

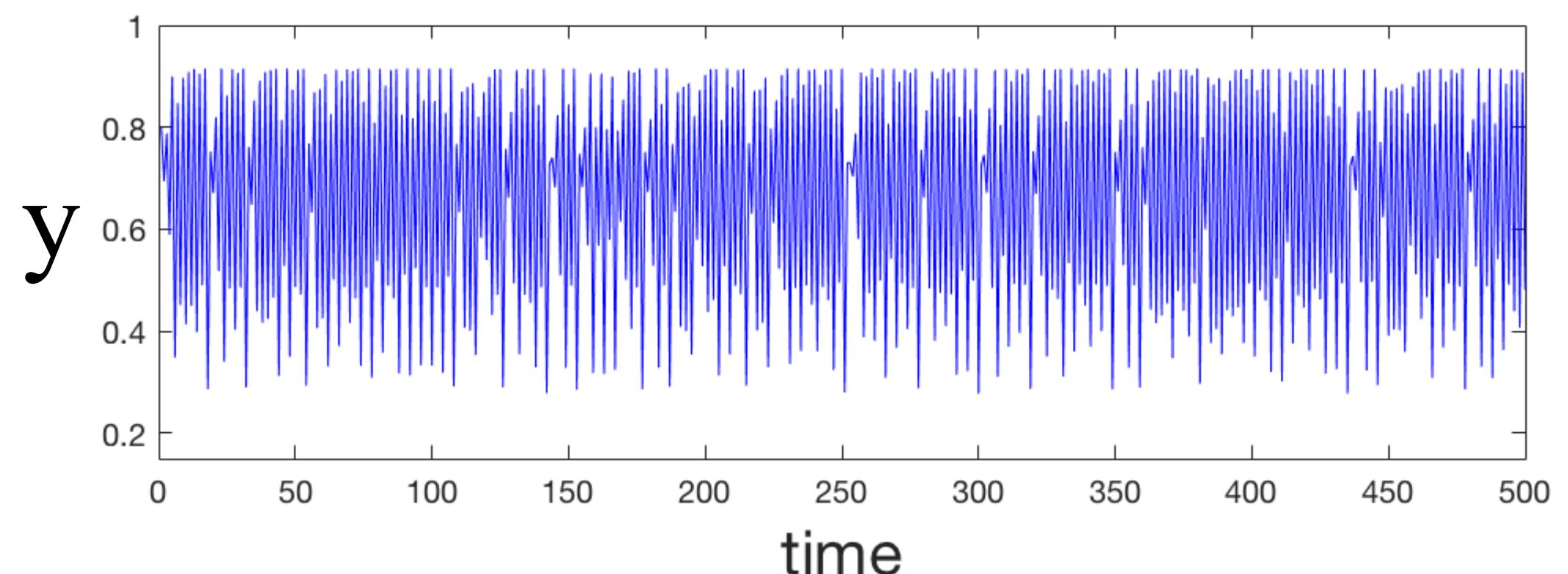
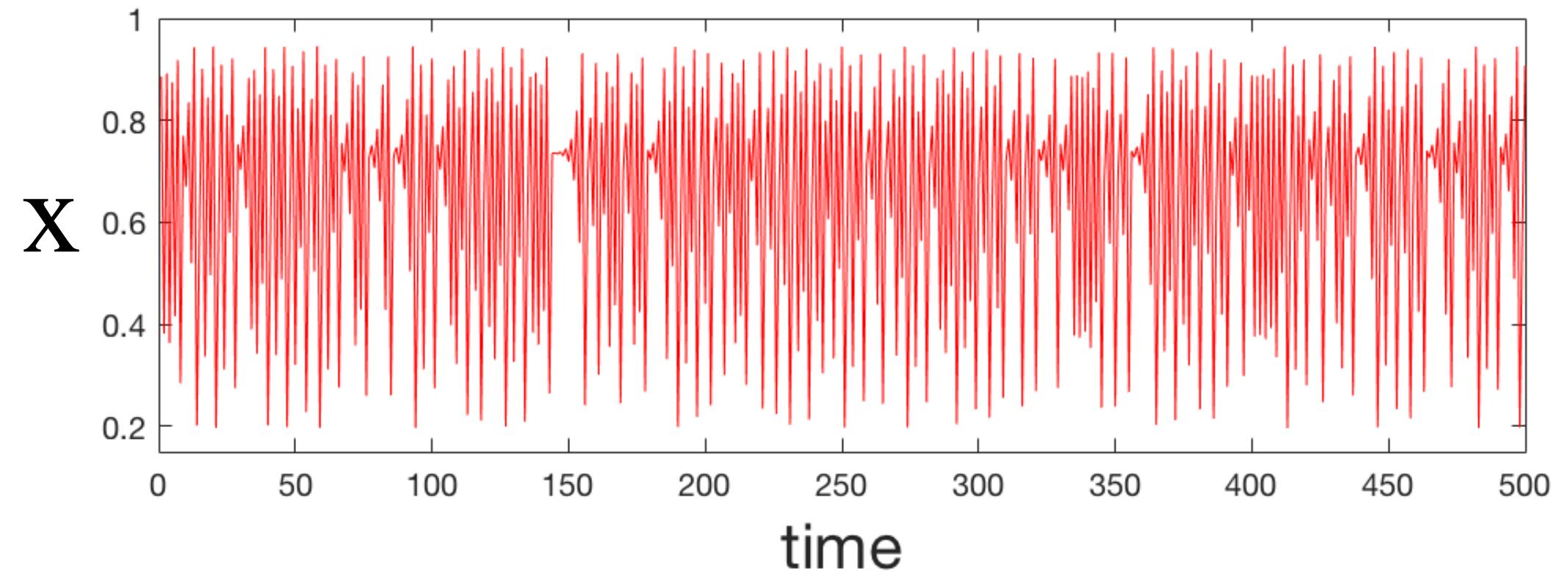
A new method for quantifying Earth system interactions from time series

David Diego
Department of Earth Science, UiB

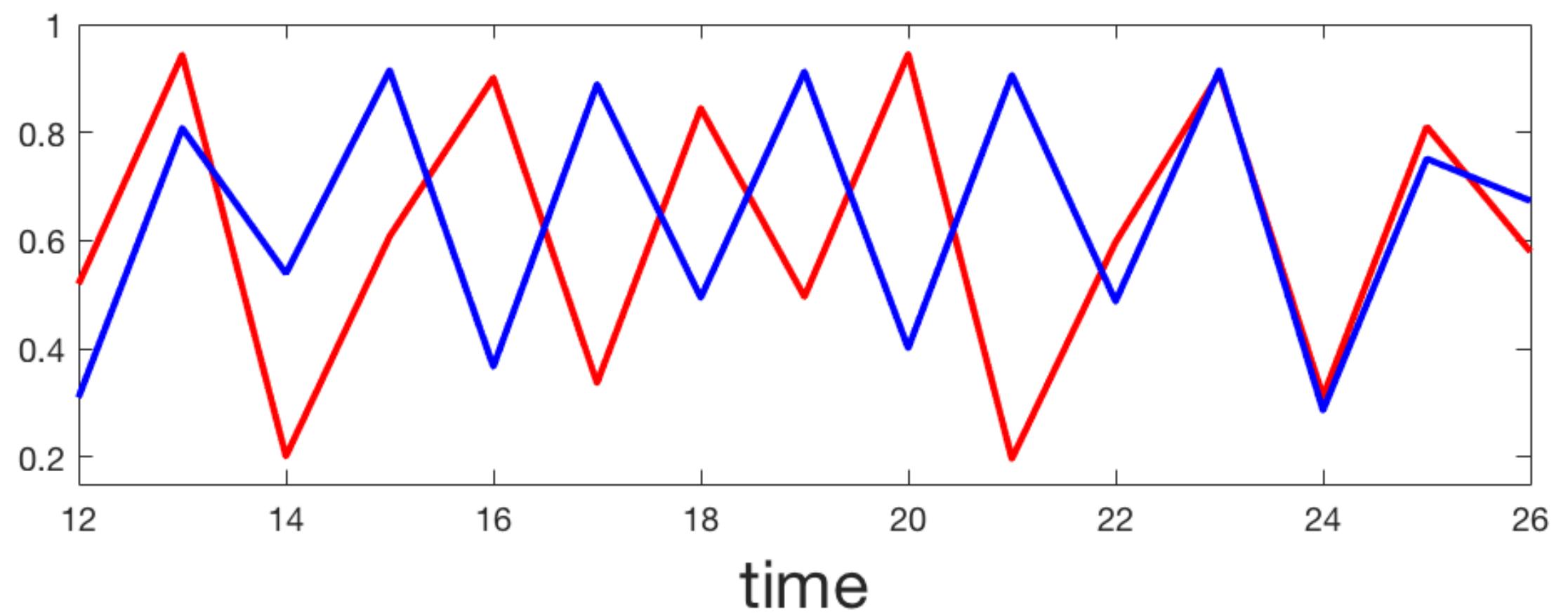
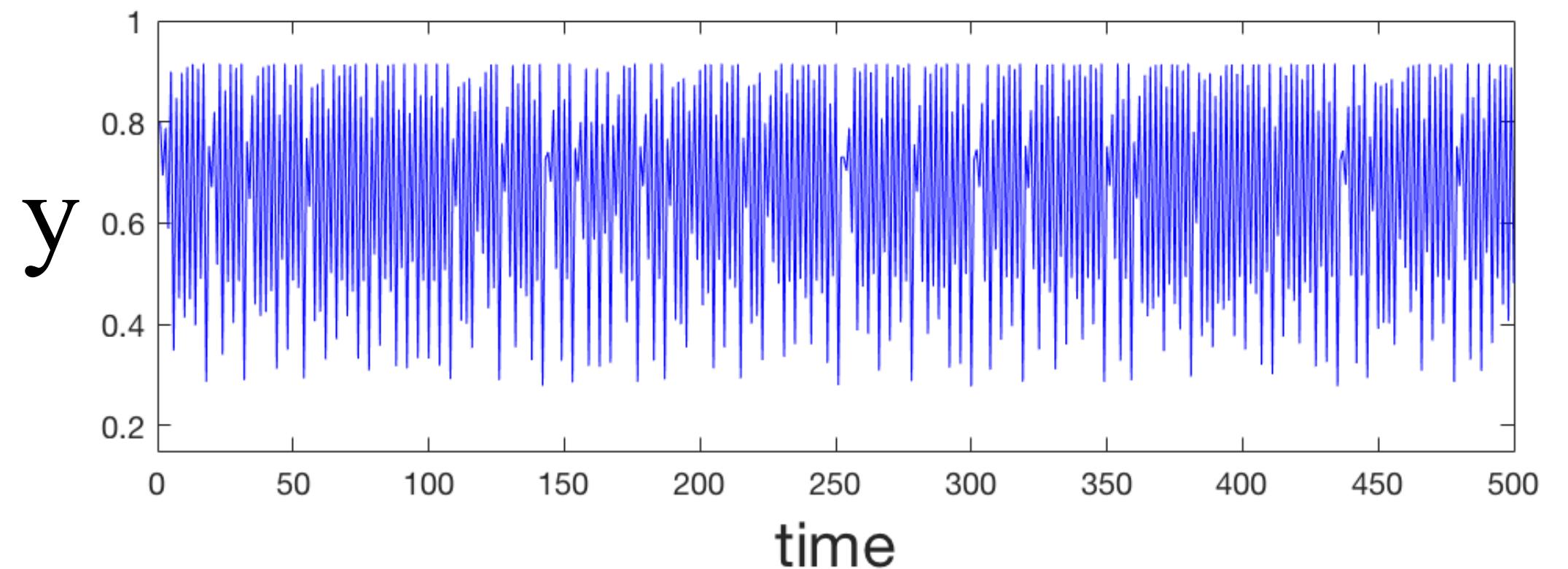
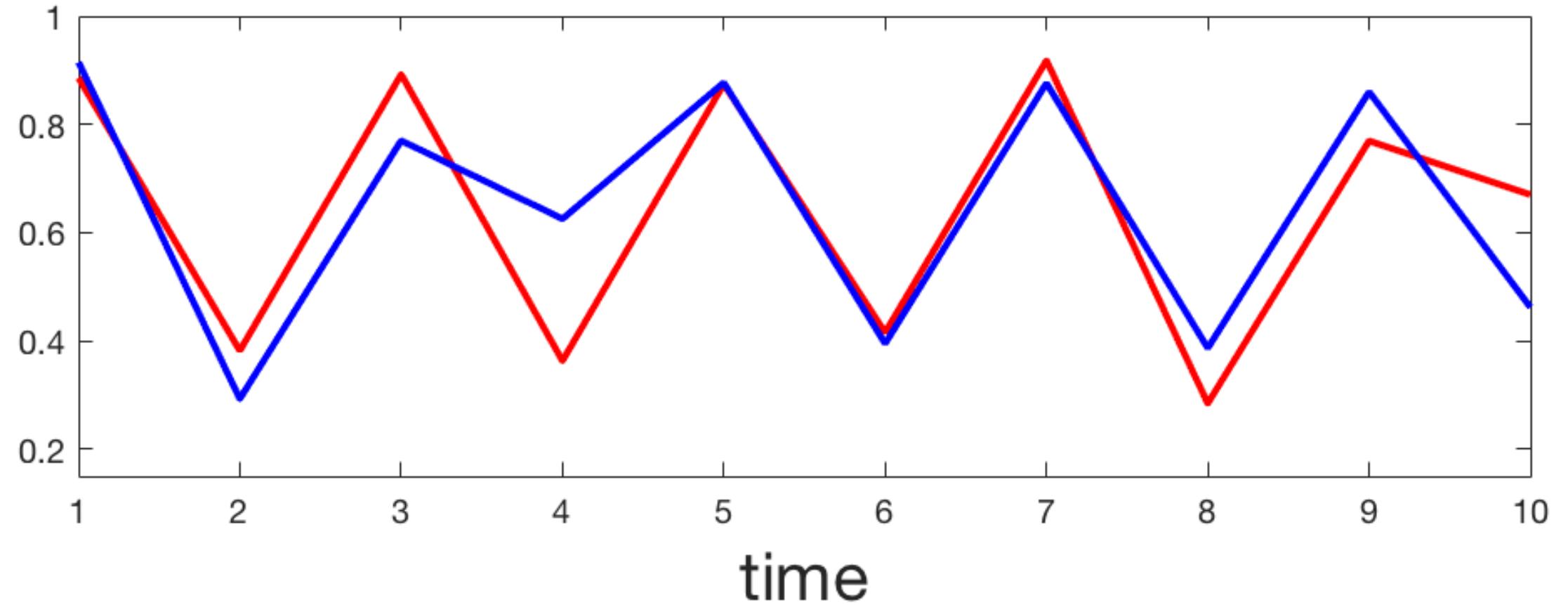
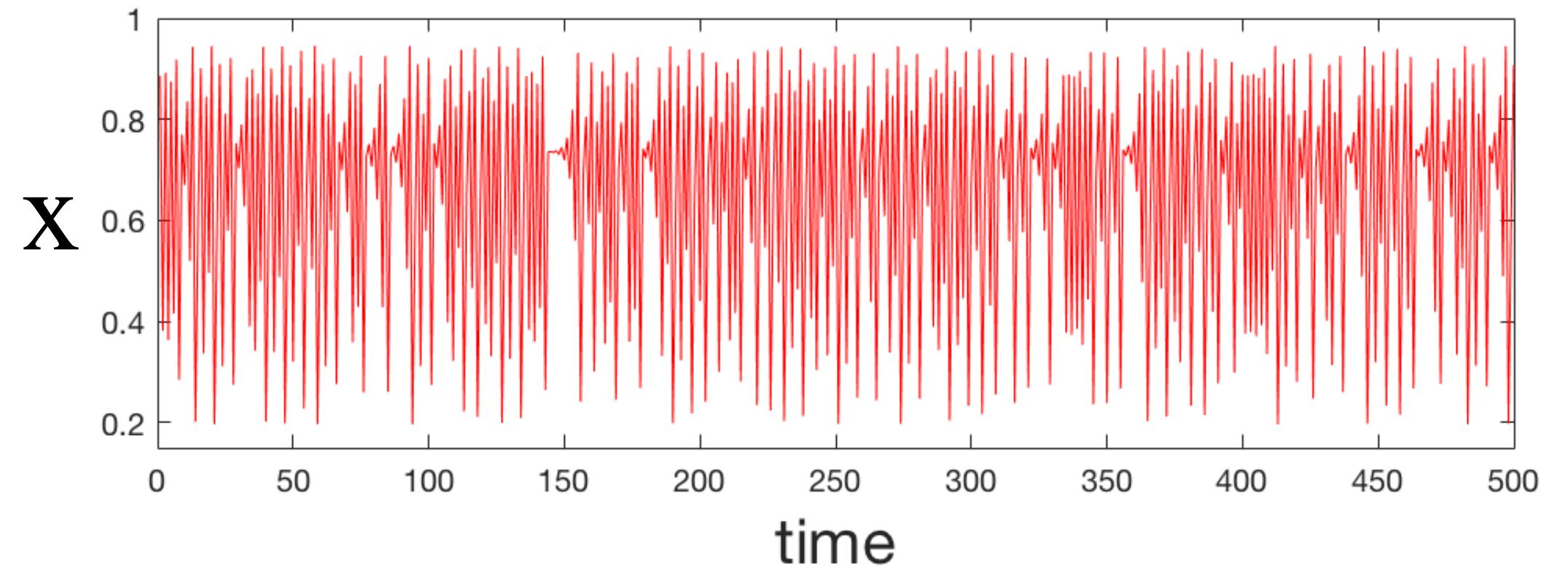
Transfer entropy computation using the Perron-Frobenius
operator
D. Diego, K.A. Haaga and B. Hannisdal

DOI: 10.1103/PhysRevE.99.042212

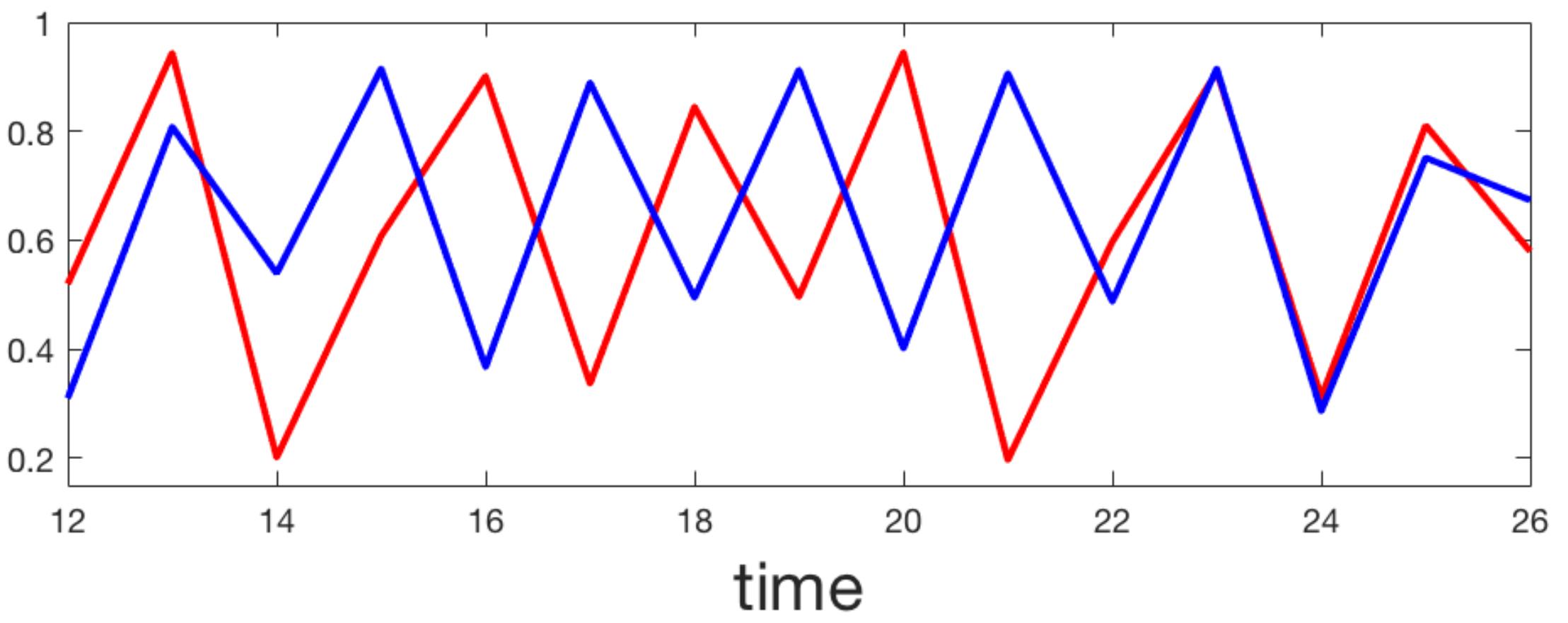
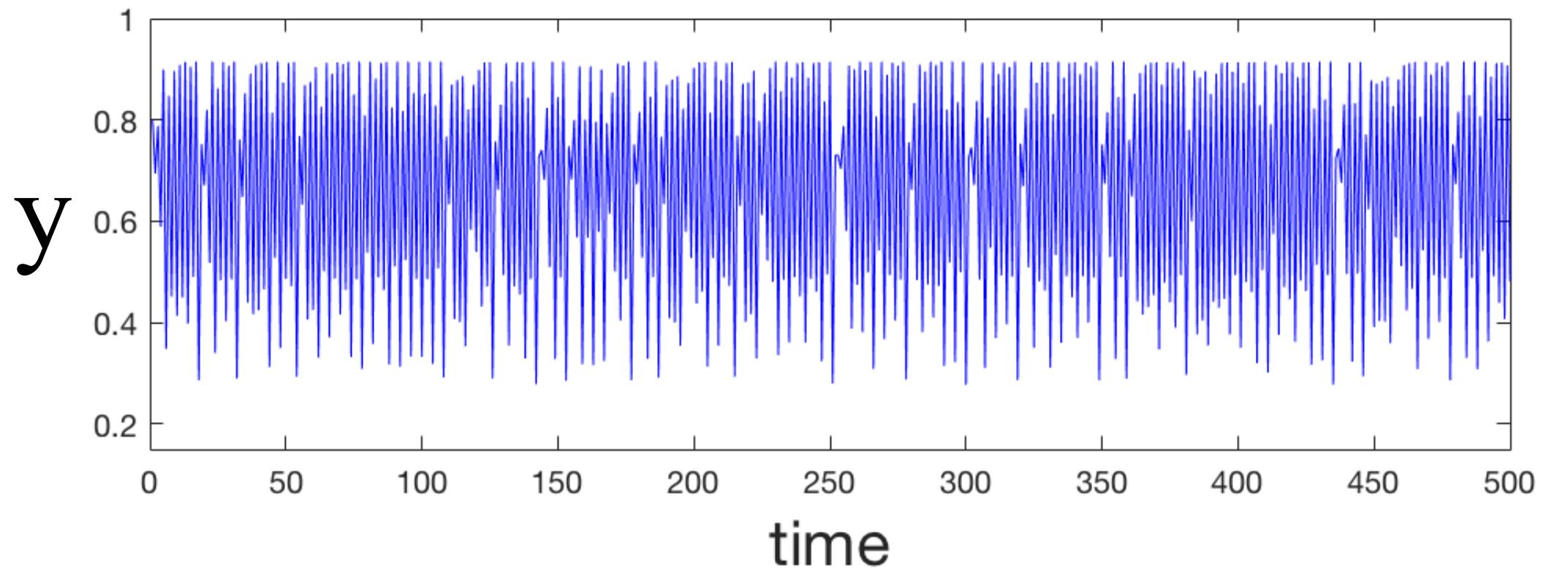
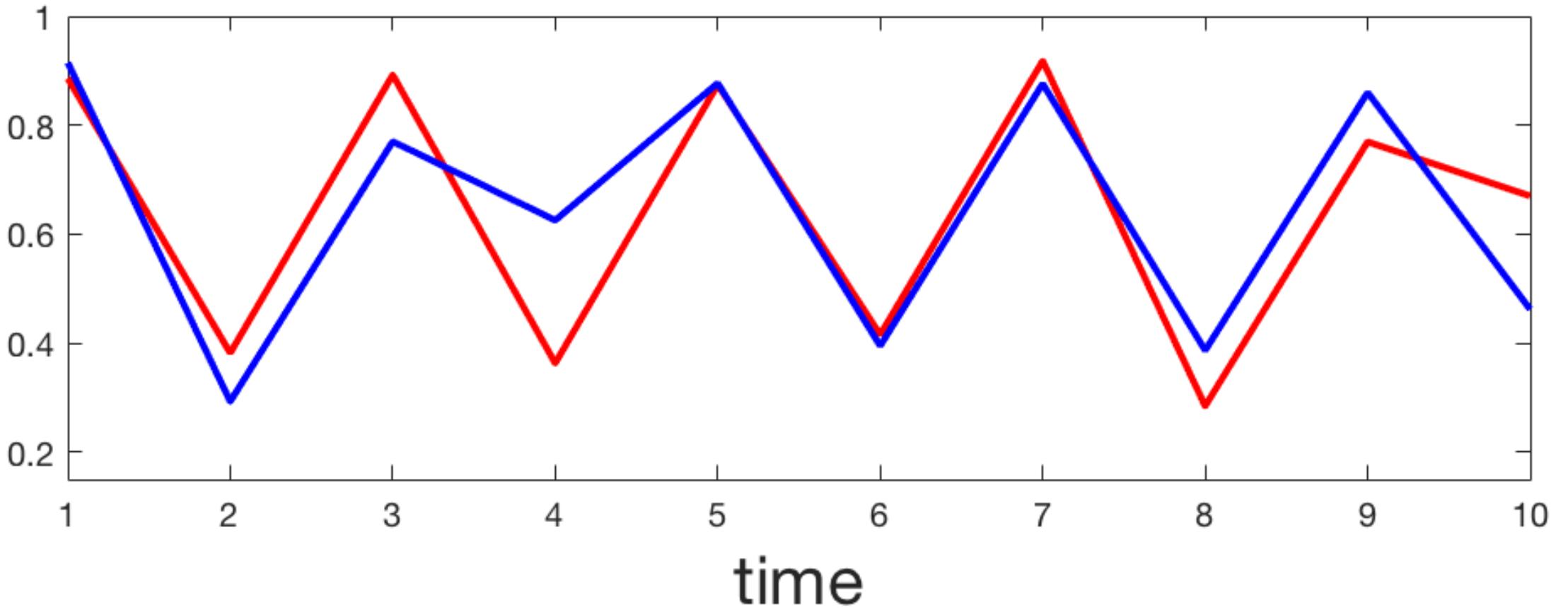
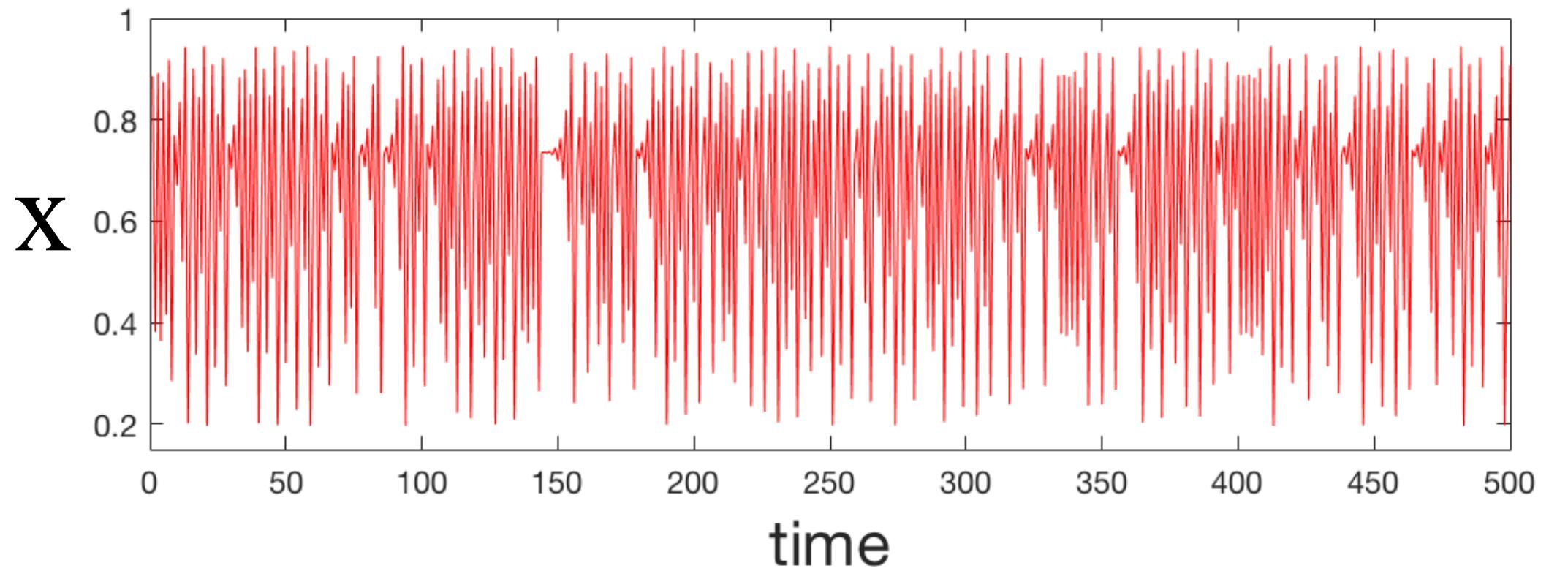
CORRELATION vs CAUSATION



