

eYSIP–2018

# A SYSTEM FOR SOLVING JIGSAW PUZZLE USING MULTIPLE ROBOTS



Aniket Anantraj Navlur  
Kiran Suvas Patil  
Ashis Kumar Maharana  
Abinav Sarkar  
Kalind Karia

Duration of Internship: 21/05/2018 – 06/07/2018

*2018, e-Yantra Publication*

# A System for Solving Jigsaw Puzzle using Multiple Robots

## Abstract

The prime motive of this project is to develop a multi Robot based Puzzle Solver system that can solve a Jigsaw puzzle.

## Completion status

Give details for work/project completed successfully. If work is not complete, mention the details till which task is done.

### 1.1 Hardware parts

- List of hardware
- Detail of each hardware: [Datasheet, page 5](#), [Vendor link](#),
- Connection diagram

### 1.2 Software used

- List of software used
- Detail of software: version, [download link](#),
- Installation steps



### 1.3. ASSEMBLY OF HARDWARE

---

## 1.3 Assembly of hardware

Circuit diagram and Steps of assembly of hardware with pictures for each step

### Circuit Diagram

Circuit schematic, simplified circuit diagram , block diagram of system

#### Step 1

Steps for assembling part 1

#### Step 2

Steps for assembling part 2

#### Step 3

Steps for assembling part 3

## 1.4 Software and Code

[Github link](#) for the repository of code

Brief explanation of various parts of code

## 1.5 Use and Demo

Final Setup Image

User Instruction for demonstration

[Youtube Link](#) of demonstration video

## 1.6 Future Work

What can be done to take this work ahead in future as projects.



## 1.7. BUG REPORT AND CHALLENGES

---

### 1.7 Bug report and Challenges

Any issues in code and hardware.

Any failure or challenges faced during project



# Bibliography

- [1] Ad Kamerman and Leo Monteban, *WaveLAN-II: A High-Performance Wireless LAN for the Unlicensed band*, 1997.