

eYs3dSDK_Linux

4.0.1

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Contents

Chapter 1

Introduction

This document describes the usage of Application Programming Interfaces of HD-DM-SDK

What's inside the SDK

Table 1.1 File List

Folder	Filename	Description
bin	All files	Sample executables on Linux x86_64 platform
eSPDI	eSPDI.h	Basic API declaration header
	eSPDI_def.h	Basic data struct declaration header
	eSPDI_version.h	SDK version declaration header
	libeSPDI_X86_64_4.0.0_pp.so	eSPDI shared library for Linux x86_64 platform
eSPDI/opencv	All files	OpenCV library
eSPDI/turbojpeg	All files	TurboJpeg library
eSPDI/alsa-release	All files	Alsa library
eSPDI/DepthFilter	All files	Depth filter library
doc/html	index.html	This documentation
DMPreview		A sample project demonstrating how to open multiple devices in an application

Chapter 2

File Index

2.1 File List

Here is a list of all documented files with brief descriptions:

eSPDI_source/ eSPDI.h	Etron SDK API export functions, data structure and variable definition Copyright: This file copy-right (C) 2017 by	??
eSPDI_source/ eSPDI_def.h	Main data structure, variable and macro definition and error definition Copyright: This file copy-right (C) 2017 by	??

Chapter 3

File Documentation

3.1 eSPDI_source/eSPDI.h File Reference

Etron SDK API export functions, data structure and variable definition Copyright: This file copyright (C) 2017 by.

Functions

- int [EtronDI_Init](#) (void **ppHandleEtronDI, bool blsLogEnabled)
entry point of Etron camera SDK including 1.create a CEtronDI class for accessing oncoming APIs 2.find out Etron devices 3.create a CVideoDevice class for video streaming and hardware access
- int [EtronDI_FindDevice](#) (void *pHandleEtronDI)
find out all Etron USB devices by PID, VID and ChipID, also remember device types
- void [EtronDI_Release](#) (void **ppHandleEtronDI)
release resource that EtronDI_Init had allocated
- int [EtronDI_RefreshDevice](#) (void *pHandleEtronDI)
refresh all Etron UVC devices
- int [EtronDI_SwitchBaseline](#) (int index)
Swich the baseline index.
- bool [EtronDI_IsMLBaseLine](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
Check the device is multiple baseline device.
- int [EtronDI_DoFusion](#) (unsigned char **pDepthBufList, double *pDepthMerge, unsigned char *pDepthMergeFlag, int nDWidth, int nDHeight, double fFocus, double *pBaseline, double *pWRNear, double *pWRFar, double *pWRFusion, int nMergeNum, bool bdepth2Byte11bit, int method)
Do Fusion Merge.
- int [EtronDI_GetDeviceNumber](#) (void *pHandleEtronDI)
get Etron USB device numbers
- int [EtronDI_GetDeviceInfo](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, DEVINFORMATION *pdevinfo)
get informations of Etron UVC devices, see DEVINFORMATION
- int [EtronDI_GetDeviceInfoMBL_15cm](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, DEVINFORMATION *pdevinfo)
get informations of Etron UVC devices, see DEVINFORMATION
- int [EtronDI_SelectDevice](#) (void *pHandleEtronDI, int dev_index)
do not support currently
- bool [EtronDI_IsInterleaveDevice](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)

- check module support interleave function or not*

 - int [EtronDI_EnableInterleave](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, bool enable)

enable or disable interleave function
- int [EtronDI_SetControlCounterMode](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char n↵Value)

enable or disable interleave function
- int [EtronDI_GetControlCounterMode](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char *nValue)

enable or disable interleave function
- int [EtronDI_GetSensorRegister](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nId, unsigned short address, unsigned short *pValue, int flag, SENSORMODE_INFO SensorMode)
- int [EtronDI_SetSensorRegister](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nId, unsigned short address, unsigned short nValue, int flag, SENSORMODE_INFO SensorMode)

set sensor register value
- int [EtronDI_GetFWRegister](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short address, unsigned short *pValue, int flag)

get firmware register value
- int [EtronDI_SetFWRegister](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short address, unsigned short nValue, int flag)

set firmware register value
- int [EtronDI_GetHWRegister](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short address, unsigned short *pValue, int flag)

get hardware register value
- int [EtronDI_SetHWRegister](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short address, unsigned short nValue, int flag)

set hardware register
- int [EtronDI_GetFwVersion](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, char *pszFwVersion, int n↵BufferSize, int *pActualLength)

get the firmware version of device, the version is a string
- int [EtronDI_GetPidVid](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *pPidBuf, unsigned short *pVidBuf)

get PID(product ID) and VID(vendor ID) of device
- int [EtronDI_SetPidVid](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *pPidBuf, unsigned short *pVidBuf)

set PID and VID to device
- int [EtronDI_GetSerialNumber](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char *pData, int nbufferSize, int *pLen)

get device serial number
- int [EtronDI_SetSerialNumber](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char *pData, int nLen)

set serial number to device
- int [EtronDI_GetYOffset](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int BufferLength, int *pActualLength, int index)

get Y offset (file ID 30+) value
- int [EtronDI_GetRectifyTable](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int Buffer↵Length, int *pActualLength, int index)

get rectify values (file ID 40+) from flash
- int [EtronDI_GetZDTable](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int Buffer↵Length, int *pActualLength, PZDTABLEINFO pZDTableInfo)

get disparity and Z values from flash
- int [EtronDI_GetLogData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int Buffer↵Length, int *pActualLength, int index, CALIBRATION_LOG_TYPE type)

get log data from flash

- int [EtronDI_GetUserData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int BufferLength, USERDATA_SECTION_INDEX usi)
get user data from flash
- int [EtronDI_SetYOffset](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int BufferLength, int *pActualLength, int index)
set Y offset values
- int [EtronDI_SetRectifyTable](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int BufferLength, int *pActualLength, int index)
set rectify values to flash
- int [EtronDI_SetZDTable](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int BufferLength, int *pActualLength, PZDTABLEINFO pZDTableInfo)
set disparity and Z values to flash
- int [EtronDI_SetLogData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int BufferLength, int *pActualLength, int index)
set log data to flash
- int [EtronDI_SetUserData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int BufferLength, USERDATA_SECTION_INDEX usi)
set user data to flash
- int [EtronDI_ReadFlashData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, FLASH_DATA_TYPE fdt, BYTE *pBuffer, unsigned long int BufferLength, unsigned long int *pActualLength)
read firmware code(.bin) form flash The firmware code is the combination of boot loader, firmware body and plug-in data. This input buffer length has to match with the flash data type
- int [EtronDI_WriteFlashData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, FLASH_DATA_TYPE fdt, BYTE *pBuffer, unsigned long int BufferLength, bool blsDataVerify, KEEP_DATA_CTRL kdc)
write firmware code(.bin) to flash The firmware code is the combination of boot loader, firmware body and plug-in data, also can keep original functions(Serial Number, Sensor Position, RectificationTable, ZD Table and CalibrationLog) on camera flash by KEEP_DATA_CTRL control
- int [EtronDI_GetDevicePortType](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, USB_PORT_TYPE *pUSB_Port_Type)
Get Device USB-port-type.
- int [EtronDI_GetDeviceResolutionList](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nMaxCount, ETRONDI_STREAM_INFO *pStreamInfo0, int nMaxCvoidount1, ETRONDI_STREAM_INFO *pStreamInfo1)
get the device resolution list
- int [EtronDI_Setup_v4l2_requestbuffers](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int cnt)
Setup v4l2 request buffers, default = 4.
- int [EtronDI_OpenDevice](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nEP0Width, int nEP0Height, bool bEP0MJPEG, int nEP1Width, int nEP1Height, DEPTH_TRANSFER_CTRL dtc=DEPTH_IMG_NON_TRANSFER, bool blsOutputRGB24=false, void *phWndNotice=0, int *pFPS=0, CONTROL_MODE cm=IMAGE_SN_NONSYNC)
the implement layer to open Etron camera device by V4L2(<https://en.wikipedia.org/wiki/Video4Linux>), can open color and depth at one time call, do functions as below,
- int [EtronDI_OpenDevice2](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nEP0Width, int nEP0Height, bool bEP0MJPEG, int nEP1Width, int nEP1Height, DEPTH_TRANSFER_CTRL dtc=DEPTH_IMG_NON_TRANSFER, bool blsOutputRGB24=false, void *phWndNotice=0, int *pFPS=0, CONTROL_MODE cm=IMAGE_SN_NONSYNC)
the implement layer to open Etron camera device by V4L2(<https://en.wikipedia.org/wiki/Video4Linux>), can open color and depth at one time call, do functions as below,
- int [EtronDI_OpenDeviceMBL](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nEP0Width, int nEP0Height, bool bEP0MJPEG, int nEP1Width, int nEP1Height, DEPTH_TRANSFER_CTRL dtc=DEPTH_IMG_NON_TRANSFER, bool blsOutputRGB24=false, void *phWndNotice=0, int *pFPS=0, CONTROL_MODE cm=IMAGE_SN_NONSYNC)
the implement layer to open Multiple Base Line Etron camera device by V4L2(<https://en.wikipedia.org/wiki/Video4Linux>), can open color and depth at one time call, do functions as below,