CORRELATION vs CAUSATION



CORRELATION vs CAUSATION



$$x_{n+1} = r_1 x_n (1 - x_n)$$

$$y_{n+1} = r_2 f(x_n, y_n) (1 - f(x_n, y_n))$$

$$f(x, y) = \frac{y + c x}{1 + c}$$

INFORMATION (beyond correlation)

Given two time series of data ... (almost) any data ...

$$X = \{x_1, x_2, \dots, x_n\}$$

$$Y = \{y_1, y_2, \dots, y_n\}$$

We want to quantify (estimate) how much information about Y
is contained in X and vice versa.

A standard tool is the **transfer entropy (TE)**

T. Schreiber (2000), Physical Review Letters 85, 461

Conditional probabilities and transfer entropy

Given two variables, A and B, the conditional probability for having an outcome for A given that the outcome for B is known, is defined as

$$P(a|b) = \frac{P(a, b)}{P(b)}$$

Conditional probabilities and transfer entropy

Given two variables, A and B, the conditional probability for having an outcome for A given that the outcome for B is known, is defined as

probability for obtaining a and b at the same time

$$P(a|b) = \frac{P(a, b)}{P(b)}$$

Conditional probabilities and transfer entropy

Given two variables, A and B, the conditional probability for having an outcome for A given that the outcome for B is known, is defined as

$$P(a|b) = \frac{P(a, b)}{P(b)}$$

probability for obtaining b regardless of what happens with the outcomes of A.

Conditional probabilities and transfer entropy

Given two variables, A and B, the conditional probability for having an outcome for A given that the outcome for B is known, is defined as

$$P(a|b) = \frac{P(a, b)}{P(b)}$$

$$P(b) = \sum_{a \in A} P(a, b)$$

Conditional probabilities and transfer entropy

This can be extended to three (or more) variables:

$$P(a|b, c) = \frac{P(a, b, c)}{P(b, c)}$$

Conditional probabilities and transfer entropy

$$X = \{x_1, x_2, \dots, x_n\}$$

Given two time series

$$Y = \{y_1, y_2, \dots, y_n\}$$

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Suppose one may compute the transition probabilities $P(x_{t+\tau}|x_t)$ and $P(x_{t+\tau}|x_t, y_t)$ for a fixed forward lag τ

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For some other time t' , the opposite could happen ...

$$P(x_{t'+\tau}|x_{t'}, y_{t'}) < P(x_{t'+\tau}|x_{t'})$$

Conditional probabilities and transfer entropy

A way of checking whether there is any improvement in the average is the **Transfer Entropy**

$$TE(Y \rightarrow X) = \sum_t P(x_{t+\tau}, x_t, y_t) \log_2 \frac{P(x_{t+\tau} | x_t, y_t)}{P(x_{t+\tau} | x_t)}$$

$$TE(Y \rightarrow X) \geq 0$$

$$TE(Y \rightarrow X) = 0 \text{ if and only if } P(x_{t+\tau} | x_t, y_t) = P(x_{t+\tau} | x_t) \text{ for all } t !$$

Transfer entropy comes from entropy

$$TE(Y \rightarrow X) = \sum_t P(x_{t+\tau}, x_t, y_t) \log_2 \frac{P(x_{t+\tau}|x_t, y_t)}{P(x_{t+\tau}|x_t)}$$

The entropy quantifies how much information is required to predict the outcome of a random process with probability distribution:

$$P = (p_1, \dots, p_n)$$

$$H(P) = - \sum_{i=1}^n p_i \log_2(p_i)$$

$$0 \leq H(P) \leq \log_2(n)$$

Introduced by Shannon in 1948

why the log?

$$\log_2(a \cdot b) = \log_2 a + \log_2 b$$

$$H(P_1 \cdot P_2) = H(P_1) + H(P_2)$$

Transfer entropy comes from entropy

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(silly?) examples

$$H(P) = -p_h \log_2(p_h) - p_t \log_2(p_t)$$

$$\begin{aligned} p_h &= 0.5 \\ p_t &= 0.5 \end{aligned}$$

1 bit

$$\begin{aligned} p_h &= 0.8 \\ p_t &= 0.2 \end{aligned}$$

0.72 bits

$$\begin{aligned} p_h &= 1 \\ p_t &= 0 \end{aligned}$$

0 bits

Transfer entropy (TE)

$TE(Y \rightarrow X)$ measures the relevance of the information about Y to predict the evolution of X

$TE(Y \rightarrow X)$ is taken as the flow of information from Y to X

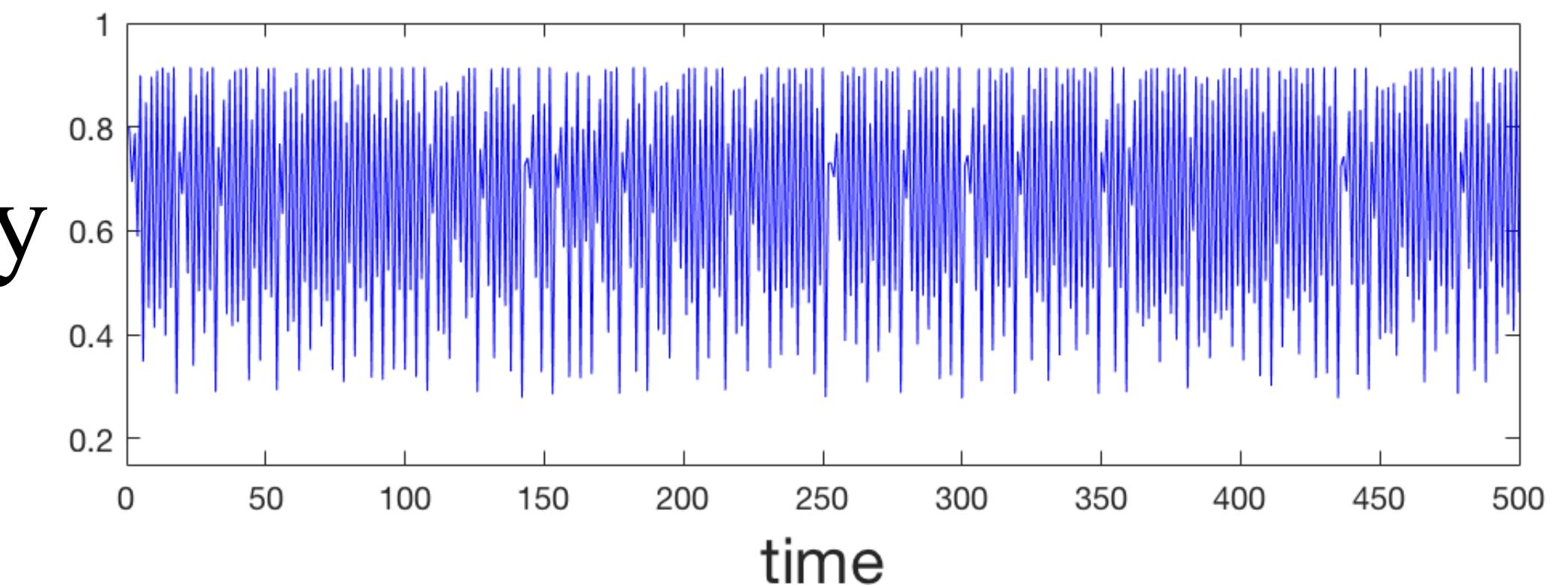
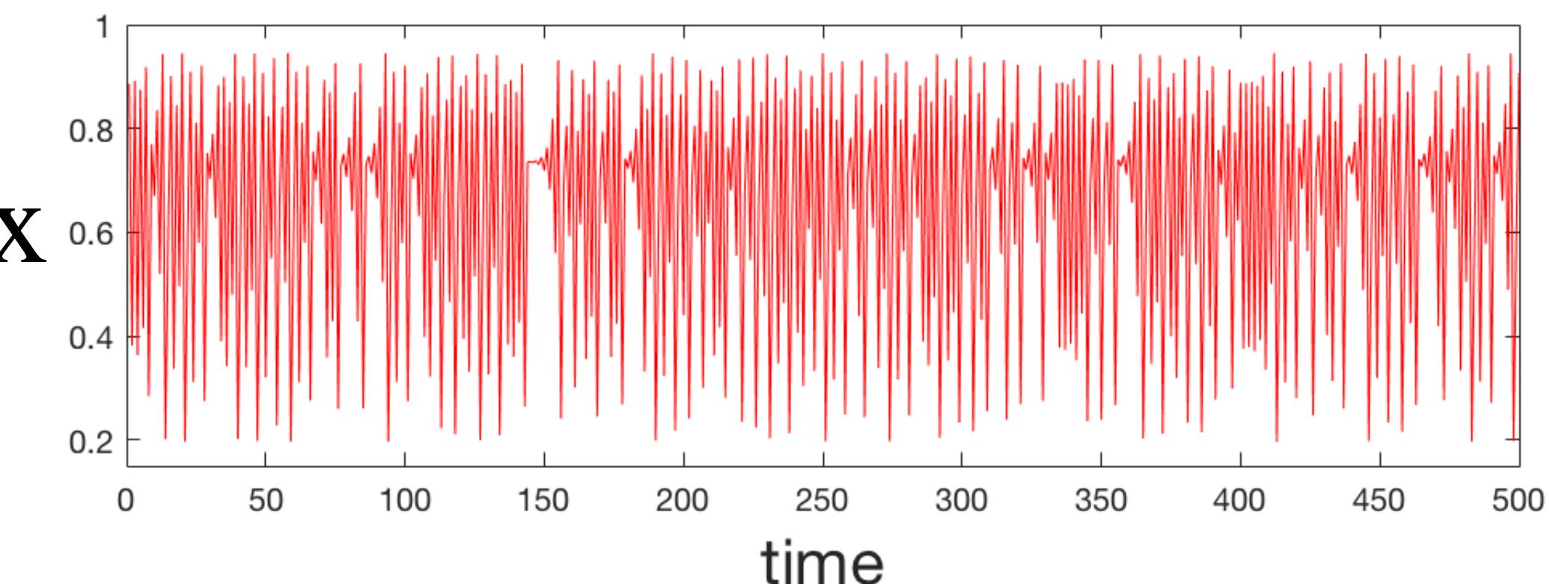
To estimate TE from Y to X we first need to get the probability distribution

$$P(x_{t+\tau}, x_t, y_t)$$

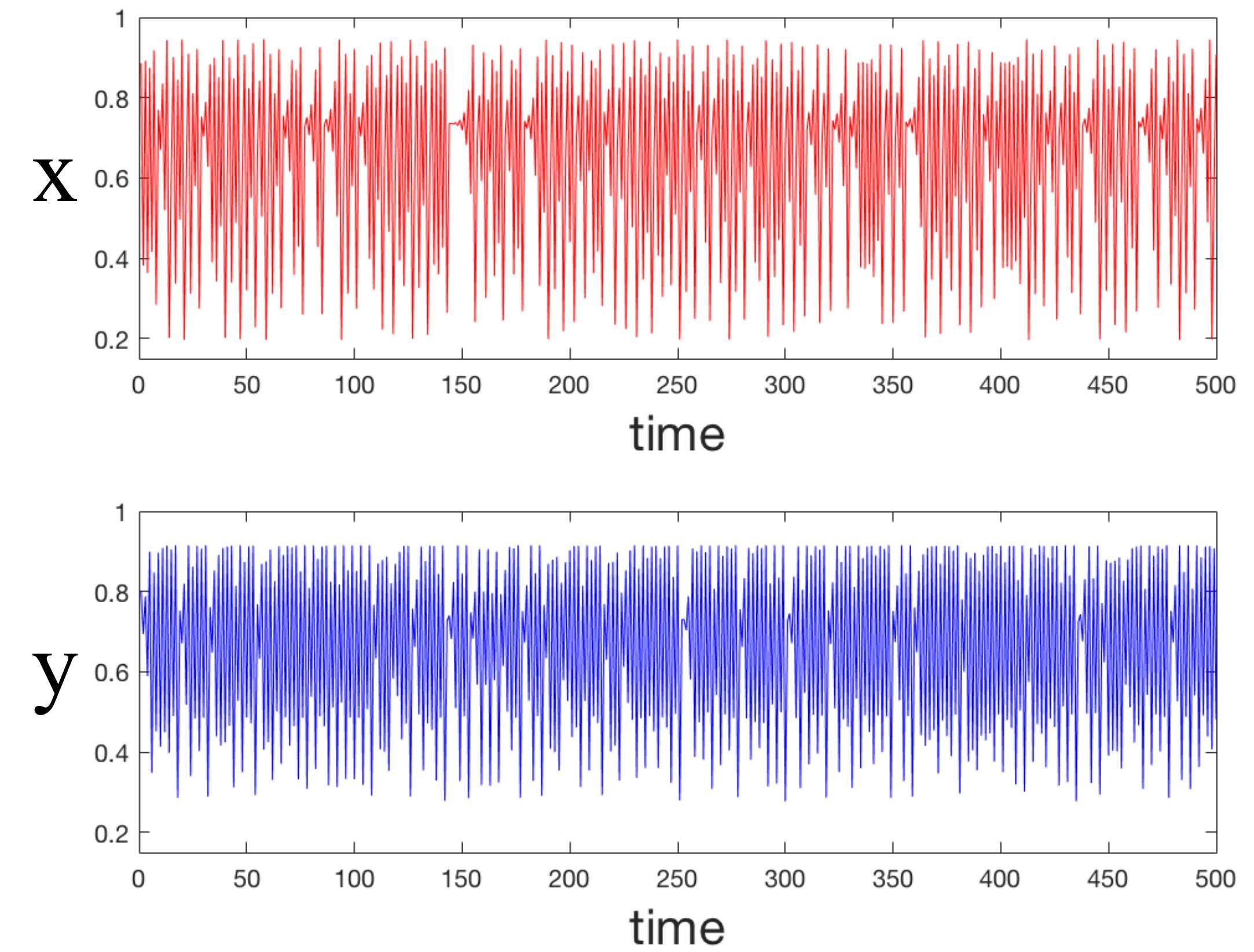
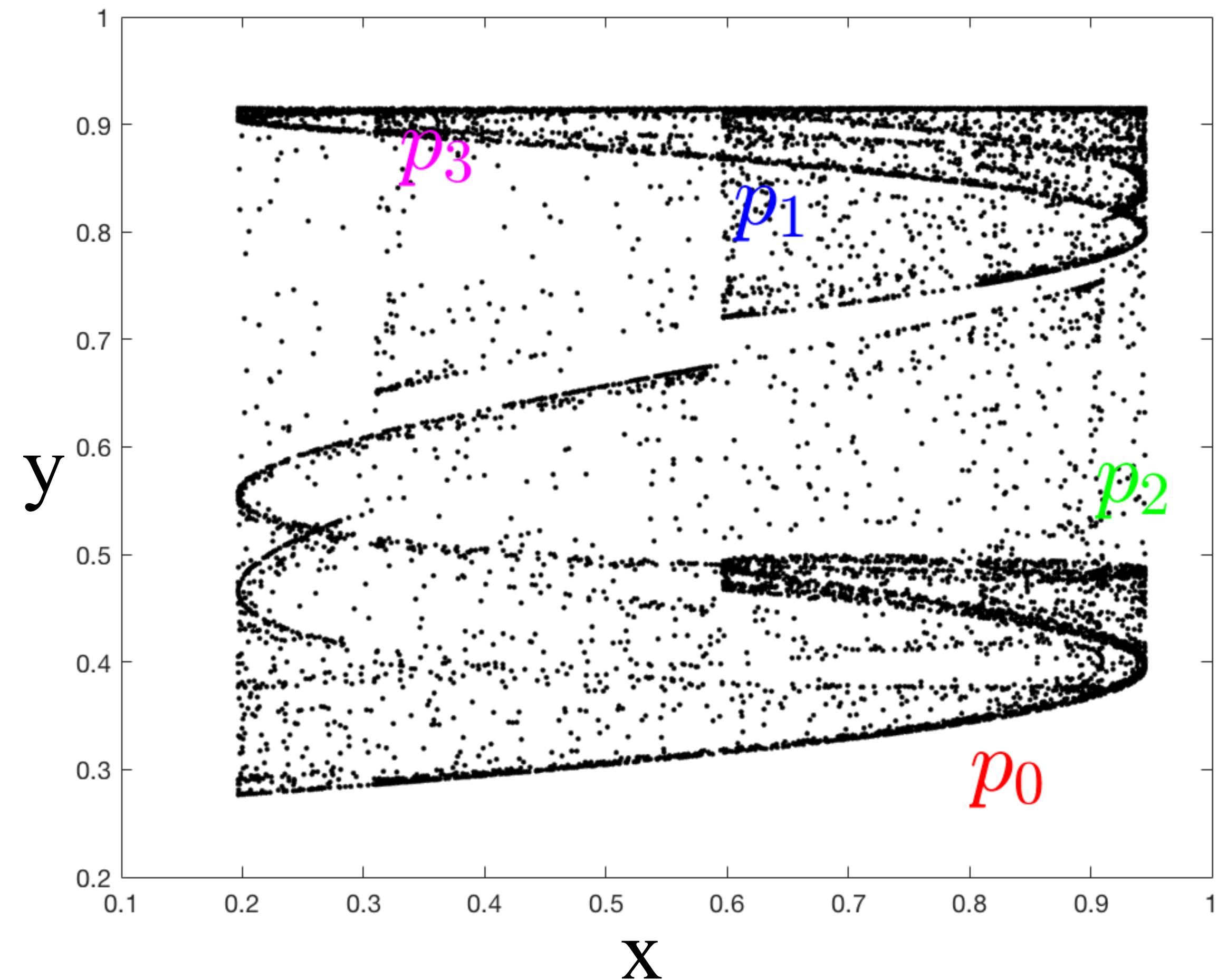
and from it, the transition probabilities $P(x_{t+\tau}|x_t)$ and $P(x_{t+\tau}|x_t, y_t)$

We use the invariant density associated to the dynamics underlying the time series X and Y (call the invariant density ρ)

