepsilon, \omega_{ref} + \varepsilon]$ in the steady state.

This role will usually adapt the generator's power in order to get the desired speed. More generally, we can imagine this role being extended to set other types of variables in a given device. This could be implemented through a feedback control loop or through a feed forward control loop. These are strategies that can be represented as a block diagram where the input signal is the difference between a reference value and the real value.

Voltage Optimizer Role

This role specific to an COLMENA agent with the requirement of being paired with a electrical and being a controllable device receives computes the optimal voltage when there is a deviation from the desired voltage.

More generally, we can imagine this role being extended to set type of value for the a state in a given device.

Load Shedding Role

This role can be taken by agents associated with a load consuming device in the grid. It is activated in the secondary response to counter a drop in frequency.

- Continuously diminishes the power being used by the load.
- When the frequency is back to a nominal value, it goes back to the desired power.

Reserve Activation Role

This role can be taken by agents associated with ancillary generation or batteries consuming device in the grid. It is activated in the secondary response to counter

a drop in frequency.

- Connect or Disconnect the reserve to the grid.
- Set the power injected to the grid.

Area Monitoring Role

This role can be taken by agents associated with in a specific geographical area. The role monitors the power balance of that area with the rest of the grid. It has access to the appropriate communication channels. When activated it's charged with:

- Monitoring the power balance in the area.
- Flagging the areas of the grid with power unbalances.

Current Security role

If current value through the line is above the security current then open publish the change of behavior in the appropriate channel. It also disconnects line to avoid a cascading failure in the grid.

Simulation Role

This role could simulate a specific event in the grid ahead of time and decide on changes that would make the grid more prepared for that specific change. The role could run Andes itself with some change in the line such a failure line or a generator disconnecting and decided on necessary changes to adapt.

3 Conclusion & Future work

Grid performance through decentralized control strategies presents an interesting opportunity for the COLMENA framework. By pairing agents with grid components, such as generators and converters, COLMENA could enable real-time monitoring and control adjustments that enhance grid stability, particularly in response to frequency disturbances and power imbalances. This approach was explored using the Kundur test case showcases the potential of COLMENA. COLMENA could change the behavior of agents in response to

changes in KPIs such as frequency stability. The agents would then send messages through the appropriate channels signaling changes in the set point of the devices that would be reflected in the ANDES simulation.

Future work should focus on expanding the scope and complexity of the use cases. This includes integrating a broader range of devices, such as advanced energy storage systems, and simulating additional scenarios that include renewable energy sources and demand response mechanisms. More specifically, we want to deploy a use case in the IEEE 118 bus system. Additionally, we will focus on clearly defining the communication channels between COLMENA agents, and the contexts and requirements that define the agents in the COLMENA framework for this use case. Finally, we also want to develop more complex roles that could properly