Jared Coleman

https://www.jaredraycoleman.com

Summary

I have a broad interest in computer science. My research interests include blockchain, mobile robotics, discrete mathematics, computational geometry, game theory, graph theory, and distributed computing.

EDUCATION

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University of Southern California Ph.D. in Computer Science; GPA: 4.0	Los Angeles, CA Aug 2020 – Present
California State University, Long Beach Master of Science in Computer Science; GPA: 4.0	Long Beach, CA Aug 2018 – May 2020
California State University, Long Beach Bachelor of Science in Computer Science; GPA: 3.6	Long Beach, CA Aug 2013 – May 2018
Experience	

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The Aerospace Corporation	El Segundo, CA
Casual Member of the Technical Staff	Aug~2020-Present
Member of the Technical Staff	$Mar\ 2020-Aug\ 2020$
Associate Member of the Technical Staff	$Sep \ 2018 - Mar \ 2020$
Intern	$Jan\ 2018-Aug\ 2018$

- Develops algorithms for optimizing data-processing pipelines to maximize time and resource efficiency.
- Helps build simulations for verifying flight software.
- Designs software that helps Aerospace rapidly develop scalable, modular, and efficient analyses for launch vehicle verification in simulation, day-of-launch, and post-flight environments.

CSULB Research Foundation

Long Beach, CA Mar 2017 - May 2018

jaredraycoleman@gmail.com

Student Research Assistant

- Developed software and simulations for systems of cooperative robots.

PUBLICATIONS

Robotic Sorting on the Grid

Jared Coleman, Oscar Morales-Ponce

To Appear at ICDCN 2022 - 23rd International Conference on Distributed Computing and Networking

Message Delivery in the Plane by Robots with Different Speeds

Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Danny Krizanc

To Appear at SSS 2021 - 23rd International Symposium on Stabilization, Safety, and Security of Distributed Systems

The Pony Express Communication Problem

Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Danny Krizanc

In Proceedings IWOCA 2021 - 32nd International Workshop on Combinatorial Algorithms

Minimizing The Maximum Distance Traveled To Form Patterns With Systems of Mobile Robots

In proceedings CCCG 2020, 32nd Canadian Conference on Computational Geometry, August 5-7, 2020 Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Jorge Urrutia, Birgit Vogtenhuber

Projects

Kubishi (https://kubishi.com)

2020 - Present

An online dictionary and encyclopedia for Owens Valley Paiute language and culture

Aerocube @ The Beach

2017

Distributed Robotics Systems for Space - A Proof of Concept