- int [EtronDI_CloseDeviceMBL](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
close Multiple Base Linedevice and free resource
- int [EtronDI_CloseDevice](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
close device and free resource
- int [EtronDI_CloseDeviceEx](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
close device and free resource for warm reset
- int [EtronDI_GetImage](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *pBuf, unsigned long int *pImageSize, int *pSerial=0, int nDepthDataType=0)
get color or depth pin image by issuing V4L2's IOCTL to get frame data
- int [EtronDI_GetColorImage](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *pBuf, unsigned long int *pImageSize, int *pSerial=0, int nDepthDataType=0)
get color image by issuing V4L2's IOCTL to get frame data
- int [EtronDI_GetDepthImage](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *pBuf, unsigned long int *pImageSize, int *pSerial=0, int nDepthDataType=0)
get depth image by issuing V4L2's IOCTL to get frame data
- int [EtronDI_SetupBlock](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, bool enable)
get color or depth pin image by issuing V4L2's IOCTL to get frame data
- int [EtronDI_Get_Color_30_mm_depth](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *pBuf, unsigned long int *pImageSize, int *pSerial=0, int nDepthDataType=0)
get color or depth pin image by issuing V4L2's IOCTL to get frame data
- int [EtronDI_Get_60_mm_depth](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *pBuf, unsigned long int *pImageSize, int *pSerial=0, int nDepthDataType=0)
get color or depth pin image by issuing V4L2's IOCTL to get frame data
- int [EtronDI_Get_150_mm_depth](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *pBuf, unsigned long int *pImageSize, int *pSerial=0, int nDepthDataType=0)
get color or depth pin image by issuing V4L2's IOCTL to get frame data
- int [EtronDI_Get2Image](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *pColorImgBuf, BYTE *pDepthImgBuf, unsigned long int *pColorImageSize, unsigned long int *pDepthImageSize, int *pSerial=0, int *pSerial2=0, int nDepthDataType=0)
get color and/or depth pin images see EtronDI_GetImage for detailed description
- int [EtronDI_GetExposureTime](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nSensorMode, float *pfExpTimeMS)
get exposure time of ISP setting in millisecond the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)
- int [EtronDI_SetExposureTime](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nSensorMode, float fExpTimeMS)
set exposure time of ISP sensor setting the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)
- int [EtronDI_GetGlobalGain](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nSensorMode, float *pfGlobalGain)
get global gain of ISP setting the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)
- int [EtronDI_SetGlobalGain](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nSensorMode, float fGlobalGain)
set global gain of ISP sensor setting the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)
- int [EtronDI_SetSensorTypeName](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, SENSOR_TYPE_↵ NAME stn)
set the sensor type you want to work on
- int [EtronDI_GetColorGain](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nSensorMode, float *pfGainR, float *pfGainG, float *pfGainB)
get color gain of ISP setting the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)
- int [EtronDI_SetColorGain](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nSensorMode, float fGainR, float fGainG, float fGainB)
set color gain of ISP
- int [EtronDI_EnableAE](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
enable auto exposure(AE) function of ISP

- int [EtronDI_DisableAE](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
disable auto exposure(AE) function of ISP
- int [EtronDI_EnableAWB](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
enable auto white balance function of ISP
- int [EtronDI_DisableAWB](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
disable auto white balance of ISP
- int [EtronDI_GetAEStatus](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, PAE_STATUS pAEStatus)
get auto exposure(AE) is enabled or disable
- int [EtronDI_GetAWBStatus](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, PAWB_STATUS pAWB↵
Status)
get auto white balance(AWB) is enabled or disable
- int [EtronDI_GetGPIOValue](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nGPIOIndex, BYTE ↵
*pValue)
get GPIO values
- int [EtronDI_SetGPIOValue](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nGPIOIndex, BYTE n↵
Value)
set GPIO values
- int [EtronDI_SetGPIOCtrl](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nGPIOIndex, BYTE n↵
Value)
set GPIO I/O control
- int [EtronDI_GetCTPropVal](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nId, long int *pValue)
get camera terminal(CT) property value By v4l2_control to get control value of camera terminal
- int [EtronDI_SetCTPropVal](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nId, long int nValue)
set camera terminal property values By v4l2_control to set
- int [EtronDI_GetPUPPropVal](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nId, long int *pValue)
get processing unit property value by v4l2_control to get processing unit(PU) property value
- int [EtronDI_SetPUPPropVal](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nId, long int nValue)
set processing unit property value by v4l2_control to set processing unit(PU) property value
- int [EtronDI_GetCTRRangeAndStep](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nId, int *pMax,
int *pMin, int *pStep, int *pDefault, int *pFlags)
*set camera terminal property values By v4l2_queryctrl to get control values of camera terminal(CT) this enumera-
tion contained the following properties: V4L2_CID_EXPOSURE_AUTO V4L2_CID_EXPOSURE_AUTO_PRIORI↵
TY V4L2_CID_EXPOSURE_ABSOLUTE V4L2_CID_EXPOSURE V4L2_CID_FOCUS_ABSOLUTE V4L2_CID_F↵
OCUS_RELATIVE V4L2_CID_FOCUS_AUTO V4L2_CID_IRIS_ABSOLUTE V4L2_CID_IRIS_RELATIVE V4L2 ↵
CID_ZOOM_ABSOLUTE V4L2_CID_ZOOM_RELATIVE V4L2_CID_PAN_ABSOLUTE V4L2_CID_PAN_RELATIVE
V4L2_CID_TILT_ABSOLUTE V4L2_CID_TILT_RELATIVE V4L2_CID_PRIVACY*
- int [EtronDI_GetPURRangeAndStep](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nId, int *pMax,
int *pMin, int *pStep, int *pDefault, int *pFlags)
*get processing unit property value By v4l2_queryctrl to get property values of processing unit(PU) this enumeration
contained the following properties: V4L2_CID_BACKLIGHT_COMPENSATION V4L2_CID_BRIGHTNESS V4L2 ↵
CID_CONTRAST V4L2_CID_GAIN V4L2_CID_POWER_LINE_FREQUENCY V4L2_CID_HUE V4L2_CID_HUE ↵
AUTO V4L2_CID_SATURATION V4L2_CID_SHARPNESS V4L2_CID_GAMMA V4L2_CID_WHITE_BALANCE ↵
TEMPERATURE V4L2_CID_AUTO_WHITE_BALANCE*
- int [EtronDI_SetDepthDataType](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short nValue)
set depth data type, 11 bit for disparity data, 14 bit for Z data notice: only PUMA type IC can support this setting
- int [EtronDI_GetDepthDataType](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *p↵
Value)
get current depth data type setting
- int [EtronDI_SetCurrentIRValue](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short nValue)
set infrared radiation(IR) value of PUMA type IC
- int [EtronDI_GetCurrentIRValue](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *p↵
Value)
get infrared radiation(IR) value of PUMA type IC

- int [EtronDI_GetIRMinValue](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *pValue)
get minimum IR value of camera module
- int [EtronDI_GetIRMaxValue](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *pValue)
get maximum IR value of camera module
- int [EtronDI_SetIRMode](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short nValue)
enable or disable IRs
- int [EtronDI_GetIRMode](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *pValue)
to check IR is turn on or off
- int [EtronDI_GetRectifyLogData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, eSPCtrl_RectLogData *pData, int index)
get rectify log data from flash, just for AXES1 device type
- int [EtronDI_GetRectifyMatLogData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, eSPCtrl_RectLogData *pData, int index)
get rectify log data from flash, just for PUMA device type
- int [EtronDI_EnablePostProcess](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, bool bEnable)
Not support now.
- int [EtronDI_PostInitial](#) (void *pHandleEtronDI)
Not support now.
- int [EtronDI_PostEnd](#) (void *pHandleEtronDI)
Not support now.
- int [EtronDI_ProcessFrame](#) (void *pHandleEtronDI, unsigned char *pYUY2Buf, unsigned char *pDepthBuf, unsigned char *OutputBuf, int width, int height)
Not support now.
- int [EtronDI_PostSetParam](#) (void *pHandleEtronDI, int Idx, int Val)
Not support now.
- int [EtronDI_PostGetParam](#) (void *pHandleEtronDI, int Idx, int *pVal)
Not support now.
- int [EtronDI_CreateSwPostProc](#) (int depthBits, void **handle)
create a software post process class
- int [EtronDI_ReleaseSwPostProc](#) (void **handle)
release a software post process class
- int [EtronDI_DoSwPostProc](#) (void *pHandleEtronDI, unsigned char *colorBuf, bool isColorRgb24, unsigned char *depthBuf, unsigned char *outputBuf, int width, int height)
do software post process on a depth buffer
- int [EtronDI_Convert_Depth_Y_To_Buffer](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char *depth_y, unsigned char *rgb, unsigned int width, unsigned int height, bool color, unsigned short nDepthDataType)
Convert Depth to RGB color or gray.
- int [EtronDI_Convert_Depth_Y_To_Buffer_offset](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char *depth_y, unsigned char *rgb, unsigned int width, unsigned int height, bool color, unsigned short nDepthDataType, int offset)
Convert Depth to RGB color or gray, added offset for 3cm baseline.
- int [EtronDI_EnableSensorIF](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, bool bIsEnable)
enable or disable sensor IF
- int [EtronDI_getUACNAME](#) (char *input, char *output)
Get Etron UAC Name.
- int [EtronDI_InitialUAC](#) (char *deviceName)
UAC initial function.
- int [EtronDI_WriteWaveHeader](#) (int fd)
Write Wave Header.
- int [EtronDI_WriteWaveEnd](#) (int fd, size_t length)
Modified Wave Header.

- int [EtronDI_GetUACData](#) (unsigned char *buffer, int length)
UAC initial function.
- int [EtronDI_ReleaseUAC](#) (void)
UAC initial function.
- int [EtronDI_InitialFlexibleGyro](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
gyro sensor initial function
- int [EtronDI_ReleaseFlexibleGyro](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
gyro sensor release function
- int [EtronDI_GetFlexibleGyroData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int length, unsigned char *pGyroData)
getting gyro data function
- int [EtronDI_GetFlexibleGyroLength](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *GyroLen)
getting length of gyro data function.
- int [EtronDI_GetImageInterrupt](#) (void)
Get Image interrupt function Get the image interrupt and then read Gyro data.
- int [EtronDI_InitialHidGyro](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
gyro sensor initial function
- int [EtronDI_ReleaseHidGyro](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo)
gyro sensor release function
- int [EtronDI_GetHidGyro](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char *pBuffer, int length)
getting gyro data function
- int [EtronDI_SetupHidGyro](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char *pCmdBuf, int cmdlength)
getting gyro data function
- int [EtronDI_GetInfoHidGyro](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned char *pCmdBuf, int cmdlength, unsigned char *pResponseBuf, int *resplength)
getting gyro data function
- int [EtronDI_GenerateLutFile](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, const char *filename)
generate look up table(LUT) for spherical display this function reads the camera user data and generate a LUT file using for 360 degree preview
- int [EtronDI_SaveLutData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, const char *filename)
Save LUT parameters in the specified file.
- int [EtronDI_GetLutData](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, BYTE *buffer, int nSize)
Read LUT parameters into the specified buffer.
- int [EtronDI_EncryptMP4](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, const char *filename)
encrypt a H.264 video
- int [EtronDI_DecryptMP4](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, const char *filename)
decrypt a H.264 video was generated by [EtronDI_EncryptMP4\(\)](#)
- int [EtronDI_GetAutoExposureMode](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short *mode)
Get Auto Exposure Mode.
- int [EtronDI_SetAutoExposureMode](#) (void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, unsigned short mode)
Setup Auto Exposure Mode.
- int [EtronDI_RotateImg90](#) (EtronDIImageType::Value imgType, int width, int height, unsigned char *src, unsigned char *dst, int len, bool clockwise)
Rotate the image to 90 degree.
- int [EtronDI_RotateImg180](#) (EtronDIImageType::Value imgType, int width, int height, unsigned char *src, unsigned char *dst, int len)
Rotate the image to 180 degree.

