

Embracing ReFrame Programmable Configurations

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Outline

- ReFrame configuration overview
- Programmable configuration for containers
- User-Environment based programmable configuration
- Conclusions







ReFrame configuration overview

The two flavors of ReFrame configuration (1 / 2)

```
site_configuration = {
    'systems': [
             'name': 'daint',
            'descr': 'Piz Daint Supercomputer',
            'hostnames': ['daint'],
            'modules_system': 'tmod32',
             'partitions': [
                     'name': 'gpu',
                     'descr': 'Hybrid nodes',
                     'scheduler': 'slurm',
                     'launcher': 'srun',
                     'access': ['-C gpu', '-A csstaff'],
                     'environs': ['gnu', 'intel', 'nvidia', 'cray'],
                     'max jobs': 100,
    'environments': [
             'name': 'gnu',
            'modules': ['PrgEnv-gnu'],
            'cc': 'cc',
             'cxx': 'CC',
            'ftn': 'ftn',
            'target_systems': ['daint']
```

```
"systems": [
    "name": "daint",
   "descr": "Piz Daint Supercomputer",
   "hostnames": [
     "daint"
   "modules system": "tmod32",
    "partitions": [
        "name": "gpu",
        "descr": "Hybrid nodes",
       "scheduler": "slurm",
       "launcher": "srun",
        "access": [
         "-C gpu",
         "-A csstaff"
        "environs": [
          "gnu",
         "intel",
          "nvidia"
          "cray"
        "max_jobs": 100
"environments": [
   "name": "gnu",
   "modules": [
     "PrgEnv-gnu"
    "cc": "cc",
   "cxx": "CC",
   "ftn": "ftn",
    "target_systems": [
      "daint"
```





The two flavors of ReFrame configuration (2 / 2)

- ReFrame can work with both the Python and the JSON flavors
- It is easy to convert from Python to JSON using the --show-config cli option
- The Python one is fully programmable using the language and its libraries
- ReFrame 4.0 and beyond supports splitting the configuration into multiple files
- For more information on the various options refer to the <u>documentation</u>





Programmable configuration for containers

Container Image Labels

Using the LABEL instruction in a Dockerfile, we can add information to a container image to be used by ReFrame

```
LABEL "rfm.features"="osu-micro-benchmarks;mpi;serial;openmp;cuda"
LABEL "rfm.cc"="mpicc"
LABEL "rfm.cxx"="mpic++"
LABEL "rfm.ftn"="mpif90"
```

```
LABEL "rfm.features"="osu-micro-benchmarks;mpi;serial;openmp"

LABEL "rfm.cc"="mpicc"

LABEL "rfm.cxx"="mpic++"

LABEL "rfm.ftn"="mpif90"
```

```
LABEL "rfm.features"="lammps"
```

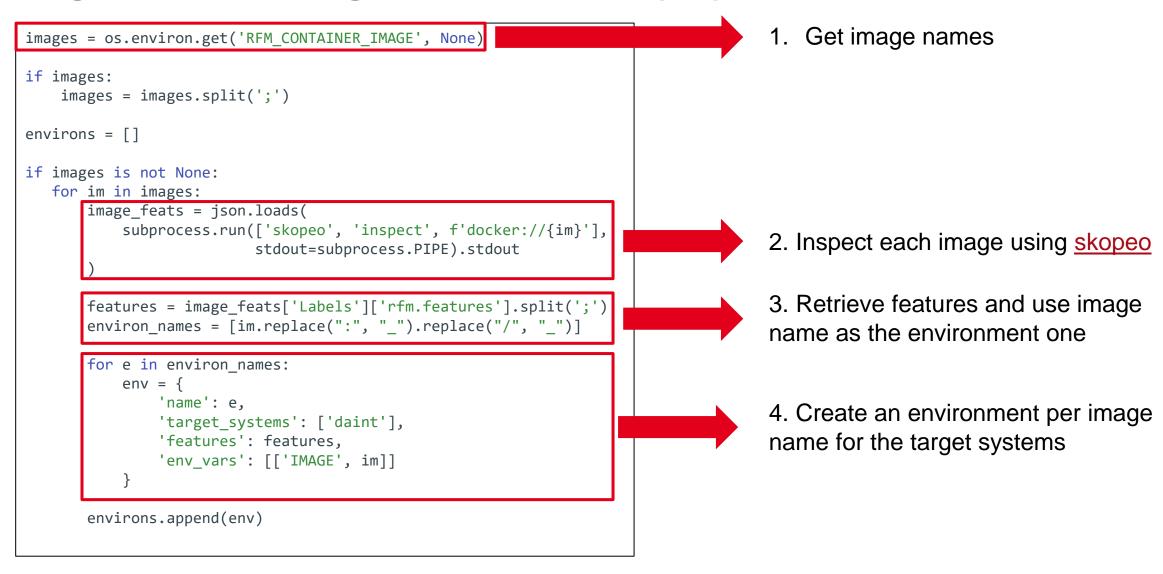
```
LABEL "rfm.features"="gromacs;cuda"
```

