

## **Backpropagation in Neural Network**

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**Backpropagation** (short for "**Backward Propagation of Errors**") is a method used to train artificial neural networks. Its goal is to reduce the difference between the model's predicted output and the actual output by adjusting the weights and biases in the network.

In this article, we will explore what backpropagation is, why it is crucial in machine learning, and how it works.

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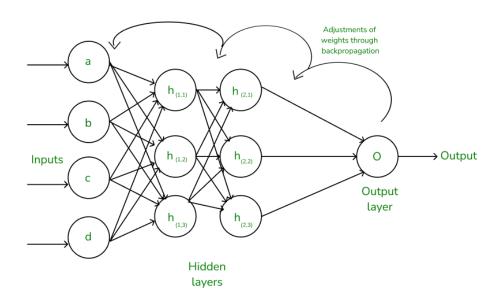
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A <u>neural network</u> is a structured system composed of computing units called neurons, which enable it to compute functions. These neurons are interconnected through edges and assigned an <u>activation function</u>, along with adjustable parameters. These parameters allow the neural network to compute specific functions. Regarding activation functions, higher activation values indicate greater neuron activation in the network.

## What is Backpropagation?

**Backpropagation** is a powerful algorithm in deep learning, primarily used to train artificial neural networks, particularly <u>feed-forward networks</u>. It works iteratively, minimizing the cost function by adjusting weights and biases.

In each epoch, the model adapts these parameters, reducing loss by following the error gradient. Backpropagation often utilizes optimization algorithms like gradient descent or stochastic gradient descent. The algorithm computes the gradient using the chain rule from calculus, allowing it to effectively navigate complex layers in the neural network to minimize the cost function.



fig(a) A simple illustration of how the backpropagation works by adjustments of weights

## Why is Backpropagation Important?

Backpropagation plays a critical role in how neural networks improve over time. Here's why:

- 1. **Efficient Weight Update**: It computes the gradient of the loss function with respect to each weight using the chain rule, making it possible to update weights efficiently.
- 2. **Scalability**: The backpropagation algorithm scales well to networks with multiple layers and complex architectures, making deep learning feasible.

3. **Automated Learning**: With backpropagation, the learning process becomes automated, and the model can adjust itself to optimize its performance.

## Working of Backpropagation Algorithm

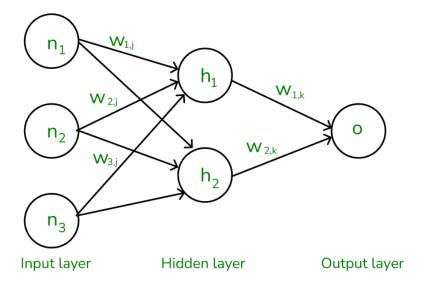
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## How Does the Forward Pass Work?

In the **forward pass**, the input data is fed into the input layer. These inputs, combined with their respective weights, are passed to hidden layers.

For example, in a network with two hidden layers (h1 and h2 as shown in Fig. (a)), the output from h1 serves as the input to h2. Before applying an activation function, a bias is added to the weighted inputs.

Each hidden layer applies an activation function like <u>ReLU (Rectified Linear Unit)</u>, which returns the input if it's positive and zero otherwise. This adds non-linearity, allowing the model to learn complex relationships in the data. Finally, the outputs from the last hidden layer are passed to the output layer, where an activation function, such as <u>softmax</u>, converts the weighted outputs into probabilities for classification.