- int [EtronDI_ResizeImgToHalf](#) (EtronDIImageType::Value imgType, int width, int height, unsigned char *src, unsigned char *dst, int len)
Resize the image to half.
- int [EtronDI_ImgMirro](#) (EtronDIImageType::Value imgType, int width, int height, unsigned char *src, unsigned char *dst)
Make the image to Mirro.
- int [EtronDI_RGB2BMP](#) (char *filename, int width, int height, unsigned char *data)
RGB to BMP.
- int [EtronDI_HoleFilled](#) (unsigned short *pDImgIn, unsigned short *pDImgOut, int width, int height, int hole↔ Filldiff)
Hole Filled.
- int [EtronDI_InitialCmdFiFo](#) (const char *pfifoName, int *pFileDescription, bool bRead)
Cmd FiFo Initial function.
- int [EtronDI_CloseCmdFiFo](#) (int FileDescription)
Cmd FiFo Close function.
- int [EtronDI_WriteCmdFiFo](#) (int FileDescription, unsigned char *pCmd, int len)
Write Cmd FiFo function.
- int [EtronDI_ReadCmdFiFo](#) (int FileDescription, unsigned char *pBuf, int len)
Read Cmd FiFo function.
- int [EtronDI_InitSRB](#) (void **pSmbHandle, int QueueSize, char *queueName)
Inital the SRB(Share Ring Buffering)
- int [EtronDI_PutSRB](#) (void *pSmbHandle, srb_packet_s *pPacket)
Put Packet to SRB.
- int [EtronDI_GetSRB](#) (void *pSmbHandle, srb_packet_s *pPacket)
Get Packet from SRB.

3.1.1 Detailed Description

Etron SDK API export functions, data structure and variable definition Copyright: This file copyright (C) 2017 by.

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3.1.2 Function Documentation

3.1.2.1 EtronDI_CloseCmdFiFo()

```
int EtronDI_CloseCmdFiFo (
    int FileDescription )
```

Cmd FiFo Close function.

Parameters

<i>int</i>	FileDescription File Description
------------	----------------------------------

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.2 EtronDI_CloseDevice()

```
int EtronDI_CloseDevice (  
    void * pHandleEtronDI,  
    PDEVSELINFO pDevSelInfo )
```

close device and free resource

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.3 EtronDI_CloseDeviceEx()

```
int EtronDI_CloseDeviceEx (  
    void * pHandleEtronDI,  
    PDEVSELINFO pDevSelInfo )
```

close device and free resource for warm reset

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.4 EtronDI_CloseDeviceMBL()

```
int EtronDI_CloseDeviceMBL (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

close Multiple Base Linedevice and free resource

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.5 EtronDI_Convert_Depth_Y_To_Buffer()

```
int EtronDI_Convert_Depth_Y_To_Buffer (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char * depth_y,
    unsigned char * rgb,
    unsigned int width,
    unsigned int height,
    bool color,
    unsigned short nDepthDataType )
```

Convert Depth to RGB color or gray.

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	char *depth_y depth data,
<i>unsigned</i>	char *rgb output data,
<i>int</i>	width image width,
<i>int</i>	height image height,

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.6 EtronDI_Convert_Depth_Y_To_Buffer_offset()

```
int EtronDI_Convert_Depth_Y_To_Buffer_offset (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char * depth_y,
    unsigned char * rgb,
    unsigned int width,
    unsigned int height,
    bool color,
    unsigned short nDepthDataType,
    int offset )
```

Convert Depth to RGB color or gray, added offset for 3cm baseline.

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	char *depth_y depth data,
<i>unsigned</i>	char *rgb output data,
<i>int</i>	width image width,
<i>int</i>	height image height,
<i>int</i>	offset dpeth_y offset,

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.7 EtronDI_CreateSwPostProc()

```
int EtronDI_CreateSwPostProc (
    int depthBits,
    void ** handle )
```

create a software post process class

Parameters

<i>int</i>	depthBits depth bit to set
<i>void</i>	**handle handle pointer to this software post process class

Returns

success: EtronDI_OK, others: see [eSPDI_ErrCode.h](#)

3.1.2.8 EtronDI_DecryptMP4()

```
int EtronDI_DecryptMP4 (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    const char * filename )
```

decrypt a H.264 video was generated by [EtronDI_EncryptMP4\(\)](#)

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>const</i>	char *filename the input video file for decryption

Returns

success: EtronDI_OK, others:see En-Decrypt.h

3.1.2.9 EtronDI_DisableAE()

```
int EtronDI_DisableAE (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

disable auto exposure(AE) function of ISP

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.10 EtronDI_DisableAWB()

```
int EtronDI_DisableAWB (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

disable auto white balance of ISP

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.11 EtronDI_DoFusion()

```
int EtronDI_DoFusion (
    unsigned char ** pDepthBufList,
    double * pDepthMerge,
    unsigned char * pDepthMergeFlag,
    int nDWidth,
    int nDHeight,
    double fFocus,
    double * pBaseline,
    double * pWRNear,
    double * pWRFar,
    double * pWRFusion,
    int nMergeNum,
    bool bdepth2Byte11bit,
    int method )
```

Do Fusion Merge.

Parameters

<i>unsigned</i>	char **pDepthBufList Point to Depth Buffer List
<i>double</i>	*pDepthMerge Point to Fusion output.
<i>unsigned</i>	char *pDepthMergeFlag Point to Fusion select fFocus Focus vale
<i>int</i>	nDWidth Image width
<i>int</i>	nDHeight Image Height
<i>double</i>	*pBaseline Point to baseline array m_baselineDist[0] = 30.0; m_baselineDist[1] = 60.0; m_baselineDist[2] = 150.0;
<i>double</i>	*pWRNear NearWorkingRange Vecror(Container)
<i>double</i>	*pWRFar FarWorkingRange Vecror(Container)
<i>double</i>	*pWRFusion FusionWorkingRange Vecror(Container)
<i>int</i>	nMergeNum Total merges
<i>int</i>	method method select 0: MBLBase 1: MBRbaseV0 2: MBRbaseV1

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.12 EtronDI_DoSwPostProc()

```
int EtronDI_DoSwPostProc (
    void * handle,
    unsigned char * colorBuf,
    bool isColorRgb24,
    unsigned char * depthBuf,
    unsigned char * outputBuf,
    int width,
    int height )
```

do software post process on a depth buffer

Parameters

<i>void*</i>	handle handle of this software post process class
<i>unsigned</i>	char* colorBuf input color buffer
<i>bool</i>	isColorRgb24 is this color buffer RGB888
<i>unsigned</i>	char* depthBuf input depth buffer
<i>unsigned</i>	char* outputBuf output buffer
<i>int</i>	width image width
<i>int</i>	height image height

Returns

success: EtronDI_OK, others: see eSPDI_ErrCode.h

3.1.2.13 EtronDI_EnableAE()

```
int EtronDI_EnableAE (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

enable auto exposure(AE) function of ISP

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.14 EtronDI_EnableAWB()

```
int EtronDI_EnableAWB (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

enable auto white balance function of ISP

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.15 EtronDI_EnableInterleave()

```
int EtronDI_EnableInterleave (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    bool enable )
```

enable or disable interleave function

Parameters

<i>pHandleEtronDI</i>	the pointer to the initialized EtronDI SDK instance
<i>pDevSelInfo</i>	pointer of device select index
<i>enable</i>	set true to enable interleave, or set false to disable interleave

Returns

success: EtronDI_OK, others: see [eSPDI_ErrCode.h](#)

3.1.2.16 EtronDI_EnableSensorIF()

```
int EtronDI_EnableSensorIF (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    bool bIsEnable )
```

enable or disable sensor IF

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>bool</i>	blsEnable true is enable, false is disable

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.17 EtronDI_EncryptMP4()

```
int EtronDI_EncryptMP4 (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    const char * filename )
```

encrypt a H.264 video

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>const</i>	char *filename the input video file for encryption

Returns

success: EtronDI_OK, others:see En-Decrypt.h

3.1.2.18 EtronDI_FindDevice()

```
int EtronDI_FindDevice (
    void * pHandleEtronDI )
```

find out all Etron USB devices by PID, VID and ChipID, also remember device types

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
-------------	----------------------------------

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.19 EtronDI_GenerateLutFile()

```
int EtronDI_GenerateLutFile (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    const char * filename )
```

generate look up table(LUT) for spherical display this function reads the camera user data and generate a LUT file using for 360 degree preview

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>const</i>	char* filename output LUT file name

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.20 EtronDI_Get2Image()

```
int EtronDI_Get2Image (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * pColorImgBuf,
    BYTE * pDepthImgBuf,
    unsigned long int * pColorImageSize,
    unsigned long int * pDepthImageSize,
    int * pColorSerial = 0,
    int * pDepthSerial = 0,
    int nDepthDataType = 0 )
```

get color and/or depth pin images see EtronDI_GetImage for detailed description

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pColorImgBuf buffer to store color image
<i>BYTE</i>	*pDepthImgBuf buffer to store depth image
<i>unsigned</i>	long int *pColorImageSize the actual color buffer size
<i>unsigned</i>	long int *pDepthImageSize the actual depth buffer size
<i>int</i>	*pColorSerial color serial number
<i>int</i>	*pDepthSerial depth serial number
<i>int</i>	nDepthDataType the depth data type, see definition in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.21 EtronDI_Get_150_mm_depth()