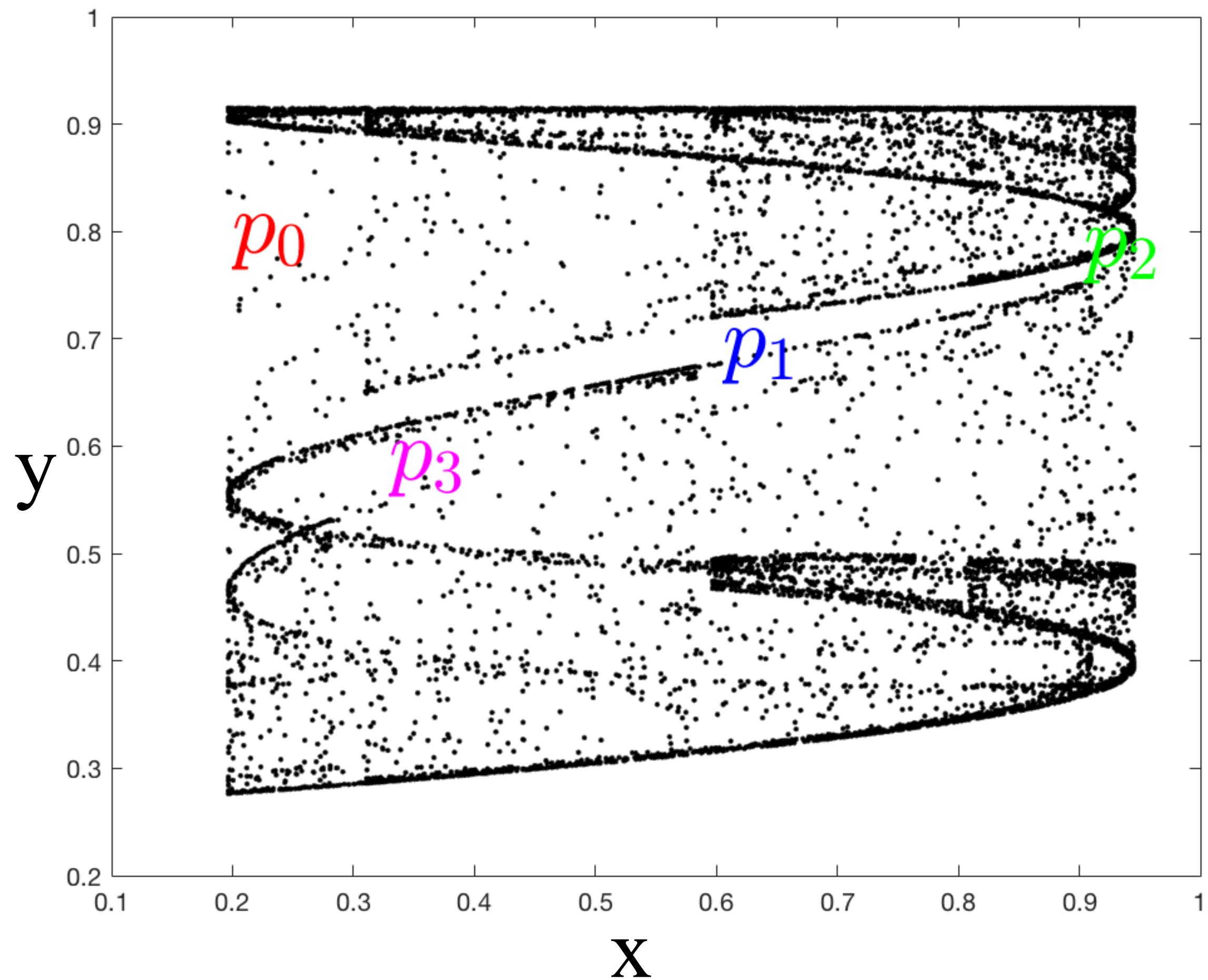
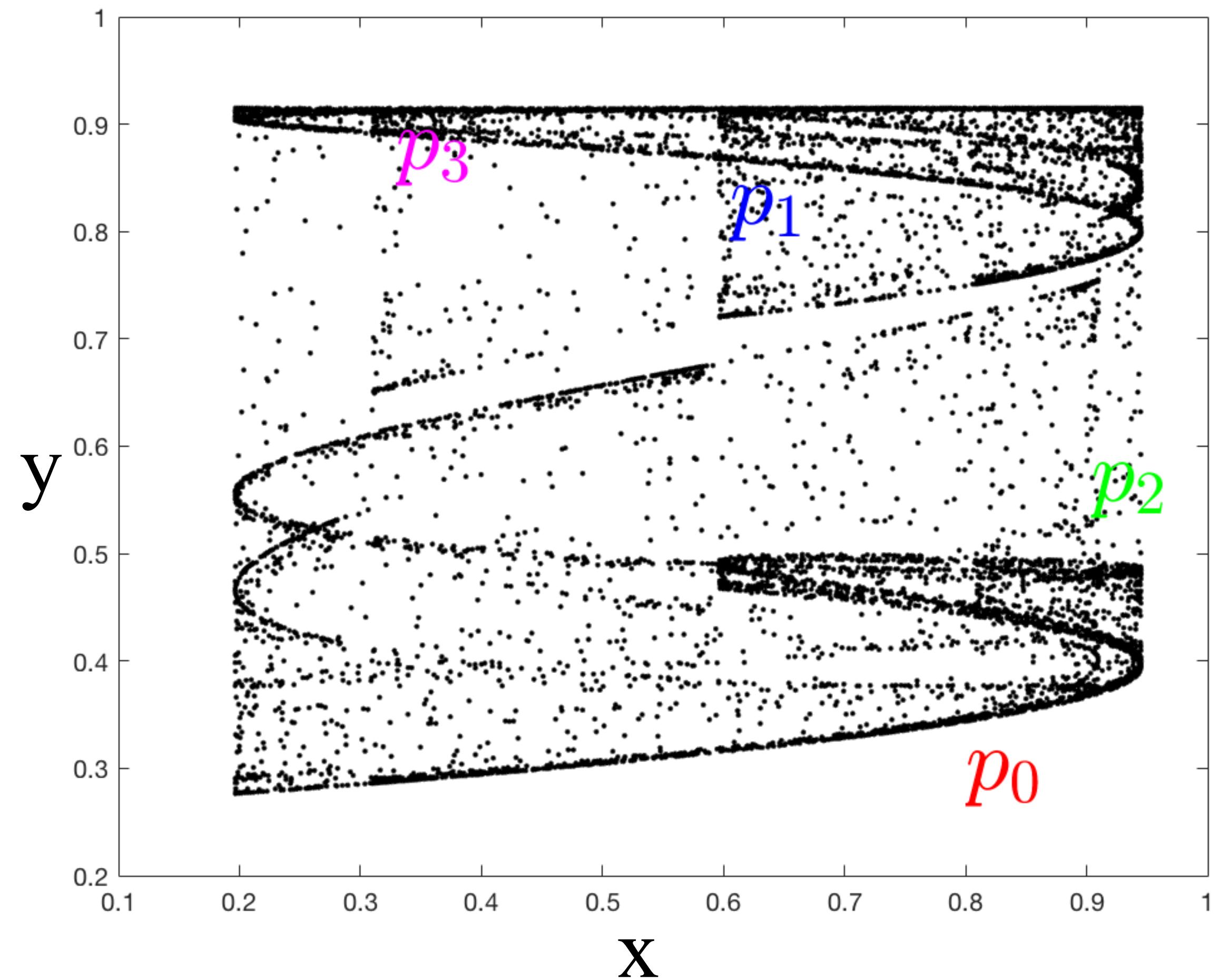
WHAT IS AN INVARIANT DENSITY?



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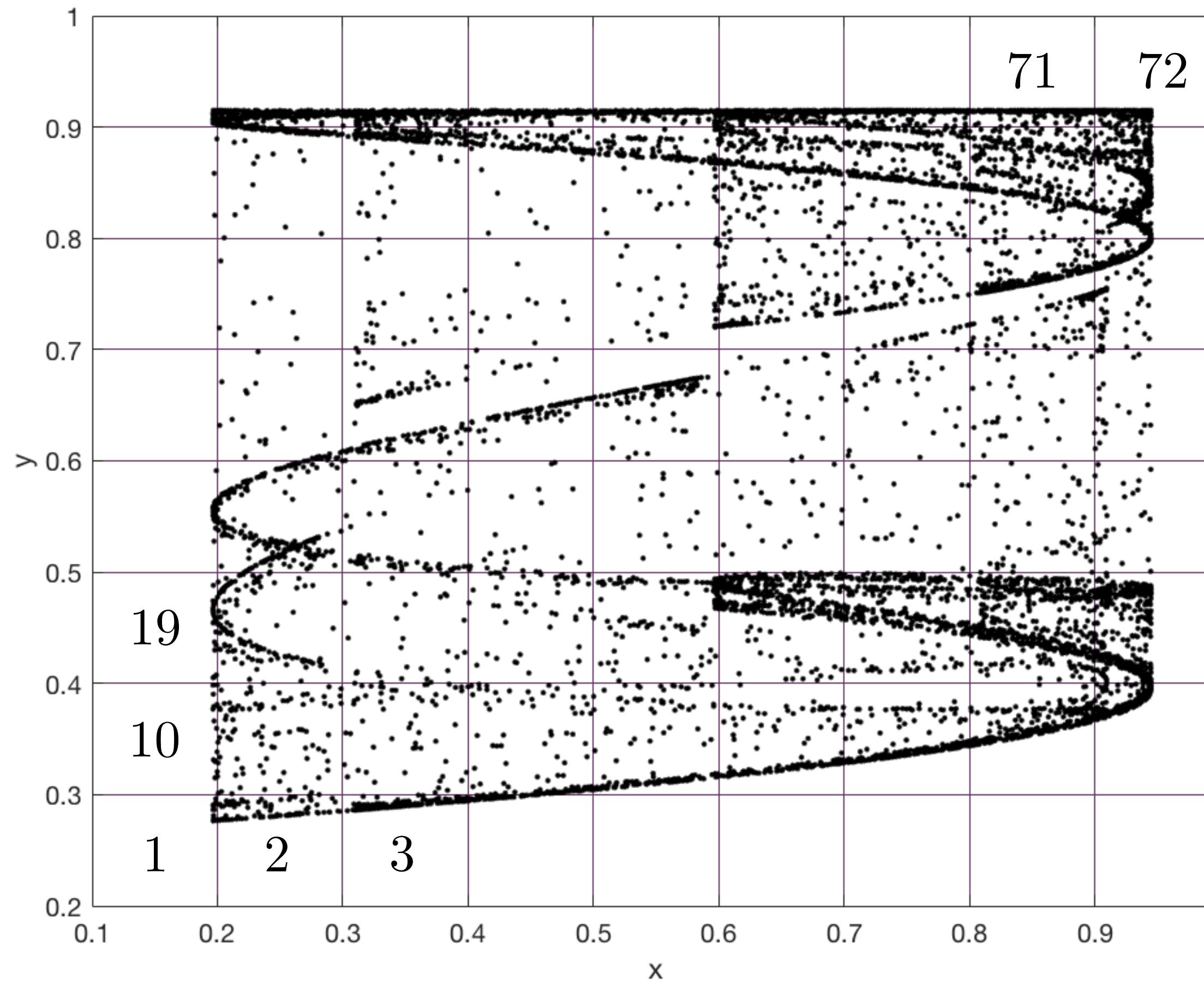


Ways to estimate the invariant density:

- Visitation frequency

Label the bins in this grid as

1, 2, ⋯, 72



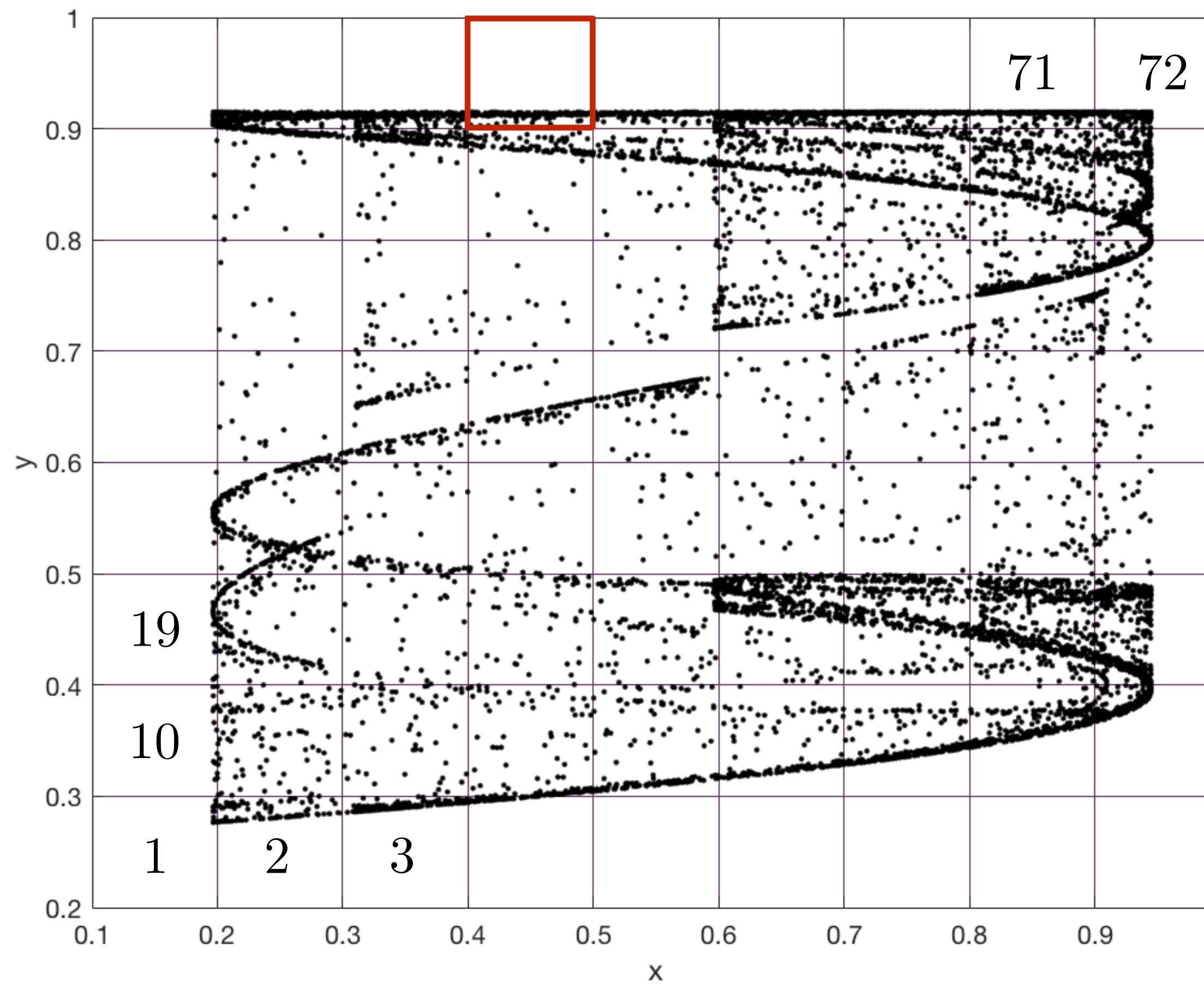
Total number of points
in the orbit: 10^4

Ways to estimate the invariant density:

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1, 2, ⋯, 72



$$\rho_{67} \sim \frac{n}{N} = \frac{189}{10^4} \simeq 0.019$$

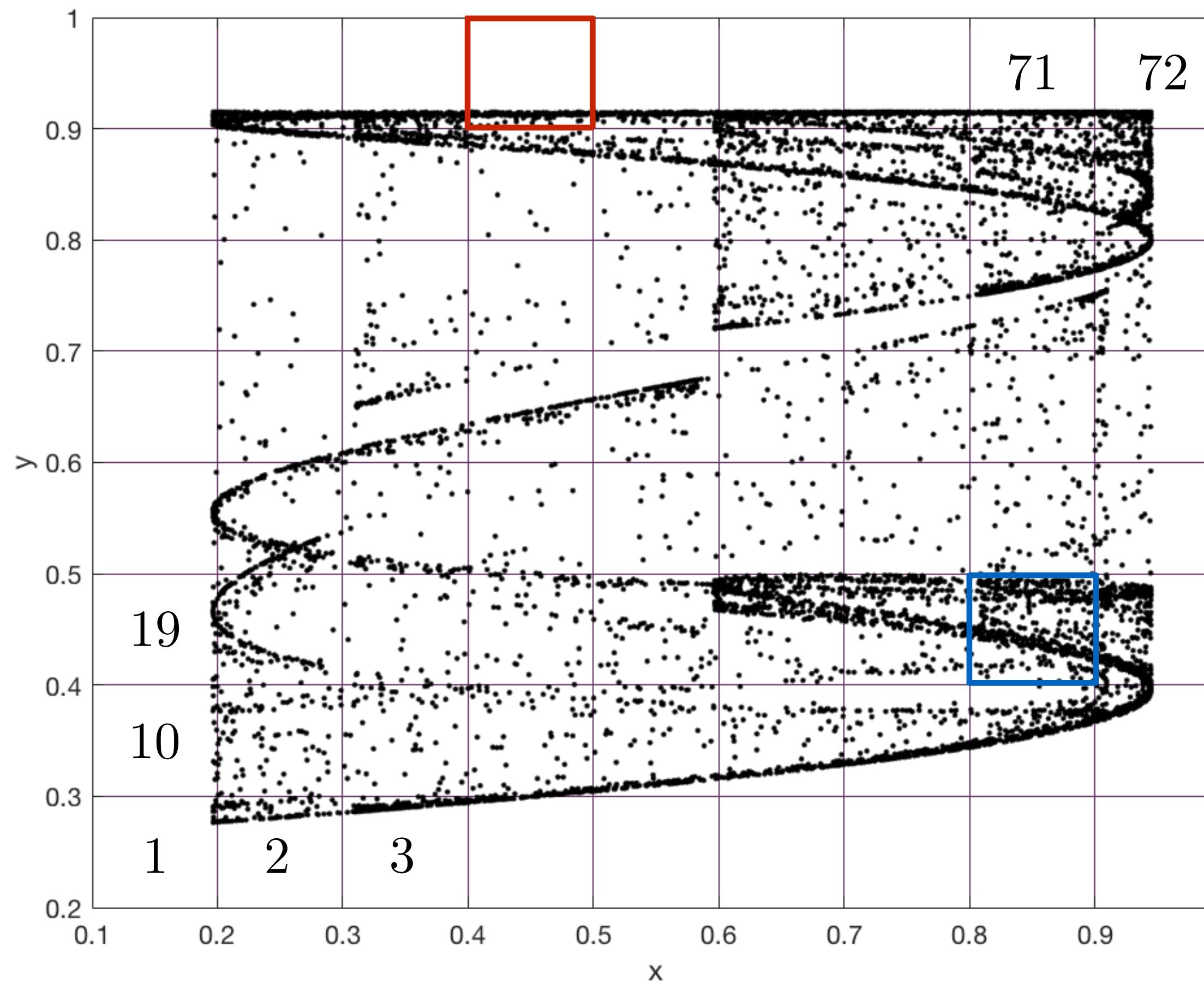
Total number of points
in the orbit: 10^4

Ways to estimate the invariant density:

- Visitation frequency

Label the bins in this grid as

1, 2, ⋯, 72



$$\rho_{67} \sim \frac{n}{N} = \frac{189}{10^4} \simeq 0.019$$

$$\rho_{26} \sim \frac{n}{N} = \frac{518}{10^4} \simeq 0.052$$

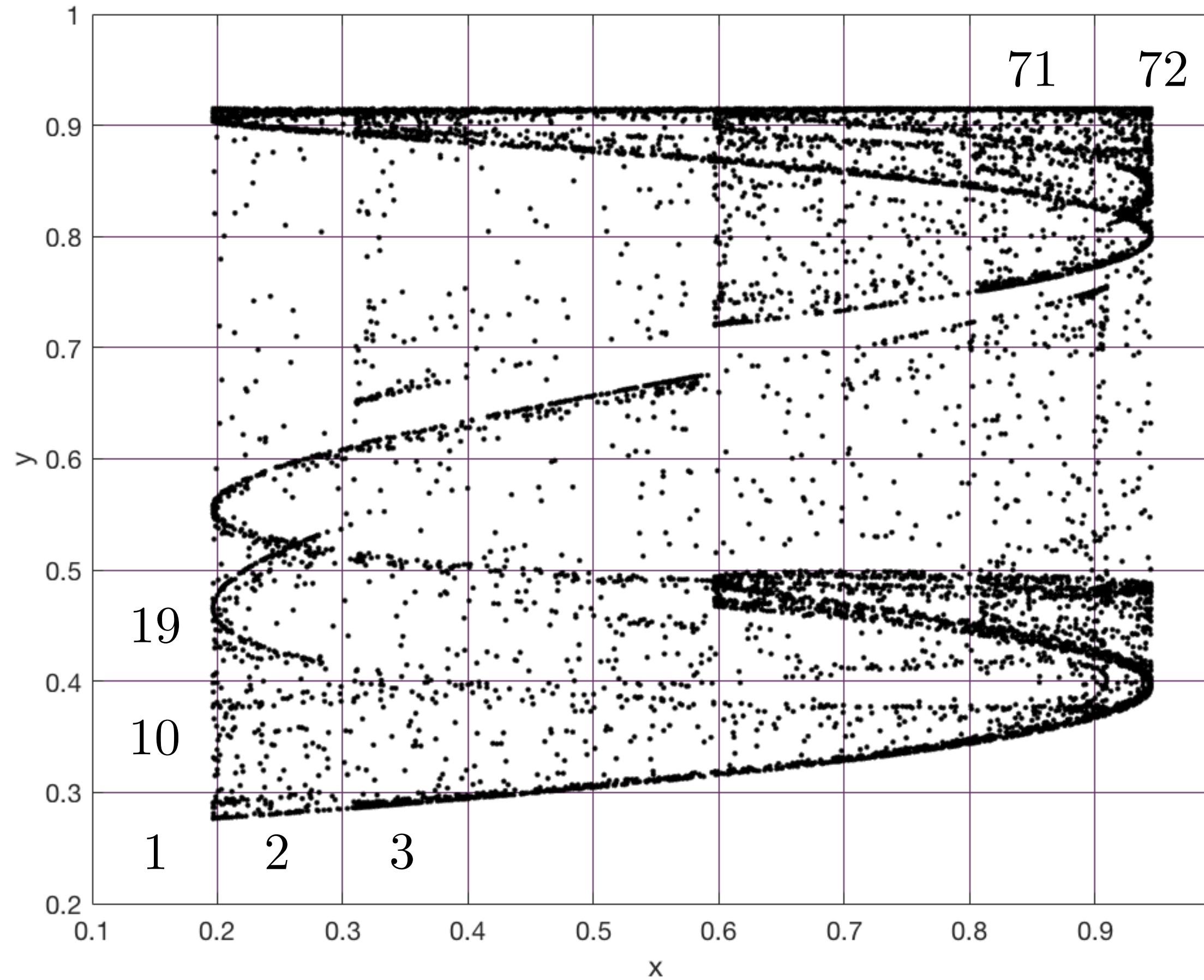
Total number of points
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Ways to estimate the invariant density:

- Via the transfer matrix (Ulam's approximation)

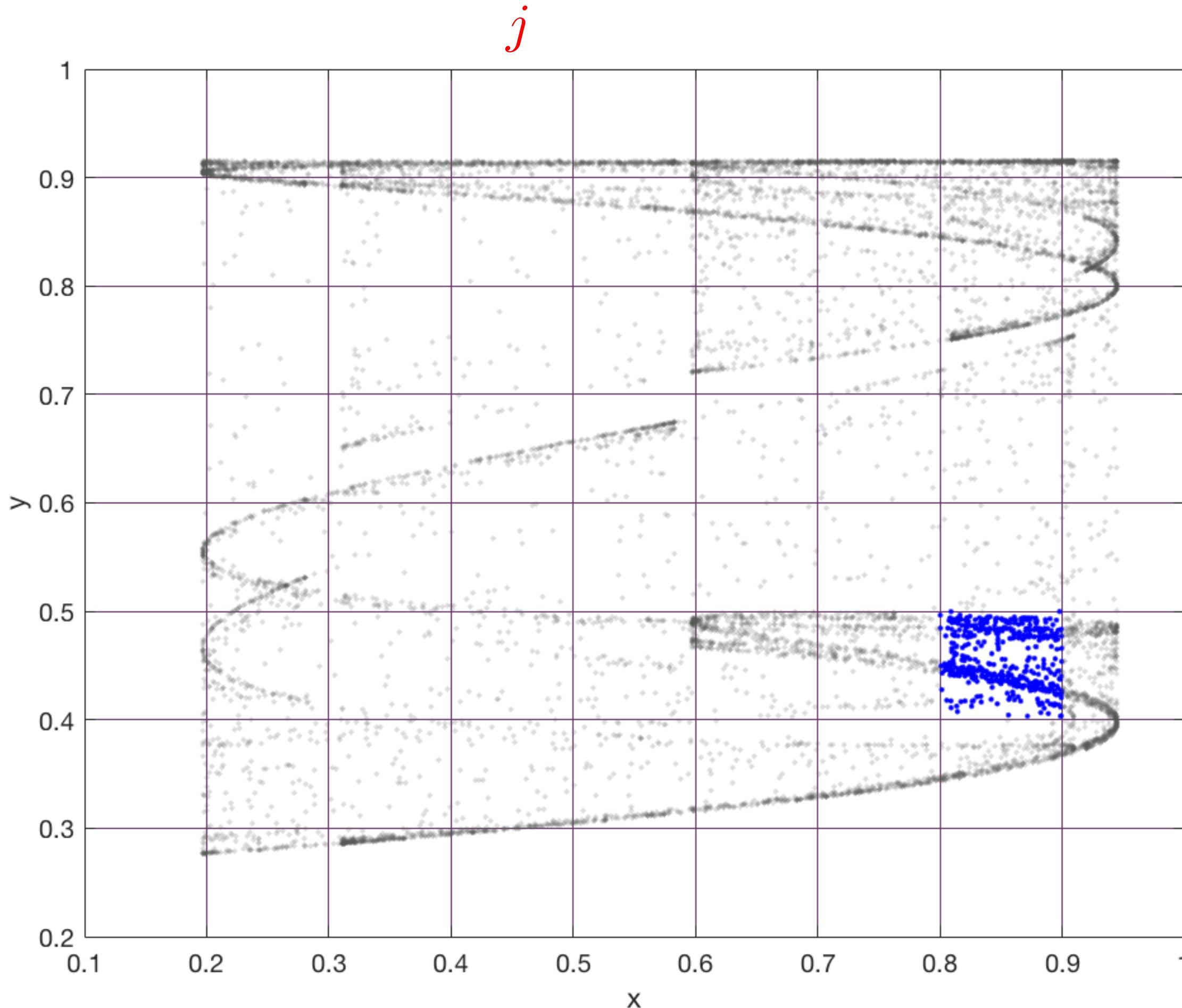
Approximate the unknown function generating the time series by a matrix of transition probabilities (**transfer matrix**):

$$T_{ij}, \quad i, j = 1, \dots, 72$$



Ways to estimate the invariant density:

