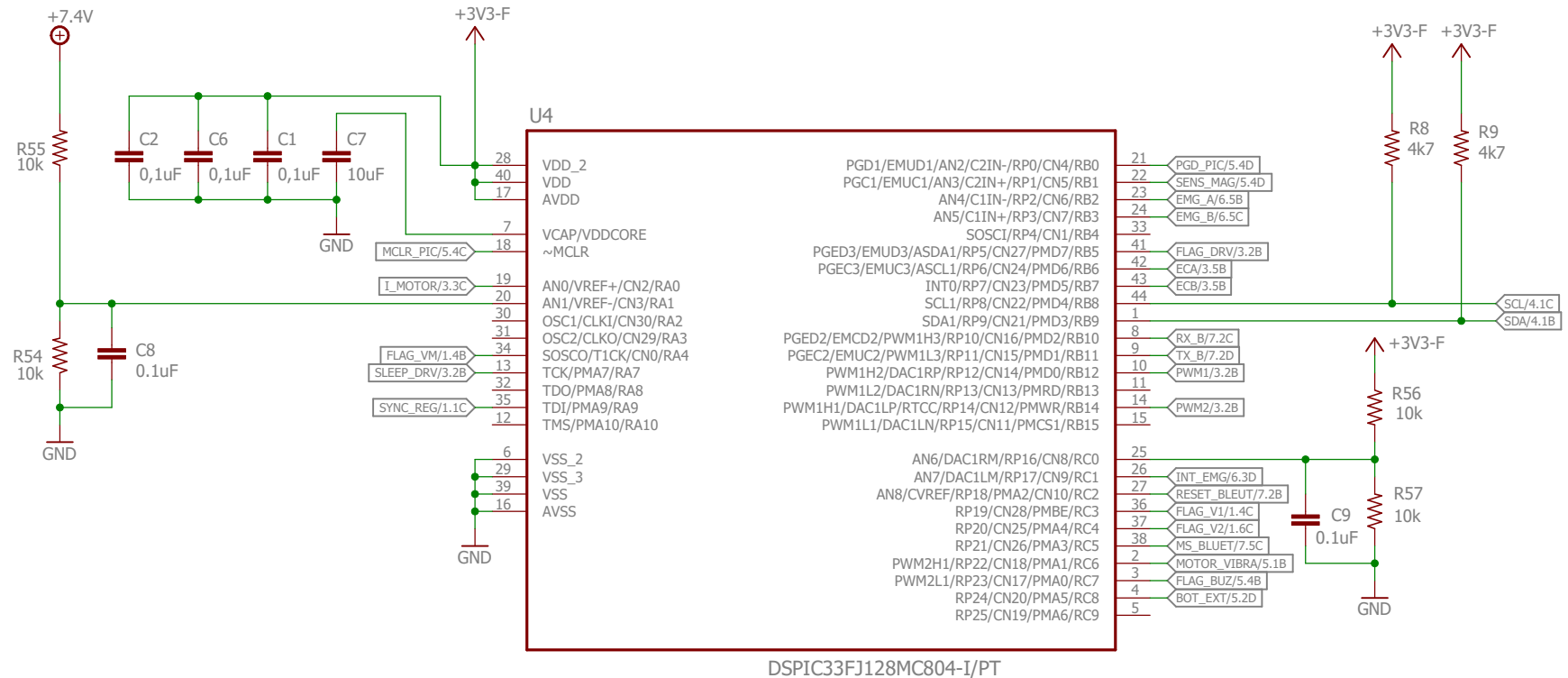


Microcontrolador mestre - dsPIC33FJ128MC804
 Controla os motores de cima através de comunicação I2C.
 Controla o motor do dedo diretamente.



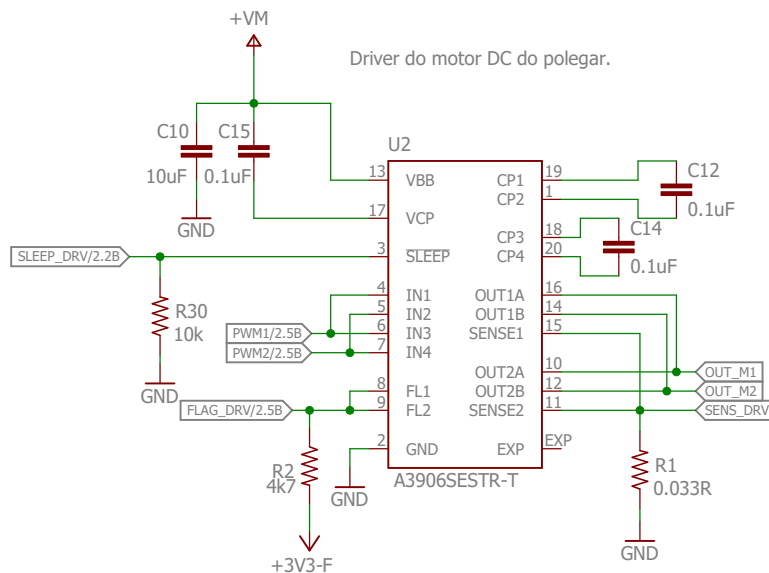
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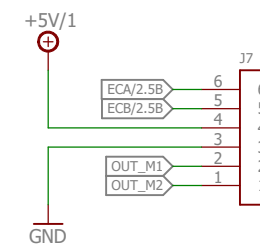
Microcontrolador