```
int EtronDI_Get_150_mm_depth (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * pBuf,
    unsigned long int * pImageSize,
    int * pSerial = 0,
    int nDepthDataType = 0 )
```

get color or depth pin image by issuing V4L2's IOCTL to get frame data

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pDepthImgBuf buffer to store image data
<i>unsigned</i>	long int *pImageSize the actual buffer size getting from device
<i>int</i>	*pDepthSerial the serial number for synchronizing depth image
<i>int</i>	nDepthDataType the depth data type, see definition in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.22 EtronDI_Get_60_mm_depth()

```
int EtronDI_Get_60_mm_depth (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * pBuf,
    unsigned long int * pImageSize,
    int * pSerial = 0,
    int nDepthDataType = 0 )
```

get color or depth pin image by issuing V4L2's IOCTL to get frame data

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pBuf buffer to store image data
<i>unsigned</i>	long int *pImageSize the actual buffer size getting from device
<i>int</i>	*pSerial the serial number for synchronizing color and depth image
<i>int</i>	nDepthDataType the depth data type, see definition in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.23 EtronDI_Get_Color_30_mm_depth()

```
int EtronDI_Get_Color_30_mm_depth (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * pBuf,
    unsigned long int * pImageSize,
    int * pSerial = 0,
    int nDepthDataType = 0 )
```

get color or depth pin image by issuing V4L2's IOCTL to get frame data

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pBuf buffer to store image data
<i>unsigned</i>	long int *pImageSize the actual buffer size getting from device
<i>int</i>	*pSerial the serial number for synchronizing color and depth image
<i>int</i>	nDepthDataType the depth data type, see definition in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.24 EtronDI_GetAESTatus()

```
int EtronDI_GetAESTatus (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    PAE_STATUS pAESTatus )
```

get auto exposure(AE) is enabled or disable

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>PAE_STATUS</i>	pAESTatus see enum definition as to AE_STATUS in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.25 EtronDI_GetAutoExposureMode()

```
int EtronDI_GetAutoExposureMode (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short * mode )
```

Get Auto Exposure Mode.

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler.
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index.
<i>unsigned</i>	short* mode pointer of the mode value. 0: Average, 1: Left (or Front) camera, 2: Right (or Back) camera

Returns

success: EtronDI_OK, others: [eSPDI_def.h](#)

3.1.2.26 EtronDI_GetAWBStatus()

```
int EtronDI_GetAWBStatus (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    PAWB_STATUS pAWBStatus )
```

get auto white balance(AWB) is enabled or disable

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>PAWB_STATUS</i>	pAWBStatus see enum definition as to AWB_STATUS in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.27 EtronDI_GetColorGain()

```
int EtronDI_GetColorGain (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nSensorMode,
    float * pfGainR,
    float * pfGainG,
    float * pfGainB )
```

get color gain of ISP setting the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nSensorMode which sensor(sensor A, B or Both) to get A is 0, B is 1, Both is 2
<i>float</i>	*pfGainR pointer of red gain value of ISP setting
<i>float</i>	*pfGainG pointer of green gain value of ISP setting
<i>float</i>	*pfGainB pointer of blue gain value of ISP setting

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.28 EtronDI_GetColorImage()

```
int EtronDI_GetColorImage (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * pBuf,
    unsigned long int * pImageSize,
    int * pSerial = 0,
    int nDepthDataType = 0 )
```

get color image by issuing V4L2's IOCTL to get frame data

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pBuf buffer to store image data
<i>unsigned</i>	long int *pImageSize the actual buffer size getting from device
<i>int</i>	*pSerial the serial number for synchronizing color and depth image
<i>int</i>	nDepthDataType reserved, no used.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.29 EtronDI_GetControlCounterMode()

```
int EtronDI_GetControlCounterMode (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char * nValue )
```

enable or disable interleave function

Parameters

<i>pHandleEtronDI</i>	the pointer to the initilized EtronDI SDK instance
<i>pDevSelInfo</i>	pointer of device select index
<i>*nValue</i>	pointer to frame counter mode value, 0: Frame Counter Mode, 1: Serial Counter Mode,

Returns

success: EtronDI_OK, others: see [eSPDI_ErrCode.h](#)

3.1.2.30 EtronDI_GetCTPropVal()

```
int EtronDI_GetCTPropVal (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nId,
    long int * pValue )
```

get camera terminal(CT) property value By v4l2_control to get control value of camera terminal

this enumeration contained the following properties: V4L2_CID_EXPOSURE_AUTO; V4L2_CID_EXPOSURE_A↵
UTO_PRIORITY V4L2_CID_EXPOSURE_ABSOLUTE V4L2_CID_EXPOSURE V4L2_CID_FOCUS_ABSOLUTE
V4L2_CID_FOCUS_RELATIVE V4L2_CID_FOCUS_AUTO V4L2_CID_IRIS_ABSOLUTE V4L2_CID_IRIS_REL↵
ATIVE V4L2_CID_ZOOM_ABSOLUTE V4L2_CID_ZOOM_RELATIVE V4L2_CID_PAN_ABSOLUTE V4L2_CID↵
_PAN_RELATIVE V4L2_CID_TILT_ABSOLUTE V4L2_CID_TILT_RELATIVE V4L2_CID_PRIVACY

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nId specifies the member of the property set, see CT Property ID defined in eSPDI_def.h
<i>int</i>	*pValue pointer of store CT property value

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.31 EtronDI_GetCTRangeAndStep()

```
int EtronDI_GetCTRangeAndStep (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nId,
    int * pMax,
    int * pMin,
    int * pStep,
    int * pDefault,
    int * pFlags )
```

set camera terminal property values By v4l2_queryctrl to get control values of camera terminal(CT) this enumeration contained the following properties: V4L2_CID_EXPOSURE_AUTO V4L2_CID_EXPOSURE_AUTO_PRIORITY V4L2_CID_EXPOSURE_ABSOLUTE V4L2_CID_EXPOSURE V4L2_CID_FOCUS_ABSOLUTE V4L2_CID_FOCUS_RELATIVE V4L2_CID_FOCUS_AUTO V4L2_CID_IRIS_ABSOLUTE V4L2_CID_IRIS_RELATIVE V4L2_CID_ZOOM_ABSOLUTE V4L2_CID_ZOOM_RELATIVE V4L2_CID_PAN_ABSOLUTE V4L2_CID_PAN_RELATIVE V4L2_CID_TILT_ABSOLUTE V4L2_CID_TILT_RELATIVE V4L2_CID_PRIVACY

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nId specifies the member of the property set, see CT Property ID defined in eSPDI_def.h
<i>long</i>	int *pMax maximum value, inclusive. This field gives an upper bound for the control
<i>long</i>	int *pMin minimum value, inclusive. This field gives a lower bound for the control
<i>long</i>	int *pStep This field gives a step size for the control see enum https://www.linuxtv.org/downloads/v4l-dvb-apis-old/vidioc-queryctrl.html#v4l2-ctrl-type how the step value is to be used for each possible control type. Note that this an unsigned 32-bit value
<i>long</i>	int *pDefault The default value of a V4L2_CTRL_TYPE_INTEGER, _BOOLEAN, _BITMASK, _MENU or _INTEGER_MENU control. Not valid for other types of controls. Note that drivers reset controls to their default value only when the driver is first loaded, never afterwards.
<i>long</i>	int *pFlags control flags, see https://www.linuxtv.org/downloads/v4l-dvb-apis-old/vidioc-queryctrl.html#control-flags

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.32 EtronDI_GetCurrentIRValue()

```
int EtronDI_GetCurrentIRValue (
    void * pHandleEtronDI,
```

```
PDEVSELINFO pDevSelInfo,
unsigned short * pValue )
```

get infrared radiation(IR) value of PUMA type IC

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short *pValue current 1 byte IR value setting

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.33 EtronDI_GetDepthDataType()

```
int EtronDI_GetDepthDataType (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short * pValue )
```

get current depth data type setting

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>WORD</i>	*pValue pointer of current depth data type in device

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.34 EtronDI_GetDepthImage()

```
int EtronDI_GetDepthImage (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * pBuf,
    unsigned long int * pImageSize,
    int * pSerial = 0,
    int nDepthDataType = 0 )
```

get depth image by issuing V4L2's IOCTL to get frame data

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pBuf buffer to store image data
<i>unsigned</i>	long int *pImageSize the actual buffer size getting from device
<i>int</i>	*pSerial the serial number for synchronizing color and depth image
<i>int</i>	nDepthDataType the depth data type, see definition in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.35 EtronDI_GetDeviceInfo()

```
int EtronDI_GetDeviceInfo (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    DEVINFORMATION * pdevinfo )
```

get informations of Etron UVC devices, see DEVINFORMATION

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>DEVINFORMATION*</i>	pdevinfo pointer of device information

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.36 EtronDI_GetDeviceInfoMBL_15cm()

```
int EtronDI_GetDeviceInfoMBL_15cm (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    DEVINFORMATION * pdevinfo )
```

get informations of Etron UVC devices, see DEVINFORMATION

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>DEVINFORMATION*</i>	pdevinfo pointer of device information

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.37 EtronDI_GetDeviceNumber()

```
int EtronDI_GetDeviceNumber (
    void * pHandleEtronDI )
```

get Etron USB device numbers

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
-------------	----------------------------------

Returns

number of Etron device

3.1.2.38 EtronDI_GetDeviceResolutionList()

```
int EtronDI_GetDeviceResolutionList (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nMaxCount0,
    ETRONDI_STREAM_INFO * pStreamInfo0,
    int nMaxCount1,
    ETRONDI_STREAM_INFO * pStreamInfo1 )
```

get the device resolution list

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nMaxCount0 max count of endpoint1 resolutions
<i>ETRONDI_STREAM_INFO</i>	*pStreamInfo0 resolution infos of endpoint1
<i>int</i>	nMaxCount1 max count of endpoint2 resolutions
<i>ETRONDI_STREAM_INFO</i>	*pStreamInfo1 resolutions infos of endpoint2

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.39 EtronDI_GetExposureTime()

