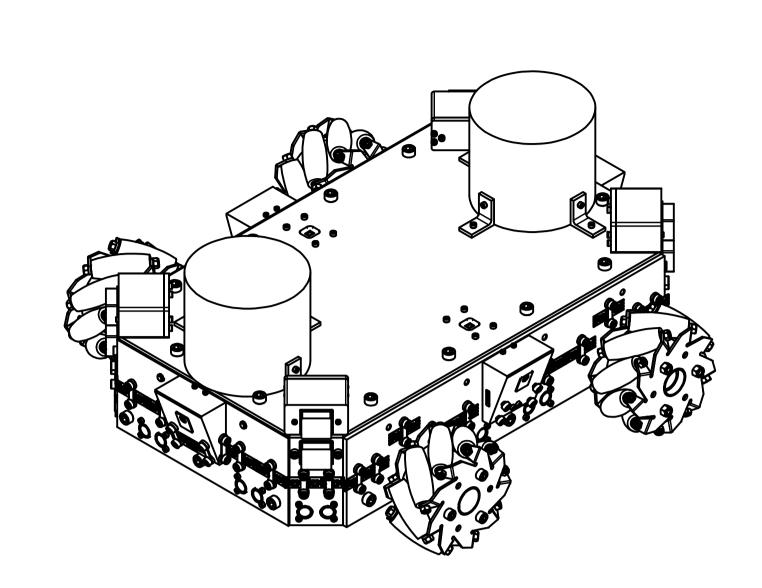
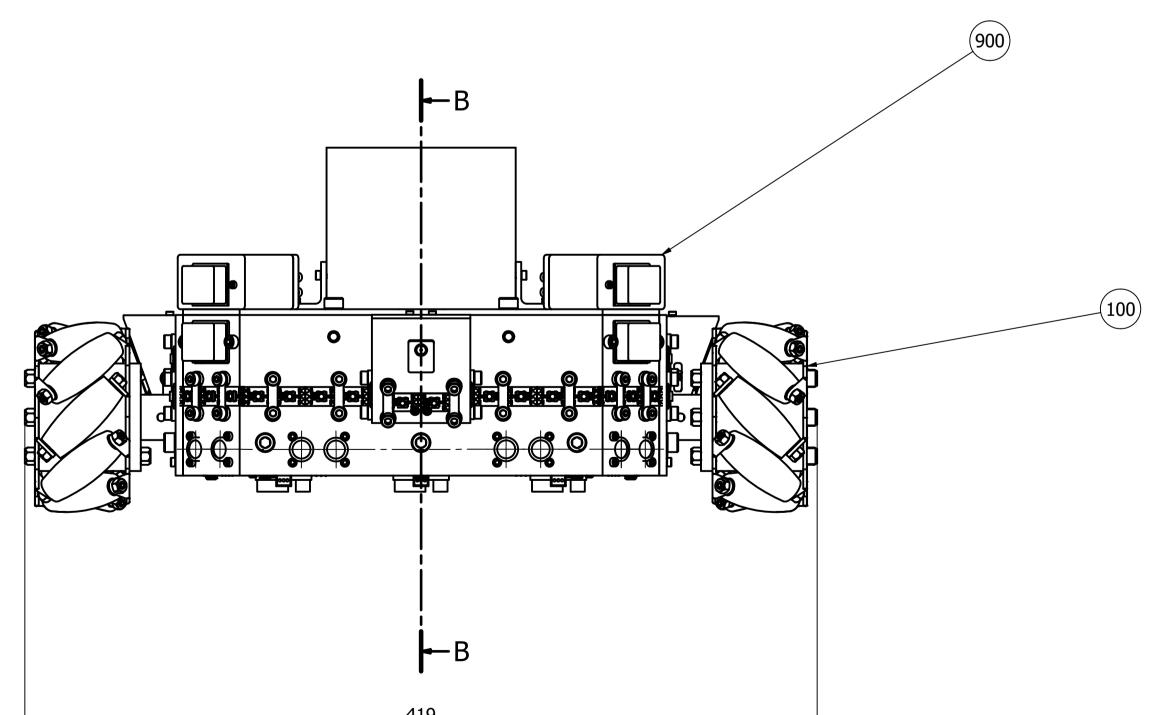
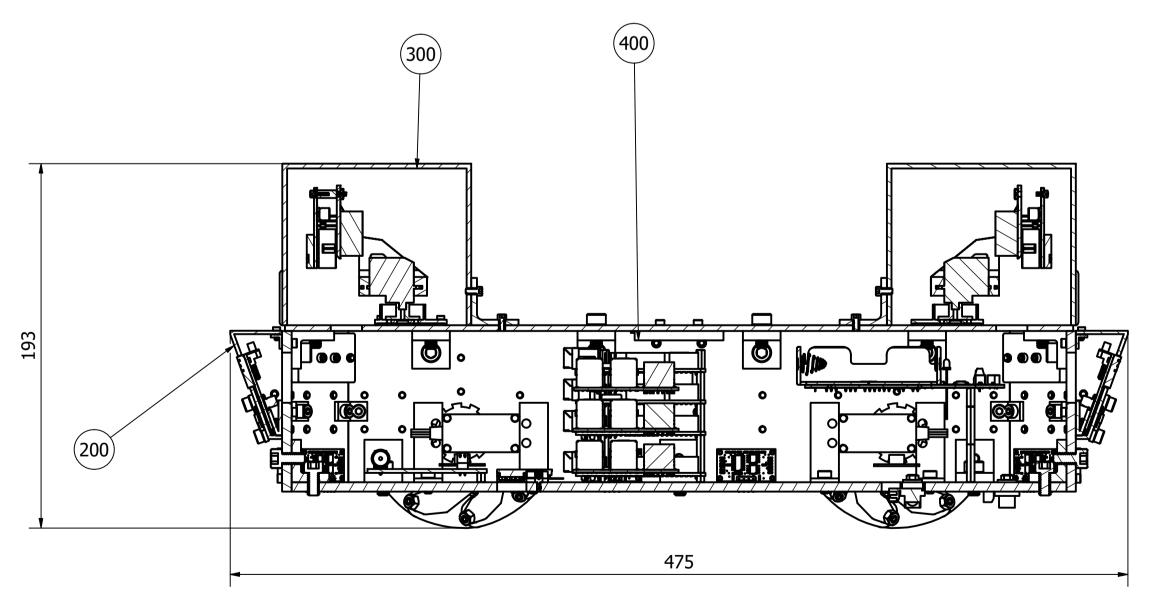