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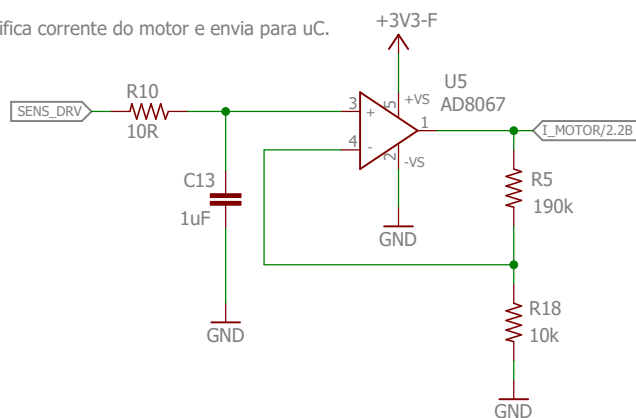
Sheet: 2/7



Conector do Encoder do polegar.
Conectot F.: NSHR-06V-S
Conector M.: SM06B-NSHSS-TB (LF)(SN)
Terminal: SSSL-003T-P0.2



Amplifica corrente do motor e envia para uC.



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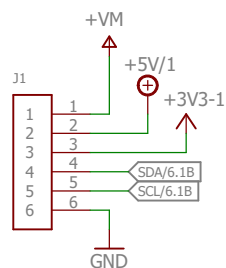
Polegar

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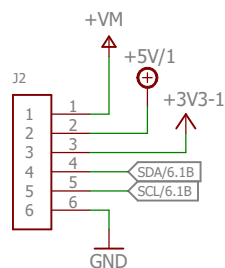
Sheet: 3/7

Conector dos dedos.
 Conector F.: NSHR-06V-S
 Conector M.: SM06B-NSHSS-TB (LF)(SN)
 Terminal: SSSL-003T-P0.2

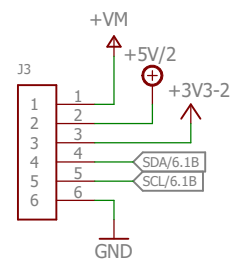
Saída Dedo indicador



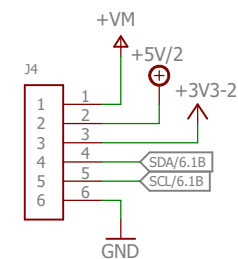
Saída Dedo Médio



Saída Dedo Anelar



Saída Dedo Mindinho



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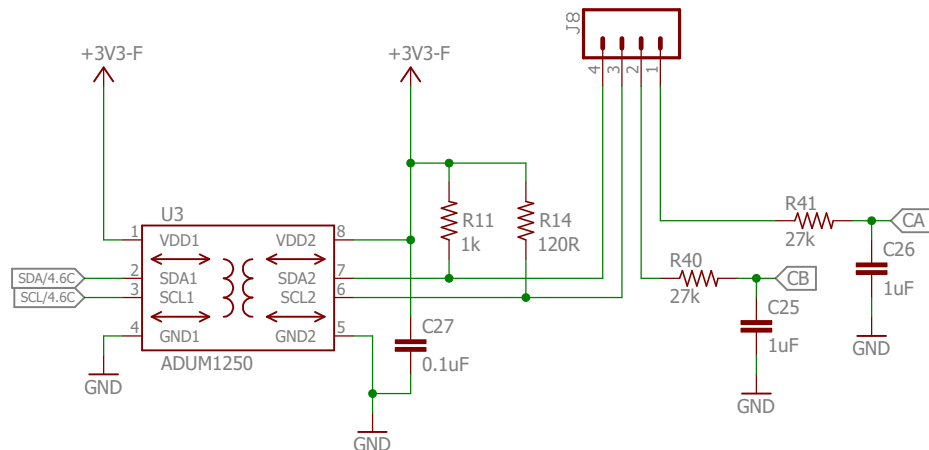
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Demais dedos

