Andrew Mei Wu

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Deeply committed to using and improving AI for products that matter.

EDUCATION

The University of Texas at Austin

Austin, TX | August 2019-May 2024

B.S. & M.S. IN COMPUTER SCIENCE - GPA 3.94

- TA for Neural Networks Spring 2022
- Relevant Coursework: (Grad Courses*)

Robot Learning*; Planning, Search, and Reasoning under Uncertainty*; Learning for Controls and Dynamics*; Distributed Computing*; Communication Complexity*; Boolean Functions*; Neural Nets; AI; Data Mining; Autonomous Robots 1 & 2; Cyperphysical Systems

EXPERIENCE

Zadar Labs 2 | AI/ML Engineer Intern

San Jose, CA | May-August 2023

- Engineered an object-centric camera-radar depth completion algorithm achieving a 10x speed improvement with real-time performance at 180 FPS.
- Adapted and realized a **state-of-the-art unsupervised learning object detector** from LiDAR for radar applications, laying the groundwork for the company's deep learning dataset.
- Identified key marketing opportunities and used my photography skills to help conceptualize, capture, and edit company photos and videos resulting in their first LinkedIn posts, tens of thousands of impressions, and heavily increased business inquiries.

Amazon | AWS Software Development Engineer Intern

Santa Clara, CA | May-August 2022

- Designed and implemented groundwork for a new customer-facing tool for **automatic docker container generation for Machine Learning Applications**, contributing the first code and foundational prototypes for this tool.
- Created workflow to **automatically detect third-party packages and corresponding version sets**, hooking it up with AWS EC2 and AWS SageMaker.

Sandia National Laboratories | Research Intern

Albuquerque, NM | May-August 2021

• Developed an **embedded**, **real-time sensing subsystem combining multiple gamma ray detectors**, determining ideal sensor settings via PID and anomalous radioisotope events via ensembled nets, connected with RabbitMQ messaging and PostgreSQL logging.

PROJECTS

MULTI-TASK BEHAVIOR TRANSFORMERS 7

PYTHON, PYTORCH, HYDRA, ROBOMIMIC

- Implemented **Behavior Transformers** of for the **robomimic simulation framework** of and extended its capabilities for **transfer learning** and **multi-task learning**.
- Achieved **improved generalization in multi-task learning** and observed **positive transfer effects** in robomimic benchmarks.

SUPERTUXKART STATE-BASED AGENT [7]

PYTHON, PYTORCH

1St of 23 Teams in CS342 Neural Networks Intra-Class Tournament

- Led the development of a state-based agent for a 2v2 Mario Kart-style ice hockey game, winning among 170+ students.
- Explored SuperTux internals to optimize **DAgger imitation learning** by generating only wins.
- Designed and compared agents using REINFORCE, off-policy imitation, and gradient-free optimization.

GESTURE RECOGNITION CAR ✓

PYTHON, PYTORCH, ROS

• Led and engineered a PID-based person-following and tracking system with gesture-based commands like start, stop, follow by integrating gesture recognition libraries with YOLO on a F1/10 car.

SKILLS

- Languages: Python, Go, C++, Java, RISC-V, Bash, SQL
- Tech & Tools: PyTorch, ROS, Docker, PyTorch Lightning, Hydra, WandB, RabbitMQ, AWS, Git, DaVinci Resolve, Photoshop