

Computational Imaging and Spectroscopy

Scene analysis I: Spectrum representation and recovery

Thierry SOREZE DTU July 2024



DTU Fotonik
Department of Photonics Engineering



Suppose we have a device with three colour sensors, whose spectral sensitivities are $C_k(\lambda)$, k=1,2,3. The three sensor responses for a colour signal $S(\lambda)$ will be:

$$\begin{cases} R_1 = \sum_{\lambda} C_1(\lambda)S(\lambda) \\ R_2 = \sum_{\lambda} C_2(\lambda)S(\lambda) \\ R_3 = \sum_{\lambda} C_3(\lambda)S(\lambda) \end{cases}$$

Which can be written in matrix from as

$$r = Ms$$



Linear decomposition

We can use a linear decomposition to represent a spectra P discretized in n bins of width $\Delta\lambda$ and write:

$$P(\lambda) = \sum_{k=1}^{n} a_k b_k(\lambda)$$

Where a_k are weights and $b_k(\lambda)$ a set a of basis functions.

Several basis functions have been proposed in the literature. The most popular basis are given by **PCA**



Linear decomposition

Fourier

$$B = \sum_{i=0}^{D} a_i \cdot \sin(i\lambda \pi)$$

Polynomial

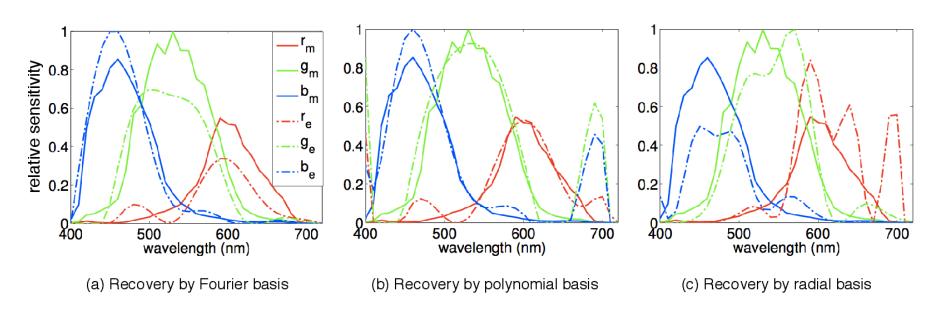
$$B = \sum_{i=0}^{D} a_i \cdot \lambda^i$$

Radial basis

$$B = \sum_{i=0}^{D} a_i \cdot \exp\left(-\frac{(\lambda - \mu_i)^2}{\sigma^2}\right)$$



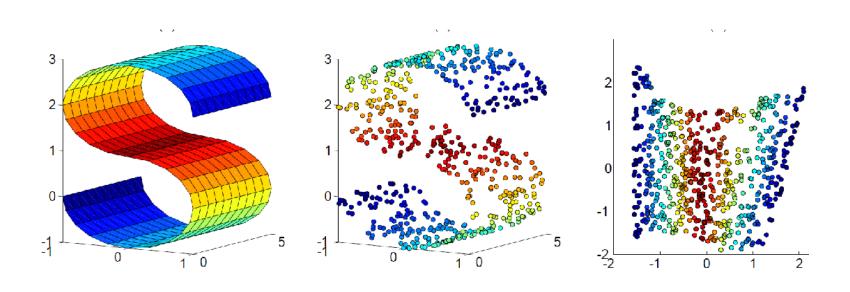
Linear decomposition



Jiang et al.

