view\_frames Result Recorded at time: 1654072267.701 dummy\_link Broadcaster: /robot\_state\_publisher Broadcaster: /my\_tf2\_broadcaster Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 0.000 ( 1654072267.701 sec old) Most recent transform: 1654072267.670 ( 0.031 sec old) Buffer length: 4.900 sec Buffer length: 0.000 sec base\_link camera\_link Broadcaster: /robot\_state\_publisher Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 1654072267.672 ( 0.029 sec old) Most recent transform: 0.000 ( 1654072267.701 sec old) Most recent transform: 0.000 ( 1654072267.701 sec old) Most recent transform: 0.000 ( 1654072267.701 sec old) Buffer length: 4.900 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec camera\_color\_frame camera\_aligned\_depth\_to\_color\_frame Link1 camera\_depth\_frame Broadcaster: /robot\_state\_publisher Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Average rate: 10.204 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1654072267.701 sec old) Most recent transform: 0.000 ( 1654072267.701 sec old) Most recent transform: 1654072267.672 ( 0.029 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec Link2 camera\_depth\_optical\_frame camera\_color\_optical\_frame Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1654072267.672 ( 0.029 sec old) Buffer length: 4.900 sec Link3 Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1654072267.672 ( 0.029 sec old) Buffer length: 4.900 sec Link4 Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1654072267.672 ( 0.029 sec old) Buffer length: 4.900 sec Link5 Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Most recent transform: 1654072267.672 ( 0.029 sec old) Buffer length: 4.900 sec Link6 Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1654072267.701 sec old) Buffer length: 0.000 sec panda\_hand Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1654072267.672 ( 0.029 sec old) Most recent transform: 1654072267.672 ( 0.029 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec panda\_leftfinger panda\_rightfinger