```
int EtronDI_GetExposureTime (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nSensorMode,
    float * pfExpTimeMS )
```

get exposure time of ISP setting in millisecond the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)

Parameters

<i>void</i>	*pHandleEtronDI pHandleEtronDI
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nSensorMode which sensor(sensor A, B or Both) to get A is 0, B is 1, Both is 2
<i>float</i>	*pfExpTimeMS pointer of getting exposure time in millisecond by pixel clock, pixel per line, exposure line to get exposure time

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.40 EtronDI_GetFlexibleGyroData()

```
int EtronDI_GetFlexibleGyroData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int length,
    unsigned char * pGyroData )
```

getting gyro data function

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	length Gyro Data Length
<i>unsigned</i>	char *pGyroData pointer of Gyro Data.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.41 EtronDI_GetFlexibleGyroLength()

```
int EtronDI_GetFlexibleGyroLength (
    void * pHandleEtronDI,
```

```
PDEVSELINFO pDevSelInfo,
unsigned short * GyroLen )
```

getting length of gyro data function.

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short* GyroLen pointer of Gyro Data Lenhth.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.42 EtronDI_GetFWRegister()

```
int EtronDI_GetFWRegister (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short address,
    unsigned short * pValue,
    int flag )
```

get firmware register value

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short address register address
<i>unsigned</i>	short *pValue pointer of value got from register address
<i>int</i>	flag address and value data length(2 or 1 byte) ie FG_Address_2Byte FG_Value_2Byte is 2 byte address and 2 byte value #define FG_Address_1Byte 0x01 #define FG_Address_2Byte 0x02 #define FG_Value_1Byte 0x10 #define FG_Value_2Byte 0x20

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.43 EtronDI_GetFwVersion()

```
int EtronDI_GetFwVersion (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
```

```

char * pszFwVersion,
int  nBufferSize,
int  * pActualLength )

```

get the firmware version of device, the version is a string

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>char</i>	*pszFwVersion firmware version string
<i>int</i>	nBufferSize input buffer length to receive FW version
<i>int</i>	*pActualLength the actual length of FW version in byte

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.44 EtronDI_GetGlobalGain()

```

int EtronDI_GetGlobalGain (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int  nSensorMode,
    float * pfGlobalGain )

```

get global gain of ISP setting the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nSensorMode which sensor(sensor A, B or Both) to get A is 0, B is 1, Both is 2
<i>float</i>	*pfGlobalGain pointer of global gain value

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.45 EtronDI_GetHidGyro()

```

int EtronDI_GetHidGyro (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char * pBuffer,
    int  length )

```

getting gyro data function

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	char *pGyroData pointer of Gyro Data Buffer.
<i>int</i>	length Input buffer Length, should be >= 24

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.46 EtronDI_GetHWRegister()

```
int EtronDI_GetHWRegister (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short address,
    unsigned short * pValue,
    int flag )
```

get hardware register value

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short address register address
<i>unsigned</i>	short *pValue pointer of value got from register address
<i>int</i>	flag address and value data length(2 or 1 byte) ie FG_Address_2Byte FG_Value_2Byte is 2 byte address and 2 byte value #define FG_Address_1Byte 0x01 #define FG_Address_2Byte 0x02 #define FG_Value_1Byte 0x10 #define FG_Value_2Byte 0x20

Returns

success: EtronDI_OK, others: see [eSPDI_ErrCode.h](#)

3.1.2.47 EtronDI_GetImage()

```
int EtronDI_GetImage (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * pBuf,
    unsigned long int * pImageSize,
    int * pSerial = 0,
    int nDepthDataType = 0 )
```

get color or depth pin image by issuing V4L2's IOCTL to get frame data

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pBuf buffer to store image data
<i>unsigned</i>	long int *pImageSize the actual buffer size getting from device
<i>int</i>	*pSerial the serial number for synchronizing color and depth image
<i>int</i>	nDepthDataType the depth data type, see definition in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.48 EtronDI_GetImageInterrupt()

```
int EtronDI_GetImageInterrupt (
    void )
```

Get Image interrupt function Get the image interrupt and then read Gyro data.

Returns

success: 0, others: not got interrupt

3.1.2.49 EtronDI_GetInfoHidGyro()

```
int EtronDI_GetInfoHidGyro (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char * pCmdBuf,
    int cmdlength,
    unsigned char * pResponseBuf,
    int * resplength )
```

getting gyro data function

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	char *pCmdBuf pointer of Gyro Cmd Buffer.
<i>int</i>	cmdlength Command Length.
<i>unsigned</i>	char *pResponseBuf pointer of ResponseBuffer.
<i>int</i>	resplength Response Length

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.50 EtronDI_GetIRMaxValue()

```
int EtronDI_GetIRMaxValue (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short * pValue )
```

get maximum IR value of camera module

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short *pValue the maximum 1 byte IR value can be set

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.51 EtronDI_GetIRMinValue()

```
int EtronDI_GetIRMinValue (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short * pValue )
```

get minimum IR value of camera module

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short *pValue the minimum 1 byte IR value can be set

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.52 EtronDI_GetIRMode()

```
int EtronDI_GetIRMode (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short * pValue )
```

to check IR is turn on or off

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short *pValue get IR was enabled or not D[7:4]: Reserved D3: Channel 3 D2: Channel 2 D1: Channel 1 D0: Channel 0 1: Enable Channel 0: Disable Channel If want to control ch0 and ch1, ubMode[3:0] must set to 0x03

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.53 EtronDI_GetLogData()

```
int EtronDI_GetLogData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int BufferLength,
    int * pActualLength,
    int index,
    CALIBRATION_LOG_TYPE type )
```

get log data from flash

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer buffer to store log data
<i>int</i>	BufferLength input buffer length, must be 4096
<i>int</i>	*pActualLength actual length has written to buffer
<i>int</i>	index index to identify log data for corresponding depth
<i>CALIBRATION_LOG_TYPE</i>	type which calibration log to get

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.54 EtronDI_GetLutData()

```
int EtronDI_GetLutData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int nSize )
```

Read LUT parameters into the specified buffer.

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE*</i>	buffer memory to store LUT data
<i>int</i>	nSize length of buffer in bytes

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.55 EtronDI_GetPidVid()

```
int EtronDI_GetPidVid (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short * pPidBuf,
    unsigned short * pVidBuf )
```

get PID(product ID) and VID(vendor ID) of device

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short *pPidBuf 4 byte buffer to store PID value
<i>unsigned</i>	short *pVidBuf 4 byte buffer to store VID value

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.56 EtronDI_GetPUPPropVal()

```
int EtronDI_GetPUPPropVal (
    void * pHandleEtronDI,
```

```

PDEVSELINFO pDevSelInfo,
int nId,
long int * pValue )

```

get processing unit property value by v4l2_control to get processing unit(PU) property value

this enumeration contained the following properties: V4L2_CID_BACKLIGHT_COMPENSATION V4L2_CID_BRIGHTNESS V4L2_CID_CONTRAST V4L2_CID_GAIN V4L2_CID_POWER_LINE_FREQUENCY V4L2_CID_HUE V4L2_CID_HUE_AUTO V4L2_CID_SATURATION V4L2_CID_SHARPNESS V4L2_CID_GAMMA V4L2_CID_WHITE_BALANCE_TEMPERATURE V4L2_CID_AUTO_WHITE_BALANCE

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nId specifies the member of the property set see PU property ID defined in eSPDI_def.h
<i>long</i>	int *pValue pointer of store PU property value

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.57 EtronDI_GetPURangeAndStep()

```

int EtronDI_GetPURangeAndStep (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nId,
    int * pMax,
    int * pMin,
    int * pStep,
    int * pDefault,
    int * pFlags )

```

get processing unit property value By v4l2_queryctrl to get property values of processing unit(PU) this enumeration contained the following properties: V4L2_CID_BACKLIGHT_COMPENSATION V4L2_CID_BRIGHTNESS V4L2_CID_CONTRAST V4L2_CID_GAIN V4L2_CID_POWER_LINE_FREQUENCY V4L2_CID_HUE V4L2_CID_HUE_AUTO V4L2_CID_SATURATION V4L2_CID_SHARPNESS V4L2_CID_GAMMA V4L2_CID_WHITE_BALANCE_TEMPERATURE V4L2_CID_AUTO_WHITE_BALANCE

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nId nId specifies the member of the property set, see CT Property ID defined in eSPDI_def.h
<i>long</i>	int *pMax maximum value, inclusive. This field gives an upper bound for the control
<i>long</i>	int *pMin minimum value, inclusive. This field gives a lower bound for the control
<i>long</i>	int *pStep This field gives a step size for the control see enum https://www.linuxtv.org/downloads/v4l-dvb-apis-old/vidioc-queryctrl.html#v4l2-ctrl-type how the step value is to be used for each possible control type. Note that this an unsigned 32-bit value

Parameters

<i>long</i>	int *pDefault The default value of a V4L2_CTRL_TYPE_INTEGER, _BOOLEAN, _BITMASK, _MENU or _INTEGER_MENU control. Not valid for other types of controls. Note that drivers reset controls to their default value only when the driver is first loaded, never afterwards.
<i>long</i>	int *pFlags control flags, see https://www.linuxtv.org/downloads/v4l-dvb-apis-old/vidioc-queryctrl.html#control-flags

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.58 EtronDI_GetRectifyLogData()

```
int EtronDI_GetRectifyLogData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    eSPCtrl_RectLogData * pData,
    int index )
```

get rectify log data from flash, just for AXES1 device type

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>eSPCtrl_RectLogData</i>	*pData 4096 bytes of rectify log data, see eSPCtrl_RectLogData for detailed members
<i>index,user</i>	data section from 0 ~ 9

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.59 EtronDI_GetRectifyMatLogData()

```
int EtronDI_GetRectifyMatLogData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    eSPCtrl_RectLogData * pData,
    int index )
```

get rectify log data from flash, just for PUMA device type

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>eSPCtrl_RectLogData</i>	*pData 4096 bytes of rectify log data, see eSPCtrl_RectLogData for detailed members
<i>index,user</i>	data section from 0 ~ 9

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.60 EtronDI_GetRectifyTable()