- Via the transfer matrix (Ulam's approximation)

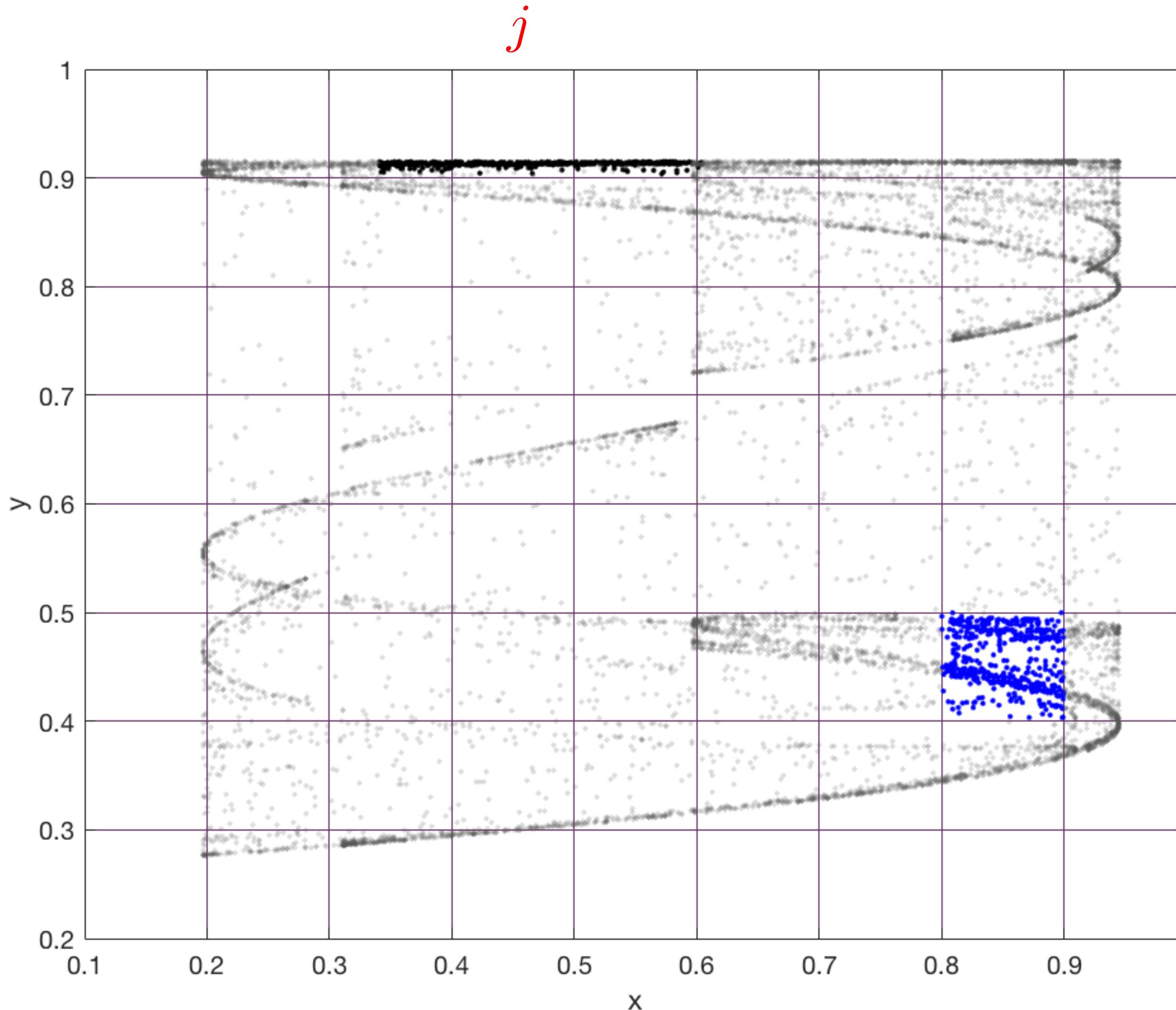


T_{ij} ?

Suppose p_1, p_2, \dots, p_{N_i} are the points
in the orbit falling in the i -th bin ...

Ways to estimate the invariant density:

- Via the transfer matrix (Ulam's approximation)

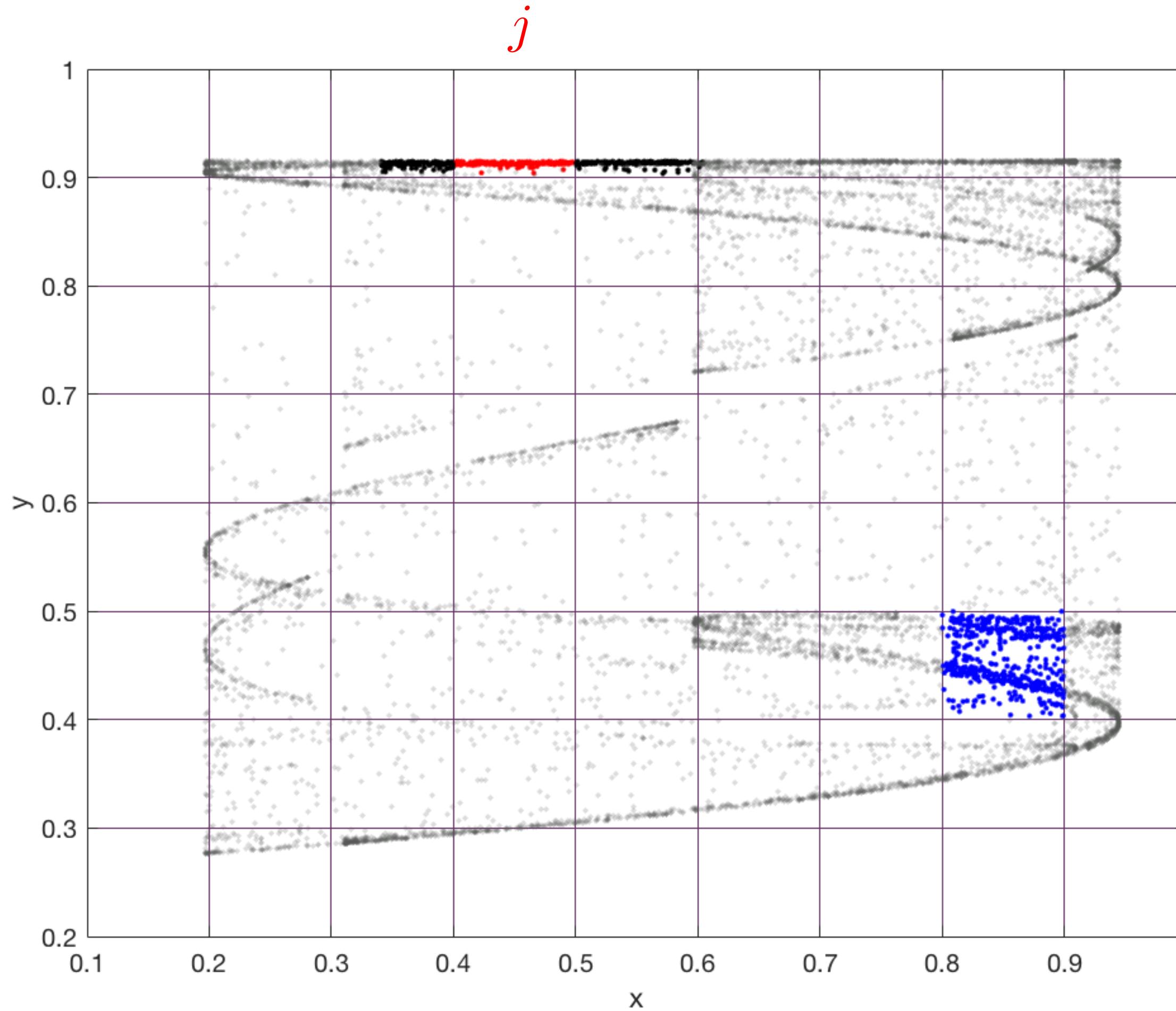


T_{ij} ?

Suppose p_1, p_2, \dots, p_{N_i} are the points in the orbit falling in the i -th bin ... where will those points be in the next time step?

Ways to estimate the invariant density:

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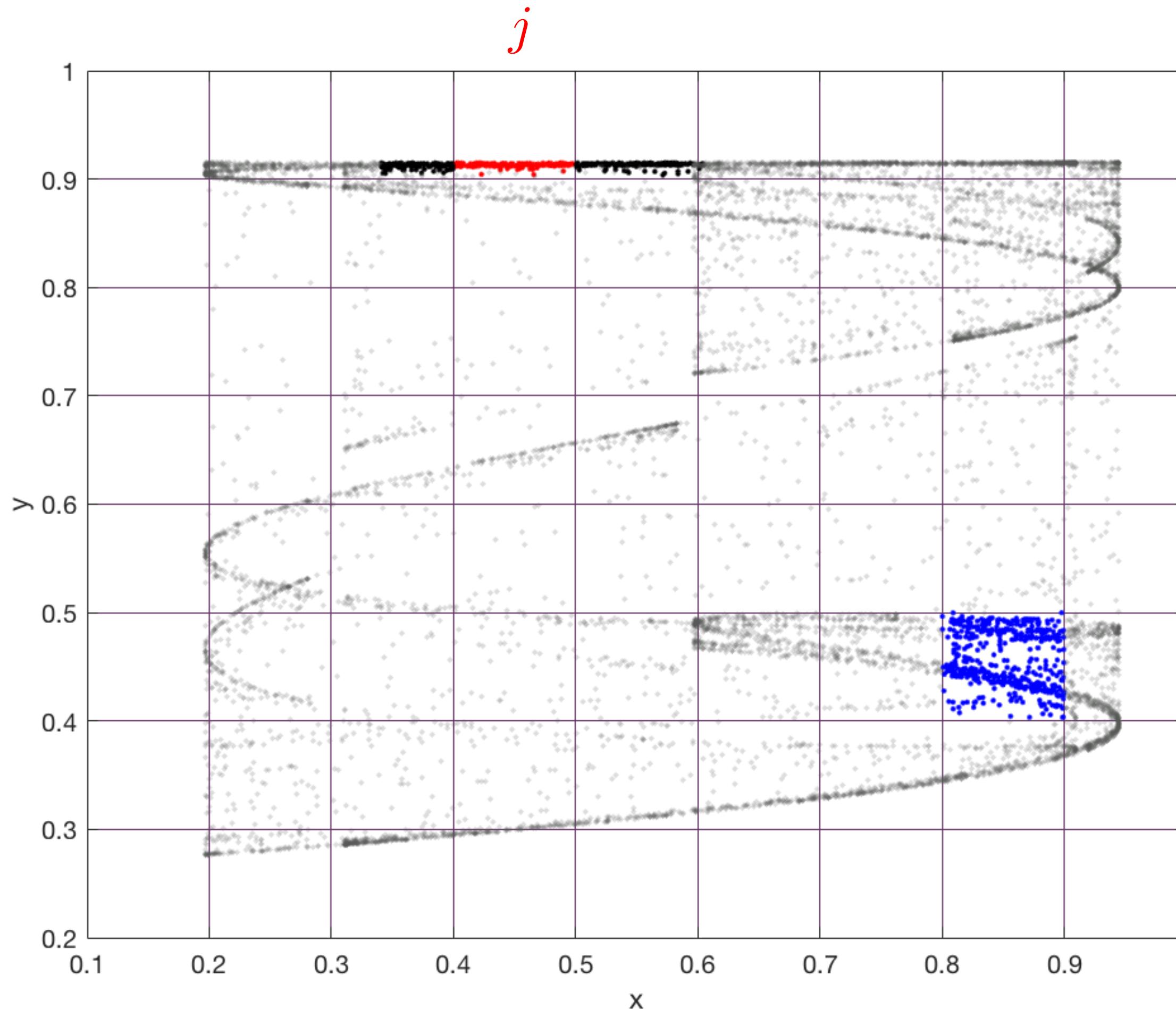


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Suppose p_1, p_2, \dots, p_{N_i} are the points
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where will those points be in the next time
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suppose that n_j fall into the j -th bin ...

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T_{ij} ?

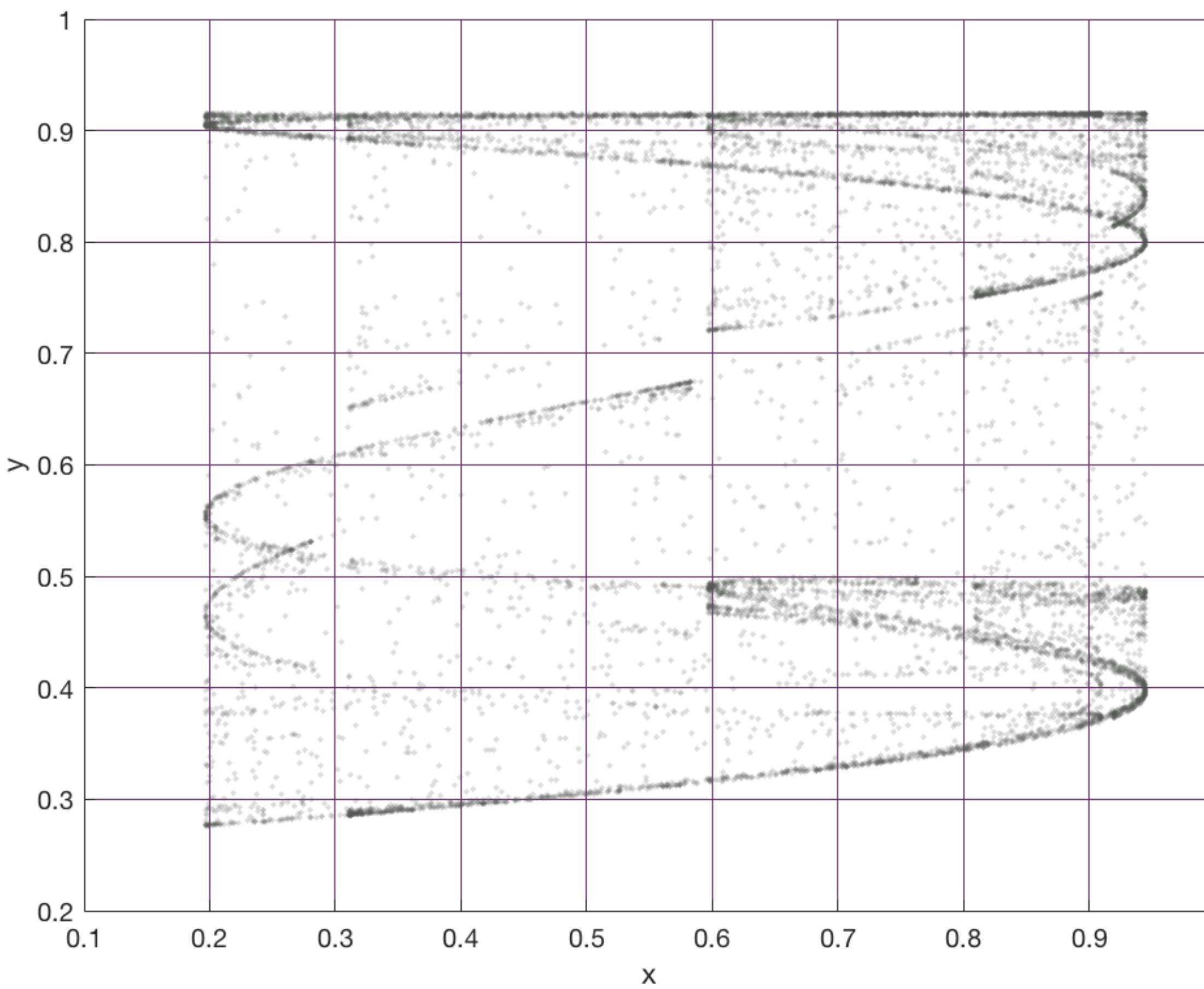
Suppose p_1, p_2, \dots, p_{N_i} are the points
in the orbit falling in the i -th bin ...
where will those points be in the next time
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suppose that n_j fall into the j -th bin ...

Then

$$T_{ij} = \frac{n_j}{N_i}$$

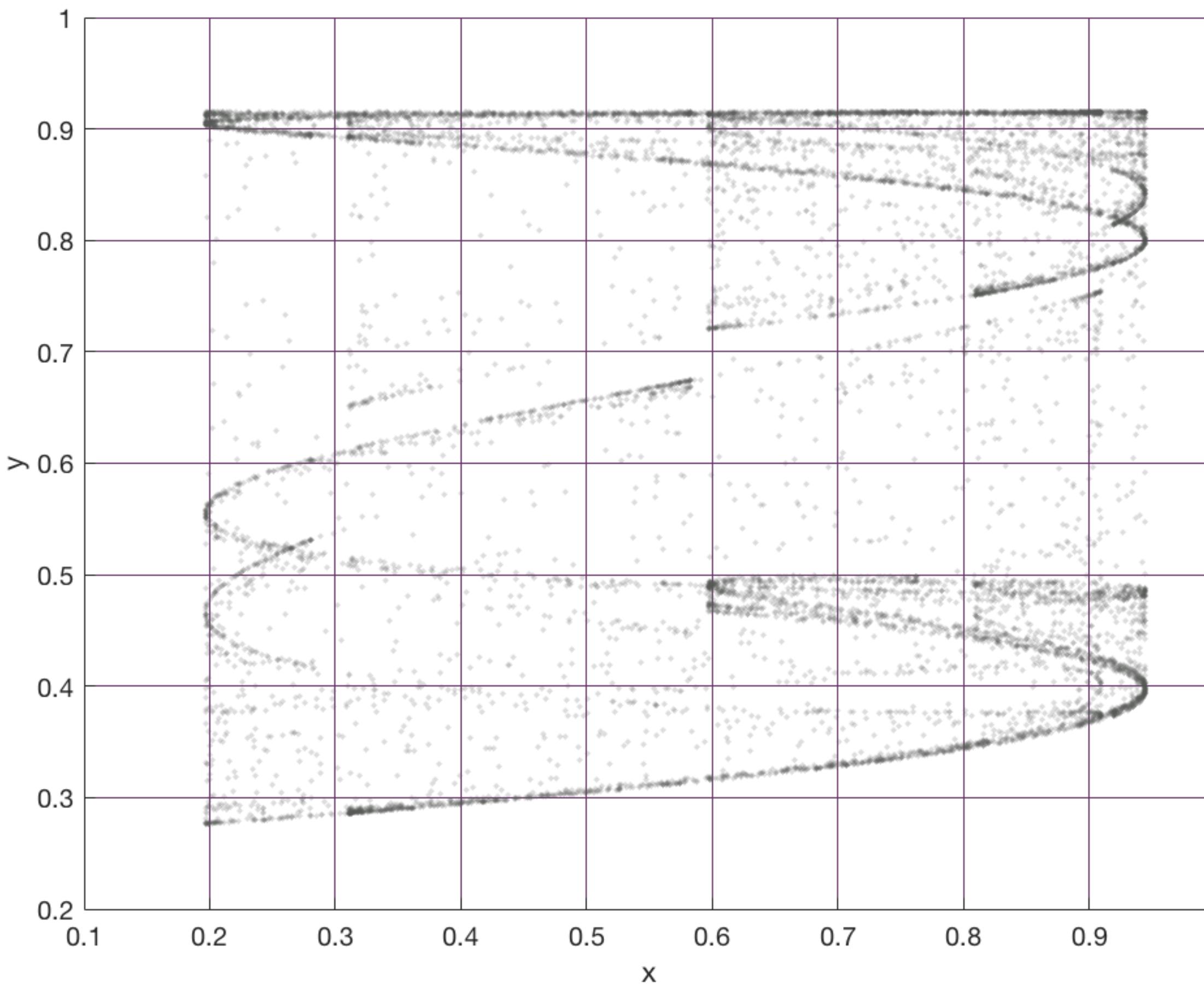
Probability of going
from bin i to bin j

How to compute the invariant density from T ?



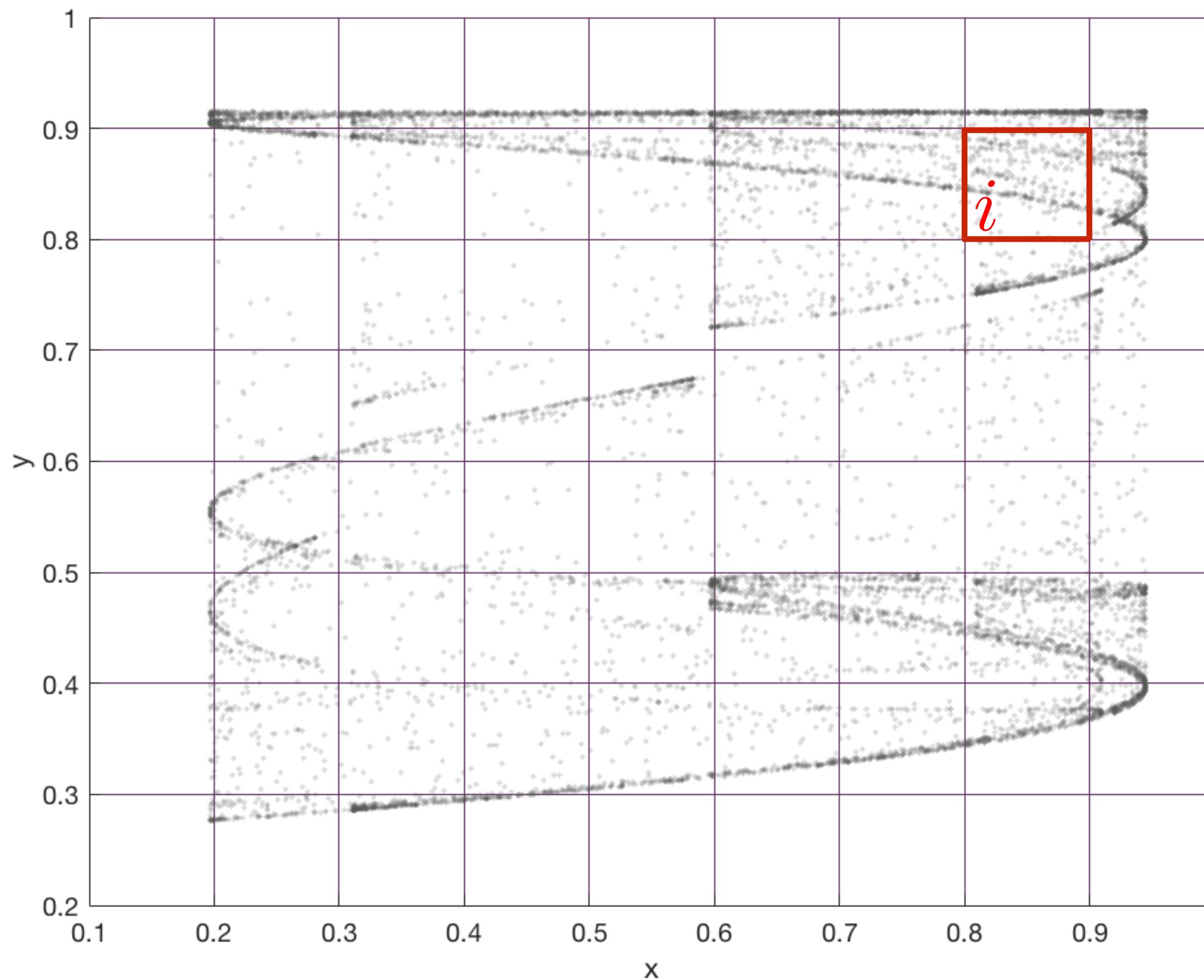
How to compute the invariant density from T ?

Let $P = (P_1, \dots, P_{72})$ be a probability distribution over the bins.