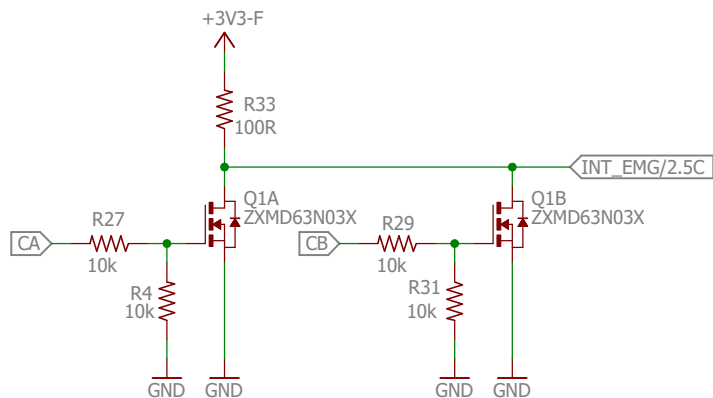
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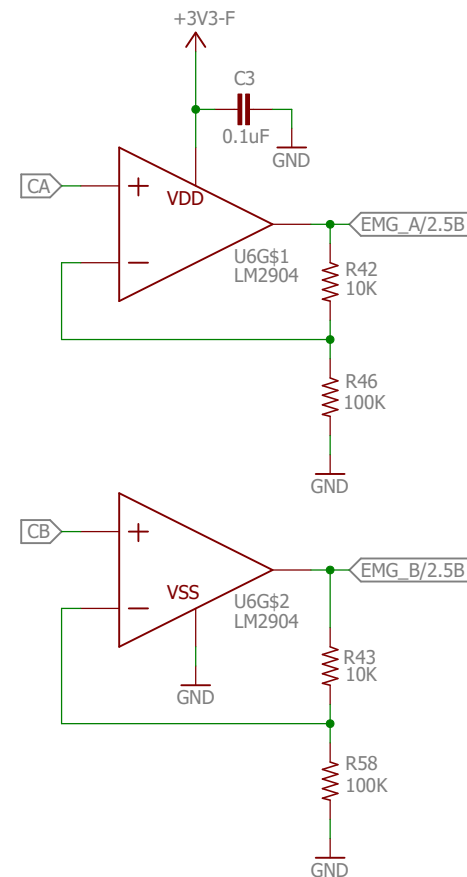
Conector com duas funções:
 Pinos 1 e 2 recebe os sinais de controle para o movimento dos dedos, com filtro passa baixa.
 Pinos 3 e 4 para comunicação I2C, o qual passa por um CI isolador.
 Conector M.: SM04B-NSHSS-TB (LF)(SN)
 Conector F.: NSHR-04V-S
 Terminal: SSHL-003T-P0.2



Porta NAND que ativa acionamento por EMG.



Amplificador dos canais de EMG, usando como buffer.



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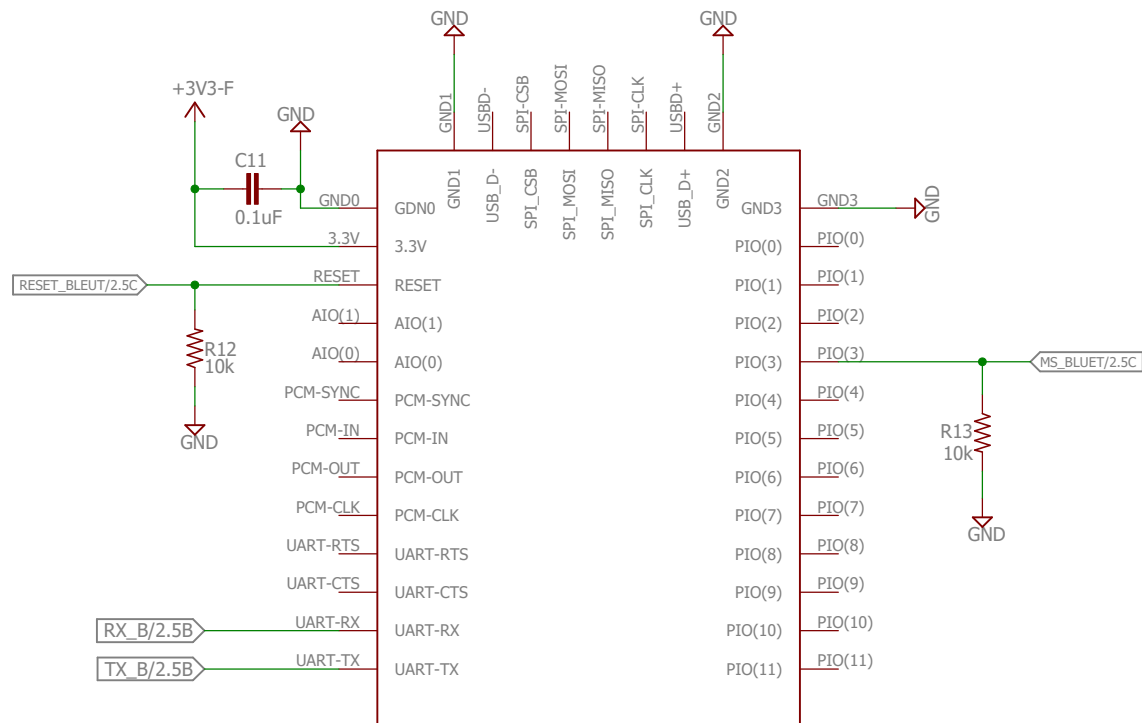
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EMG e Comunicação I2C

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Modulo de comunicacao Bluetooth - HC06
 pino 1 - Tx
 pino 2 - Rx
 Pino 11 - Reset
 Pino 12 - Vcc (+3v3)
 Pinos 13, 21, 22 - GND
 Pino 26 - Master/Slave



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Bluetooth

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