Elisha A. KOMOLAFE



Research Interests

Rehabilitation Robots, Reinforcement Learning, Robotics, Control Engineering, Brain-Computer-Interface, Machine Learning

Professional Summary

Electronic and Electrical Engineer from Obafemi Awolowo University in Ile-Ife, Nigeria with experience in reinforcement learning for robotics. Contributed to the development of the first Rehabilitation robot designed for Sub-Saharan Africa. Interested in the intersection of machine learning and robot design for rehabilitation, biosignal processing and instrumentation, reinforcement learning, and control engineering

EDUCATION

Obafemi Awolowo University (O.A.U.), Ile-Ife, Nigeria

2016 - 2022

Bsc. Electronic and Electrical Engineering. — GPA 3.96/5.00

Relevant Coursework: Control Systems Engineering I & II, Introduction to Modern Control, Intelligent Control and Instrumentation Engineering.

o Dissertation Topic: "Design and development of a small scale bilateral rehabilitation robot for stroke rehabilitation and a low-cost force-torque sensor". Supervised by Dr. K.P. Ayodele

Neurological Association of South Africa, EEG Online

May 2020 - Nov 2020

Diploma in Clinical Electroencephalography (EEG)

Relevant Coursework: Principles of Electroencephalography, Application of Encephalography in Clinical Practice

Neuromatch Academy – Computational Neuroscience Course

July 2020

Online Summer School

Neuromatch Academy – Deep Learning Course

July 2022

Online Summer School

IBRO-SIMONS Computational Neuroscience Imbizo

Aug 2022 – Sep 2022

Cape Town, South Africa

RESEARCH EXPERIENCE

Biosignal Processing, Instrumentation and Control Lab

2017-Present

Undergraduate Research Assistant to Dr. K.P. Ayodele

- Control scheme for a remote weather station. Completed the initial design of the timing diagram and flowchart for the wireless weather station.
- Robotic hand orthosis for rehabilitation. Assisted with the testing and usability testing of a 3D printed hand orthosis.
- Design and development of laboratory boards for electronic labs. Created a resistor board for the EEE 291 laboratory practicals.
- Assembly of Signal Generators for electronics lab Assembled a signal generator kit that can produce different signal types for electronics labs.
- **Autofocusing microscope.** Created a motor system to control the focusing knobs of a microscope for autofocusing on a sample.
- Subtractive Manufacturing with a CO2 laser cutter. Operated and supervised the operation of the Laser cutter.

Gilead Biomedical Engineering

Research Assistant

Projects:

- o Applications of Reinforcement Learning for Robotic control in a virtual environment. Implemented Reinforcement learning methods to train robots in the virtual environment on a task.
- Repair of a faulty wheelchair car lift Collaborated with other student interns to repair a faulty Hamar Al600 car lift.
- o Data collection from a load cell using I2C, Hx711 amplifier and Labview DAQ board. Co-produced a data-acquisition system to collect data from a loadcell to LabVIEW using I2C protocol.

Applied Artificial Intelligence and Robotics Research Lab

2019- Present

Research Assistant

• Rehabilitation robots

Assisted during the development of the PULSR robotic rehabilitation platform

 Bilateral rehabilitation robots review Completed a Literature review on upper-limb rehabilitation robots for an updated state of the art review.

Summer school project

July 2020

Neuromatch Academy Computational Neuroscience Course

Title: Decoding of the Visual Cortex using Kay-Gallant Dataset. To decode seen images from brain activation data using edge detection and machine learning techniques.

Summer school project

July 2020

Neuromatch Academy Deep Learning Course

Title: Multi Agent Reinforcement Learning in Gambling and the effect on Group fMRI readings. To utilize reinforcement learning to create a multi-agent simulation from single-person brain activation data.

Summer school project

Aug 2022 – Sep 2022

IBRO-SIMONS Computational Neuroscience Imbizo

- o Mini project: "Exploring generic decoding of seen objects using visual features." To explore if linear regression decode objects from the brain activity in different regions.
- o Project: "Learning to walk in a simulation." Implementing Reinforcement learning methods in training a bipedal agent to walk

Conferences

Nigerian Federation For Neurorehabilitation, Sub-Saharan Regional Conference 2018

Theme: Neurorehabilitation in Africa: Challenges and New Horizons

Faculty of Technology Conference 2019

2019

Theme: Diversification of Developing Economies: imperatives for sustainable environment and technological innovations.

Nigerian Society of Neurological Sciences (NSNS) Annual Scientific Conference 2022

Theme: Multidisciplinary Care and Collaboration in the Neurological sciences

PUBLICATIONS

A review on the structure and control techniques used in bilateral rehabilitation robots for stroke rehabilitation. (In Preparation)

Presentations

Ayodele, K.P., Komolafe, M.A., Olugbon, F.J., Komolafe, E.A. (2019). A Myoelectric Robotic Orthosis For Hand Neuro-rehabilitation of Stroke Patients in resource-poor settings. Oral presentation at NFNR 2018.

Sep 2019 – Jan 2020

Professional Societies and Activities

WFNR (World Federation of Neurorehabilitation Young WFNR Member ICORR (International Consortium for Rehabilitation Robotics) Member Aug 2022— Present Member

WORK EXPERIENCE

Faculty of Technology Conference OAUTekConf2019

Sep 2019

Assistant Technician

- Performed projection for abstract presentation sessions and Implemented teleconferencing for remote participants.
- Teamed up with the technical team to deliver audio-visual support during the conference.

Teaching Assistant

Nov - Dec, 2021

Marked and Graded Laboratory reports of ~200 year II engineering students for EEE 291. EEE 291 – Fundamentals of Electronic and Electrical Engineering Laboratory I

SOFTWARE, PROGRAMMING, LANGUAGES AND CERTIFICATES

Software LATEX, Rhino 3D, Matlab, Corel Draw, k40D, Diagrams.Net, V-REP

Programming Languages Python, C

Languages English, Yoruba

Certificates Cisco IT Essentials, CCNA Routing and Switching: Introduction to Networks