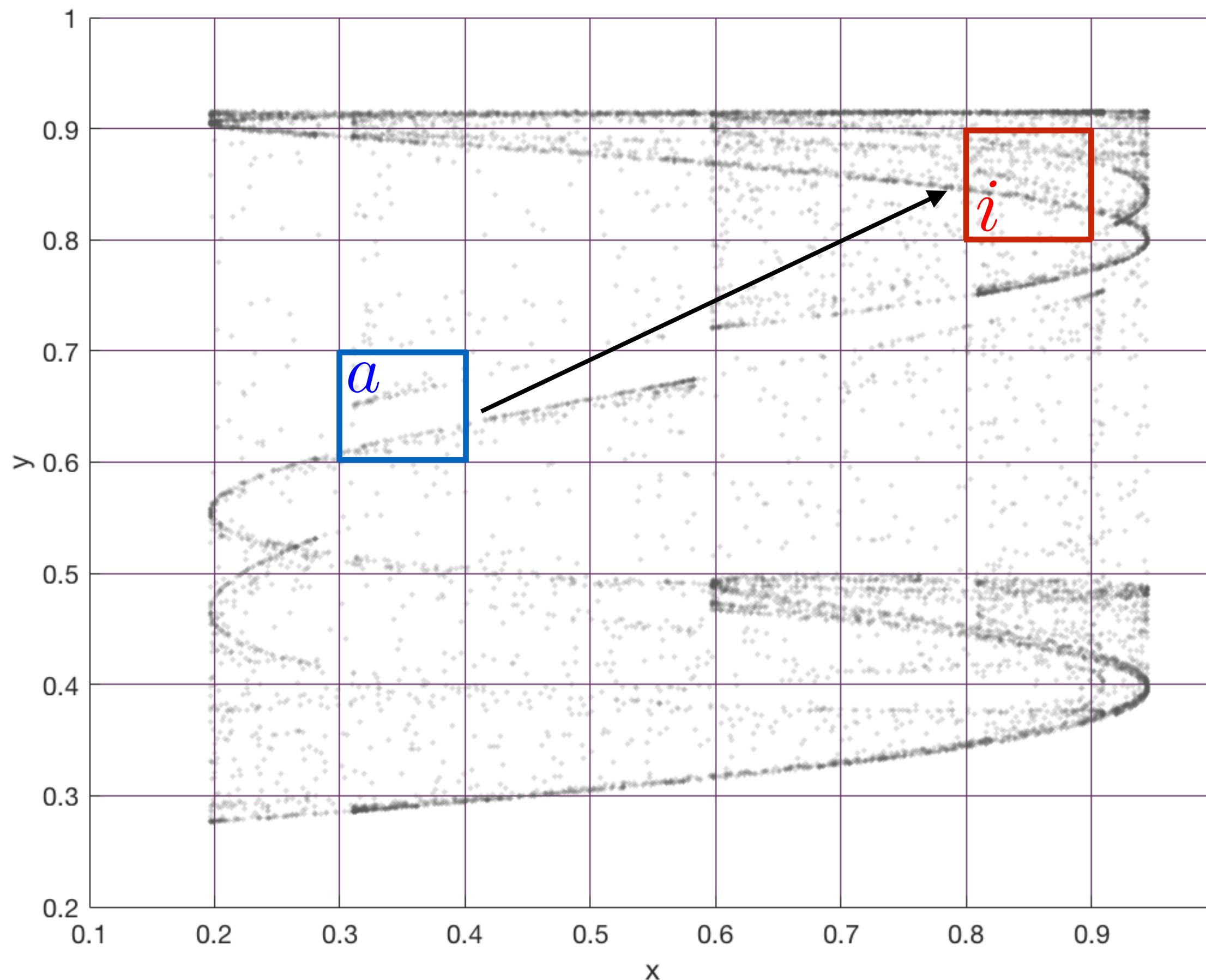
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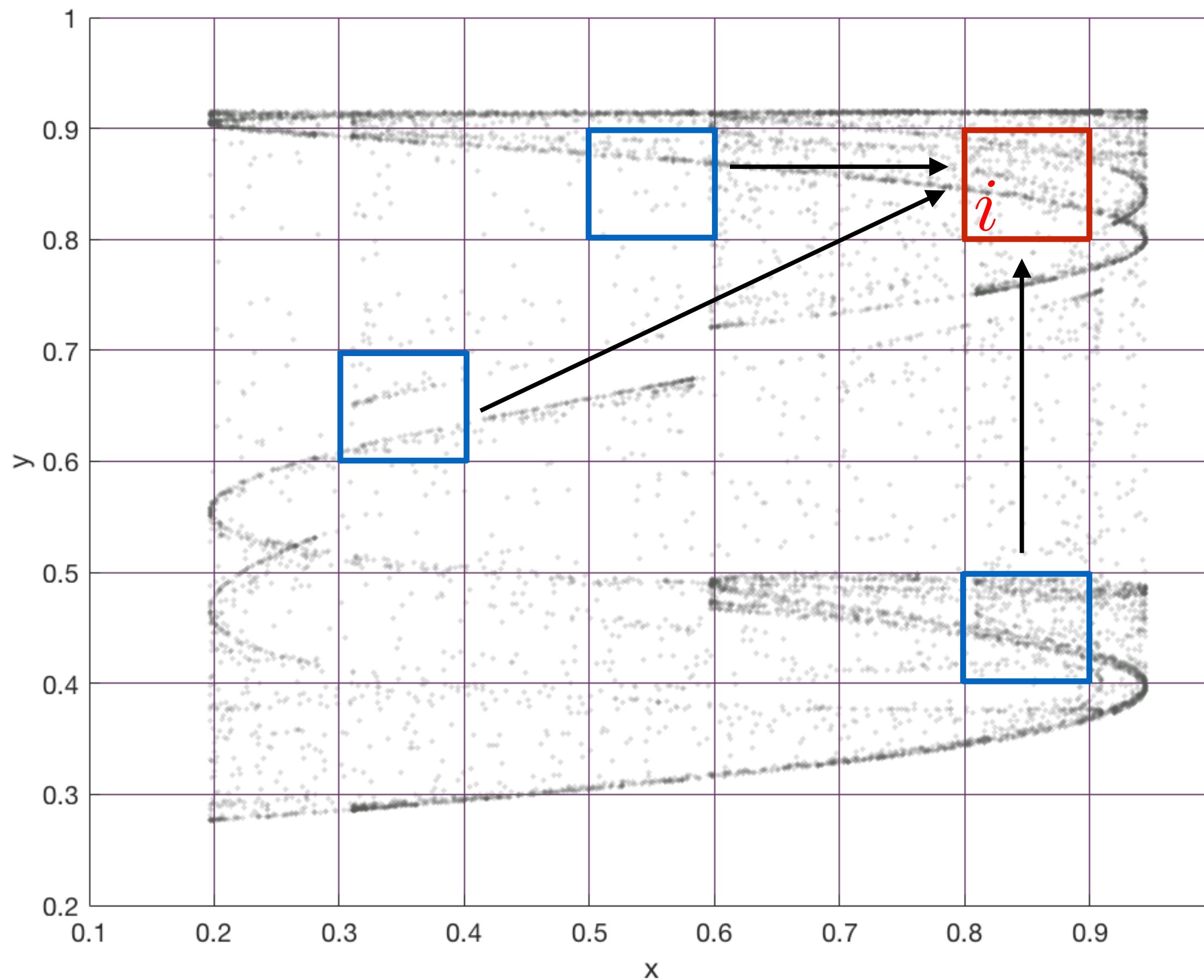
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$$P_a T_{ai}$$

How to compute the invariant density from T ?

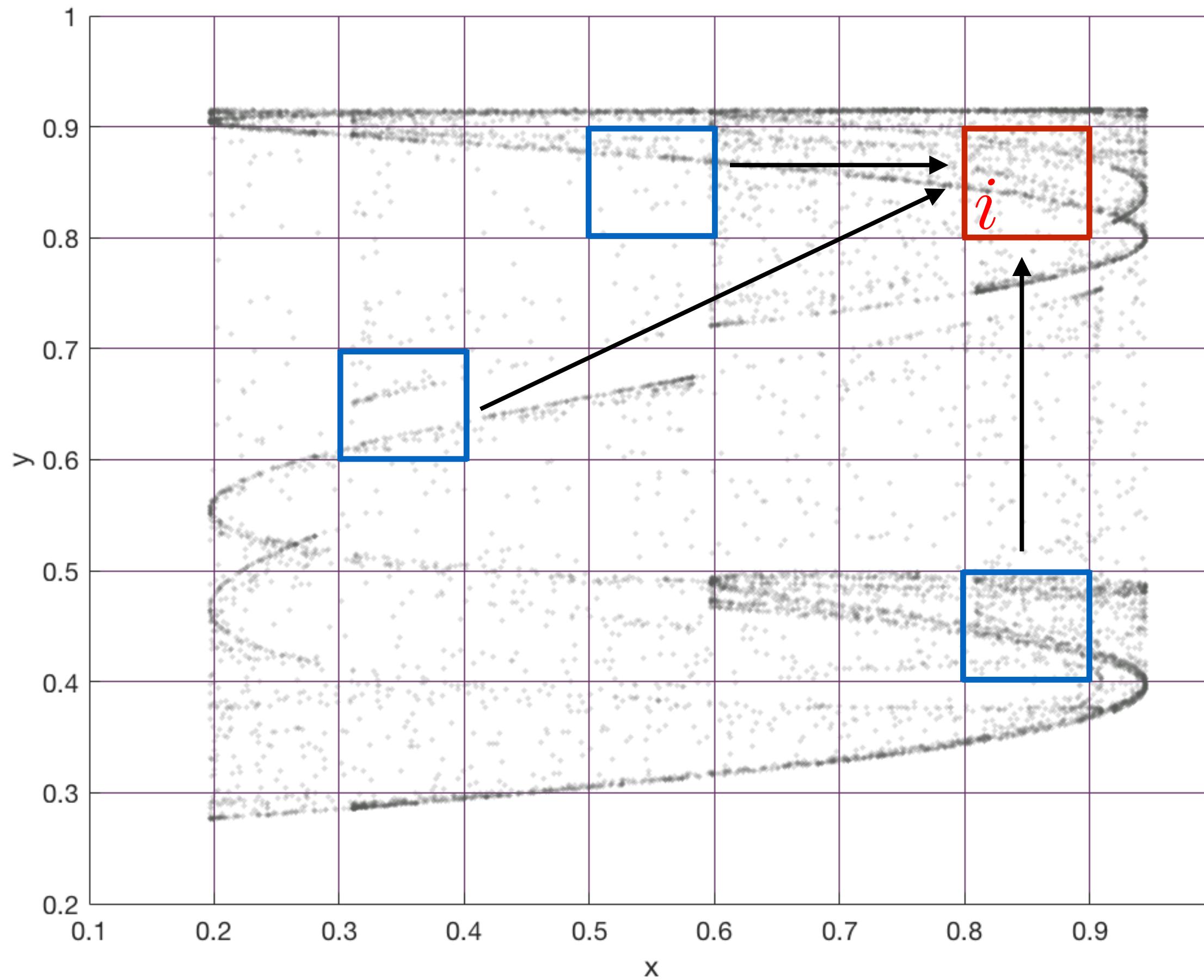
Let $P = (P_1, \dots, P_{72})$ be a probability distribution over the bins.



$$P'_{\textcolor{red}{i}} = \sum_{a=1}^{72} P_{\textcolor{blue}{a}} T_{ai} \neq P_{\textcolor{red}{i}}$$

How to compute the invariant density from T ?

Let $P = (P_1, \dots, P_{72})$ be a probability distribution over the bins.



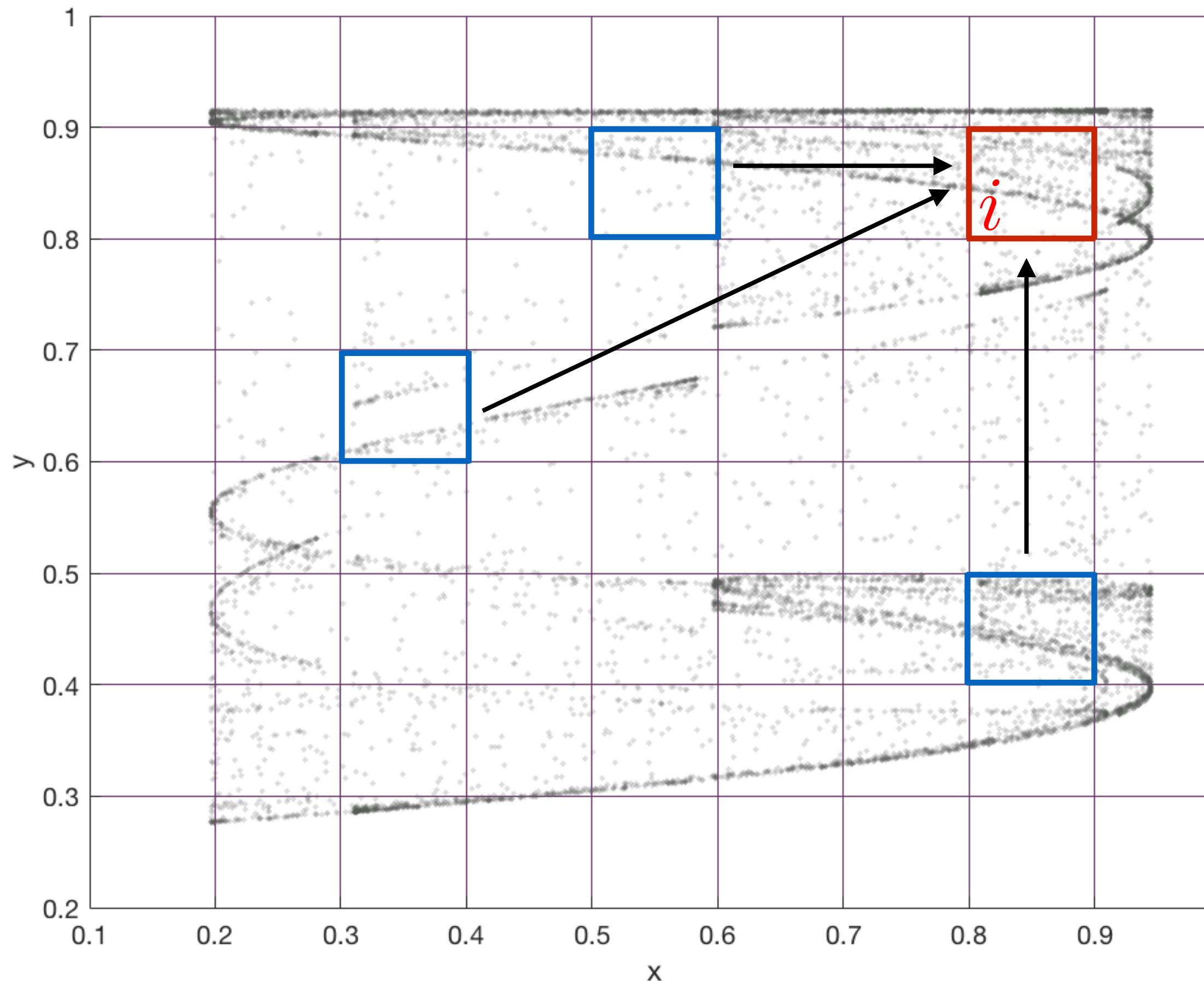
$$P'_i = \sum_{a=1}^{72} P_a T_{ai} \neq P_i$$

$$\begin{aligned} P(1) &= P \cdot T \\ P(2) &= P(1) \cdot T \\ P(3) &= P(2) \cdot T \end{aligned} \quad \Rightarrow \quad \lim_{n \rightarrow \infty} P(n) = \rho$$

⋮

How to compute the invariant density from T ?

Let $P = (P_1, \dots, P_{72})$ be a probability distribution over the bins.



$$P'_i = \sum_{a=1}^{72} P_a T_{ai} \neq P_i$$

$$P(1) = P \cdot T$$

$$P(2) = P(1) \cdot T$$

$$P(3) = P(2) \cdot T$$

$$\lim_{n \rightarrow \infty} P(n) = \rho$$

⋮

ρ_i is the probability for the system to occupy the i -th bin

$$\sum_{a=1}^{72} \rho_a T_{ai} = \rho_i$$

ρ is invariant under the action of T

Starting from (almost) any probability distribution

$P(0)$, the sequence ...

$$P(1) = P(0) \cdot T$$

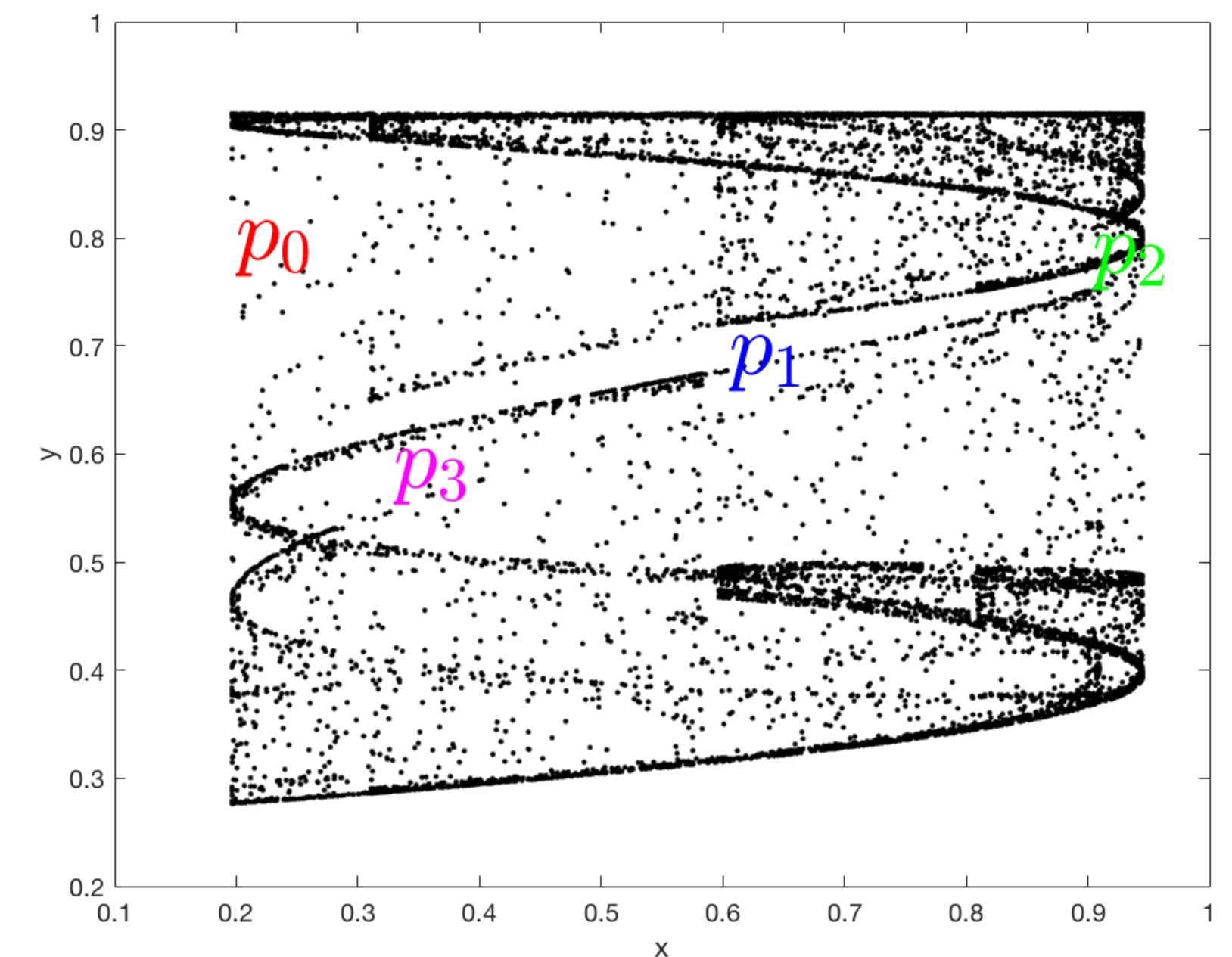
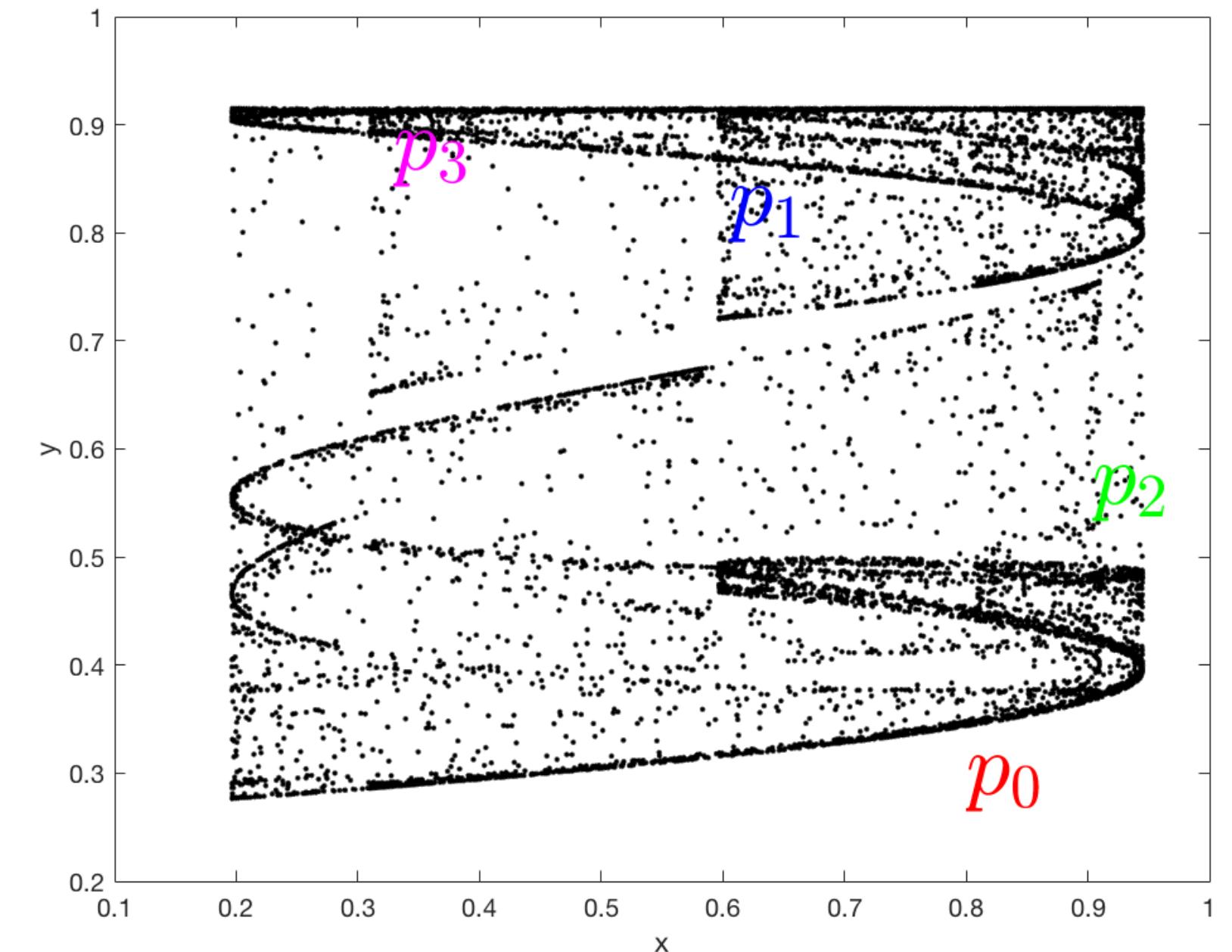
$$P(2) = P(1) \cdot T$$

$$P(3) = P(2) \cdot T$$

⋮

has the same limit

$$\lim_{n \rightarrow \infty} P(n) = \rho$$

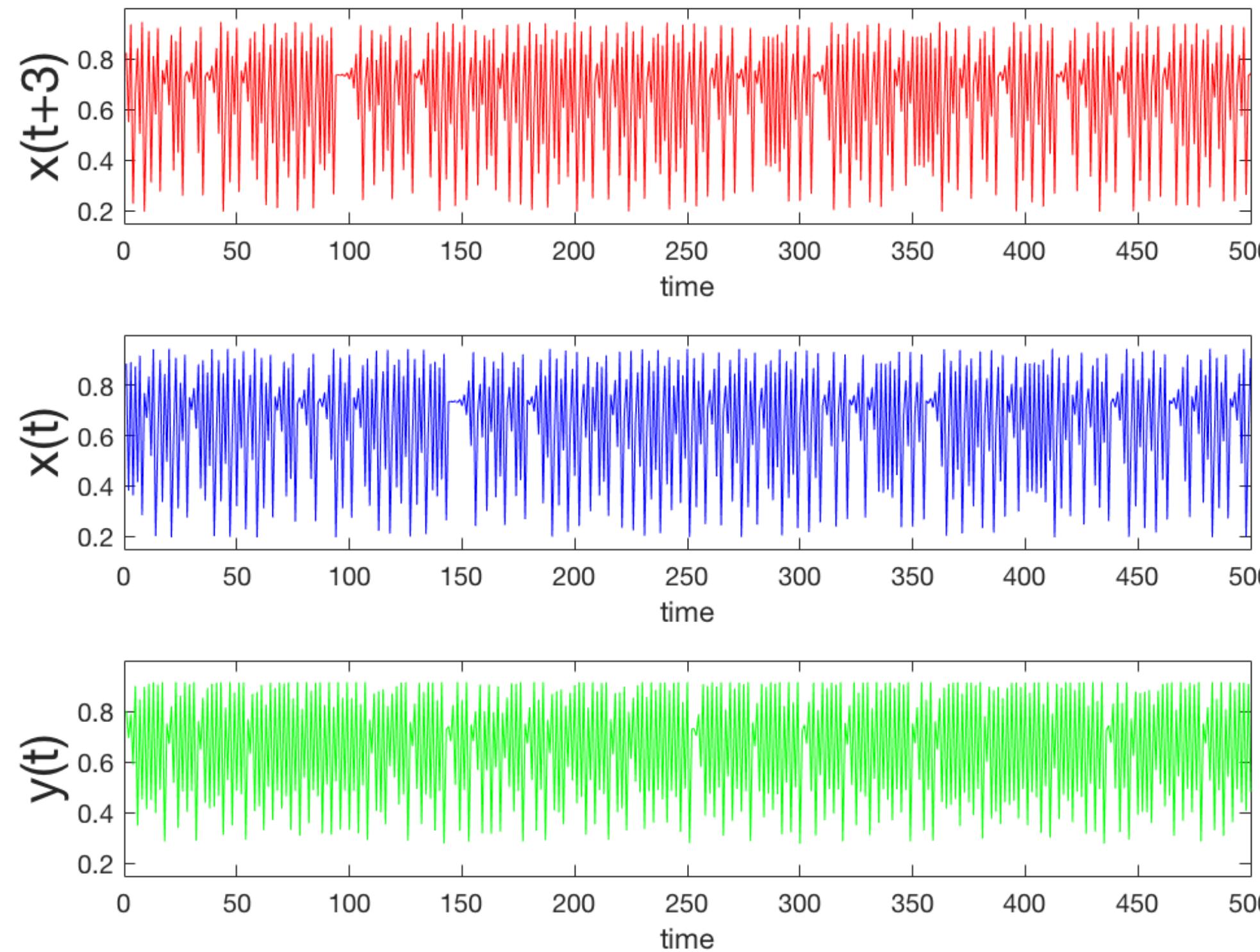


How then do we compute $P(x_{t+\tau}, x_t, y_t)$?

