1. SSE =
$$\sum_{i=1}^{N} (y_i - b_0 - b_1 z_{i1} - b_2 z_{i2})^2$$

2. $\frac{dSSE}{db_0} = -2 \sum_{i} y_i - b_0 - b_1 z_{i1} - b_2 z_{i2}$
 $\frac{dSSE}{db_1} = -2 \sum_{i} z_{i1} (y_i - b_0 - b_1 z_{i1} - b_2 z_{i2})$
 $\frac{dSSE}{db_2} = -2 \sum_{i} z_{i2} (y_i - b_0 - b_1 z_{i1} - b_2 z_{i2})$

3. residuals = $e_i = y_i - y_i = y_i - b_0 - b_1 z_{i1} - b_2 z_{i2}$

At optimum partial derivative = 0

 $\frac{dSSE}{db_0} = -2 \sum_{i} e_i = 0$
 $\frac{dSSE}{db_0} = -2 \sum_{i} e_i = 0$
 $\frac{dSSE}{db_1} = -2 \sum_{i} e_i = 0$
 $\frac{dS$

$$\begin{pmatrix}
N & O & O \\
O & \Sigma z_{i1}^{2} & \Sigma z_{i1} z_{i2} \\
O & \Sigma z_{i1} z_{i2} & \Sigma z_{i2}^{2}
\end{pmatrix}$$

$$b_{0} = \begin{pmatrix}
\Sigma v_{i} \\
\Sigma v_{i} z_{i1} \\
\Sigma v_{i} z_{i2}
\end{pmatrix}$$

$$\Delta$$

$$\Delta$$

$$\frac{A}{N} = \begin{pmatrix}
1 & 0 & 0 \\
0 & \frac{1}{N} \sum_{z_{1}}^{2} z_{1}^{2} & \frac{1}{N} \sum_{z_{1}}^{2} z_{1}z_{2} \\
0 & \frac{1}{N} \sum_{z_{1}}^{2} z_{1}^{2} & \frac{1}{N} \sum_{z_{1}}^{2} z_{1}z_{2}
\end{pmatrix}$$

$$\frac{A}{N} = \begin{pmatrix}
1 & 0 & 0 \\
0 & var(x_{1}) & car(x_{1}, x_{2}) \\
0 & cor(x_{1}, x_{2}) & var(x_{2})
\end{pmatrix}$$

$$\frac{A}{N} = \begin{pmatrix}
1 & 0 & 0 \\
0 & var(x_{1}) & car(x_{1}, x_{2}) \\
0 & cor(x_{1}, x_{2}) & var(x_{2})
\end{pmatrix}$$

$$\frac{C}{N} = \begin{pmatrix}
\frac{1}{N} \sum_{z_{1}}^{N} z_{1}z_{1} \\
\frac{1}{N} \sum_{z_{1}}^{N} z_{1}z_{1}
\end{pmatrix}$$

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\frac{1}{N} \sum_{z_{1}}^{N} z_{1}z_{1} \\
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\frac{1}{N} \sum_{z_{1}}^{N} z_{1}z_{2}
\end{pmatrix}$$

Dividing by N or the sample size takes the average of the product. Variance is the average of squared terms and covariance is the average of cross-product terms. Therefore it makes sense that dividing by N leads to variance and covariance	•
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