## How Does the Backward Pass Work?

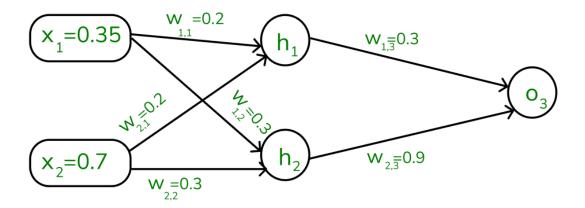
In the backward pass, the error (the difference between the predicted and actual output) is propagated back through the network to adjust the weights and biases. One common method for error calculation is the <u>Mean Squared Error (MSE)</u>, given by:

 $MSE = (Predicted Output - Actual Output)^2$ 

Once the error is calculated, the network adjusts weights using **gradients**, which are computed with the chain rule. These gradients indicate how much each weight and bias should be adjusted to minimize the error in the next iteration. The backward pass continues layer by layer, ensuring that the network learns and improves its performance. The activation function, through its derivative, plays a crucial role in computing these gradients during backpropagation.

## **Example of Backpropagation in Machine Learning**

Let's walk through an example of backpropagation in machine learning. Assume the neurons use the sigmoid activation function for the forward and backward pass. The target output is 0.5, and the learning rate is 1.



Example (1) of backpropagation sum

Here's how backpropagation is implemented:

## **Forward Propagation**

## 1. Initial Calculation

The weighted sum at each node is calculated using:

$$a_j = \sum (w_i, j * x_i)$$

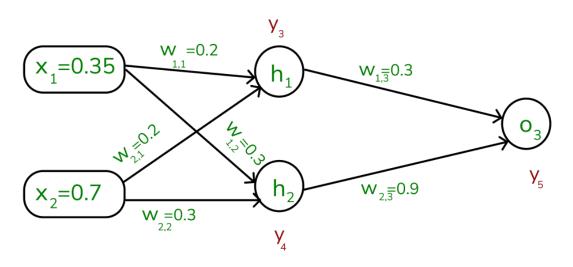
Where.

- $a_j$  is the weighted sum of all the inputs and weights at each node,
- $w_{i,j}$  represents the weights associated with the  $j^{th}$  input to the  $i^{th}$  neuron,
- $x_i$  represents the value of the  $j^{th}$  input,

## 2. Sigmoid Function

The sigmoid function returns a value between 0 and 1, introducing non-linearity into the model.

$$y_j=rac{1}{1+e^{-a_j}}$$



To find the outputs of y3, y4 and y5

## 3. Computing Outputs

At h1 node,

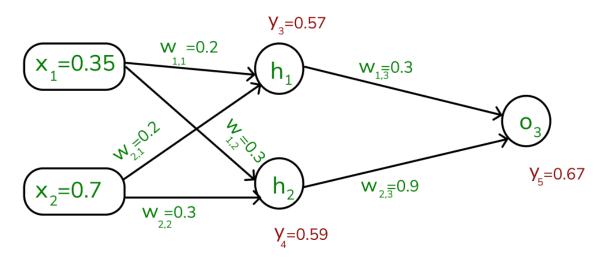
$$a_1 = (w_{1,1}x_1) + (w_{2,1}x_2)$$
  
=  $(0.2 * 0.35) + (0.2 * 0.7)$   
=  $0.21$ 

Once, we calculated the  $a_1$  value, we can now proceed to find the  $y_3$  value:

$$y_j = F(a_j) = rac{1}{1+e^{-a_1}}$$
  $y_3 = F(0.21) = rac{1}{1+e^{-0.21}}$   $y_3 = 0.56$ 

Similarly find the values of  $y_4$  at  $h_2$  and  $y_5$  at  $O_3$ .

$$a_2 = (w_{1,2} * x_1) + (w_{2,2} * x_2) = (0.3 * 0.35) + (0.3 * 0.7) = 0.315$$
  $y_4 = F(0.315) = \frac{1}{1 + e^{-0.315}}$   $a_3 = (w_{1,3} * y_3) + (w_{2,3} * y_4) = (0.3 * 0.57) + (0.9 * 0.59) = 0.702$   $y_5 = F(0.702) = \frac{1}{1 + e^{-0.702}} = 0.67$ 



Values of y3, y4 and y5

## 4. Error Calculation

Note that, our actual output is 0.5 but we obtained 0.67.