We start off by computing the invariant density ...

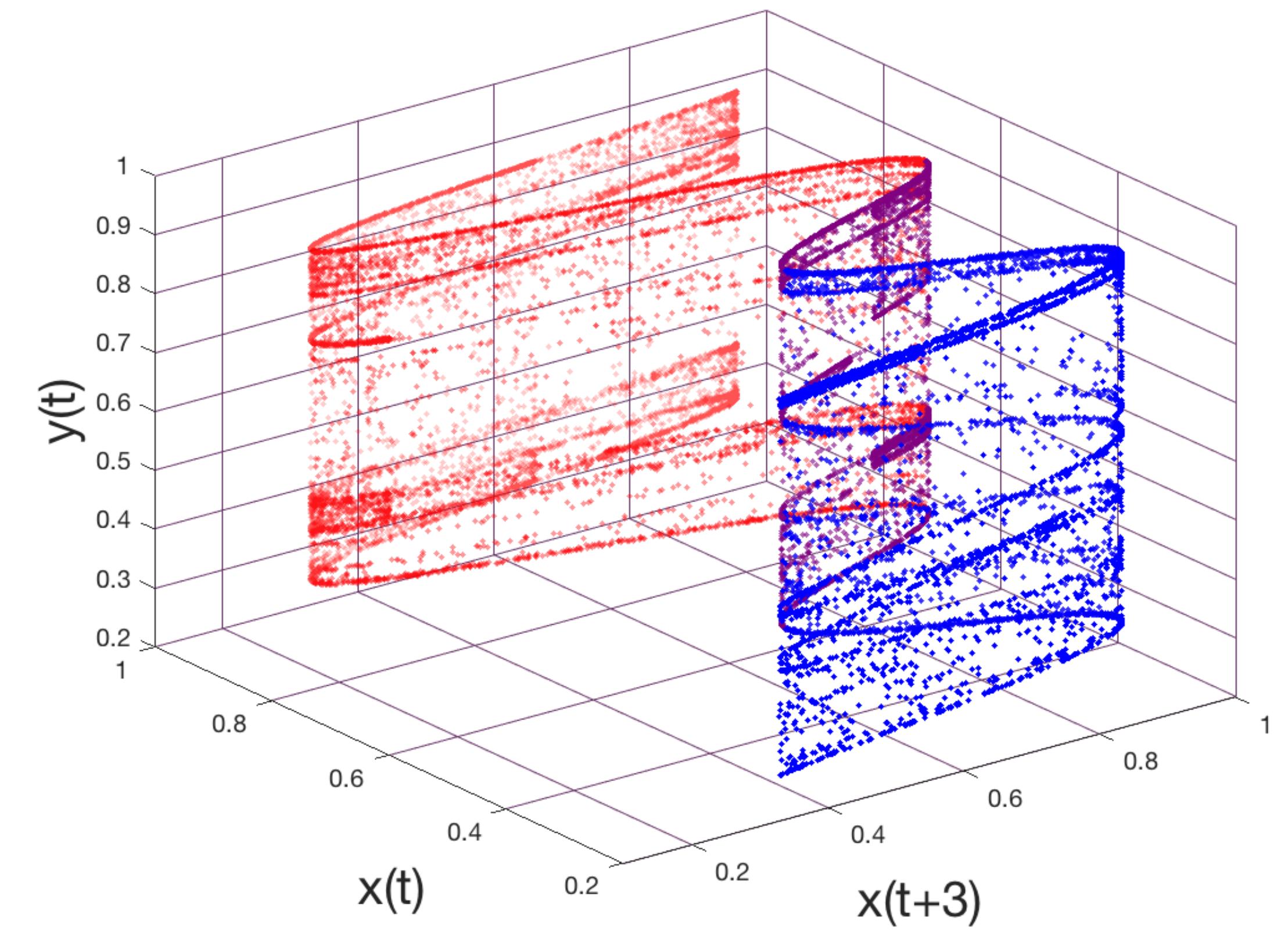
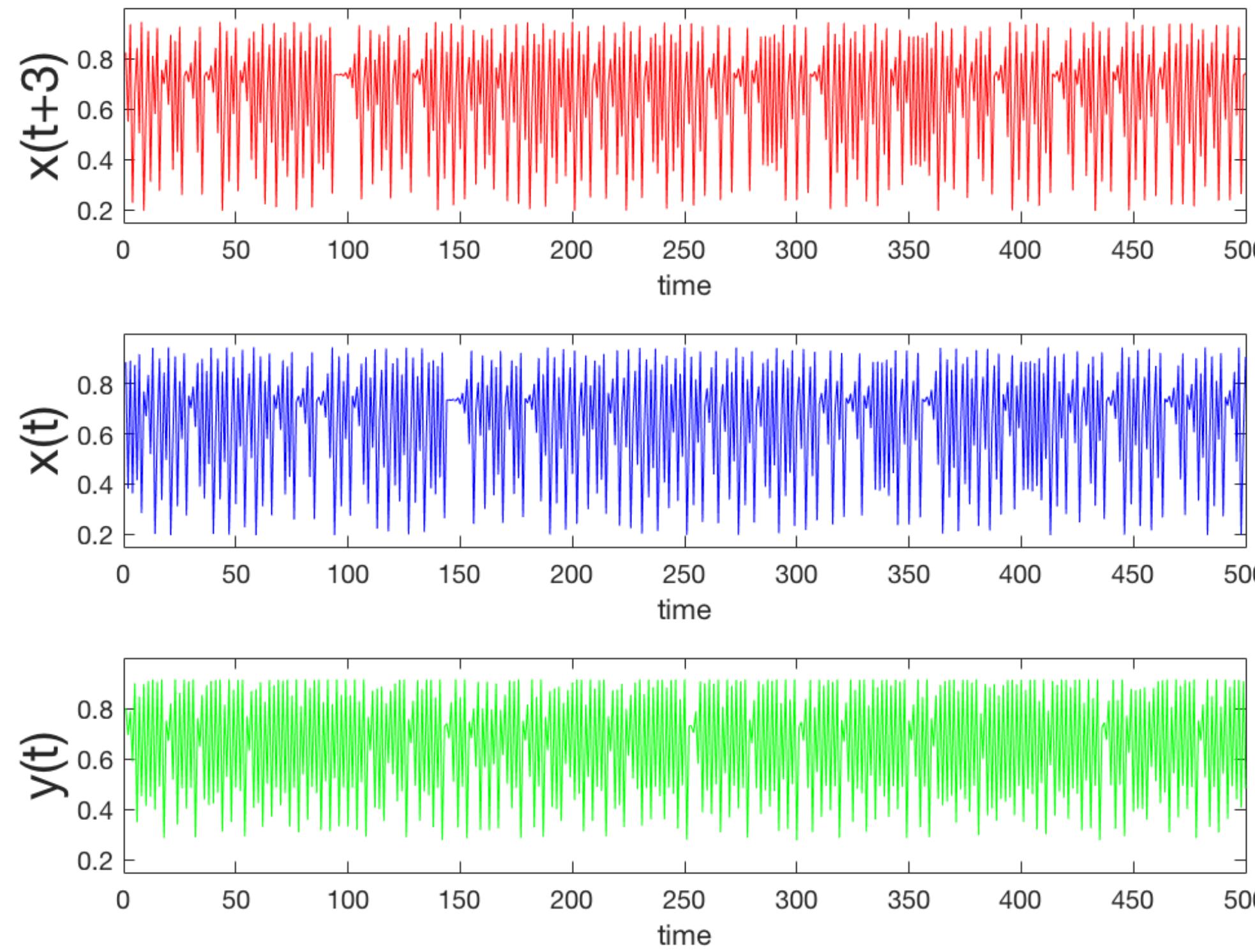
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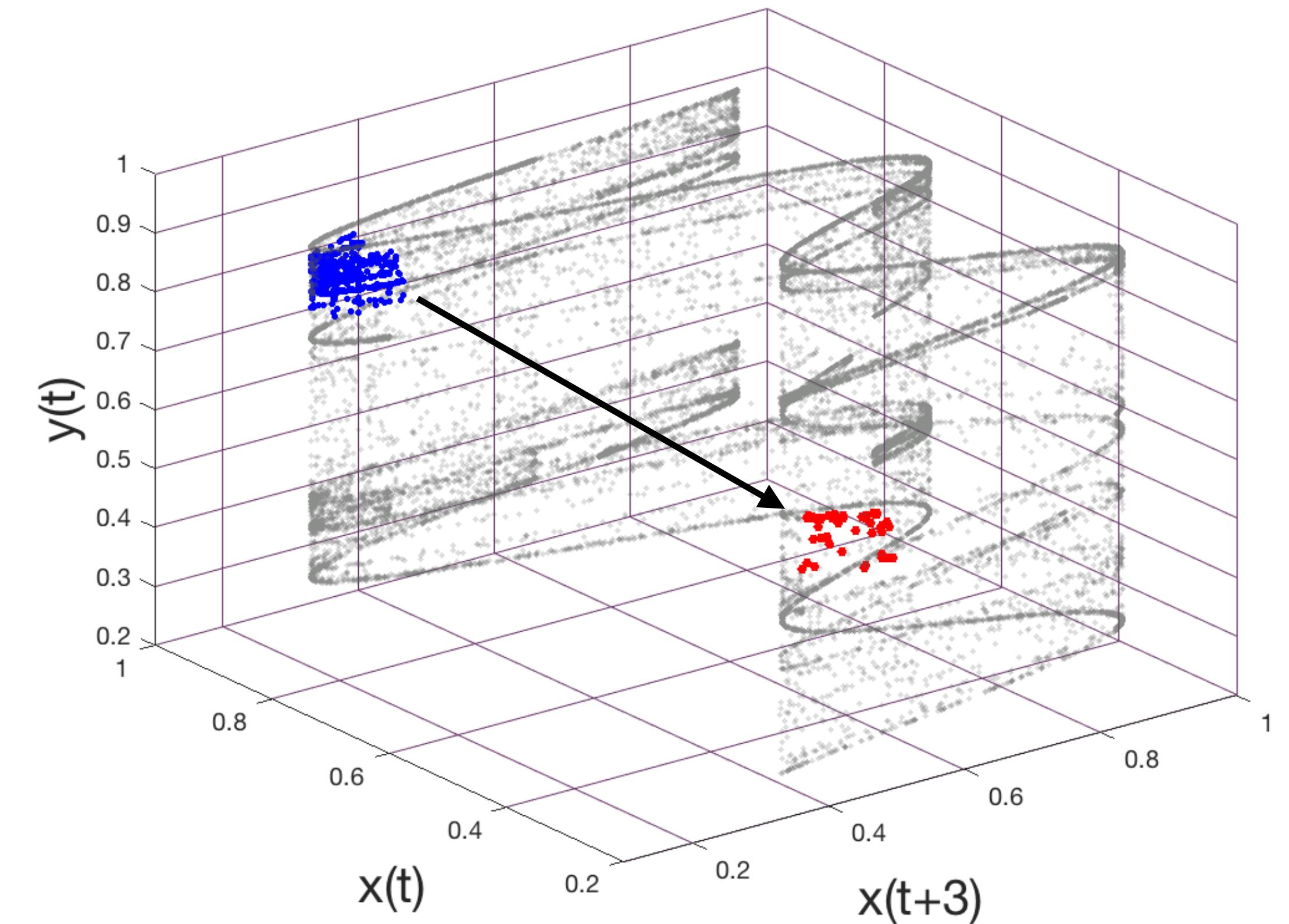
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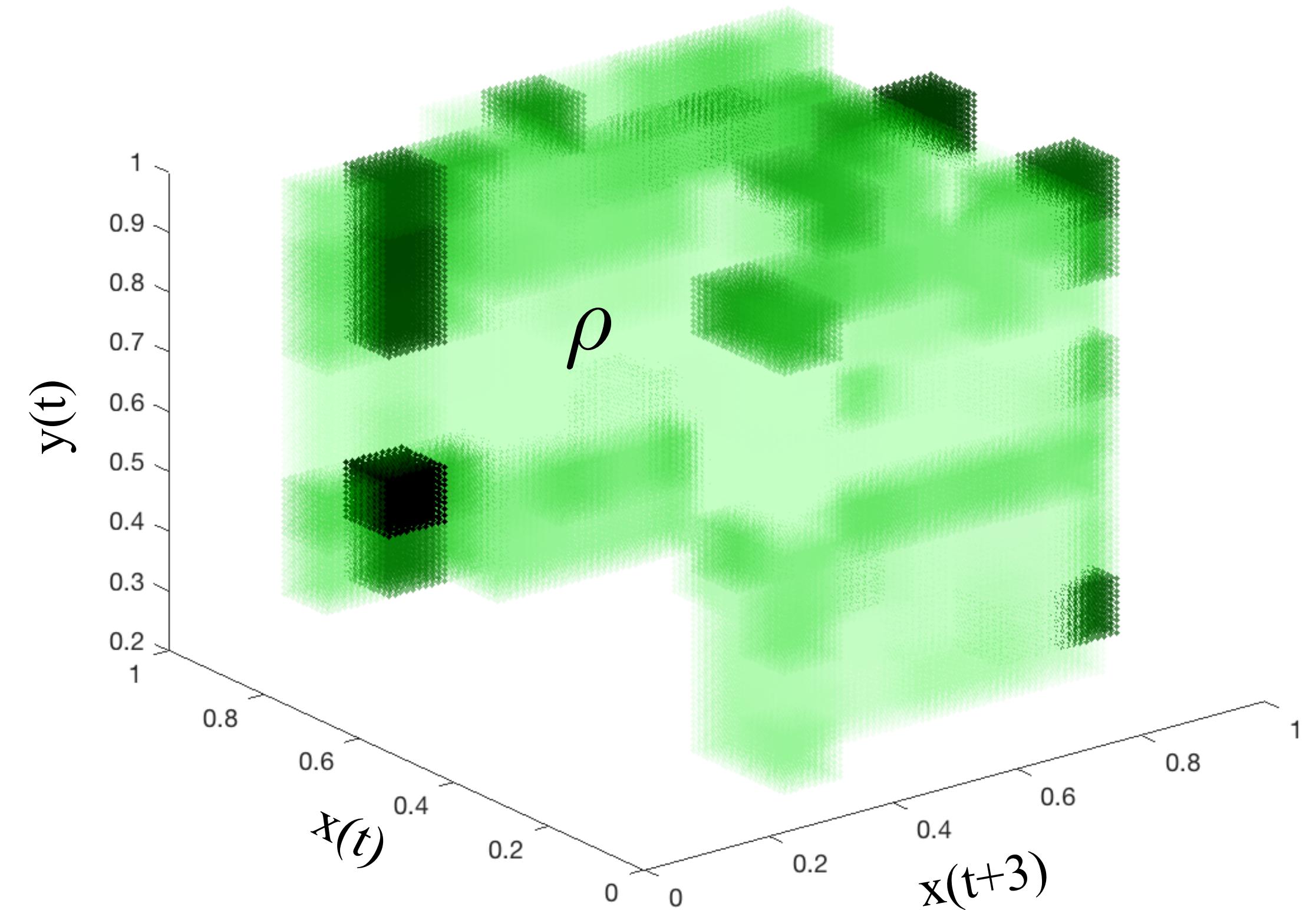
$$P(1) = P(0) \cdot T$$

:

:

$$\rho = \lim_{n \rightarrow \infty} P(n)$$

$$P(x_{t+3}, x_t, y_t)$$



$$P(1) = P(0) \cdot T$$

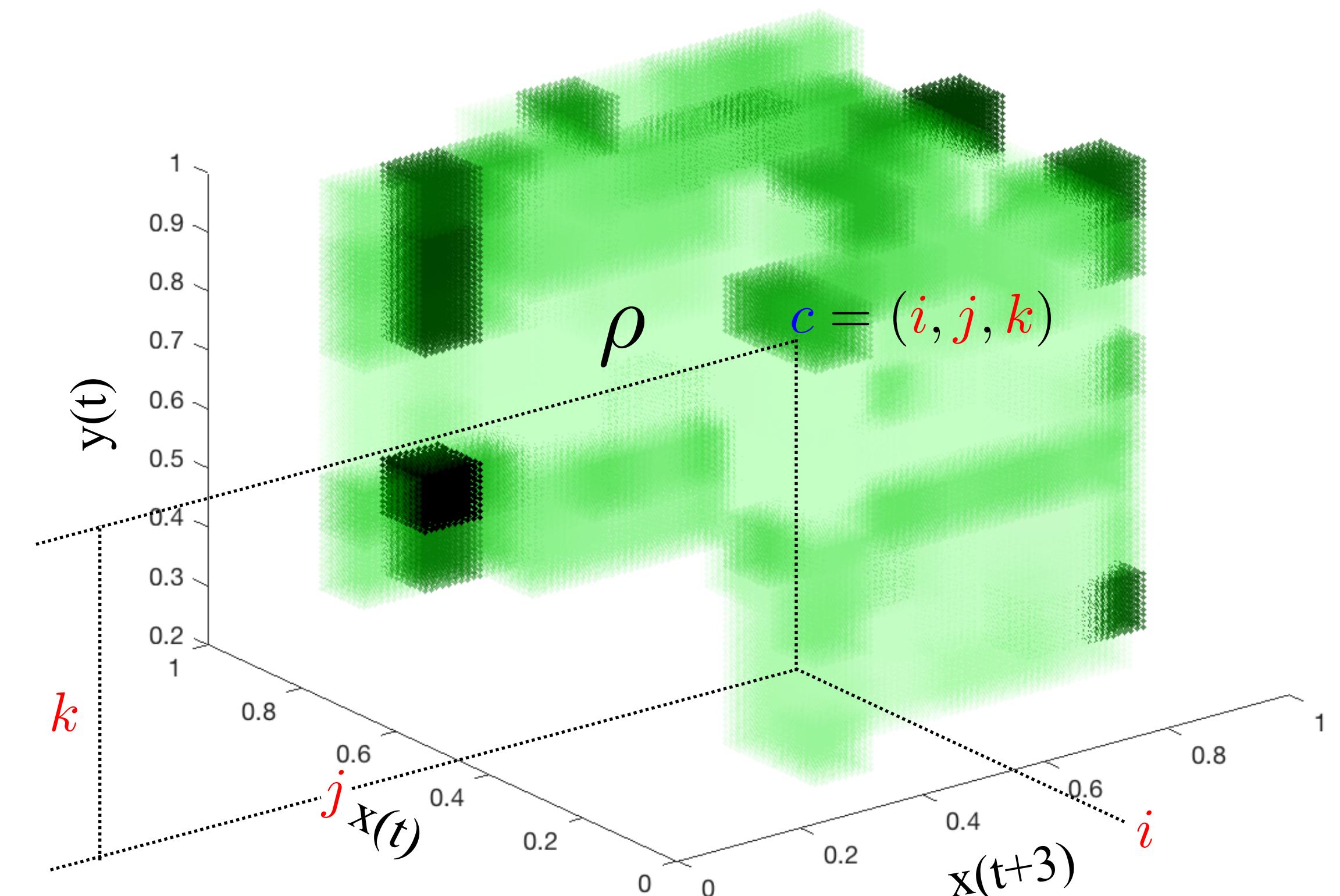
:

:

$$\rho = \lim_{n \rightarrow \infty} P(n)$$

$$P(i, j, k) = \rho(c) \quad \leftarrow \quad P(x_{t+3}, x_t, y_t)$$

Probability for the system
to occupy the bin with center c



$$P(1) = P(0) \cdot T$$

:

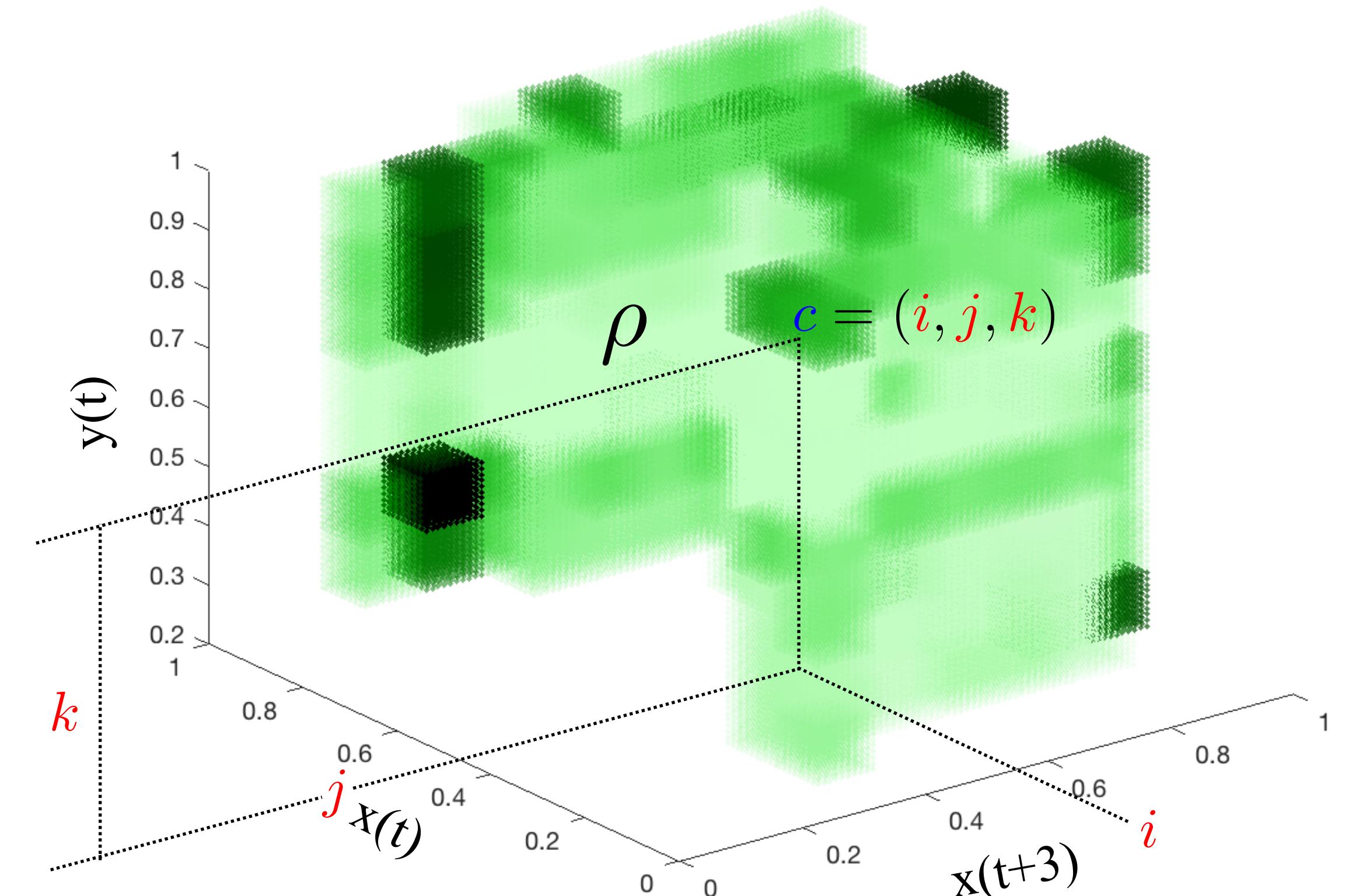
:

$$\rho = \lim_{n \rightarrow \infty} P(n)$$

$$P(i, j, k) = \rho(c) \quad \longleftarrow \quad P(x_{t+3}, x_t, y_t)$$

$$P(i|j, k) = \frac{P(i, j, k)}{\sum_m P(m, j, k)} \quad \longleftarrow \quad P(x_{t+3}|x_t, y_t)$$

$$P(i|j) = \frac{\sum_m P(i, j, m)}{\sum_r \sum_s P(r, j, s)} \quad \longleftarrow \quad P(x_{t+3}|x_t)$$



$$P(1) = P(0) \cdot T$$

:

