

Lecture 15

Code generation part 2

Code generation

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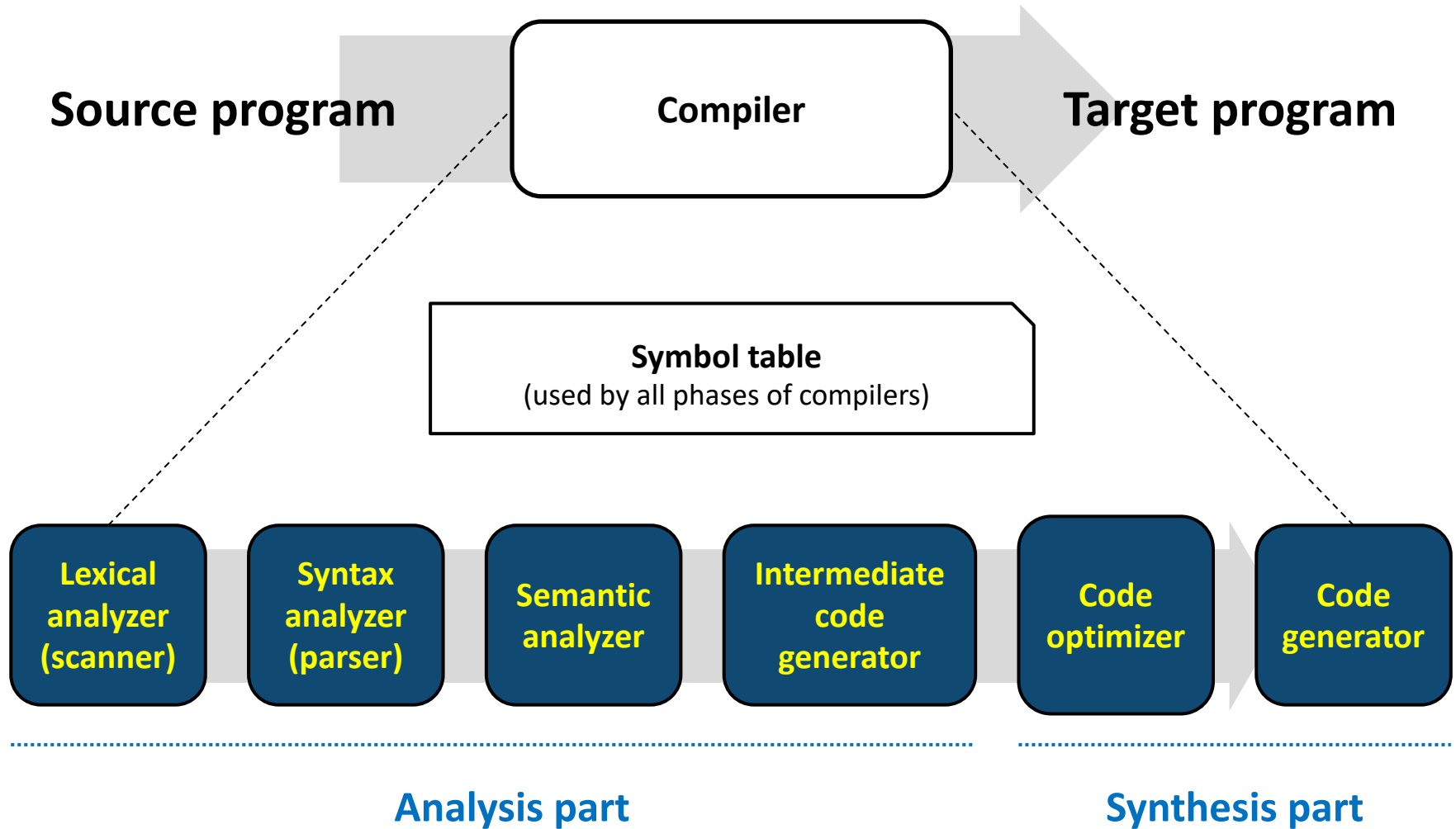
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Overview



Code generator

Translates an intermediate representation (e.g., three address code) into a machine-level code (e.g., assembly code)



- Data copy operations
- Arithmetic operations
- Comparison operators
- Control jumps

**Q. How to support
such high-level structures
in machine-level code???**

- Data copy operations
- Arithmetic operations
- Comparison operators
- Control jumps

- **Objects**

(primitive type variables, arrays, ...)

- **Function calls**

- **Parameter passing**

Runtime environment!!

Code generator

Translates an intermediate representation (e.g., three address code) into a machine-level code (e.g., assembly code)



Goal of this stage

- Choose the appropriate machine instructions for each intermediate representation instruction
 - With the use of runtime environments
- Efficiently allocate finite machine resources (e.g., registers, caches, ...)

Assembly languages

Any low-level (machine-level) programming language

Each assembly language is specific to a particular computer architecture

In our class, we shall use a **MIPS** computer as our target machine

MIPS: Microprocessor without Interlocked Pipelined Stages

- MIPS-based processors were the best selling processors (in the 90s)
- Tons of embedded systems are still using MIPS
- All other mainstream CPU architectures (e.g., x86) also work in a similar way with MIPS

MIPS assembly

Characteristics

- Only load and store instructions access memory
- All other instructions (e.g., arithmetic instructions) use **registers** as operands
- **Register??** dedicated memory locations that
 - Can be accessed quickly
 - Can have computations performed on them
 - But, exist in small quantity
 - **So, it is very important to manage registers properly and efficiently**
- MIPS has 32 general purpose registers

MIPS assembly

Especially, in this class,

- We use a **32-bit** machine architecture
 - Assuming that all objects are **4-byte aligned**
- We use only **two types of registers**
 - **\$sp**: a register for storing a stack pointer which points the next location of the top-of-stack
 - **\$r0, \$r1, ...**: registers for storing temporary values
- We assume that there are **an infinite number** of registers (\$r0, \$r1,)
- We translate **each piece of intermediate representations directly to assembly**

MIPS assembly

Basic instructions

- *lw reg1 offset(reg2)*: load 32-bit word from address $\text{reg2} + \text{offset}$ into reg1
- *sw reg1 offset(reg2)*: store 32-bit word in reg1 at address $\text{reg2} + \text{offset}$
- *add reg1 reg2 reg3*: $\text{reg1} = \text{reg2} + \text{reg3}$
 - *mul reg1 reg2 reg3*: $\text{reg1} = \text{reg2} * \text{reg3}$
 - *sub reg1 reg2 reg3*: $\text{reg1} = \text{reg2} - \text{reg3}$
 - *div reg1 reg2 reg3*: $\text{reg1} = \text{reg2} / \text{reg3}$
- *seq reg1 reg2 reg3*: $\text{reg1} = \text{reg2} == \text{reg3}$
 - *sne reg1 reg2 reg3*: $\text{reg1} = \text{reg2} != \text{reg3}$
 - *sgt reg1 reg2 reg3*: $\text{reg1} = \text{reg2} > \text{reg3}$
 - *sge reg1 reg2 reg3*: $\text{reg1} = \text{reg2} \geq \text{reg3}$
 - *slt reg1 reg2 reg3*: $\text{reg1} = \text{reg2} < \text{reg3}$
 - *sle reg1 reg2 reg3*: $\text{reg1} = \text{reg2} \leq \text{reg3}$

MIPS assembly

Basic instructions

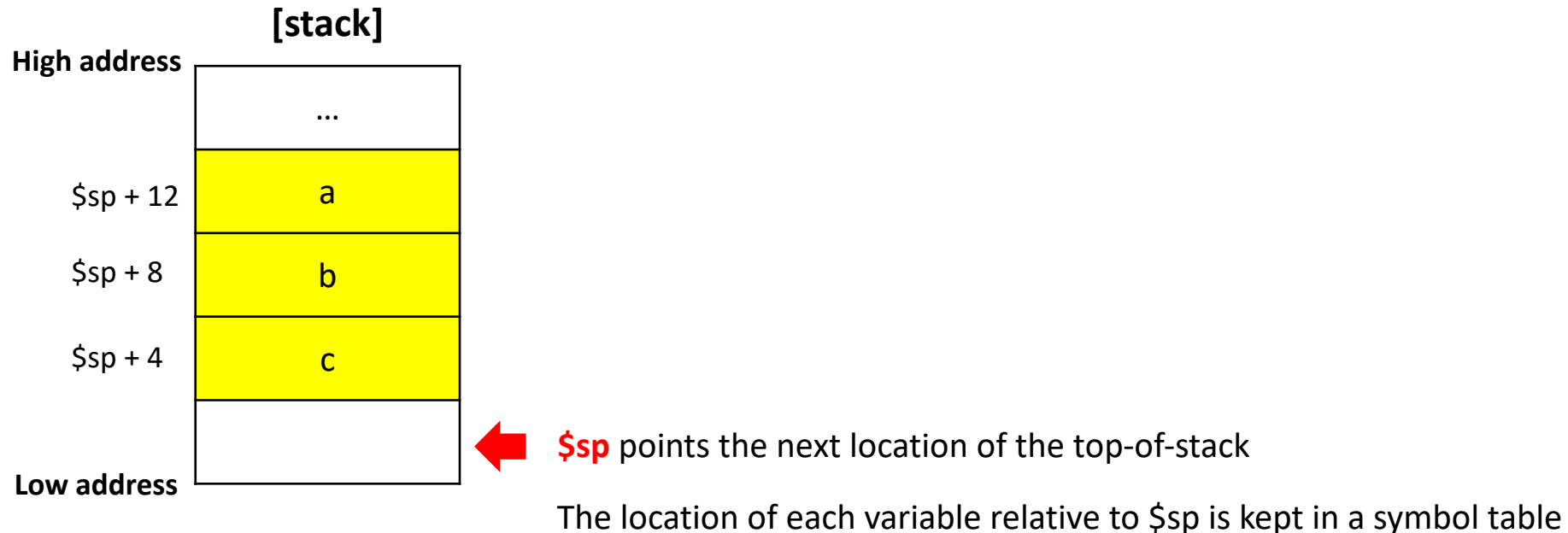
- *li reg1 immediate* (e.g., constant numbers): $\text{reg1} = \text{immediate}$
- *addi (subi, muli, or divi) reg1 reg2 immediate*: $\text{reg1} = \text{reg2} + \text{immediate}$
- *seqi (snei, sgti, sgei, slti, or slei) reg1 reg2 immediate*: $\text{reg1} = \text{reg2} == \text{immediate}$

Code generation for simple operations

Let's suppose that we have a TAC: "**a** = **b** + **c**"

When we execute the TAC, the variables (a, b, and c) already exist in the stack

Because they are the local variables used in the currently-running function



Code generation for simple operations

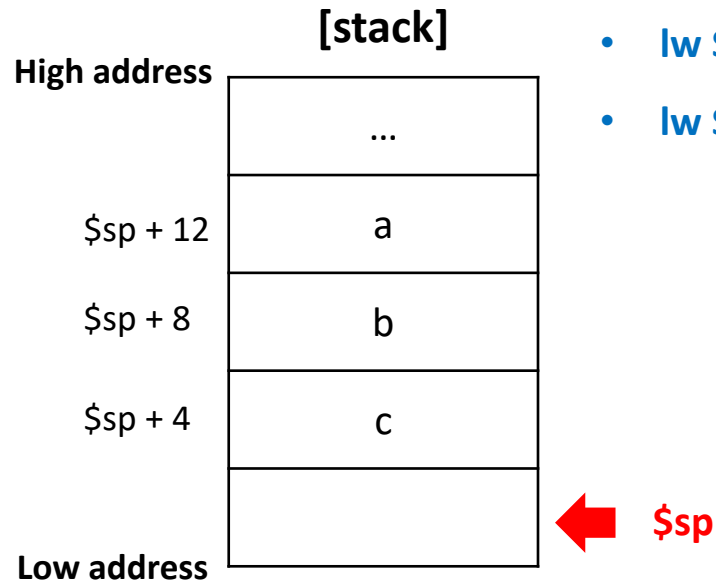
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When we execute the TAC, the variables (a, b, and c) already exist in the stack

Because they are the local variables used in the currently-running function

Step1: Load variables from memory to registers

- **lw \$r0 8(\$sp)**
- **lw \$r1 4(\$sp)**

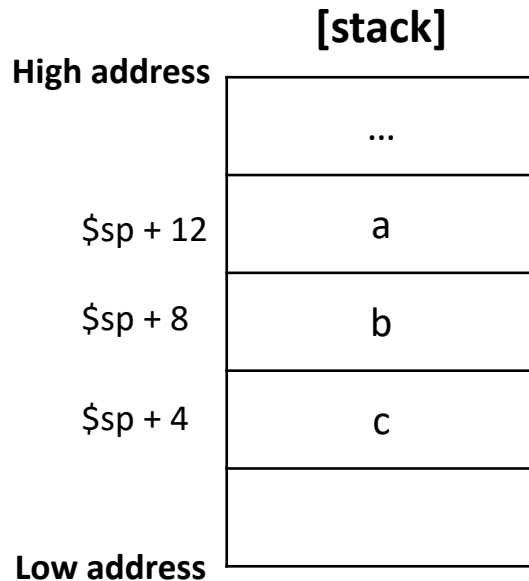


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Because they are the local variables used in the currently-running function



Step1: Load variables from memory to registers

- lw \$r0 8(\$sp)
- lw \$r1 4(\$sp)

Step2: Do the add operation with registers

- **add \$r2 \$r0 \$r1**

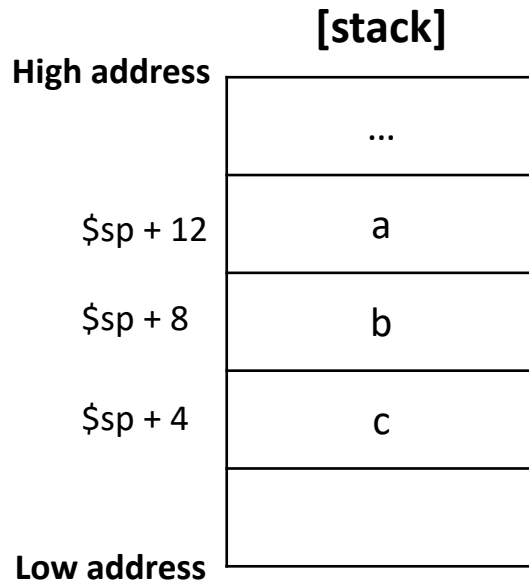


Code generation for simple operations

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Step1: Load variables from memory to registers

- lw \$r0 8(\$sp)
- lw \$r1 4(\$sp)

Step2: Do the add operation with registers

- add \$r2 \$r0 \$r1

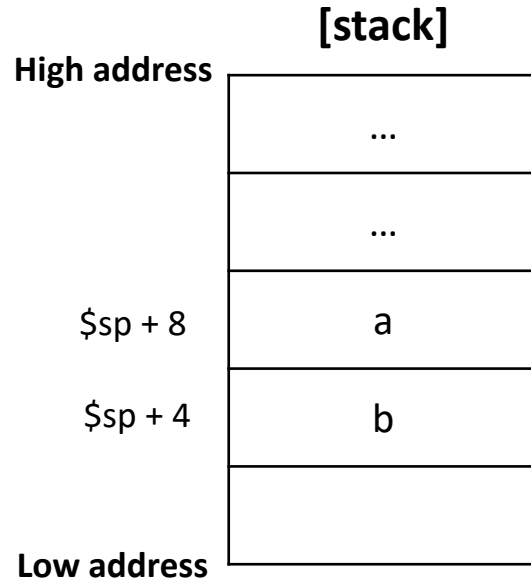
Step 3: Store the computation result to memory

- **sw \$r2 12(\$sp)**



Code generation for simple operations

Let's suppose that we have a TAC: **"a = b < 3"**



Step1: Load variables from memory to registers

- lw \$r0 4(\$sp)

**Step2: Do the comparison operation
with registers and immediate**

- slti \$r1 \$r0 3

Step 3: Store the computation result to memory

- sw \$r1 8(\$sp)

Code generation for conditional jumps

New MIPS assembly instructions for flow control

- ***j label***: unconditional jump to label (goto label)
- ***beq reg1 reg2 label***: if reg1 == reg2 goto label
 - Instead of beq, we can use bne (!=), bgt (>), bge (>=), blt (<), ble (<=)
- ***beqz reg1 label***: if reg1 == 0 goto label
 - Instead of beqz, we can use bnez (!= 0)
- ***beqi reg1 immediate label***: if reg1 == immediate goto label
 - Instead of beqi, we can use bnei (!=), bgti (>), bgei (>=), blti (<), blei (<=)

Code generation for conditional jump

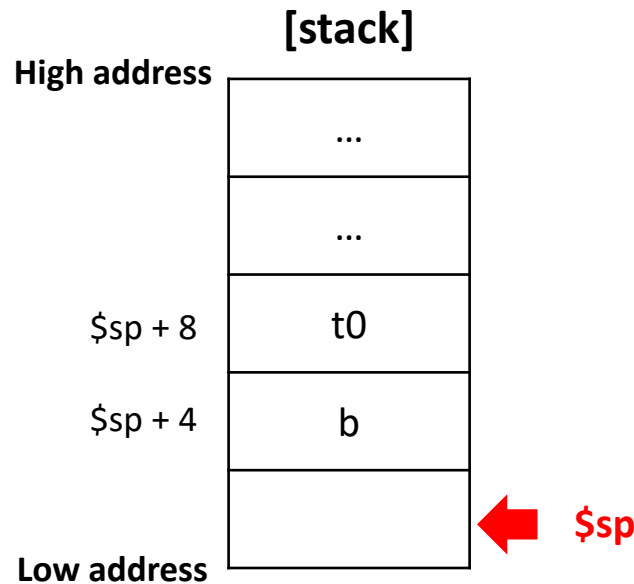
Example

[TAC]

$t0 = b < 3$

if $t0$ goto L0

L0:



[Assembly]

lw $\$r0$ 4($\$sp$)

slti $\$r1$ $\$r0$ 3

sw $\$r1$ 8($\$sp$)

lw $\$r0$ 8($\$sp$)

bnez $\$r0$ L0

L0:

Code generation for conditional jump

Practice

[TAC]

L0:

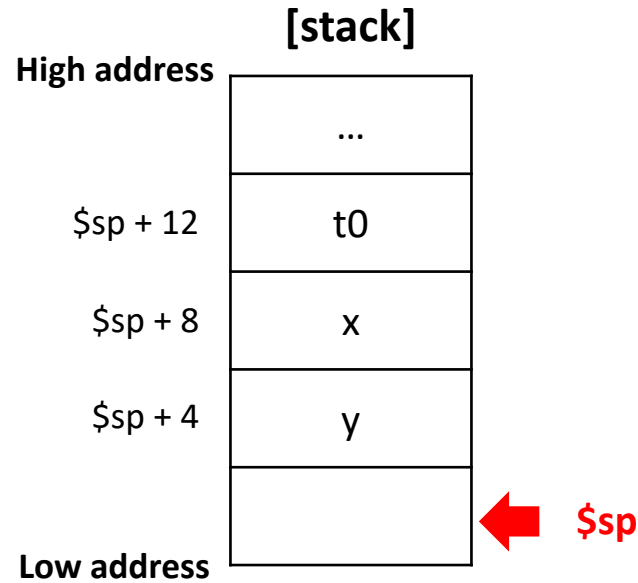
t0 = x < y

itnot t0 goto L1

x = x + 1

goto L0

L1:



Code generation for conditional jump

Practice

[TAC]

L0:

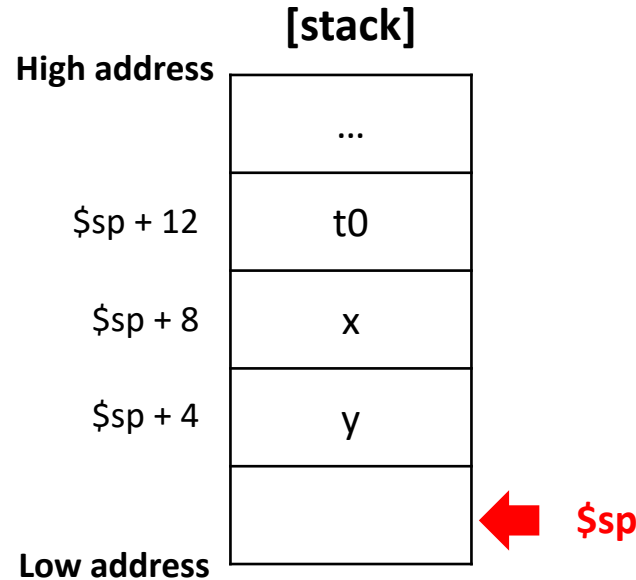
$t0 = x < y$

itnot t0 goto L1

$x = x + 1$

goto L0

L1:



[Assembly]

L0:

lw \$r0 8(\$sp)

lw \$r1 4(\$sp)

slt \$r2 \$r0 \$r1

sw \$r2 12(\$sp)

lw \$r0 12(\$sp)

beqz \$r0 L1

lw \$r0 8(\$sp)

addi \$r1 \$r0 1

sw \$r1 8(\$sp)

j L0

L1:

Code generation for function calls

Before foo() is called

- An activation record of main() is stored in a stack

[TAC]

begin foo

t0 = a + 1

return t0

end foo

begin main

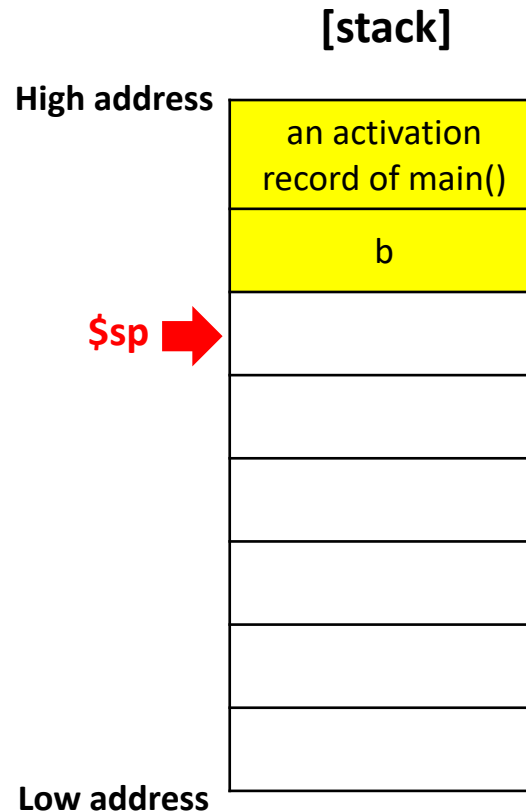
...

param 3

b = call foo, 1

...

end main



Code generation for function calls

When a function `foo()` is called in a function `main()`,

- Store an activation record of `foo()` into the stack

[TAC]

begin foo

`t0 = a + 1`

`return t0`

end foo

begin main

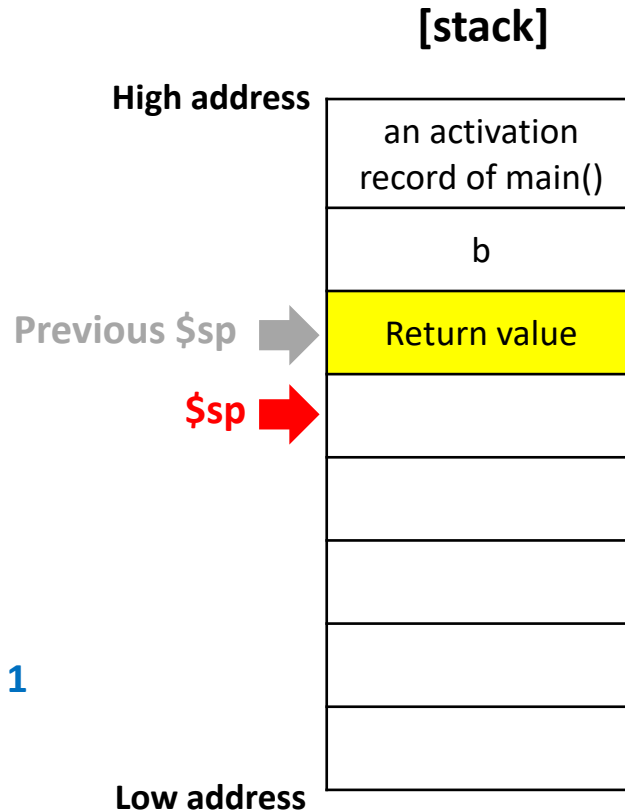
...

`param 3`

`b = call foo, 1`

...

end main



Create a space for the return value of `foo()`

- `subi $sp $sp 4`

Code generation for function calls

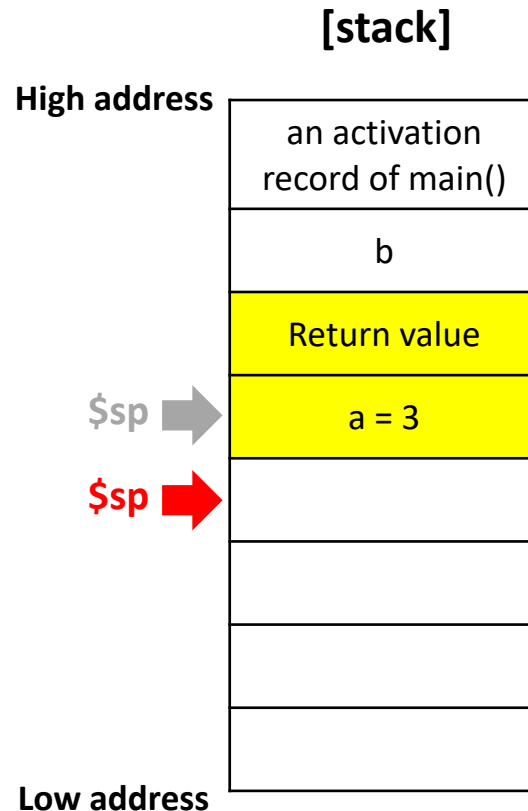
When a function `foo()` is called in a function `main()`,

- Store an activation record of `foo()` into the stack

[TAC]

```
begin foo
  t0 = a + 1
  return t0
end foo
```

```
begin main
  ...
  param 3
  b = call foo, 1
  ...
end main
```



Create a space for the return value of `foo()`

- `subi $sp $sp 4`

Store input parameters

- `li $r0 3`
- `sw $r0 0($sp)`
- `subi $sp $sp 4`

Code generation for function calls

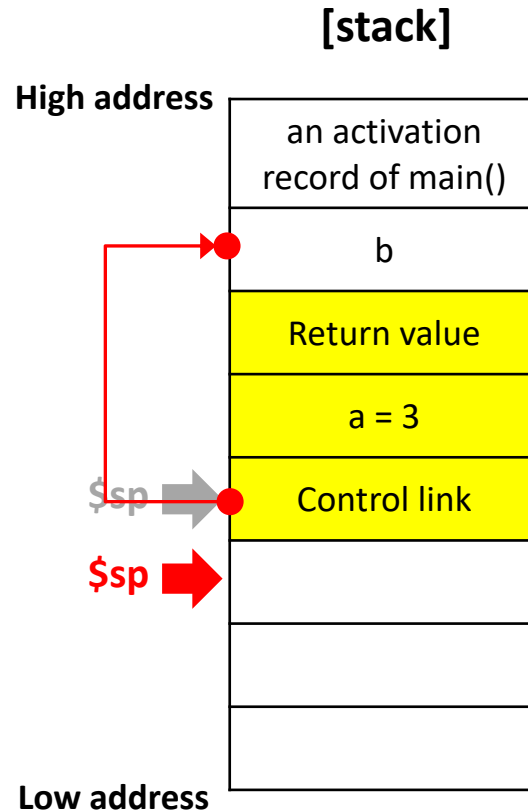
When a function `foo()` is called in a function `main()`,

- Store an activation record of `foo()` into the stack

[TAC]

```
begin foo
  t0 = a + 1
  return t0
end foo
```

```
begin main
  ...
  param 3
  b = call foo, 1
  ...
end main
```



Create a space for the return value of `foo()`

- `subi $sp $sp 4`

Store input parameters

- `li $r0 3`
- `sw $r0 0($sp)`
- `subi $sp $sp 4`

Store control link

(the start address of an activation record of `main()`)

- `addi $r0 $sp 12`
- `sw $r0 0($sp)`
- `subi $sp $sp 4`

Code generation for function calls

When a function `foo()` is called in a function `main()`,

- Store an activation record of `foo()` into the stack

[TAC]

begin foo

`t0 = a + 1`

`return t0`

end foo

begin main

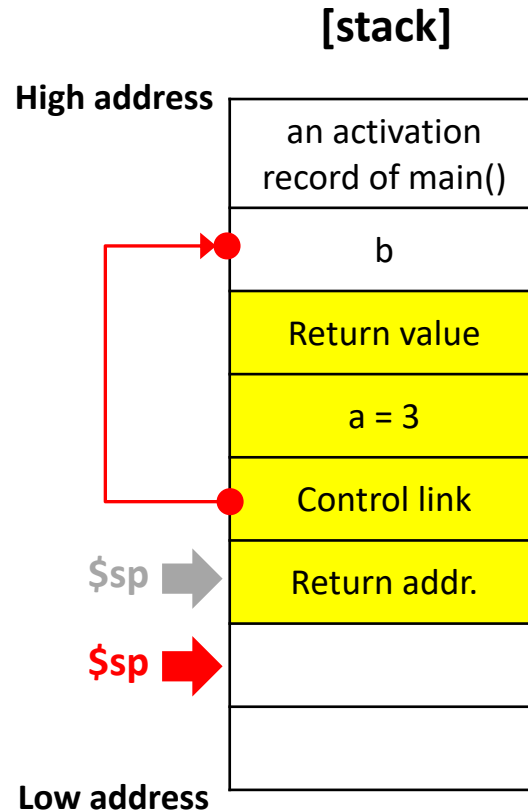
...

param 3

`b = call foo, 1`

...

end main



Store current machine status

(e.g., return address)

- `sw $ra 0($sp)`
(`$ra` is a register for return addresses)
- `subi $sp $sp 4`

Code generation for function calls

When a function `foo()` is called in a function `main()`,

- Store an activation record of `foo()` into the stack

[TAC]

begin foo

`t0 = a + 1`

 return t0

end foo

begin main

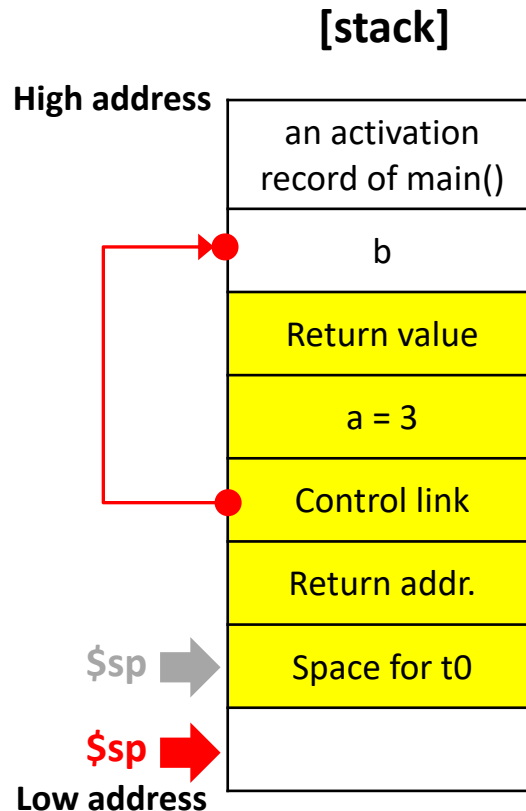
...

param 3

`b = call foo, 1`

...

end main



Store current machine status

(e.g., return address)

- `sw $ra 0($sp)`
(`$ra` is a register for return addresses)
- `subi $sp $sp 4`

Create a space for the local variables of `foo()`

(The information about which variable will be used in `foo()` is stored in a symbol table)

- `subi $sp $sp 4`

Code generation for function calls

When a function `foo()` is executed,

[TAC]

begin foo

t0 = a + 1

return t0

end foo

begin main

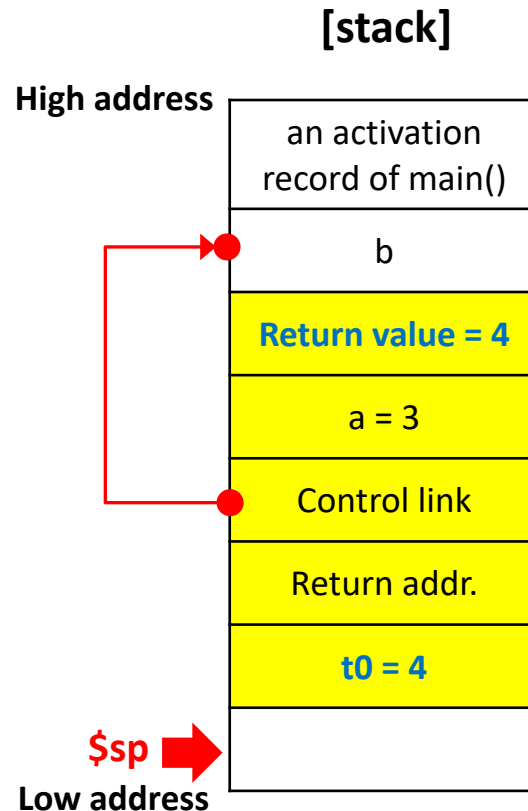
...

param 3

b = call foo, 1

...

end main



Compute t0 = a + 1

- lw \$r0 16(\$sp)
- addi \$r1 \$r0 1
- sw \$r1 4(\$sp)

Store the return value (t0)

- lw \$r0 4(\$sp)
- sw \$r0 20(\$sp)

Code generation for function calls

When the execution of a function foo() is completed

Restore machine status (e.g., return address)

- lw \$ra 8(\$sp)

[TAC]

begin foo

t0 = a + 1

return t0

end foo

begin main

...