To calculate the error, we can use the below formula:

$$Error_j = y_{target} - y_5$$

$$Error = 0.5 - 0.67 = -0.17$$

Using this error value, we will be backpropagating.

## **Backpropagation**

## 1. Calculating Gradients

The change in each weight is calculated as:

$$\Delta w_{ij} = \eta imes \delta_j imes O_j$$

Where:

- $\delta_j$  is the error term for each unit,
- $\eta$  is the learning rate.

## 2. Output Unit Error

For O3:

$$\delta_5 = y_5(1 - y_5)(y_{target} - y_5)$$

$$= 0.67(1 - 0.67)(-0.17) = -0.0376$$

## 3. Hidden Unit Error

For h1:

$$egin{aligned} \delta_3 &= y_3 (1-y_3) (w_{1,3} imes \delta_5) \ &= 0.56 (1-0.56) (0.3 imes -0.0376) = -0.0027 \end{aligned}$$

For h2:

$$egin{aligned} \delta_4 &= y_4 (1-y_4) (w_{2,3} imes \delta_5) \ &= 0.59 (1-0.59) (0.9 imes -0.0376) = -0.0819 \end{aligned}$$

## 4. Weight Updates

For the weights from hidden to output layer:

$$\Delta w_{2,3} = 1 imes (-0.0376) imes 0.59 = -0.022184$$

New weight:

$$w_{2,3}({\sf new}) = -0.22184 + 0.9 = 0.67816$$

For weights from input to hidden layer:

$$\Delta w_{1,1} = 1 imes (-0.0027) imes 0.35 = 0.000945$$

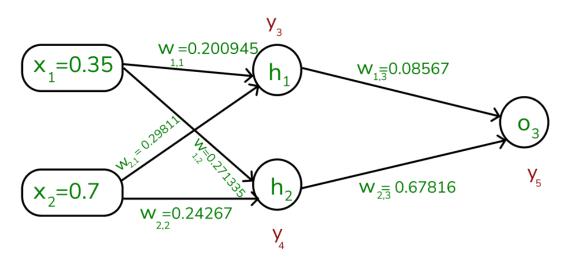
New weight:

$$w_{1.1}(\text{new}) = 0.000945 + 0.2 = 0.200945$$

Similarly, other weights are updated:

- $w_{1,2}(\text{new}) = 0.271335$
- $w_{1,3}(\text{new}) = 0.08567$
- $w_{2,1}(\text{new}) = 0.29811$
- $w_{2,2}(\text{new}) = 0.24267$

The updated weights are illustrated below,



Through backward pass the weights are updated

## Final Forward Pass:

After updating the weights, the forward pass is repeated, yielding:

- $y_3 = 0.57$
- $y_4 = 0.56$
- $y_5 = 0.61$

Since  $y_5 = 0.61$  is still not the target output, the process of calculating the error and backpropagating continues until the desired output is reached.

This process demonstrates how backpropagation iteratively updates weights by minimizing errors until the network accurately predicts the output.

$$Error = y_{target} - y_5$$
  
=  $0.5 - 0.61 = -0.11$ 

This process is said to be continued until the actual output is gained by the neural network.

# Backpropagation Implementation in Python for XOR Problem

This code demonstrates how backpropagation is used in a neural network to solve the XOR problem. The neural network consists of:

- Input layer with 2 inputs,
- Hidden layer with 4 neurons,
- Output layer with 1 output neuron.

## Key steps:

- 1. **Forward pass:** The inputs are passed through the network, activating the hidden and output layers using the sigmoid function.
- 2. **Backward pass (Backpropagation):** The errors between the predicted and actual outputs are computed. The gradients are calculated using the derivative of the sigmoid function, and weights and biases are updated accordingly.
- 3. **Training:** The network is trained over 10,000 epochs using the backpropagation algorithm with a learning rate of 0.1, progressively reducing the error.

