

TREES!!

TREEES

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Editor:

Abstract

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Keywords: TREEES

1. Introduction

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2. Bayesian Optimization and Bandit-Based Algorithms

2.1 Bayesian Optimization

2.2 SuccessiveHalving and Hyperband

3. A Trio of Tree Algorithms

3.1 SequentialHalving with Decision Tree inputs

3.2 SequentialTree

3.2.1 ALGORITHM

Algorithm 1 SequentialTree

```

procedure SEQUENTIALTREE(Box constrained space  $\mathcal{X} \subset \mathbb{R}^d$ , budget  $T, \eta, m$ )
  Assign  $\mathcal{P} = \{\mathcal{X}\}$ 
  Assign n_nodes =  $m$ 
  for  $r = 1 \dots \log_\eta(m)$  do
    The number of pulls per element of  $\mathcal{P}$   $n_r = \left\lfloor \frac{T}{|\mathcal{P}| \lceil \log_\eta(m) \rceil} \right\rfloor$ 
     $\mathcal{A}_r = \emptyset$ 
     $\hat{B}_r = \emptyset$ 
    for  $p \in \mathcal{P}$  do
      Remove  $p$  from  $\mathcal{P}$ 
      Sample  $\{x_{p1}, \dots, x_{pn_r}\}$  independently and uniformly over  $p$ 
      Let  $\{y_{p1}, \dots, y_{pn_r}\}$  be the result of querying the function at these points
      Train a decision tree with n_nodes nodes,  $t_p = \text{DECISIONTREE}(y_p \sim X_p)$ 
      Add the n_nodes partitions defined by  $t_p$  to  $\mathcal{A}_r$ 
      Add the prediction from  $t_p$  for each partition to  $\hat{B}_r$ .
    end for
    if  $|\mathcal{P}| > \eta^2$  then
      Set  $\mathcal{P}$  to be the elements of  $\mathcal{A}_r$  with predictions in the top  $\frac{|\mathcal{P}|}{\eta^2}$  of  $\hat{B}_r$ 
    else
      Let  $\hat{p}$  be the element of  $\mathcal{P}$  with the best prediction
      return MIDPOINT( $\hat{p}$ )
    end if
    n_nodes =  $\eta$ 
  end for
end procedure

```

3.3 PartitionTree

3.3.1 ALGORITHM

Algorithm 2 PartitionTree

```

procedure PARTITIONTREE(Box constrained space  $\mathcal{X} \subset \mathbb{R}^d$ , budget  $T$ ,  $\eta$ , rounds  $R$ )
   $m = \eta^2$ 
   $\mathcal{P} = \{\mathcal{X}\}$ 
  for  $r = 1, \dots, R$  do The number of pulls per element of  $\mathcal{P}$   $n_r = \left\lfloor \frac{T}{|\mathcal{P}|R} \right\rfloor$ 
     $\mathcal{A}_r = \emptyset$ 
     $\hat{B}_r = \emptyset$ 
    for  $p \in \mathcal{P}$  do
      Remove  $p$  from  $\mathcal{P}$ 
      Sample  $\{x_{p1}, \dots, x_{pn_r}\}$  independently and uniformly over  $p$ 
      Let  $\{y_{p1}, \dots, y_{pn_r}\}$  be the result of querying the function at these points
      Train a decision tree with  $m$  nodes,  $t_p = \text{DECISIONTREE}(y_p \sim X_p)$ 
      Add the  $m$  partitions defined by  $t_p$  to  $\mathcal{A}_r$ 
      Add the prediction from  $t_p$  for each partition to  $\hat{B}_r$ .
    end for
    Set  $\mathcal{P}$  to be the elements of  $\mathcal{A}_r$  with predictions in the top  $\frac{|\mathcal{P}|}{\eta}$  of  $\hat{B}_r$ 
    Let  $\hat{p}$  be the element of  $\mathcal{P}$  with the best prediction
     $m = \eta$ 
  end for
  return MIDPOINT( $\hat{p}$ )
end procedure

```

4. Empirical Evaluation

5. Conclusion

Acknowledgments

We would like to acknowledge

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Appendix A.