

view_frames Result

Recorded at time: 8.344

robot1_tf/odom

Broadcaster: /gazebo
Average rate: 30.199
Buffer length: 4.967
Most recent transform: 8.333
Oldest transform: 3.366

robot1_tf/base_footprint

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1_tf/base_link

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1_tf/Lidar_v2_1

Broadcaster: /robot1/robot_state_publisher
Average rate: 30.199
Buffer length: 4.967
Most recent transform: 8.334
Oldest transform: 3.367

robot1_tf/right_back_wheel_v2_1

Broadcaster: /robot1/robot_state_publisher
Average rate: 30.199
Buffer length: 4.967
Most recent transform: 8.334
Oldest transform: 3.367

robot1_tf/Driving_Wheel_Nylon_v2_1