



Key		
→ Data/Message flow	File on disk	Directory mounted to Docker container from RPi path ~/.config/helix
-----> Data transferred on file read or trigger	ROS2 timer	Arrow tip: timer start/stop Line out: timeout callback
ROS2 nodes	Also like this	Grouping of default nodes/topics created by ros2_control
ROS2 topics Message type	Arrow tip: broadcasting to the topic Line out: to subscriber	An instance of the HelixKinematicPCCModel class defined in the helix_models repo
ROS2 Services Message type		Grouping of the data used to execute a trajectory asynchronously using a timer
callback functions in ROS2 nodes	Arrow tip: function call/trigger Line out: broadcast to topic	