Accessible by the programmable configuration at runtime





Programmable configuration workflow (1/2)



Programmable configuration workflow (2/2)

```
if environs:
   partitions = [
            'name': f'gpu',
           'environs': [e['name'] for e in environs],
                                                                                5. Assign the environment names
           'features': ['gpu', 'nvgpu', 'remote'],
site_configuration = {
    'systems': [
           'name': 'daint',
                                                                                 6. Put the actual environments in the
    'environments': environs,
                                                                                 site configuration
```

ReFrame tests with features

```
import reframe as rfm
import reframe.utility.sanity as sn
@rfm.simple test
class OSULatency(rfm.RunOnlyRegressionTest):
    valid systems = ['*']
   valid prog environs = ['+osu-micro-benchmarks'
                                                                                           Required features
   @run after('setup')
    def setup container platform(self):
                                                                                           Retrieve image name injected
        self.container_platform.image = self.current_environ.env_vars['IMAGE']
                                                                                           by the configuration
@rfm.simple test
class OSULatencyCuda(OSULatency):
                                                                                           Both the system and the
   valid systems = ['+nvgpu']
                                                                                           environment have to provide the
   valid prog environs = ['+osu-micro-benchmarks +cuda']
                                                                                           required features
@rfm.simple test
class LAMMPSCPUCheck(rfm.RunOnlyRegressionTest):
    scale = parameter(['small', 'large'])
   valid systems = ['*']
   valid prog environs = ['+lammps']
```

Putting it all together

```
Images to test
[rfmuser@daint ~]$ export RFM CONTAINER IMAGE='teojgo/mvapich2 osu:5.9 cuda;teojgo/mpich osu:5.9;teojgo/lammps:latest'
[rfmuser@daint ~]$ reframe <cli options>
[======] Running 6 check(s)
[-----] start processing checks
                                                                                                                               One environment per image
 DRY
          | LAMMPSCPUCheck %scale=large /e4795b9b @daint:gpu+teojgo lammps latest
       OK ] ( 1/14) LAMMPSCPUCheck %scale=large /e4795b9b @daint:gpu+teoigo lammps latest
          LAMMPSCPUCheck %scale=large /e4795b9b @daint:mc+teojgo lammps latest
 DRY
       OK ] ( 2/14) LAMMPSCPUCheck %scale=large /e4795b9b @daint:mc+teoigo lammps latest
          LAMMPSCPUCheck %scale=small /867ddbf9 @daint:gpu+teojgo lammps latest
 DRY
       OK ] ( 3/14) LAMMPSCPUCheck %scale=small /867ddbf9 @daint:gpu+teojgo lammps latest
          LAMMPSCPUCheck %scale=small /867ddbf9 @daint:mc+teojgo lammps latest
 DRY
       OK ] ( 4/14) LAMMPSCPUCheck %scale=small /867ddbf9 @daint:mc+teojgo lammps latest
          ] OSULatencyCuda /42896efa @daint:gpu+teojgo mvapich2 osu 5.9 cuda
[ DRY
       OK ] (5/14) OSULatencyCuda /42896efa @daint:gpu+teojgo mvapich2 osu 5.9 cuda
                                                                                                                                Both system and environ
 DRY
           OSUBandwidthCuda /9b75552e @daint:gpu+teoigo myapich2 osu 5.9 cuda
       OK ] ( 6/14) OSUBandwidthCuda /9b75552e @daint:gpu+teojgo mvapich2 osu 5.9 cuda
                                                                                                                                features have to be satisfied
           OSUBandwidth /bd272703 @daint:gpu+teojgo mvapich2 osu 5.9 cuda
 DRY
       OK ] ( 7/14) OSUBandwidth /bd272703 @daint:gpu+teojgo mvapich2 osu 5.9 cuda
           OSUBandwidth /bd272703 @daint:gpu+teojgo mpich osu 5.9
 DRY
       OK ] (8/14) OSUBandwidth /bd272703 @daint:gpu+teojgo mpich osu 5.9
 DRY
          ] OSUBandwidth /bd272703 @daint:mc+teojgo mvapich2 osu 5.9 cuda
       OK ] ( 9/14) OSUBandwidth /bd272703 @daint:mc+teojgo mvapich2 osu 5.9 cuda
          ] OSUBandwidth /bd272703 @daint:mc+teojgo mpich osu 5.9
[ DRY
       OK ] (10/14) OSUBandwidth /bd272703 @daint:mc+teojgo mpich osu 5.9
          ] OSULatency /1583f36f @daint:gpu+teojgo_mvapich2_osu_5.9_cuda
 DRY
       OK | (11/14) OSULatency /1583f36f @daint:gpu+teojgo mvapich2 osu 5.9 cuda
           OSULatency /1583f36f @daint:gpu+teojgo mpich osu 5.9
 DRY
       OK ] (12/14) OSULatency /1583f36f @daint:gpu+teojgo mpich osu 5.9
 DRY
           OSULatency /1583f36f @daint:mc+teojgo mvapich2 osu 5.9 cuda
       OK ] (13/14) OSULatency /1583f36f @daint:mc+teojgo_mvapich2_osu_5.9_cuda
          OSULatency /1583f36f @daint:mc+teojgo mpich osu 5.9
 DRY
       OK ] (14/14) OSULatency /1583f36f @daint:mc+teojgo mpich osu 5.9
[-----] all spawned checks have finished
```







