

ensemble projection

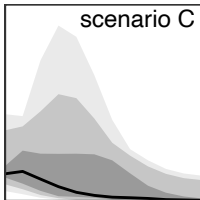
scenario A



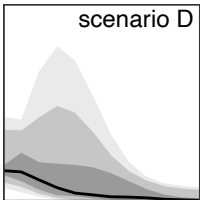
scenario B



scenario C



scenario D



projection horizon