

# Machine Learning for Autonomous Systems

by

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Submitted to the EECS \ in partial fulfillment of the requirements for the degree of

*Doctor*

at the

**MASSACHUSETTS INSTITUTE OF TECHNOLOGY**

May 2025

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Novel ML algorithms for autonomous vehicle navigation.

# **Chapter 1**

## **Introduction**

Autonomous vehicles require robust perception.

## **Chapter 2**

### **Methods**

We develop a hybrid neural-symbolic approach.

## **Chapter 3**

### **Conclusion**

State-of-the-art performance achieved.