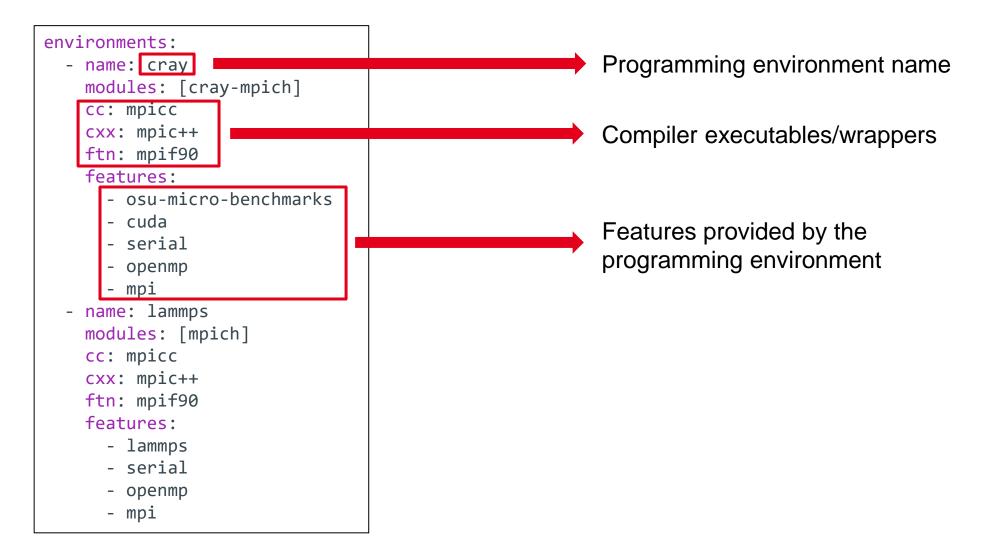
User environment based programmable configuration

CSCS User Environments in a Nutshell

- Squashfs images containing a software stack comprised of one or more programming environments
- Created using the CSCS developed <u>stackinator</u> cli application which accepts yaml files describing the components of the stack
- Mounted on a user selected path via a CSCS developed <u>Slurm plugin</u>
- Can make use of host libraries needed for best performance
- Are accompanied by a yaml file (work in progress) which is consumed by ReFrame the provided environments and their features