```
int EtronDI_GetRectifyTable (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int BufferLength,
    int * pActualLength,
    int index )
```

get rectify values (file ID 40+) from flash

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer buffer to store rectify table data
<i>int</i>	BufferLength input buffer length, must be 1024
<i>int</i>	*pActualLength actual length has written to buffer
<i>int</i>	index index(from 0 ~ 9) to identify rectify table for corresponding depth

Returns

success:EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.61 EtronDI_GetSensorRegister()

```
int EtronDI_GetSensorRegister (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nId,
    unsigned short address,
    unsigned short * pValue,
    int flag,
    SENSORMODE_INFO SensorMode )
```

get value from sensor register

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nId sensor slave address see Videodevice.h for sensor slave address setting
<i>unsigned</i>	short address register address
<i>unsigned</i>	short *pValue pointer of value got from register address
<i>int</i>	flag address and value data length(2 or 1 byte) ie FG_Address_2Byte FG_Value_2Byte is 2 byte address and 2 byte value #define FG_Address_1Byte 0x01 #define FG_Address_2Byte 0x02 #define FG_Value_1Byte 0x10 #define FG_Value_2Byte 0x20
<i>SENSORMODE_INFO</i>	SensorMode sensor mode(sensor A, B or Both) A is 0, B is 1, Both is 2

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.62 EtronDI_GetSerialNumber()

```
int EtronDI_GetSerialNumber (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char * pData,
    int nbufferSize,
    int * pLen )
```

get device serial number

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pData output buffer to store serial number string
<i>int</i>	nbufferSize pData buffer length in byte, 2 byte(WideChar) is a unit
<i>int</i>	*pLen pointer of actual serial number length

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.63 EtronDI_GetSRB()

```
int EtronDI_GetSRB (
    void * pSrbHandle,
    srb_packet_s * pPacket )
```

Get Packet from SRB.

Parameters

<i>void</i>	*pSrbHandle pointer to SRB class
<i>packet_s</i>	*pPacket Input Packet

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.64 EtronDI_GetUACData()

```
int EtronDI_GetUACData (
    unsigned char * buffer,
    int length )
```

UAC initial function.

Parameters

<i>unsigned</i>	char *buffer pointer of UAC buffer
<i>int</i>	length UAC buffer length

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.65 EtronDI_getUACNAME()

```
int EtronDI_getUACNAME (
    char * input,
    char * output )
```

Get Etron UAC Name.

Parameters

<i>char</i>	*input Point to device Address.
<i>char</i>	*output Point to device Name.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.66 EtronDI_GetUserData()

```
int EtronDI_GetUserData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int BufferLength,
    USERDATA_SECTION_INDEX usi )
```

get user data from flash

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer buffer to store user data
<i>int</i>	BufferLength input buffer length
<i>USERDATA_SECTION_INDEX</i>	usi which user index data to select

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.67 EtronDI_GetYOffset()

```
int EtronDI_GetYOffset (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int BufferLength,
    int * pActualLength,
    int index )
```

get Y offset (file ID 30+) value

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer buffer to store Y offset values
<i>int</i>	BufferLength must be 256
<i>int</i>	*pActualLength the buffer length, always be 256
<i>int</i>	index index value to file ID 30

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.68 EtronDI_GetZDTable()

```
int EtronDI_GetZDTable (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int BufferLength,
    int * pActualLength,
    PZDTABLEINFO pZDTableInfo )
```

get disparity and Z values from flash

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer bufer to store ZD table
<i>int</i>	BufferLength input buffer length
<i>int</i>	*pActualLength actual length has written to buffer
<i>PZDTABLEINFO</i>	pZDTableInfo index to identify ZD table and data type for corresponding depth

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.69 EtronDI_HoleFilled()

```
int EtronDI_HoleFilled (
    unsigned short * pDImgIn,
    unsigned short * pDImgOut,
    int width,
    int height,
    int holeFillldiff )
```

Hole Filled.

Parameters

<i>unsigned</i>	short *pDImgIn Image Input
<i>unsigned</i>	short *pDImgOut Image Output
<i>int</i>	width image width
<i>int</i>	height image height
<i>int</i>	holeFillldiff Hole filled strangth, value from 0 to 2047.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.70 EtronDI_ImgMirro()

```
int EtronDI_ImgMirro (
    EtronDIImageType::Value imgType,
    int width,
    int height,
    unsigned char * src,
    unsigned char * dstBuf )
```

Make the image to Mirro.

Parameters

<i>EtronDIImageType::Value</i>	imgType Image Type
<i>int</i>	width image width
<i>int</i>	height image height
<i>unsigned</i>	char *src image source
<i>unsigned</i>	char *dstBuf image desteration

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

Parameters

<i>pHandleEtronDI</i>	the pointer to the initilized EtronDI SDK instance
<i>pDevSellInfo</i>	pointer of device select index
<i>EtronDIImageType::Value</i>	imgType Image Type
<i>int</i>	width image width
<i>int</i>	height image height
<i>unsigned</i>	char *src image source
<i>unsigned</i>	char *dstBuf image desteration

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.71 EtronDI_Init()

```
int EtronDI_Init (
    void ** ppHandleEtronDI,
    bool bIsLogEnabled )
```

entry point of Etron camera SDK including 1.create a CEtronDI class for accessing oncming APIs 2.find out Etron devices 3.create a CVideoDevice class for video streaming and hardware access

Parameters

<i>**ppHandleEtronDI</i>	a pointer of pointer to access CEtronDI class
<i>blsLogEnabled</i>	generate log or not

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.72 EtronDI_InitialCmdFiFo()

```
int EtronDI_InitialCmdFiFo (
    const char * pfifoName,
    int * pFileDescription,
    bool bRead )
```

Cmd FiFo Initial function.

Parameters

<i>const</i>	char *pfifoName Point to the cmd fifo name
<i>int</i>	*pFileDescription Point to the file description
<i>bRead</i>	Indicate Read or Write Cmd fifo

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.73 EtronDI_InitialFlexibleGyro()

```
int EtronDI_InitialFlexibleGyro (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

gyro sensor initial function

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.74 EtronDI_InitialHidGyro()

```
int EtronDI_InitialHidGyro (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

gyro sensor initial function

Parameters

<i>void*</i>	<i>pHandleEtronDI</i> CEtronDI handler
<i>PDEVSELINFO</i>	<i>pDevSelInfo</i> pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.75 EtronDI_InitialUAC()

```
int EtronDI_InitialUAC (
    char * deviceName )
```

UAC initial function.

Parameters

<i>char</i>	<i>*deviceName</i> Point to device Name.
-------------	--

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.76 EtronDI_InitSRB()

```
int EtronDI_InitSRB (
    void ** pSrbHandle,
    int QueueSize,
    char * queueName )
```

Initial the SRB(Share Ring Buffering)

Parameters

<i>void</i>	**pSrbHandle a pointer of pointer to SRB class
<i>int</i>	QueueSize
<i>char</i>	srbName SRM Name

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.77 EtronDI_IsInterleaveDevice()

```
bool EtronDI_IsInterleaveDevice (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

check module support interleave function or not

Parameters

<i>pHandleEtronDI</i>	the pointer to the initilized EtronDI SDK instance
<i>pDevSelInfo</i>	pointer of device select index

Returns

true: support interleave, false: not support

3.1.2.78 EtronDI_IsMLBaseLine()

```
bool EtronDI_IsMLBaseLine (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

Check the device is multiple baseline device.

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index

Returns

true: multiplies baseline device, false: normally device.

3.1.2.79 EtronDI_OpenDevice()

```
int EtronDI_OpenDevice (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nEP0Width,
    int nEP0Height,
    bool bEP0MJPG,
    int nEP1Width,
    int nEP1Height,
    DEPTH_TRANSFER_CTRL dtc = DEPTH_IMG_NON_TRANSFER,
    bool bIsOutputRGB24 = false,
    void * phWndNotice = 0,
    int * pFPS = 0,
    CONTROL_MODE cm = IMAGE_SN_NONSYNC )
```

the implement layer to open Etron camera device by V4L2(<https://en.wikipedia.org/wiki/Video4Linux>), can open color and depth at one time call, do functions as below,

1. initialize the USB device by V4L2 protocol 1.1 query device v4l2 capability 1.2 must have video capability 1.3 must have streaming capability 1.4 issue resolution mode to UVC driver and check result 1.5 initialize memory buffer mapping from kernel to user mode
2. enumerate frame interval to set frame rate
3. start video capture processes

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nEP0Width width of endpoint1(color) resolution
<i>int</i>	nEP0Height height of endpoint1(color) resolution
<i>bool</i>	bEP0MJPG endpoint1 output is MJPEG ?
<i>int</i>	*pFPS input frame rate setting

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.80 EtronDI_OpenDevice2()

```
int EtronDI_OpenDevice2 (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nEP0Width,
    int nEP0Height,
    bool bEP0MJPG,
    int nEP1Width,
    int nEP1Height,
    DEPTH_TRANSFER_CTRL dtc = DEPTH_IMG_NON_TRANSFER,
```

```

bool bIsOutputRGB24 = false,
void * phWndNotice = 0,
int * pFPS = 0,
CONTROL_MODE cm = IMAGE_SN_NONSYNC )

```

the implement layer to open Etron camera device by V4L2(<https://en.wikipedia.org/wiki/Video4Linux>), can open color and depth at one time call, do functions as below,

1. initialize the USB device by V4L2 protocol 1.1 query device v4l2 capability 1.2 must have video capability 1.3 must have streaming capability 1.4 issue resolution mode to UVC driver and check result 1.5 initialize memory buffer mapping from kernel to user mode
2. enumerate frame interval to set frame rate
3. start video capture processes

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nEP0Width width of endpoint1(color) resolution
<i>int</i>	nEP0Height height of endpoint1(color) resolution
<i>bool</i>	bEP0MJPG endpoint1 output is MJPEG ?
<i>int</i>	nEP1Width width of endpoint2(depth) resolution
<i>int</i>	nEP1Height height of endpoint2(depth) resolution
<i>DEPTH_TRANSFER_CTRL</i>	dtc depth image output transfer

1. default is transferred to color(DEPTH_IMG_COLORFUL_TRANSFER) by calling from [EtronDI_OpenDevice\(\)](#)
2. DEPTH_IMG_GRAY_TRANSFER : transfer to gray
3. DEPTH_IMG_NON_TRANSFER : no transfer

Parameters

<i>bool</i>	bIsOutputRGB24 output color image is RGB format
<i>void</i>	*phWndNotice reserved, not use
<i>int</i>	*pFPS input frame rate setting
<i>CONTROL_MODE</i>	cm reserved, not use

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.81 EtronDI_OpenDeviceMBL()

