

QUIK START GUIDE	
Description	Command
Download package and unzip in the following folder.	<code>cd ~/catkin_ws/src/</code>
Install python package djitellopy with the command line.	<code>pip3 install djitellopy</code>
Do a catkin_make in the command line	<code>cd ~/catkin_ws/</code>
	<code>catkin_make</code>
Power on drone. Wait for the led lamp to flashes yellow	
Connect to the drones Wi-Fi or connect the drone to your Wi-Fi network	
Launch the package you want	<code>roslaunch dji_tello_pkg tello_teleop.launch</code>
	<code>roslaunch dji_tello_pkg tello_teleop_camara.launch</code>
	<code>roslaunch dji_tello_pkg tello_swarm_teleop_sequentieel.launch</code>
	<code>roslaunch dji_tello_pkg tello_swarm_teleop_parallel.launch</code>
	<code>roslaunch dji_tello_pkg tello_show.launch</code>