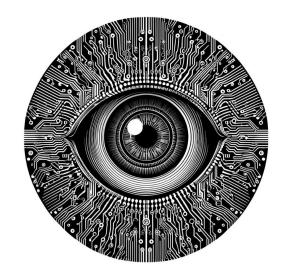


PyTorch Datasets and Dataloaders



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Learning goals

- Create Dataset objects in PyTorch to wrap images and target values together
- Implement DataLoader PyTorch objects to feed data to a model
- Understand the connection between DataLoader and Stochastic Gradient Descent

The batch dimension is important for our models



torch image tensors follow the format: [N, C, H, W] where:

- N = batch size (number of images)
- c = channels (e.g., 1 for grayscale, 3 for RGB)
- H = height in pixels
- w = width in pixels

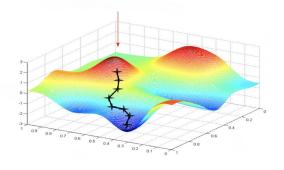
```
print(torch_tensor_gray.shape)
# torch.Size([1, 1, 28, 28])
```

Feeding torch tensors to a PyTorch model

```
# Define the train loader with batch size and shuffling
batch size = 32
train_loader = DataLoader(dataset=train_dataset,
                         batch_size=batch_size,
                         shuffle=True)
                                                      Tip: use the nvidia-smi bash command to
                                                      check the RAM available in your GPU
# Move model to device (GPU/CPU)
model = model.to(device)
# Training loop
for images, labels in train_loader:
  # Remember that data has to be explicitly sent to the GPU
  images, labels = images.to(device), labels.to(device)
  output = model(images)
  batch_loss = loss_function(output, labels)
```

Shuffling the training set only

```
# Create data loaders
batch_size = 32
# Notice that we shuffle the training loader, but not the validation or test loaders.
# This practice of shuffling the training set is one of the techniques
# that have been shown to improve training.
train_loader = DataLoader(train_subset, batch_size=batch_size, shuffle=True)
valid_loader = DataLoader(valid_subset, batch_size=batch_size, shuffle=False)
test_loader = DataLoader(test_set, batch_size=batch_size, shuffle=False)
```



$$w_{ij} = w_{ij} - (\text{learning rate} * \frac{dL}{dw_{ij}})$$

Dataloader depends on Dataset

```
# Define the MNIST Dataset class as a subclass of Dataset
class MNISTDataset(Dataset):
    # Content of the dataset
    # gets called on dataset_instance = MNISTDataset(<params>)
    def __init__(self, dataframe, labels=True, transform=None):
    ...
    def __len__(self):
        # What gets called on len(dataset_instance)
        return len(self.data)

def __getitem__(self, idx):
    # What gets called on dataset_instance[index]
...
    return image_tensor, label_tensor
```

Practice creating a Dataset



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https://www.kaggle.com/competitions/digit-recognizer



Summary

Dataset objects wrap images and labels together

 Provide a standard way to access data through __getitem__ and __len__ methods

Dataloaders split datasets in batches

 Dataloaders shuffle the training data and maintain sequential order for validation and test sets

Dataloaders are fundamental to implement Stochastic Gradient Descent

 Their random sampling and shuffling of training samples provide the 'stochastic' part of Stochastic Gradient Descent





References

Datasets and Dataloaders

https://pytorch.org/tutorials/beginner/basics/data_tutorial.html

MNIST on PyTorch's datasets

https://pytorch.org/vision/0.20/generated/torchvision.datasets.MNIST.html

MNIST on Fiftyone

https://try.fiftyone.ai/datasets/mnist/samples