This implementation highlights how backpropagation adjusts weights and biases to minimize the loss and improve predictions over time.

```
import numpy as np

class NeuralNetwork:
    def __init__(self, input_size, hidden_size, output_size):
        self.input_size = input_size
        self.hidden_size = hidden_size
        self.output_size = output_size
```

```
# Initialize weights
        self.weights_input_hidden = np.random.randn(self.input_size,
self.hidden_size)
        self.weights hidden output =
np.random.randn(self.hidden size, self.output size)
        # Initialize the biases
        self.bias hidden = np.zeros((1, self.hidden size))
        self.bias output = np.zeros((1, self.output size))
    def sigmoid(self, x):
        return 1 / (1 + np.exp(-x))
    def sigmoid derivative(self, x):
        return x * (1 - x)
    def feedforward(self, X):
        # Input to hidden
        self.hidden_activation = np.dot(X, self.weights_input_hidden)
+ self.bias hidden
        self.hidden_output = self.sigmoid(self.hidden_activation)
        # Hidden to output
        self.output_activation = np.dot(self.hidden_output,
self.weights_hidden_output) + self.bias_output
        self.predicted output = self.sigmoid(self.output activation)
        return self.predicted_output
    def backward(self, X, y, learning_rate):
        # Compute the output layer error
        output_error = y - self.predicted_output
        output delta = output error *
self.sigmoid derivative(self.predicted output)
        # Compute the hidden Layer error
        hidden error = np.dot(output delta,
self.weights_hidden_output.T)
        hidden delta = hidden error *
self.sigmoid derivative(self.hidden output)
        # Update weights and biases
        self.weights hidden output += np.dot(self.hidden output.T,
output delta) * learning rate
        self.bias_output += np.sum(output_delta, axis=0,
keepdims=True) * learning_rate
        self.weights input hidden += np.dot(X.T, hidden delta) *
learning rate
        self.bias_hidden += np.sum(hidden_delta, axis=0,
keepdims=True) * learning_rate
    def train(self, X, y, epochs, learning_rate):
        for epoch in range(epochs):
            output = self.feedforward(X)
            self.backward(X, y, learning rate)
```

## Output:

```
Epoch 0, Loss:0.26804276270586413

Epoch 4000, Loss:0.012477301332301533

Epoch 8000, Loss:0.0029801470220045504

Predictions after training:

[[0.02330965]
    [0.95658721]
    [0.95049451]
    [0.05896647]]
```

# Advantages of Backpropagation for Neural Network Training

The key benefits of using the backpropagation algorithm are:

- Ease of Implementation: Backpropagation is beginner-friendly, requiring no prior neural network knowledge, and simplifies programming by adjusting weights via error derivatives.
- **Simplicity and Flexibility:** Its straightforward design suits a range of tasks, from basic feedforward to complex convolutional or recurrent networks.
- **Efficiency:** Backpropagation accelerates learning by directly updating weights based on error, especially in deep networks.

- **Generalization:** It helps models generalize well to new data, improving prediction accuracy on unseen examples.
- Scalability: The algorithm scales efficiently with larger datasets and more complex networks, making it ideal for large-scale tasks.

## Challenges with Backpropagation

While backpropagation is powerful, it does face some challenges:

- 1. Vanishing Gradient Problem: In deep networks, the gradients can become very small during backpropagation, making it difficult for the network to learn. This is common when using activation functions like sigmoid or tanh.
- 2. **Exploding Gradients**: The gradients can also become excessively large, causing the network to diverge during training.
- 3. **Overfitting**: If the network is too complex, it might memorize the training data instead of learning general patterns.

## Conclusion

Backpropagation is the engine that drives neural network learning. By propagating errors backward and adjusting the weights and biases, neural networks can gradually improve their predictions. Though it has some limitations like vanishing gradients, many techniques, such as using ReLU activation or optimizing learning rates, have been developed to address these issues.

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