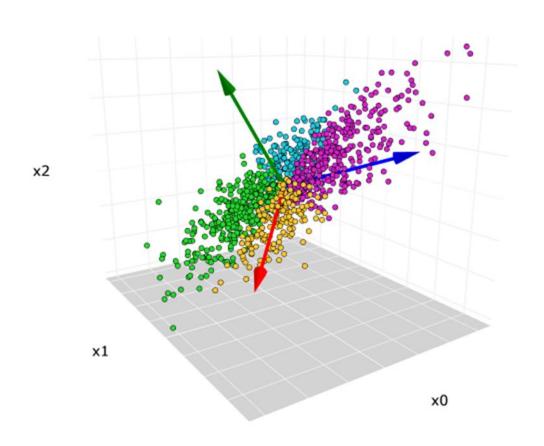


Dimensionality reduction (PCA and NNMF)





Principal component analysis (PCA)





Non negative matrix factorization (NNMF)

PCA has many applications:

Dimensionality reduction/compression Orthogonalization (ex. Color space) Classification

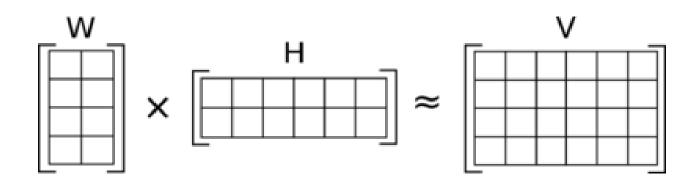
Face recognition Etc.



https://en.wikipedia.org/wiki/Principal component analysis



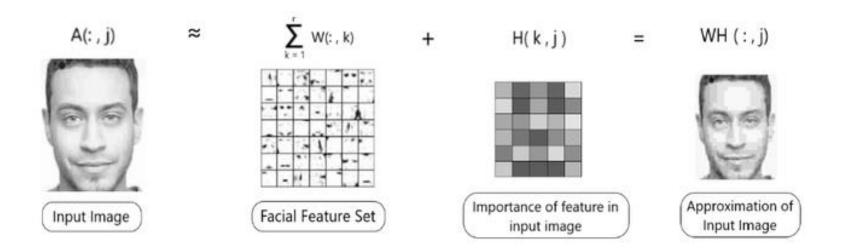
Non negative matrix factorization (NNMF)



https://en.wikipedia.org/wiki/Non-negative matrix factorization



Non negative matrix factorization (NNMF)





Principal component analysis (PCA)

Example 1: camera calibration (Jiang et al.)

$$I_{k,x} = \int_{vis} C_k(\lambda) L(\lambda) R_x(\lambda) d\lambda. \quad k \in [R, G, B]$$

In matrix form we have

$$I_k = c_k LR$$

$$\mathbf{c}_{\mathbf{k}} = \mathbf{i}_{\mathbf{k}} \cdot (\mathbf{L}\mathbf{R})^{+}$$

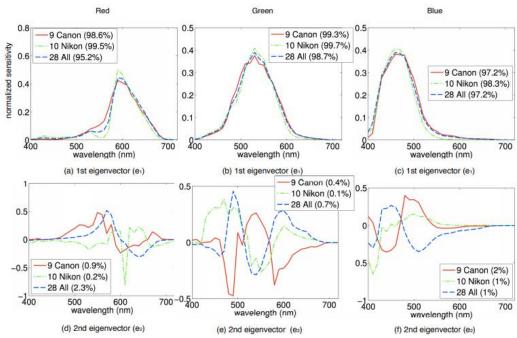
In practice direct inversion is not accurate for retrieving the camera sensitivities



Principal component analysis (PCA)

Example 1 : camera calibration (Jiang et al.)

They measured the spectral sensitivities of 28 cameras and performed PCA on each channel individually on this dataset to derived the space of spectral sensitivities of cameras.





Principal component analysis (PCA)

Example 1 : camera calibration (Jiang et al.)

In their experiments the data were explained by the first two components of **PCA** at 97%. We can write, under a known illuminant:

$$c_k = i_k (E_k LR)^+ E_k$$



Principal component analysis (PCA)

Example 2: spectral recovery

We seek to recover a spectrum $S(\lambda)$ for a triplet of XYZ. As seen we can express this spectra with a linear decomposition:

$$s = \sum_{k=1}^{n} a_k b_k$$

We can truncate this summation to the first three terms and write:

$$s \approx a_1b_1 + a_2b + a_3b_3 + \mu$$

 μ is the average of the data



Principal component analysis (PCA)