MASTER PARTS LIST								
Sub Assembly Parts List	Description							
100	Mecanum Wheel and Servo Motor Assembly							
200	Navigation Camera and Tilted Box Assembly							
300	Positional Camera and Protective Box Assembly							
400	Microphone and Top Plate Assembly							
500	Raspberry Pi Stack Assembly							
600	Arduino Stack Assembly							
700	Radiation Board, Humidity Sensor, Optical Sensor and Bottom Plate Assembly							
800	Power PCB							
900	Contact Plate Assembly							
1000	Robot Frame, Connectors, Ultrasonic Sensors and LED Strip Assembly							







B-B (1:2)

Isometric View is at 1:3 Scale

Top View does not feature Top Plate, Back Contact Plates and Back Camera box for visibility

_	Top view does not reacure top trace, back contact traces and back carriera box for visibility													
L		NLESS OTHERWISE	STATED: LINEA	$R 0 dp \pm 0.25$	mm; $1dp \pm$	0.1mm;	$2dp \pm 0.05$	mm ANG	GULAR:	± 0.5°	<sup>9</sup> (30')			
Α	LL DIMS. IN MM	Contact Details:	Remove all sharp	Designed by	Checked by	Approved by	Date		Date		PROJECT			
	SCALE: 1 : 3	EA485	edges. Ro. 0,8 unless stated	EA	EA		23/05/2020	A1	23/05/	′202 <b>q</b> ∂	GBDP-CERN			
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	THIRD ANGLE PROJECTION	IN WHOLE OR IN PART NOR DIS PARTY WITHOUT PRIOR PERMIS	CLOSED TO ANY THIRD	Engineering	BA	ИH	PART No	0		Edition 00	Sheet 1 / 1			