```

int EtronDI_OpenDeviceMBL (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nEP0Width,

```

```

    int nEP0Height,
    bool bEP0MJPG,
    int nEP1Width,
    int nEP1Height,
    DEPTH_TRANSFER_CTRL dtc = DEPTH_IMG_NON_TRANSFER,
    bool bIsOutputRGB24 = false,
    void * phWndNotice = 0,
    int * pFPS = 0,
    CONTROL_MODE cm = IMAGE_SN_NONSYNC )

```

the implement layer to open Multiple Base Line Etron camera device by V4L2(<https://en.wikipedia.org/wiki/Video4Linux>), can open color and depth at one time call, do functions as below,

1. initialize the USB device by V4L2 protocol 1.1 query device v4l2 capability 1.2 must have video capability 1.3 must have streaming capability 1.4 issue resolution mode to UVC driver and check result 1.5 initialize memory buffer mapping from kernel to user mode
2. enumerate frame interval to set frame rate
3. start video capture processes

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nEP0Width width of endpoint1(color) resolution
<i>int</i>	nEP0Height height of endpoint1(color) resolution
<i>bool</i>	bEP0MJPG endpoint1 output is MJPEG ?
<i>int</i>	nEP1Width width of endpoint2(depth) resolution
<i>int</i>	nEP1Height height of endpoint2(depth) resolution
<i>DEPTH_TRANSFER_CTRL</i>	dtc depth image output transfer

1. default is transferred to color(DEPTH_IMG_COLORFUL_TRANSFER) by calling from [EtronDI_OpenDevice\(\)](#)
2. DEPTH_IMG_GRAY_TRANSFER : transfer to gray
3. DEPTH_IMG_NON_TRANSFER : no transfer

Parameters

<i>bool</i>	bIsOutputRGB24 output color image is RGB format
<i>void</i>	*phWndNotice reserved, not use
<i>int</i>	*pFPS input frame rate setting
<i>CONTROL_MODE</i>	cm reserved, not use

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.82 EtronDI_PutSRB()

```
int EtronDI_PutSRB (
    void * pSrbHandle,
    srb_packet_s * pPacket )
```

Put Packet to SRB.

Parameters

<i>void</i>	*pSrbHandle pointer to SRB class
<i>packet_s</i>	*pPacket Input Packet

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.83 EtronDI_ReadCmdFiFo()

```
EtronDI_ReadCmdFiFo (
    int FileDescription,
    unsigned char * pBuf,
    int len )
```

Read Cmd FiFo function.

Parameters

<i>int</i>	FileDescription File description
<i>unsigned</i>	char *pCmd Point to the cmd buffer
<i>int</i>	lenIndicate the cmd length.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.84 EtronDI_ReadFlashData()

```
int EtronDI_ReadFlashData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    FLASH_DATA_TYPE fdt,
    BYTE * pBuffer,
    unsigned long int BufferLength,
    unsigned long int * pActualLength )
```

read firmware code(.bin) form flash The firmware code is the combination of boot loader, firmware body and plug-in data. This input buffer length has to match with the flash data type

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>FLASH_DATA_TYPE</i>	fdt segment type of flash be read
<i>BYTE</i>	*pBuffer buffer to store firmware code
<i>unsigned</i>	long int BufferLength input buffer length
<i>unsigned</i>	long int *pActualLength actual length has written to pBuffer

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.85 EtronDI_RefreshDevice()

```
int EtronDI_RefreshDevice (  
    void * pHandleEtronDI )
```

refresh all Etron UVC devices

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
-------------	----------------------------------

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.86 EtronDI_Release()

```
void EtronDI_Release (  
    void ** ppHandleEtronDI )
```

release resource that EtronDI_Init had allocated

Parameters

<i>void</i>	**ppHandleEtronDI array of CEtronDI class handlers
-------------	--

Returns

none

3.1.2.87 EtronDI_ReleaseFlexibleGyro()

```
int EtronDI_ReleaseFlexibleGyro (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

gyro sensor release function

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.88 EtronDI_ReleaseHidGyro()

```
int EtronDI_ReleaseHidGyro (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo )
```

gyro sensor release function

Parameters

<i>void*</i>	<i>pHandleEtronDI</i> CEtronDI handler
<i>PDEVSELINFO</i>	<i>pDevSelInfo</i> pointer of device select index

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.89 EtronDI_ReleaseSwPostProc()

```
int EtronDI_ReleaseSwPostProc (
    void ** handle )
```

release a software post process class

Parameters

<i>void**</i>	<i>handle</i> handle pointer to this software post process class
---------------	--

Returns

success: EtronDI_OK, others: see [eSPDI_ErrCode.h](#)

3.1.2.90 EtronDI_ReleaseUAC()

```
int EtronDI_ReleaseUAC (
    void )
```

UAC initial function.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.91 EtronDI_ResizeImgToHalf()

```
int EtronDI_ResizeImgToHalf (
    EtronDIImageType::Value imgType,
    int width,
    int height,
    unsigned char * src,
    unsigned char * dst,
    int len )
```

Resize the image to half.

Parameters

<i>EtronDIImageType::Value</i>	mgType Image Type
<i>int</i>	width image width
<i>int</i>	height image height
<i>unsigned</i>	char *src image source
<i>unsigned</i>	char *dst image desteration
<i>int</i>	len desteration buffer length

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.92 EtronDI_RGB2BMP()

```
int EtronDI_RGB2BMP (
    char * filename,
    int width,
    int height,
    unsigned char * data )
```

RGB to BMP.

Parameters

<i>*filename</i>	Ouput BMP file name
<i>int</i>	width image width
<i>int</i>	height image height
<i>*data</i>	input RGB buffer.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.93 EtronDI_RotateImg180()

```
int EtronDI_RotateImg180 (
    EtronDIImageType::Value imgType,
    int width,
    int height,
    unsigned char * src,
    unsigned char * dstBuf,
    int len )
```

Rotate the image to 180 degree.

Parameters

<i>EtronDIImageType::Value</i>	mgType Image Type
<i>int</i>	width image width
<i>int</i>	height image height
<i>unsigned</i>	char *src image source
<i>unsigned</i>	char *dstBuf image desteration
<i>int</i>	len desteration buffer length

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.94 EtronDI_RotateImg90()

```
int EtronDI_RotateImg90 (
    EtronDIImageType::Value imgType,
    int width,
    int height,
    unsigned char * src,
    unsigned char * dstBuf,
    int len,
    bool clockwise )
```

Rotate the image to 90 degree.

Parameters

<i>EtronDIImageType::Value</i>	mgType Image Type
<i>int</i>	width image width
<i>int</i>	height image height
<i>unsigned</i>	char *src image source
<i>unsigned</i>	char *dstBuf image desteration
<i>int</i>	len desteration buffer length
<i>bClockwise, false</i>	not supported.
<i>bOpencv</i>	useage, not supported.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.95 EtronDI_SaveLutData()

```
int EtronDI_SaveLutData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    const char * filename )
```

Save LUT parameters in the specified file.

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>const</i>	char* filename output LUT file name

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.96 EtronDI_SelectDevice()

```
int EtronDI_SelectDevice (
    void * pHandleEtronDI,
    int dev_index )
```

do not support currently

Returns

ETronDI_NotSupport

3.1.2.97 EtronDI_SetAutoExposureMode()

```
int EtronDI_SetAutoExposureMode (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short mode )
```

Setup Auto Exposure Mode.

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler.
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index.
<i>unsigned</i>	short mode The setup mode value. 0: Average, 1: Left (or Front) camera, 2: Right (or Back) camera

Returns

success: EtronDI_OK, others: [eSPDI_def.h](#)

3.1.2.98 EtronDI_SetColorGain()

```
int EtronDI_SetColorGain (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nSensorMode,
    float fGainR,
    float fGainG,
    float fGainB )
```

set color gain of ISP

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nSensorMode which sensor(sensor A, B or Both) to get A is 0, B is 1, Both is 2
<i>float</i>	fGainR Red channel color gain value
<i>float</i>	fGainG Green channel color gain value
<i>float</i>	fGainB Blue channel color gain value

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.99 EtronDI_SetControlCounterMode()

```
int EtronDI_SetControlCounterMode (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char nValue )
```

enable or disable interleave function

Parameters

<i>pHandleEtronDI</i>	the pointer to the initilized EtronDI SDK instance
<i>pDevSelInfo</i>	pointer of device select index
<i>nValue</i>	0: Frame Counter Mode, 1: Serial Counter Mode,

Returns

success: EtronDI_OK, others: see eSPDI_ErrCode.h

3.1.2.100 EtronDI_SetCTPropVal()

```
int EtronDI_SetCTPropVal (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nId,
    long int nValue )
```

set camera terminal property values By v4l2_control to set

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nId specifies the member of the property set see CT Property ID defined in eSPDI_def.h
<i>long</i>	int nValue CT property value to set

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.101 EtronDI_SetCurrentIRValue()

```
t EtronDI_SetCurrentIRValue (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short nValue )
```

set infrared radiation(IR) value of PUMA type IC

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short nValue 1 byte IR value to set

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.102 EtronDI_SetDepthDataType()

```
EtronDI_SetDepthDataType (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short nValue )
```

set depth data type, 11 bit for disparity data, 14 bit for Z data notice: only PUMA type IC can support this setting

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short nValue depth data type you want to set, see ETRONDI_DEPTH_DATA_XXX in eSPDI_def.h

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.103 EtronDI_SetExposureTime()

```
int EtronDI_SetExposureTime (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nSensorMode,
    float fExpTimeMS )
```

set exposure time of ISP sensor setting the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)