Example 2: spectral recovery

We can express the XYZ triplet by using the following expression

$$c \approx \begin{bmatrix} \mathbf{X}^{\mathbf{T}} \\ \mathbf{Y}^{\mathbf{T}} \\ \mathbf{Z}^{\mathbf{T}} \end{bmatrix} \tilde{s} = \begin{bmatrix} \mathbf{X}^{\mathbf{T}} \\ \mathbf{Y}^{\mathbf{T}} \\ \mathbf{Z}^{\mathbf{T}} \end{bmatrix} [\mathbf{b_1} \mathbf{b_2} \mathbf{b_3}] \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} + c_{\mu} = \mathbf{M} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} + c_{\mu}$$

We can therefore approximate the weights:

$$\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \approx \mathbf{M}^{-1} (c - c_{\mu}) = \begin{vmatrix} \hat{a}_1 \\ \hat{a}_2 \\ \hat{a}_3 \end{vmatrix}$$



Principal component analysis (PCA)

Example 2 : spectral recovery

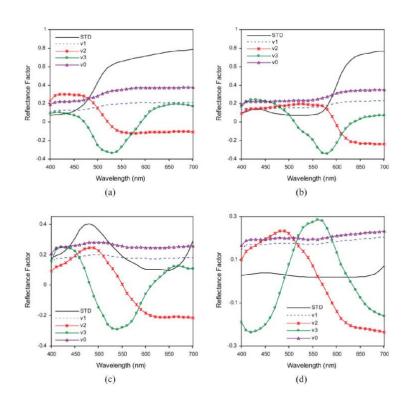
The reconstructed spectrum s is given by

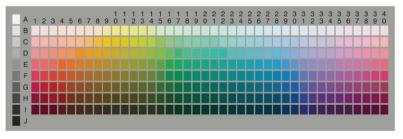
$$s \approx \hat{a}_1 b_1 + \hat{a}_2 b_2 + \hat{a}_3 b_3 + \mu$$

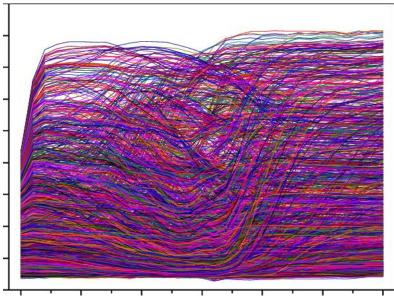


Assignment

Objective: Spectrum reconstruction of samples from the Munsell dataset









Assignment

Objective: Spectral reconstruction of samples from the Munsell dataset

Tasks:

- □Split the dataset at random (80/20): Training and test sets
- □Perform **PCA** on the training dataset to reconstruct spectra of few Munsell samples from the test datset
- □Compute error metrics (**MRAE**, **RMSE**, **GFC**) using 5 folds cross validation
- □Convert reconstructed spectra to XYZ
- □Compute color difference (delta Lab)



Assignment

Objective: Spectral reconstruction of samples from the Munsell dataset

Improvements:

□Cluster the dataset with k-means

□Perform reconstruction model per cluster

□Compare results with non clustered model

https://en.wikipedia.org/wiki/K-means_clustering



Assignment

Objective: Spectral reconstruction of samples from the Munsell dataset

https://scikit-learn.org/stable/modules/generated/sklearn.cluster.KMeans.html

https://scikit-

<u>learn.org/stable/auto_examples/cluster/plot_kmeans_silhouette_analysis.html</u>

https://scikit-learn.org/stable/modules/generated/sklearn.decomposition.PCA.html

https://scikit-learn.org/stable/modules/generated/sklearn.decomposition.NMF.html

https://scikit-learn.org/stable/modules/cross_validation.html



Assignment

Objective: Spectral reconstruction of samples from the Munsell dataset

Goodness of fit coefficient

$$GFC = \frac{|\sum_{\lambda} r(\lambda)\hat{r}(\lambda)|}{\sqrt{\sum_{\lambda} |r(\lambda)|^2} \sqrt{\sum_{\lambda} |\hat{r}(\lambda)|^2}}$$