Notes on transient states and short-term synaptic plasticity

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1 The dynamics

The equations for the two different models are:

Full depletion model
$$\begin{aligned} \dot{u} &= \frac{1 + (U_{\max} - 1)y - u}{T_u} \\ \dot{\varphi} &= \frac{1 - uy/U_{\max} - \varphi}{T_{\varphi}} \end{aligned} \qquad \dot{u} = \frac{1 - u}{T_u} + \alpha(U - u)y \\ \dot{\varphi} &= \frac{1 - uy/U_{\max} - \varphi}{T_{\varphi}} \qquad \dot{\varphi} = \frac{1 - \varphi}{T_{\varphi}} - \alpha \varphi uy \end{aligned}$$
 Therefore
$$u \in [1, U_{\max}] \qquad \qquad u \in [1, u^*] = \left[1, \frac{1 + \alpha T_u U_{\max}}{1 + \alpha T_u}\right] \\ \varphi \in [0, 1] \qquad \qquad \varphi \in [\varphi^*, 1] = \left[\frac{1}{1 + \alpha u^* T_{\varphi}}, 1\right]$$

In the full depletion model I have used $U_{\rm max}=4,\,\tau_u=30\,{\rm ms}$ and $\tau_\varphi=60\,{\rm ms},$ that create a continuously active network.

For the Tsodyks-Markram model, Bulcsù has used $\tau_u = 21 \,\mathrm{ms}$, $\tau_\varphi = 706 \,\mathrm{ms}$ that are taken from Gupta et. al 2000, $U = 4 \,\mathrm{and} \,\alpha = 1/100 \,\mathrm{ms}^{-1}$. With these parameters, the dynamics of the clique network is dominated by fixed points, see Fig. 1 on the left.

Comparing the two models, as in Fig 2, one can see that with these parameters the depression of inhibitory synapses dominates because of the small range of $u \in [1, 1.58]$, and what would be the winning clique cannot dominate over the others.

Defining a fixpoint as a point in which $\dot{x}_i < 10^{-10} \, \forall i$, we can vary U and measure when a fixpoint is reached, see Fig. 1 on the right. There is a steep increase of around $U \approx 15$, up to the total simulation time of 300 ms. A new network is generated at every run.

Unfortunately a given value of U_m does not ensure autonomous activity for networks with different number of cliques n_c , see Fig. 3.

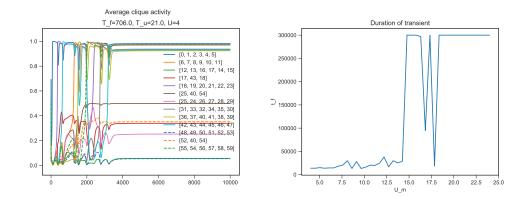


Figure 1: Left: The dynamics is characterized by fixpoints with U=4, $\tau_u=21\,\mathrm{ms},~\tau_\varphi=706\,\mathrm{ms}.$ Right: Duration of transient until a fixpoint is reached. As U increases, an autonomous activity eventually takes over.

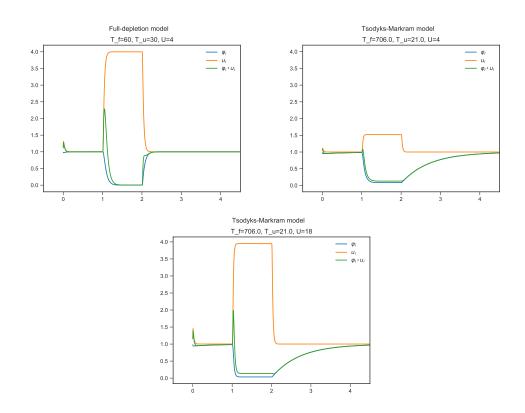


Figure 2: Top left: full depletion model used up to now. Top right: Tsodyks-Markram model from Gupta. Bottom: Tsodyks-Markram model with $u_m=18$.

Duration of transient

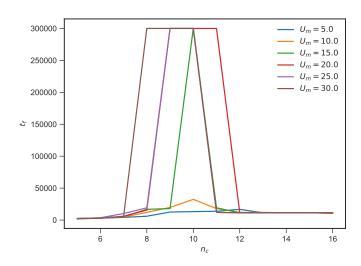


Figure 3: