# Easton Yi HUANG

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## **EDUCATION**

Ph.D. in Mechanical & Aerospace Engineering

Rutgers University-New Brunswick, School of Engineering

Aug. 2024 - Present

M.Sc. in Mechanical Engineering

National University of Singapore, College of Design and Engineering

Aug. 2022 - Jan. 2024

B.Eng. in Mechanical Design & Manufacturing and Their Automation

Dalian University of Technology, School of Mechanical Engineering NUS Suzhou Research Institute Sep. 2018 - Jul. 2021

Sep. 2021 - Jul. 2022

RESEARCH EXPERIENCE

NextG-Enabled Manufacturing of the Future (NextGEM)

Rutgers, New Brunswick, USA

2024 - Present

• Keywords: Physics-Informed Machine Learning; Digital Twins; Manufacturing.

Digital Twins Integrated Finite Element Analysis

Instructor: Prof. Jingang Yi & Prof. Yuebin Guo

Instructor: Prof. Andrew Yeh Ching Nee & Prof. Ong Soh Khim

NUS, Singapore 2022 - 2024

• Keywords: Digital Twins; Structural Health Monitoring; Finite Element Analysis; Machine Learning; Surrogate Model.

Intelligent Machine Vision for Surface Condition Inspection Instructor: Prof. Wen Feng Lu NUSRI, Soochow, China

2021 - 2022

• Keywords: Machine Vision; Defect Detection; Deep Learning; Denoising.

Development of Height-adjustable Small Stool

 ${\bf Undergraduate\ Innovation\ and\ Entrepreneurship\ Training\ Program}$ 

DUT, Dalian, China 2021 - 2022

Instructor: Dr. Tieli Zhu

• Keywords: Structural Design and Optimization.

Material Damage Modeling based on Multi-sensor Data

DUT, Dalian, China

Undergraduate Innovation and Entrepreneurship Training Program at national level

2020 - 2021

Instructor: Prof. Wei Liu

• Keywords: Drilling of CFRP; Multisensor Measurement; Machine Learning.

# COURSE PROJECTS

• Dynamics for Biped Robot Walking

Module Name: Analytical Dynamics

• Spatio-temporal Prediction based on Data-driven Machine Learning: Earthquakes Case

Module Name: Data-Driven Engineering and Machine Learning

• Predicting Additive Manufacturing Parameters based on Acoustic Analysis

Module Name: Engineering Acoustics

• Calculate and Optimize the Carbon Emissions of Product

Module Name: Sustainable Product Design & Manufacturing

• Structural Design and Analysis of Quadruped Walking Robot

Module Name: Mechanical Design 1 Course Design

• Gear Reducer Design and Optimization

Module Name: Mechanical Design 2 Course Design

#### OTHER EXPERIENCE

- Teaching Assistant, Course: 14:650:401–Dynamic Systems and Controls (Fall 2025) 2025-2026, Rutgers University, Advisor: Prof. Annalisa Scacchioli
- Graduate Assistant

2024-2025, Rutgers University, Advisor: Prof. Jingang Yi

• China Robotics and Artificial Intelligence Competition

Smart Agriculture Contest, Instructors: Dr. Feilong Wang & Prof. Shenglan Liu

• Kaggle Competition

UW-Madison GI Tract Image Segmentation (UWMGI)

• Dalian University of Technology Varsity Self-Reliance Society

Vice President (Junior), Office Manager (Sophomore), Outreach Officer (Freshman)

## **AWARDS**

- Raisler Fellowship from Rutgers University.
- Dongguan Entrepreneur Scholarship in 2024.
- First Prize in China Robotics and Artificial Intelligence Competition.
- Learning Excellence Award in DUT.
- Honorary title of Outstanding Officer of Dalian University of Technology Self-Reliance Society.

### **PUBLICATIONS**

- C1. F. Han, Y. Huang, J. Yi. "Active Training Data Selection for Gaussian Process-Based Robot Dynamics Learning and Control," in *Proc. IEEE/RSJ Int. Conf. on Intell. Robots and Syst. (IROS)*, 2025, Hangzhou, China.
- C1. Y. Huang, F. Han, J. Yi. "Data-Efficient Learning-Based Estimation of Region of Attractions for Nonlinear Dynamic Systems," in *Proc. IEEE Int. Conf. Autom. Sci. Eng. (CASE)*, 2025, Los Angeles, CA, USA.
- C2. Y. Huang, F. Han, T. Zheng, L. Hu, J. Yi, Y. Guo. "Physics-Informed Machine Learning-Based Chattering Prediction in Milling Process," in *Proc. Amer. Control Conf. (ACC)*, 2025, Denver, CO, USA.
- C3. Y. Huang. "Intelligent Machine Vision for Detection of Steel Surface Defects with Deep Learning," in *Proc. IEEE Int. Conf. Smart Internet Things (SmartIoT)*, 2023, Xining, China.

# PAPER REVIEW

American Control Conference
IEEE International Conference on Automation Science and Engineering
IEEE International Conference on Intelligent Transportation Systems
IEEE International Conference on Robotics and Automation
2025
IEEE International Conference on Robotics and Automation