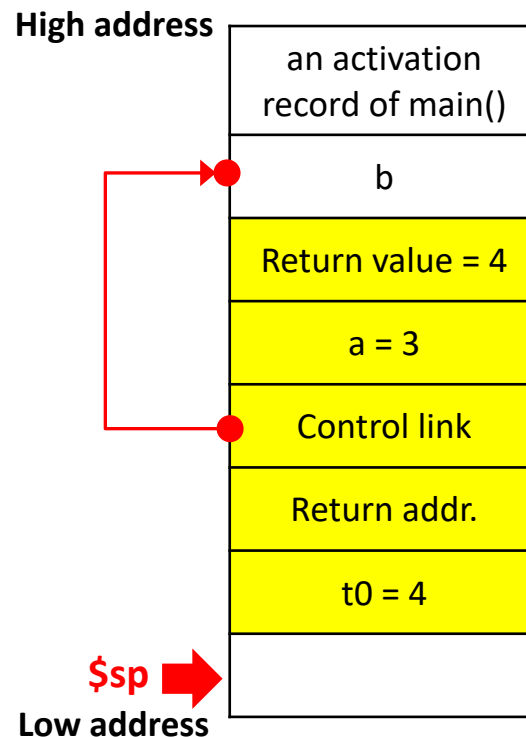
param 3

b = call foo, 1

...

end main

[stack]



Code generation for function calls

When the execution of a function foo() is completed

[TAC]

begin foo

t0 = a + 1

return t0

end foo

begin main

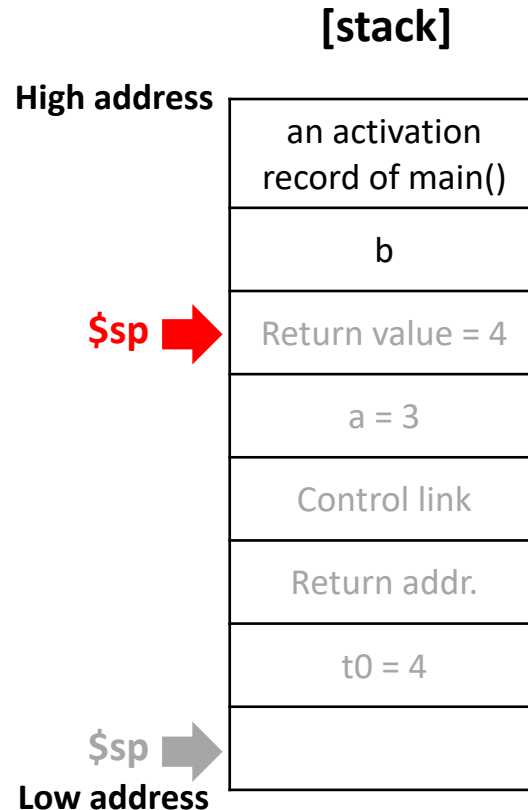
...

param 3

b = call foo, 1

...

end main



Restore machine status (e.g., return address)

- lw \$ra 8(\$sp)

The activation record of foo() is popped out

(Just move \$sp to the address
to which the control link points)

- lw \$r0 12(\$sp)
- subi \$sp \$r0 4

Code generation for function calls

When the execution of a function foo() is completed

[TAC]

begin foo

t0 = a + 1

return t0

end foo

begin main

...

param 3

b = call foo, 1

...

end main

[stack]

High address

\$sp →

an activation record of main()
b = 4
Return value = 4
a = 3
Control link
Return addr.
Space for t0 = 4

Low address

Restore machine status (e.g., return address)

- lw \$ra 8(\$sp)

The activation record of foo() is popped out

(Just move \$sp to the address to which the control link points)

- lw \$r0 12(\$sp)
- subi \$sp \$r0 4

Go back to the return address and do work!

- **jr \$ra** (Jump to the address in \$ra)
- lw \$r0 0(\$sp) (copy the return value)
- sw \$r0 4(\$sp)

Problems in our assumptions

Especially, in this class,

- We assume that there are an infinite number of registers (\$r0, \$r1,)

It is not realistic

- In practice, we have a limited number of registers
- We translate each piece of intermediate representations directly to assembly

It allows simplicity in generating assembly, but compromising efficiency

- It issues unnecessary loads and stores

Code generator

Translates an intermediate representation (e.g., three address code) into a machine-level code (e.g., assembly code)



Goal of this stage

- Choose the appropriate machine instructions for each intermediate representation instruction
 - With the use of runtime environments
- Efficiently allocate finite machine resources (e.g., registers, caches, ...)

Through a better register allocation!!