1.主机发送广播

bb aa 1a 00 54 b0 00 00 01 03 78 e6 3d 1f 06 00 00 00 07 00 00 00 08 00 00 00

2.hub发送注册码

3.主机回复注册成功

bb aa 12 00 3d 3a 01 00 01 04 00 00 00 00 00 00 00 00

4.发送sensor device 注册

5.回复sensor device 注册成功

BB AA 12 00 60 1C 00 00 02 04 29 00 25 00 02 00 00 00

BB AA 12 00 61 8C 00 00 02 04 29 00 25 00 03 00 00 00

6.主机发送设置类

Id = 0

bb aa 2b 00 b2 73 00 00 01 0a 03 00 00 00 00 00 00 00 00 00 00 00 5b 32 2c 28 30 2c 30 2c 36 30 29 2c 28 31 2c 31 2c 36 30 29 5d

7.触发条件

Id = 0

条件 梯形曲线值 = 1

bb aa 20 00 49 dd 00 00 02 0a 03 00 00 00 00 00 00 00 00 00 00 00 01 00 28 31 29 3d 3d 28 30 29

8.动作执行

excute.id = 0x00000000;

excute.device\_id = 0x00000003;

excute.storage = 0;

excute.action\_id\_v = 0x00000000;

bb aa 20 00 6d 73 00 00 03 0a 03 00 00 00 00 00 00 00 00 00 00 00 03 00 00 00 00 00 00 00 00 00

9.触发与动作（双向）

dotask.id = 0x00000000;

dotask.condition\_id = 0;

dotask.excuteAction\_id = 0;

dotask.start = 0;

dotask.continue\_t = 60;

dotask.delay = 10;

bb aa 28 00 fb be 00 00 04 0a 03 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 3c 00 00 00 0a 00