:

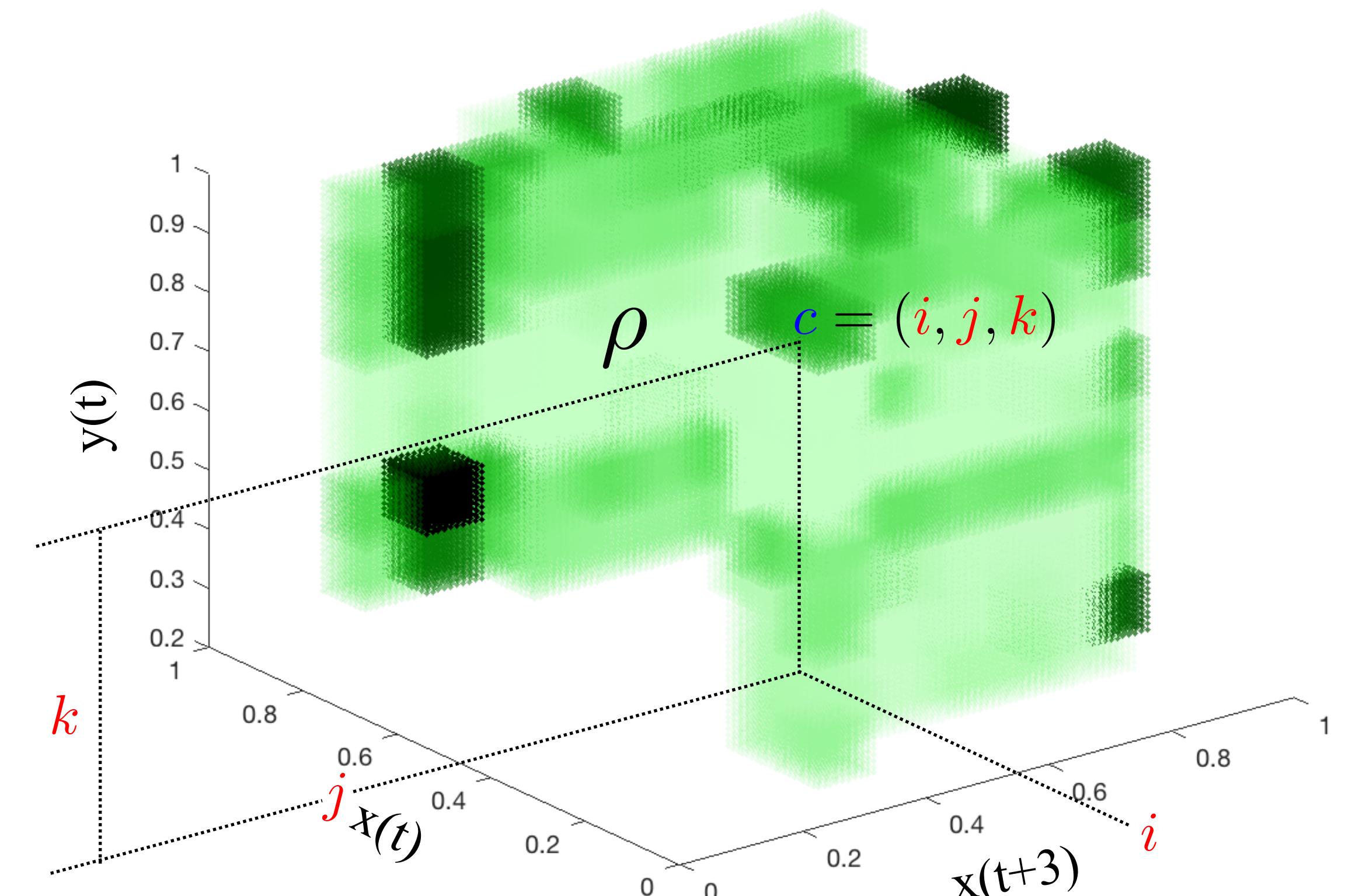
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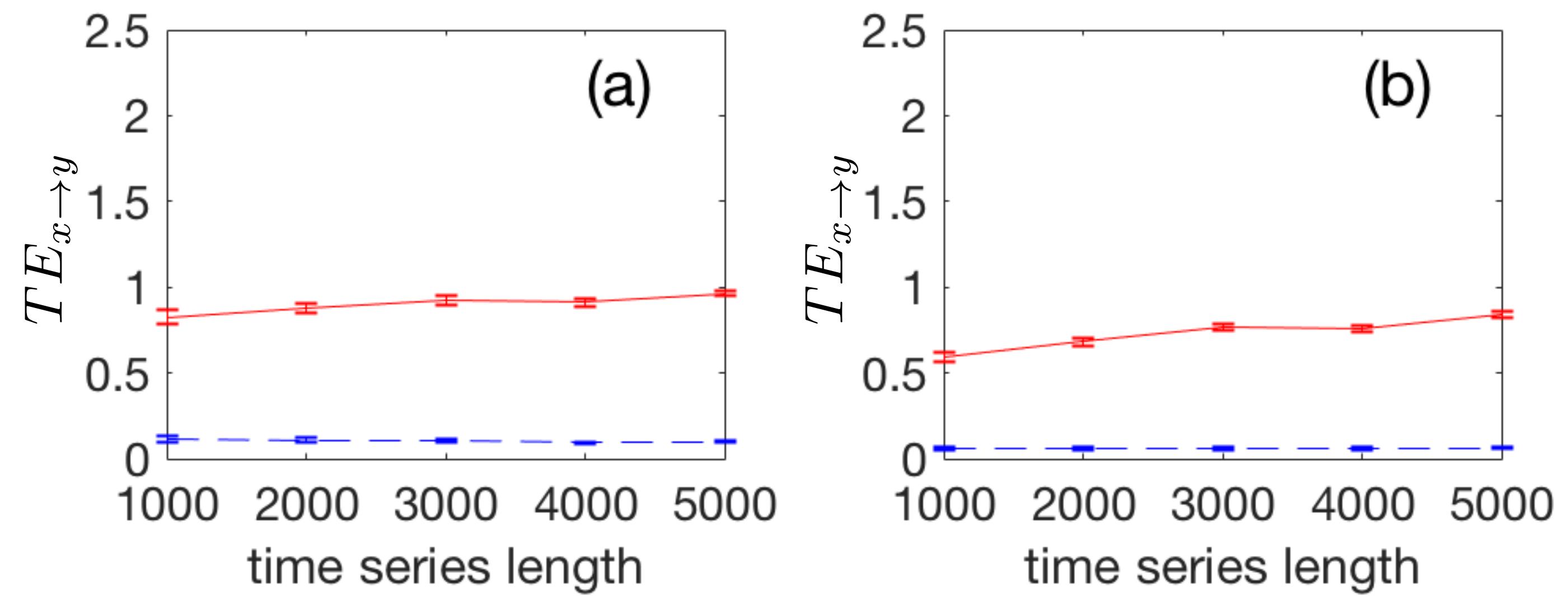
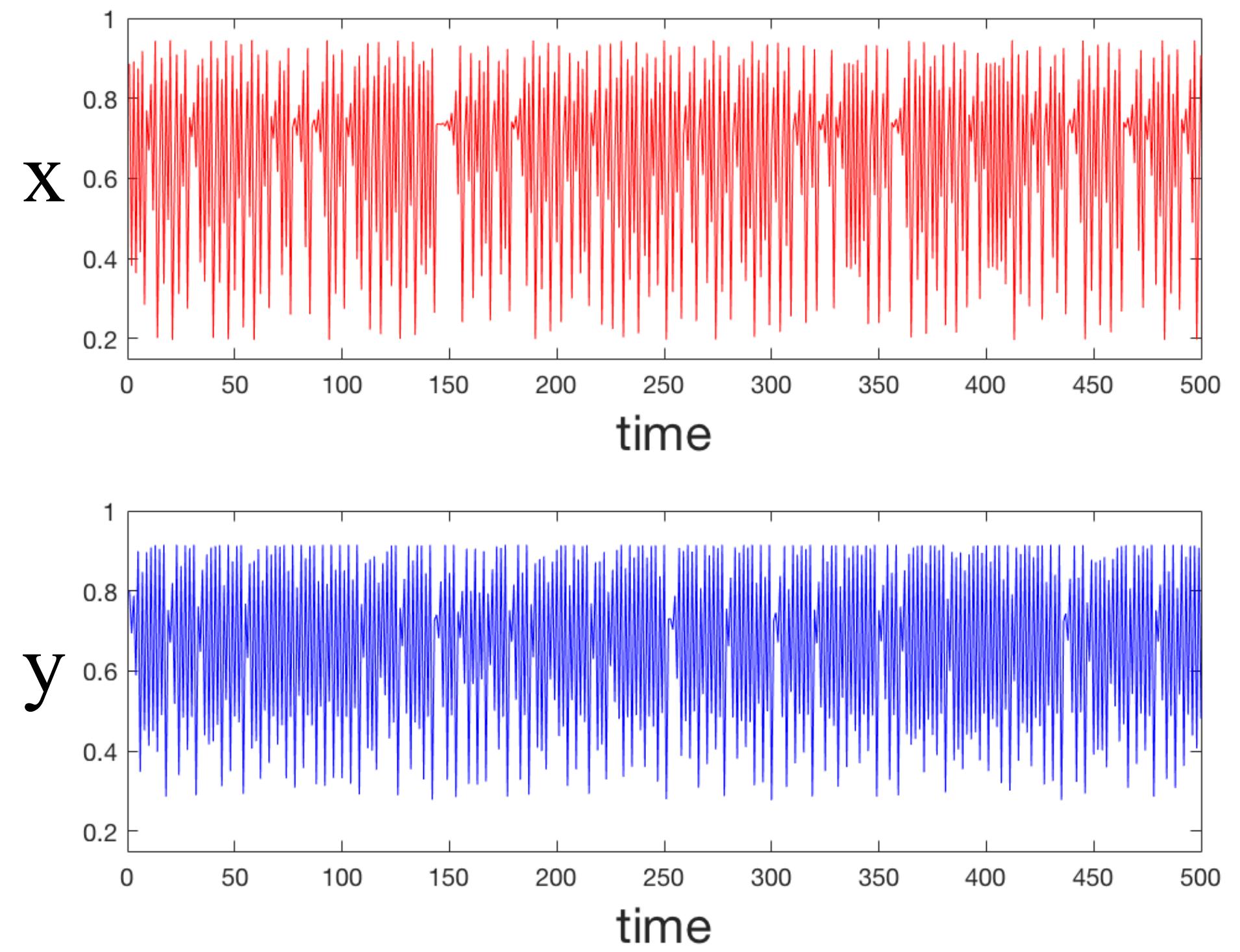
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$$P(i|j) = \frac{\sum_m P(i, j, m)}{\sum_r \sum_s P(r, j, s)}$$

$$TE(Y \rightarrow X) = \sum_{i,j,k} P(i, j, k) \log_2 \frac{P(i|j, k)}{P(i|j)}$$





(a) From the transfer matrix

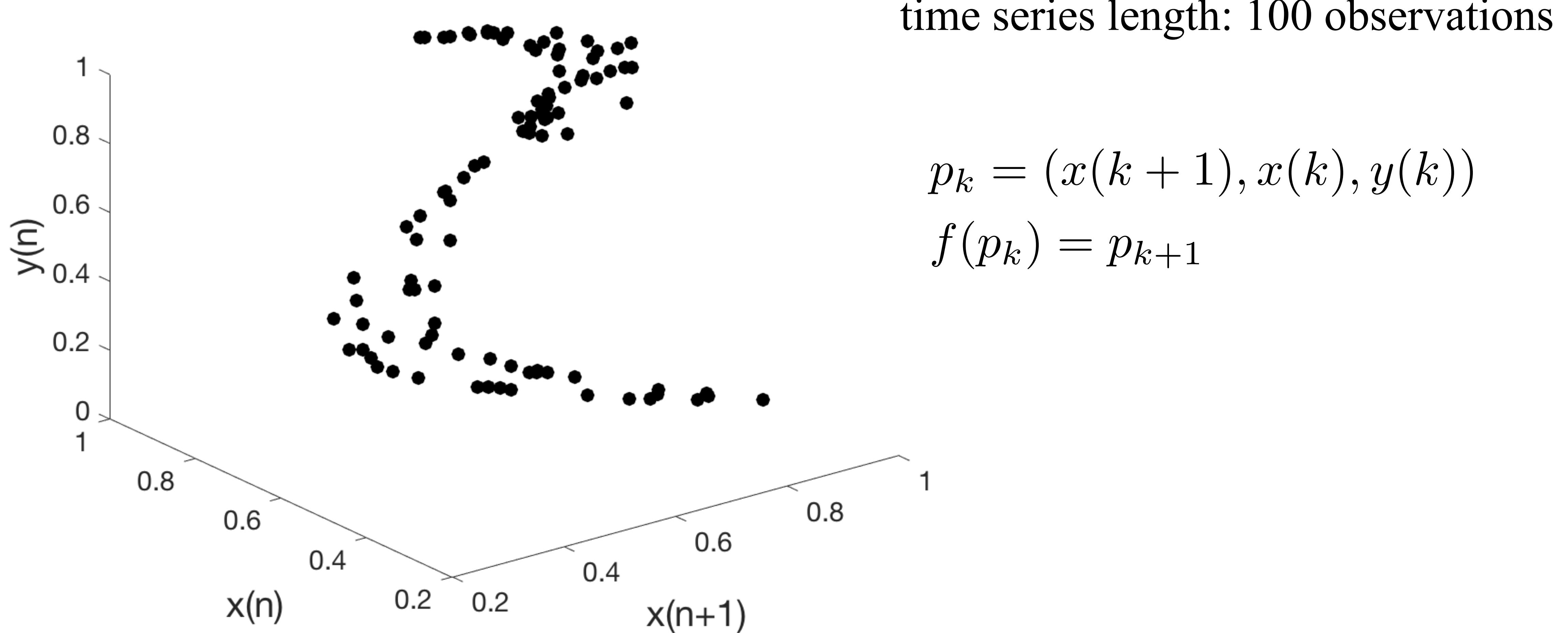
(b) From kernel density estimation

We know that the coupling
is unidirectional

$$x \rightarrow y$$

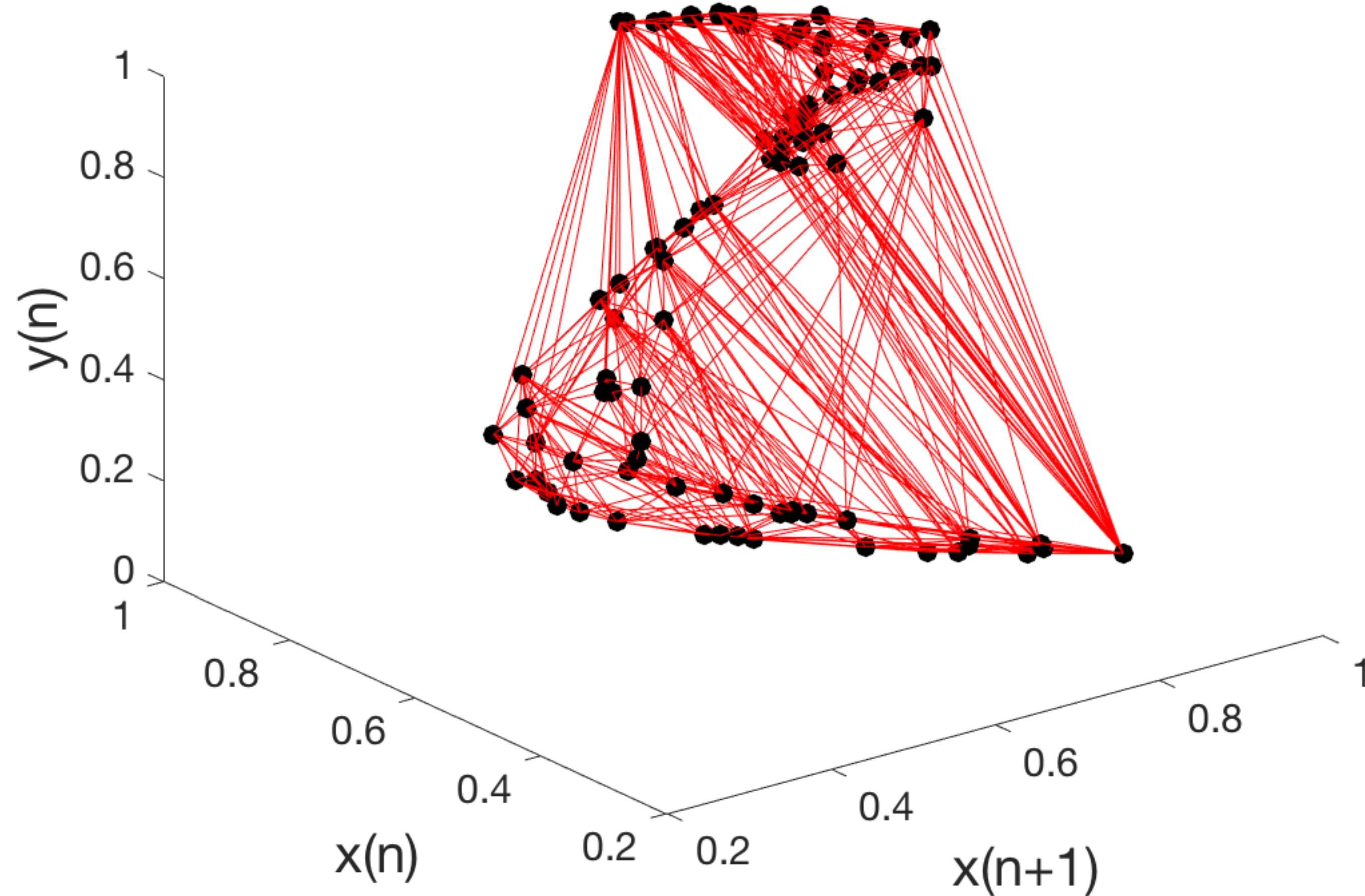
Steuer et al. (2002),
Bioinformatics 18, S231