EtronDI_SetExposureTime(void *pHandleEtronDI, PDEVSELINFO pDevSelInfo, int nSensorMode, float fExpTimeMS)

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nSensorMode which sensor(sensor A, B or Both) to set A is 0, B is 1, Both is 2
<i>float</i>	fExpTimeMS pointer of setting exposure time in millisecond check sensor spec for detailed setting, we need pixel clock, pixel per line, V blank and exposure line

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.104 EtronDI_SetFWRegister()

```
int EtronDI_SetFWRegister (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short address,
    unsigned short nValue,
    int flag )
```

set firmware register value

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short address register address
<i>unsigned</i>	short nValue register value to set
<i>int</i>	flag address and value data length(2 or 1 byte) ie FG_Address_1Byte FG_Value_1Byte is 1 byte address and 1 byte value #define FG_Address_1Byte 0x01 #define FG_Address_2Byte 0x02 #define FG_Value_1Byte 0x10 #define FG_Value_2Byte 0x20

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.105 EtronDI_SetGlobalGain()

```
int EtronDI_SetGlobalGain (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nSensorMode,
    float fGlobalGain )
```

set global gain of ISP sensor setting the target sensor type was set in [EtronDI_SetSensorTypeName\(\)](#)

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nSensorMode which sensor(sensor A, B or Both) to get A is 0, B is 1, Both is 2
<i>float</i>	fGlobalGain pointer of global gain value

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.106 EtronDI_SetHWRegister()

```
int EtronDI_SetHWRegister (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short address,
    unsigned short nValue,
    int flag )
```

set hardware register

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short address register address
<i>unsigned</i>	short nValue register value to set
<i>int</i>	flag address and value data length(2 or 1 byte) ie FG_Address_1Byte FG_Value_1Byte is 1 byte address and 1 byte value #define FG_Address_1Byte 0x01 #define FG_Address_2Byte 0x02 #define FG_Value_1Byte 0x10 #define FG_Value_2Byte 0x20

Returns

success: EtronDI_OK, others: see [eSPDI_ErrCode.h](#)

3.1.2.107 EtronDI_SetIRMode()

```
EtronDI_SetIRMode (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short nValue )
```

enable or disable IRs

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short nValue 8 bit definition as below to turn on/off IR D[7:4]: Reserved D3: Channel 3 D2: Channel 2 D1: Channel 1 D0: Channel 0 1: Enable Channel 0: Disable Channel If want to control ch0 and ch1, ubMode[3:0] must set to 0x03

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.108 EtronDI_SetLogData()

```
int EtronDI_SetLogData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int BufferLength,
    int * pActualLength,
    int index )
```

set log data to flash

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer log data to set
<i>int</i>	BufferLength buffer length, must be 4096
<i>int</i>	*pActualLength always return 4096
<i>int</i>	index index to identify log data for corresponding depth

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.109 EtronDI_SetPidVid()

```
int EtronDI_SetPidVid (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned short * pPidBuf,
    unsigned short * pVidBuf )
```

set PID and VID to device

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	short *pPidBuf 4 byte PID value buffer to set
<i>unsigned</i>	short *pVidBuf 4 byte VID value buffer to set

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.110 EtronDI_SetPUPropVal()

```
int EtronDI_SetPUPropVal (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nId,
    long int nValue )
```

set processing unit property value by v4l2_control to set processing unit(PU) property value

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nId specifies the member of the property set see PU Property ID defined in eSPDI_def.h
<i>int</i>	nValue value to set

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.111 EtronDI_SetRectifyTable()

```
int EtronDI_SetRectifyTable (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int BufferLength,
    int * pActualLength,
    int index )
```

set rectify values to flash

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer rectify values to set
<i>int</i>	BufferLength bufer length, must be 1024
<i>int</i>	*pActualLength always return 1024
<i>int</i>	index index(from 0 ~ 9) to identify rectify table for corresponding depth

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.112 EtronDI_SetSensorRegister()

```
int EtronDI_SetSensorRegister (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int nId,
    unsigned short address,
    unsigned short nValue,
    int flag,
    SENSORMODE__INFO SensorMode )
```

set sensor register value

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	nId sensor slave address see Videodevice.h for sensor slave address setting
<i>unsigned</i>	short address register address
<i>unsigned</i>	short nValue value to set
<i>int</i>	flag address and value data length(2 or 1 byte) ie FG_Address_1Byte FG_Value_1Byte is 1 byte address and 1 byte value #define FG_Address_1Byte 0x01 #define FG_Address_2Byte 0x02 #define FG_Value_1Byte 0x10 #define FG_Value_2Byte 0x20
<i>SENSORMODE__INFO</i>	SensorMode sensor mode(sensor A, B or Both) A is 0, B is 1, Both is 2

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.113 EtronDI_SetSensorTypeName()

```
int EtronDI_SetSensorTypeName (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    SENSOR_TYPE_NAME stn )
```

set the sensor type you want to work on

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>SENSOR_TYPE_NAME</i>	stn which sensor you want to work on

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.114 EtronDI_SetSerialNumber()

```
int EtronDI_SetSerialNumber (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char * pData,
    int nLen )
```

set serial number to device

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*pData pointer of buffer to store serial number, it is WildChar
<i>int</i>	nLen pData length in byte

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.115 EtronDI_Setup_v4l2_requestbuffers()

```
int EtronDI_Setup_v4l2_requestbuffers (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    int cnt )
```

Setup v4l2 request buffers, default = 4.

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>int</i>	cnt Should be >= 0

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.116 EtronDI_SetupBlock()

```
int EtronDI_SetupBlock (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    bool enable )
```

get color or depth pin image by issuing V4L2's IOCTL to get frame data

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>bool</i>	enable Enable the Blocking mode or not)

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.117 EtronDI_SetupHidGyro()

```
int EtronDI_SetupHidGyro (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    unsigned char * pCmdBuf,
    int cmdlength )
```

getting gyro data function

Parameters

<i>void*</i>	pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>unsigned</i>	char *pGyroData pointer of Gyro Data Buffer.
<i>int</i>	length Input buffer Length, shoul

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.118 EtronDI_SetUserData()

```
int EtronDI_SetUserData (
    void * pHandleEtronDI,
```

```

PDEVSELINFO pDevSelInfo,
BYTE * buffer,
int BufferLength,
USERDATA_SECTION_INDEX usi )

```

set user data to flash

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer user buffer data to set
<i>int</i>	BufferLength buffer length to write
<i>USERDATA_SECTION_INDEX</i>	usi which user section data to set

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.119 EtronDI_SetYOffset()

```

int EtronDI_SetYOffset (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    BYTE * buffer,
    int BufferLength,
    int * pActualLength,
    int index )

```

set Y offset values

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer buffer data to set
<i>int</i>	BufferLength buffer length
<i>int</i>	*pActualLength always return 256
<i>int</i>	index index value to file ID 30

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.120 EtronDI_SetZDTable()

```

int EtronDI_SetZDTable (
    void * pHandleEtronDI,

```

```

PDEVSELINFO pDevSelInfo,
BYTE * buffer,
int BufferLength,
int * pActualLength,
PZDTABLEINFO pZDTableInfo )

```

set disparity and Z values to flash

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI handler
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>BYTE</i>	*buffer ZD values to set
<i>int</i>	BufferLength corresponding length of ZD table in buffer
<i>int</i>	*pActualLength buffer length written to flash, should be same as BufferLength
<i>PZDTABLEINFO</i>	pZDTableInfo index and depth type of this ZD

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.121 EtronDI_SwitchBaseline()

```

int EtronDI_SwitchBaseline (
    int index )

```

Switch the baseline index.

Parameters

<i>int</i>	index Baseline index 1: 30 mm 2: 60 mm 3: 150 mm
------------	--

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.122 EtronDI_WriteCmdFiFo()

```

int EtronDI_WriteCmdFiFo (
    int FileDescription,
    unsigned char * pCmd,
    int len )

```

Write Cmd FiFo function.

Parameters

<i>int</i>	FileDescription File description
<i>unsigned</i>	char *pCmd Point to the cmd buffer
<i>int</i>	lenIndicate the cmd length.

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.123 EtronDI_WriteFlashData()

```
int EtronDI_WriteFlashData (
    void * pHandleEtronDI,
    PDEVSELINFO pDevSelInfo,
    FLASH_DATA_TYPE fdt,
    BYTE * pBuffer,
    unsigned long int BufferLength,
    bool bIsDataVerify,
    KEEP_DATA_CTRL kdc )
```

write firmware code(.bin) to flash The firmware code is the combination of boot loader, firmware body and plug-in data, also can keep original functions(Serial Number, Sensor Position, RectificationTable, ZD Table and CalibrationLog) on camera flash by KEEP_DATA_CTRL control

Parameters

<i>void</i>	*pHandleEtronDI CEtronDI class
<i>PDEVSELINFO</i>	pDevSelInfo pointer of device select index
<i>FLASH_DATA_TYPE</i>	fdt segment type of flash be wrote
<i>BYTE</i>	*pBuffer buffer of firmware code
<i>unsigned</i>	long int BufferLength Buffer length to be wrote
<i>BOOL</i>	blsDataVerify write data verification flag, if true this function will read data again and do a byte to byte comparison
<i>KEEP_DATA_CTRL</i>	kdc keep function flags

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.124 EtronDI_WriteWaveEnd()

```
int EtronDI_WriteWaveEnd (
    int fd,
    size_t length )
```

Modified Wave Header.

Parameters

<i>int</i>	fd wave file descript.
------------	------------------------

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.1.2.125 EtronDI_WriteWaveHeader()

```
int EtronDI_WriteWaveHeader (  
    int fd )
```

Write Wave Header.

Parameters

<i>int</i>	fd wave file descript.
------------	------------------------

Returns

success: EtronDI_OK, others: see [eSPDI_def.h](#)

3.2 eSPDI_source/eSPDI_def.h File Reference

main data structure, variable and macro definition and error definition Copyright: This file copyright (C) 2017 by

3.2.1 Detailed Description

main data structure, variable and macro definition and error definition Copyright: This file copyright (C) 2017 by

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