Example uenv describing the features per environment



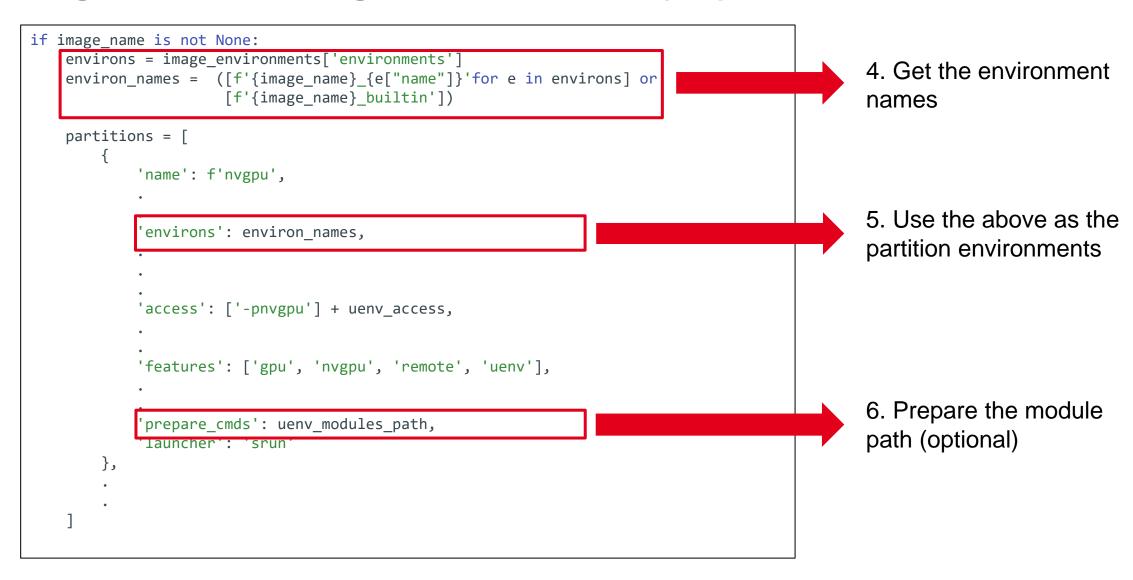


Programmable configuration workflow (1/3)

```
1. Retrieve image path
uenv file = os.environ.get('UENV FILE', None)
uenv_mount = os.environ.get('UENV_MOUNT', '/user-environment')
                                                                                                and mount point
uenv access = []
uenv modules path = []
image name = None
partitions = []
features = []
if uenv_file is not None:
   uenv access = [
       f'--uenv-file={uenv file}',
                                                                                            2. Create Slurm options
       f'--uenv-mount={uenv mount}',
   uenv_modules_path = [f'module use {uenv_mount}/modules'
   image path = pathlib.Path(uenv file)
   image name = image path.stem
with open(image path.parent / f'{image name}.yaml') as image envs:
                                                                                            3. Load the yaml file
   image environments = yaml.load(image envs.read(), Loader=yaml.BaseLoader)
```



Programmable configuration workflow (2/3)





Programmable configuration workflow (3/3)

```
environs = image environments['environments']
if environs:
    actual environs = []
for e in environs:
    env = {
        'target_systems': ['clariden-uenv']
                                                                                             7. Create the actual
   env.update(e)
                                                                                             environments
    env['name'] = f'{image name} {e["name"]}'
    actual_environs.append(env)
site configuration = {
    'systems': [
            'name': 'clariden-uenv',
                                                                                             8. Assign the partitions
            'partitions': partitions
                                                                                             9. Assign the environments
    'environments': actual environs,
```