Alternative approach for sparse time series: Triangulation approach



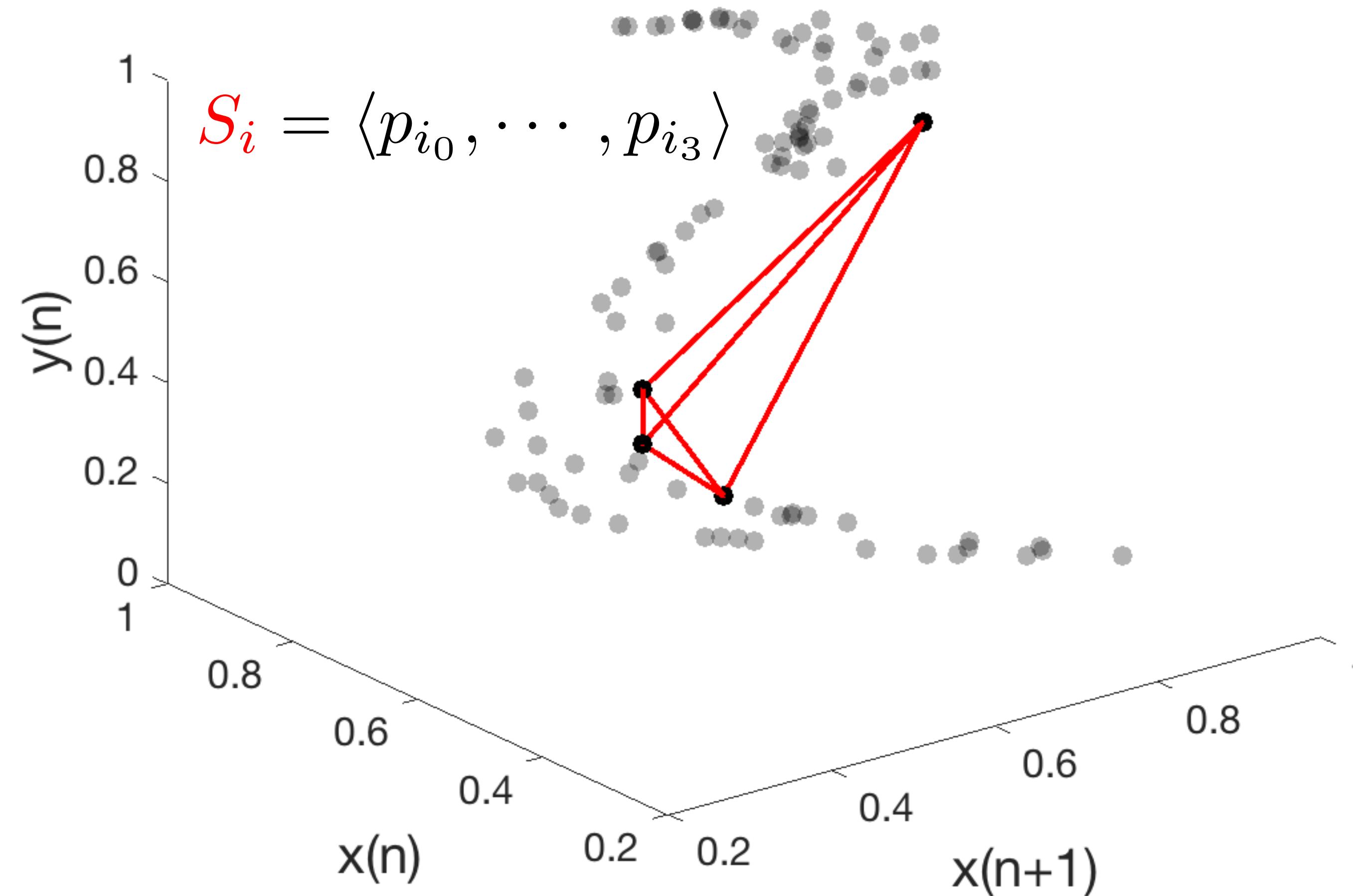
Triangulation approach

Each simplex is formed by 4 embedded points



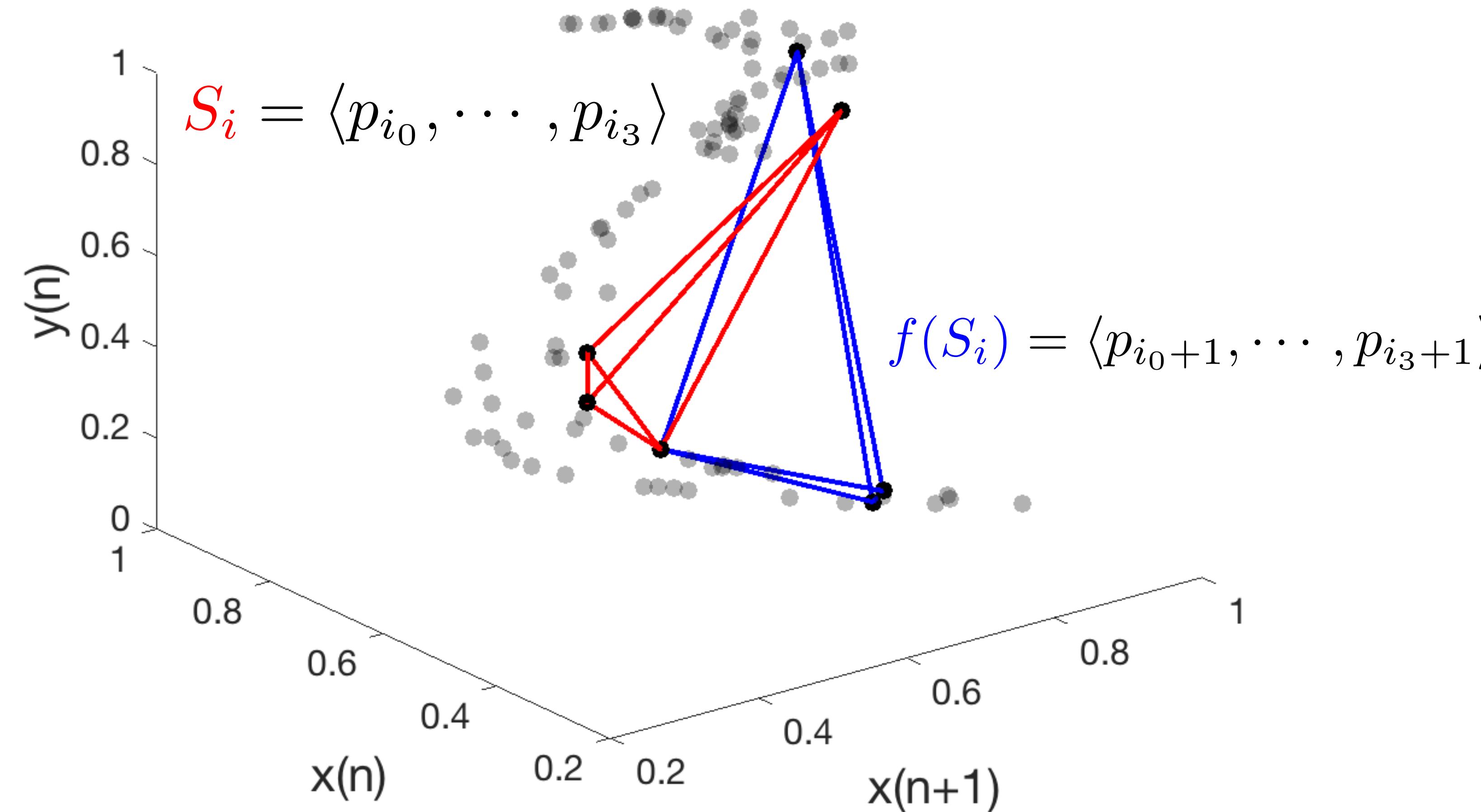
Triangulation approach

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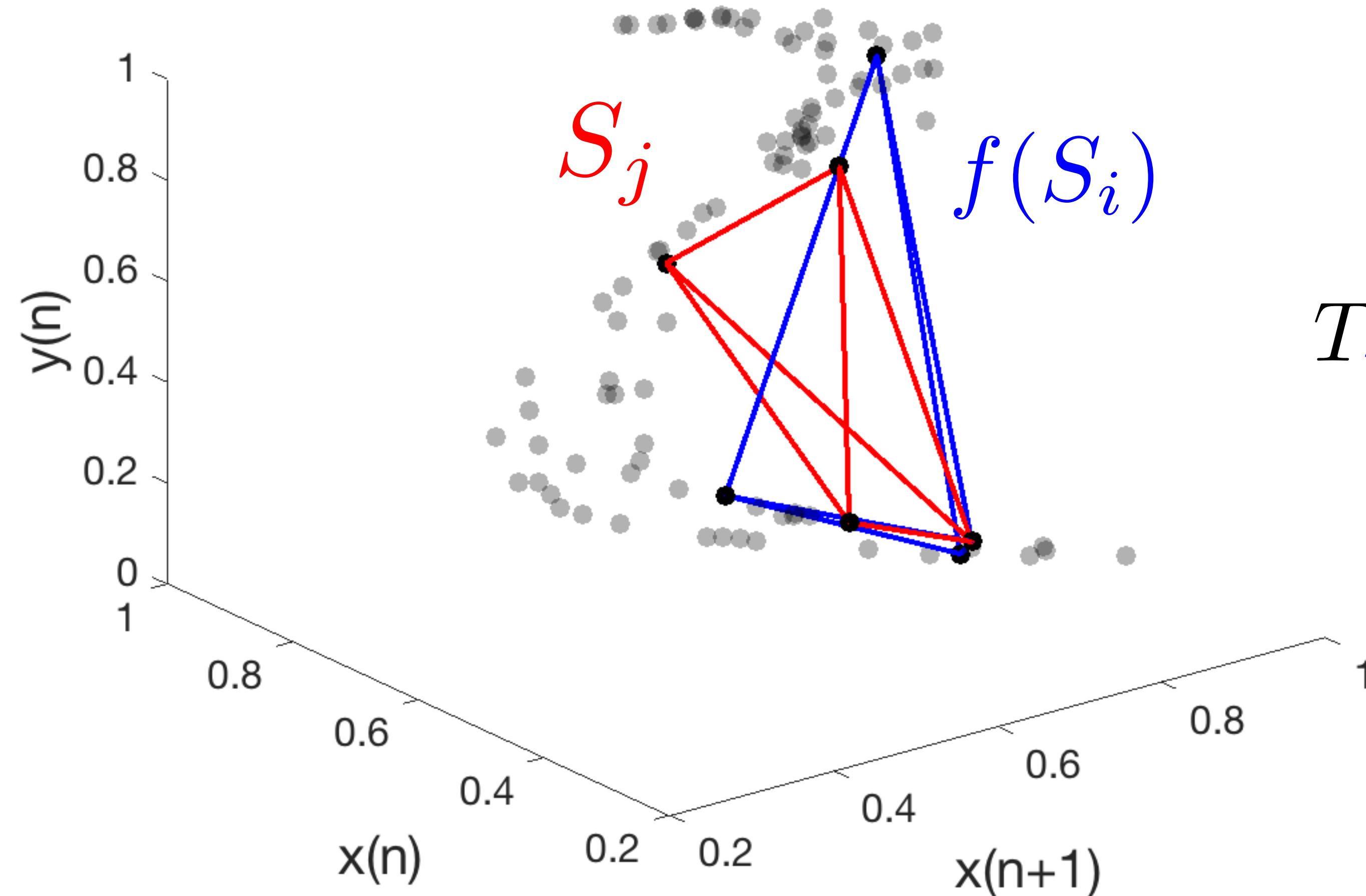


Triangulation approach

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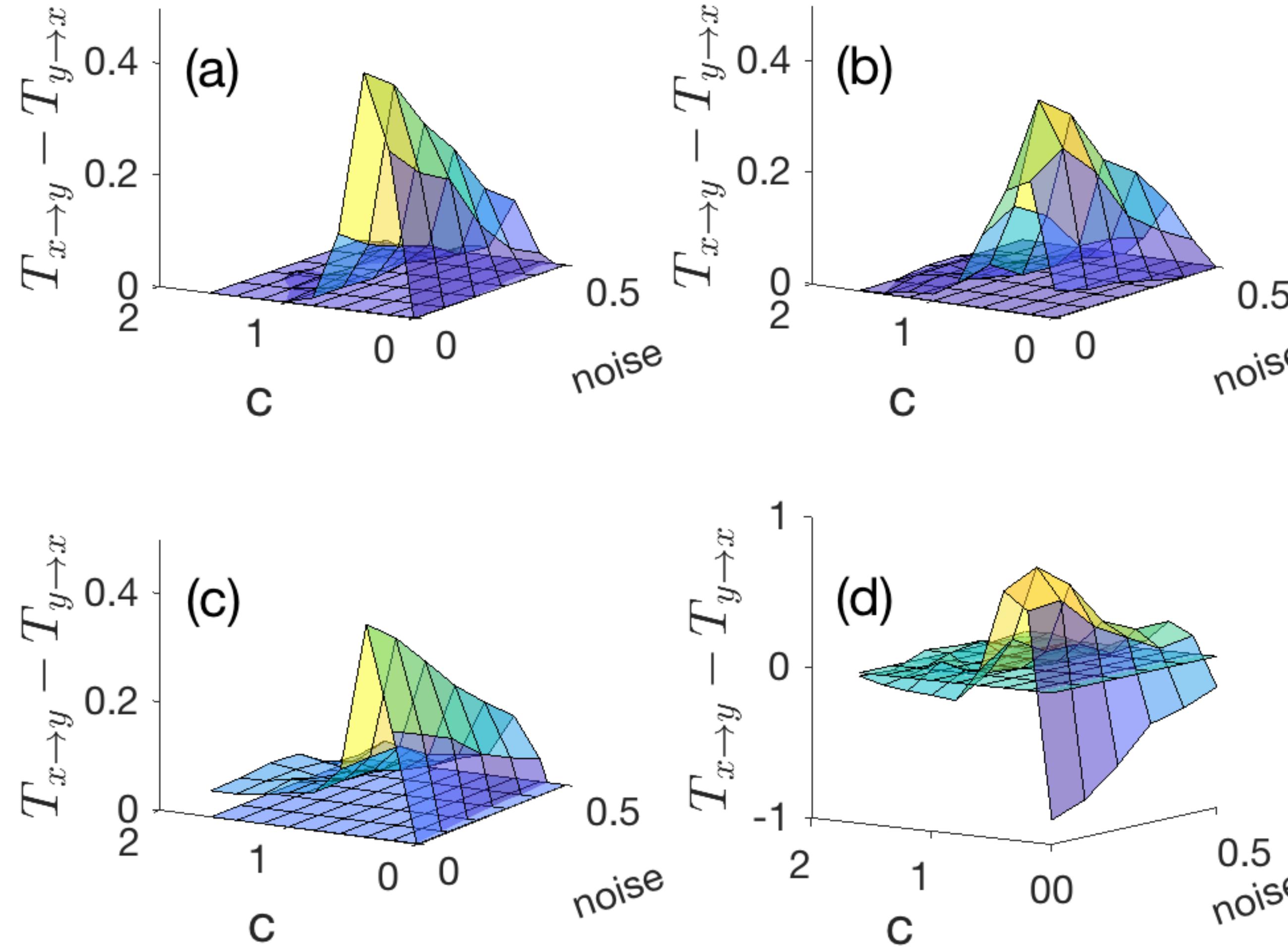


Triangulation approach



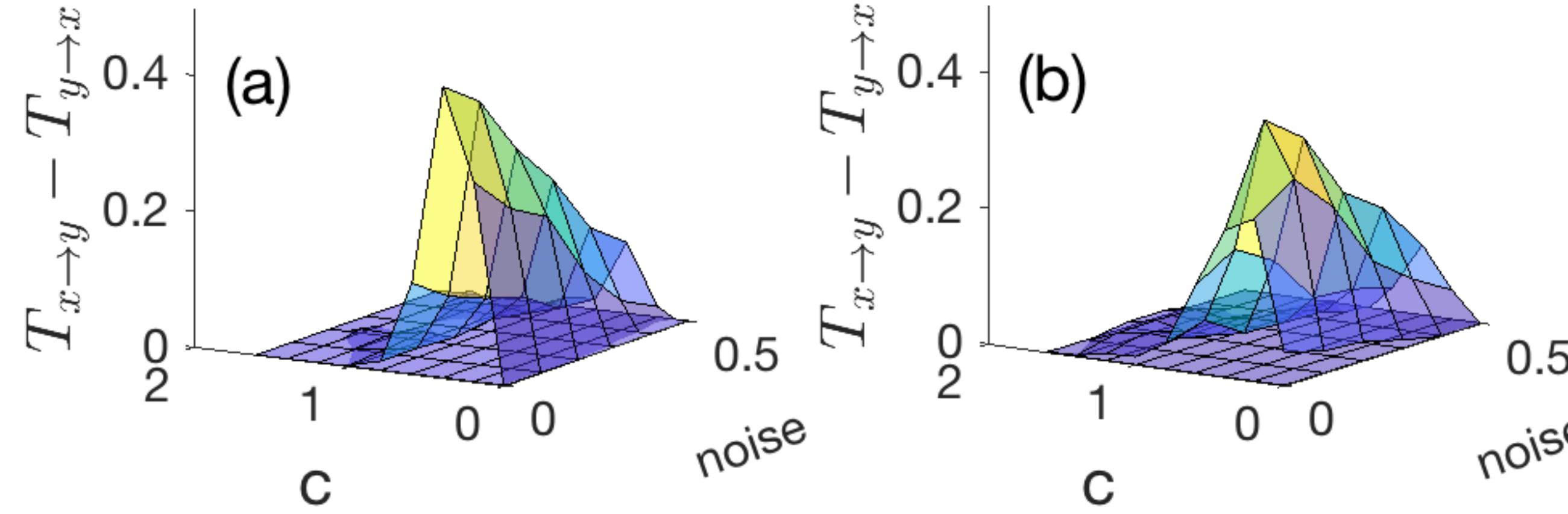
$$T_{ij} = \frac{vol(f(S_i) \cap S_j)}{vol(f(S_i))}$$

The transfer matrix approach is robust for sparse and noisy time series



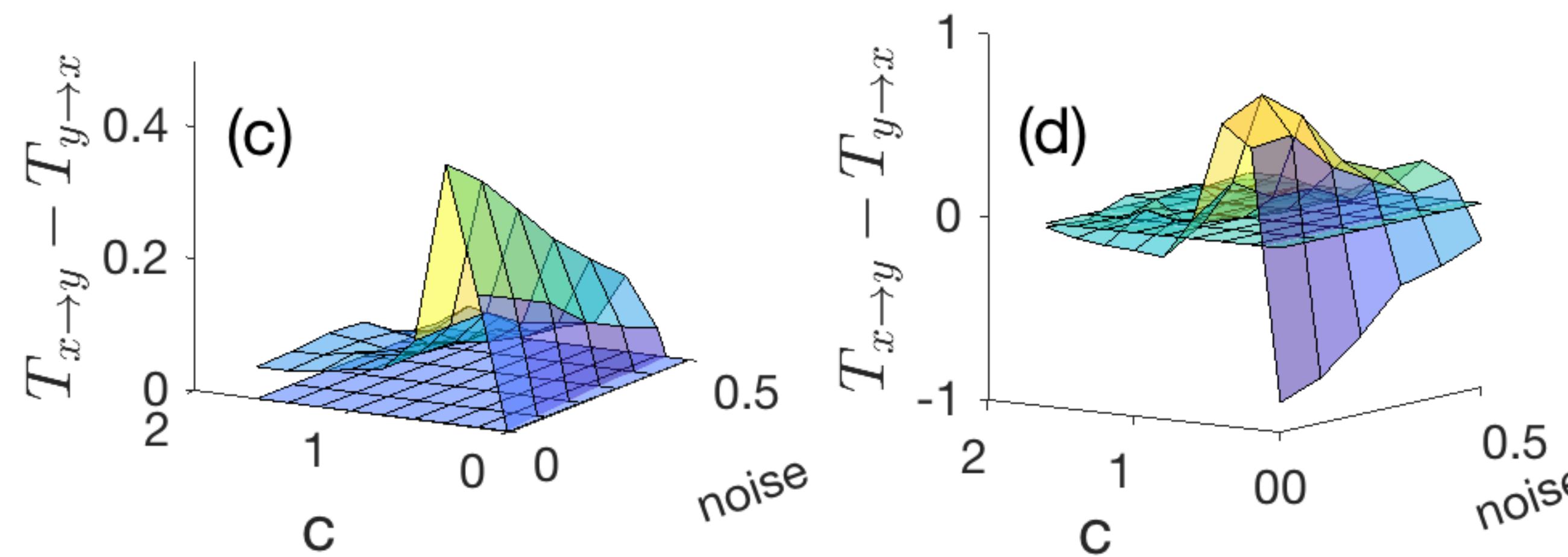
time series length: 100 observations

The transfer matrix approach is robust for sparse and noisy time series



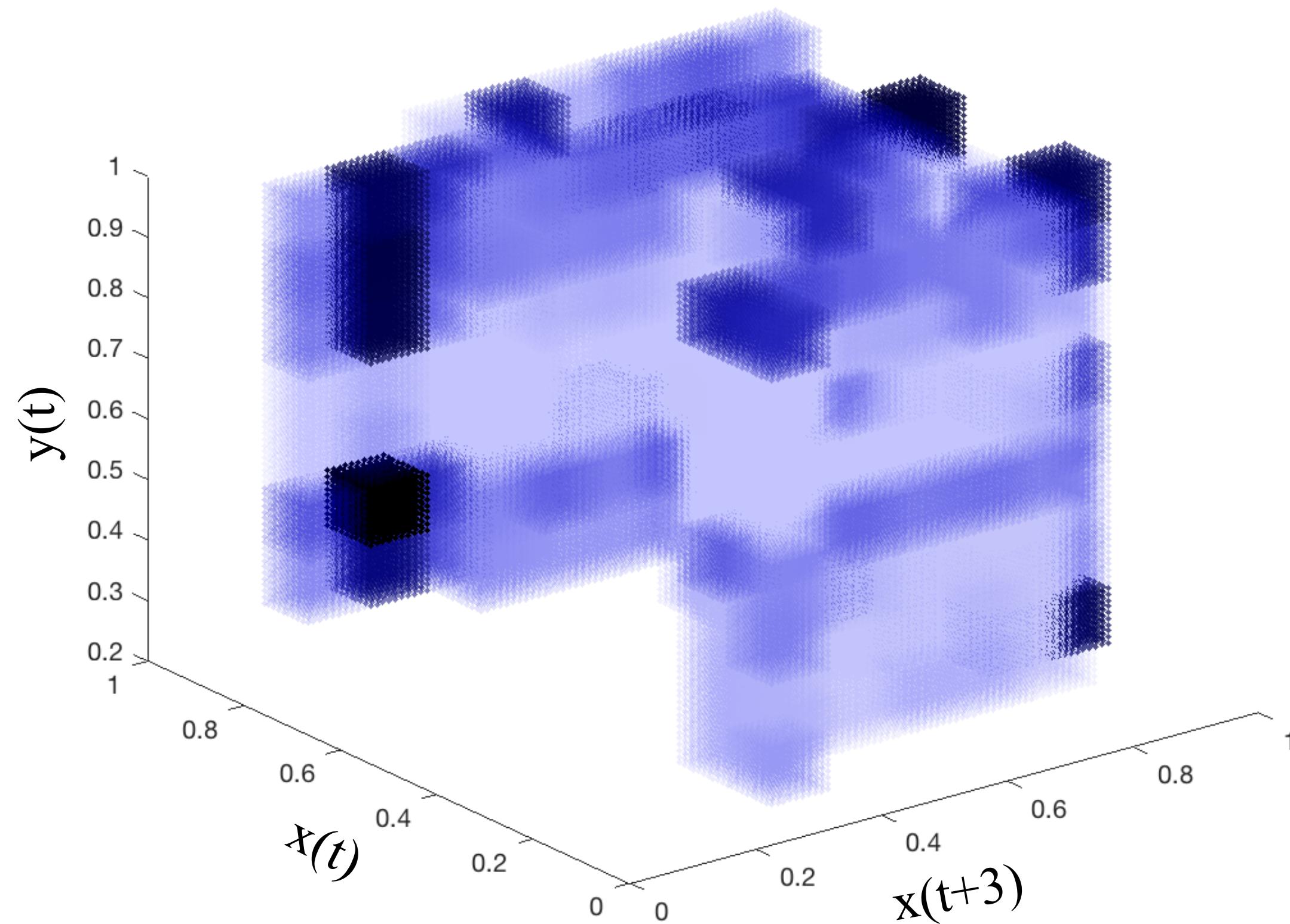
- (a) trans. matrix
- (b) trans. matrix (triangulation approach)
- (c) kernel density estimation
- (d) nearest neighbors counting

Kraskov et al. (2004), Phys Rev E 69

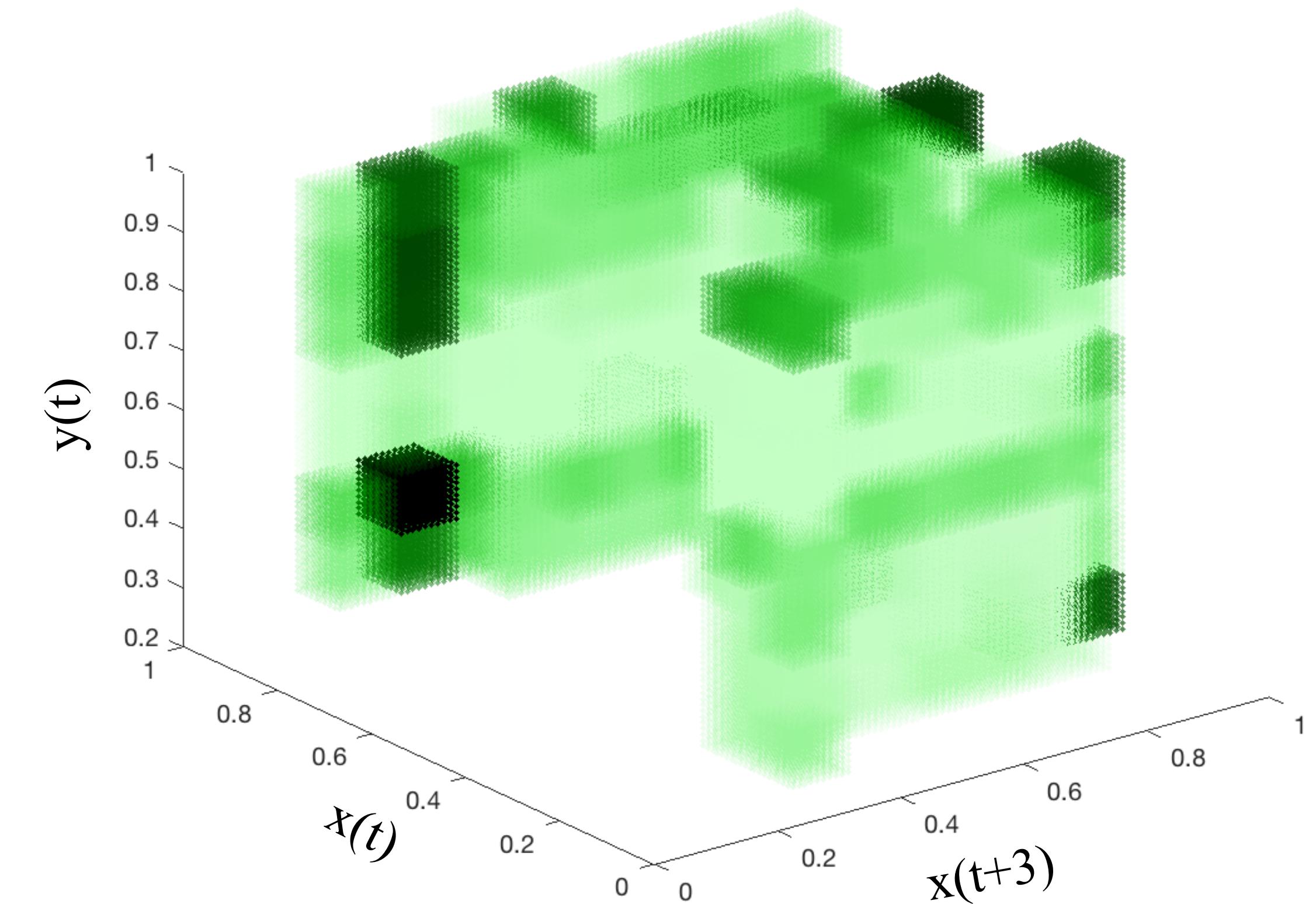


time series length: 100 observations

ρ from the visitation freq.



ρ from the transfer matrix



Why then bother with the transfer matrix?

The transfer matrix approximates the dynamical behavior

It enables a number of possibilities:

- Extension and/or interpolation of time series.
- Generation of null hypotheses for causality testing.
- Revealing important aspects of long term behavior:

Attracting regions on the phase space

Estimating fractal dimensions of the attractor

In summary

More info/details in:

<https://github.com/kahaaga/CausalityTools.jl>

and

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THANKS