

view_frames Result

Recorded at time: 2132.695

map

Broadcaster: /amcl
Average rate: 40.441 Hz
Most recent transform: 2132.720 (-0.025 sec old)
Buffer length: 2.176 sec

odom

Broadcaster: /gazebo
Average rate: 10.476 Hz
Most recent transform: 2132.631 (0.064 sec old)
Buffer length: 2.100 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2132.695 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2132.695 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2132.695 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.486 Hz
Most recent transform: 2132.651 (0.044 sec old)
Buffer length: 2.098 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.486 Hz
Most recent transform: 2132.651 (0.044 sec old)
Buffer length: 2.098 sec

right_wheel