Putting it all together

```
[rfmuser@uenv-cluster]$ export UENV_FILE=<path to uenv squashfs>
[rfmuser@uenv-cluster]$ reframe <cli options>
[======] Running 28 check(s)
[-----] start processing checks
            OSULatencyCuda /42896efa @clariden-uenv nvgpu+cray-mpich cuda11.8 osu59 cray
[ DRY
       OK ] ( 1/54) OSULatencyCuda /42896efa @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
            OSUBandwidthCuda /9b75552e @clariden-uenv:nvgpu+cray-mpich_cuda11.8 osu59 cray
 DRY
       OK ] ( 2/54) OSUBandwidthCuda /9b75552e @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
[ DRY
          OSUBandwidth /bd272703 @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
       OK ] ( 3/54) OSUBandwidth /bd272703 @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
           ] OSULatency /1583f36f @clariden-uenv:amdgpu+cray-mpich cuda11.8 osu59 cray
[ DRY
       OK ] (6/54) OSULatency /1583f36f @clariden-uenv:amdgpu+cray-mpich cudal1.8 osu59 cray
           HelloWorldTestMPIOpenMP %linking=static %lang=f90 /0163156f @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
[ DRY
       OK ] (7/54) HelloWorldTestMPIOpenMP %linking=static %lang=f90 /0163156f @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
 DRY
            HelloWorldTestMPIOpenMP %linking=static %lang=f90 /0163156f @clariden-uenv:amdgpu+cray-mpich cuda11.8 osu59 cray
       OK ] ( 8/54) HelloWorldTestMPIOpenMP %linking=static %lang=f90 /0163156f @clariden-uenv:amdgpu+cray-mpich cuda11.8 osu59 cray
[ DRY
          | HelloWorldTestMPIOpenMP %linking=static %lang=cpp /417f4cbe @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
       OK | (51/54) HelloWorldTestSerial %linking=dynamic %lang=cpp /c361f2ee @clariden-uenv:nvgpu+cray-mpich_cuda11.8_osu59_cray
            HelloWorldTestSerial %linking=dynamic %lang=cpp /c361f2ee @clariden-uenv:amdgpu+cray-mpich cuda11.8 osu59 cray
[ DRY
       OK ] (52/54) HelloWorldTestSerial %linking=dynamic %lang=cpp /c361f2ee @clariden-uenv:amdgpu+cray-mpich cuda11.8 osu59 cray
           HelloWorldTestSerial %linking=dynamic %lang=c /dd310517 @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
[ DRY
       OK ] (53/54) HelloWorldTestSerial %linking=dynamic %lang=c /dd310517 @clariden-uenv:nvgpu+cray-mpich cuda11.8 osu59 cray
           | HelloWorldTestSerial %linking=dynamic %lang=c /dd310517 @clariden-uenv:amdgpu+cray-mpich cuda11.8 osu59 cray
T DRY
       OK | (54/54) HelloWorldTestSerial %linking=dynamic %lang=c /dd310517 @clariden-uenv:amdgpu+cray-mpich cuda11.8 osu59 cray
[-----] all spawned checks have finished
  PASSED ] Ran 54/54 test case(s) from 28 check(s) (0 failure(s), 0 skipped, 0 aborted)
```



One partition per uenv







Conclusions

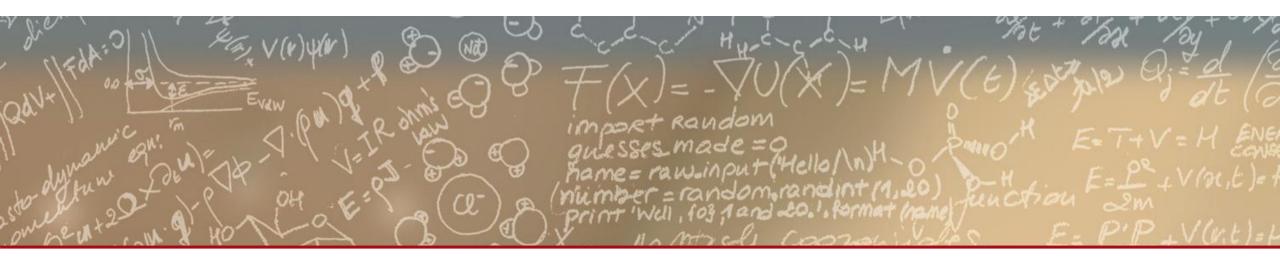
Conclusions

- Programmable configuration gives full access to the Python language and libraries
- The final configuration can be generated on the fly based on the environment(s) and/or system(s) to be tested
- Generating a configuration based on the features of system(s)/environments(s)
 moves the responsibility on them to state what features they provide
- LABELS in container images can be used by ReFrame to generate a configuration at runtime and run the required tests
- By inspecting the features that the uenv stacks provide (e.g via a yaml file)
 ReFrame can test the corresponding functionality









Thank you for your attention

Questions?