

Gesture Interpretation And Multilingual Translation

PROJECT REPORT

21AD1513- INNOVATION PRACTICES LAB

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BONAFIDE CERTIFICATE

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ABSTRACT

This research presents a novel real-time hand gesture detection system that utilizes the synergistic capabilities of Convolutional Neural Networks (CNN) and Long Short-Term Memory (LSTM) networks to achieve reliable and effective gesture recognition. By harnessing CNNs for their powerful spatial feature extraction and LSTMs for their proficiency in understanding temporal sequences, the proposed system overcomes the limitations of traditional gesture recognition methods. The implementation is enhanced through the integration of a user-friendly interface built with Flask, enabling functionalities such as real-time communication, multilingual translation, and speech synthesis, which together foster accessibility for a broad range of users, including those with hearing impairments. The experimental results underscore the system's robustness in identifying a diverse set of gestures under varying environmental conditions, highlighting its potential for applications in areas like virtual reality, sign language interpretation, and remote device control. As we look to the future, significant enhancements are envisioned, including the integration of advanced Natural Language Processing (NLP) techniques that will allow for the generation of grammatically coherent sentences from recognized gestures, thereby improving the communication experience. Furthermore, we plan to develop multi-user support capabilities, increase adaptability to various lighting and background scenarios, enable gesture customization, and explore the incorporation of additional modalities such as voice recognition and facial expression analysis. These advancements aim to enrich the user experience, making the system more versatile and responsive to the needs of its users. In conclusion, this research contributes to the ongoing advancements in gesture recognition technology and human-computer interaction. By pushing the boundaries of current capabilities, the proposed system not only serves immediate practical needs but also lays the groundwork for future innovations that can transform how individuals interact with machines and with each other through gesture-based communication. The exploration of these enhancements promises to deliver a more holistic and engaging user experience, further cementing the role of gesture recognition systems in contemporary technological landscapes.

Keywords : Hand Gesture Recognition, CNN, Bi-LSTM, Multilingual Translation.

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LIST OF ABBREVIATIONS

ABBREVIATIONS	MEANING
FPS	FRAMES PER SECOND
CV	COMPUTER VISION
LSTM	LONG SHORT-TERM MEMORY
BI-LSTM	BIDIRECTIONAL - LONG SHORT-TERM MEMORY
CNN	CONVOLUTIONAL NEURAL NETWORK
ASL	AMERICAN SIGN LANGUAGE
ISL	INDIAN SIGN LANGUAGE

CHAPTER 1

INTRODUCTION

1.1 Overview

1.1.1 Definition and Importance of Hand Gesture Recognition

Hand gesture recognition refers to the process by which computer systems interpret human hand movements as commands or communication signals. This technology has become increasingly important as it offers an intuitive, natural method for human-computer interaction. Its significance is highlighted in applications such as virtual and augmented reality, where it provides a seamless interface between users and digital environments. The ability to recognize hand gestures accurately enhances accessibility, enabling people with disabilities to interact with technology more easily. Furthermore, in the context of hygiene and health, touchless interfaces reduce the need for physical contact, preventing the spread of germs.

1.1.2 Evolution of Gesture Recognition Technology

Gesture recognition technology has evolved significantly from its early stages. Initially, it relied on hardware-based systems that required gloves or other sensors to capture hand movements. Over time, advancements in computer vision and machine learning have enabled software-based systems that use camera feeds to detect and interpret gestures. These developments have made the technology more accessible and practical, reducing the dependency on specialized equipment. With the introduction of deep learning, gesture recognition has achieved higher accuracy and versatility, allowing for more complex and nuanced

hand movements to be recognized. This evolution continues to expand the potential applications and improve user experiences.

1.1.3 Current Challenges and Opportunities

Despite its advancements, hand gesture recognition technology faces several challenges. One major challenge is the computational power required for real-time processing, which can be a limiting factor for mobile and embedded systems. Another issue is the variability in hand sizes, shapes, and movement styles among different users, which can affect the system's accuracy. Environmental factors, such as lighting conditions and background noise, also pose significant hurdles. However, these challenges present opportunities for further innovation, such as developing more efficient algorithms and enhancing the system's adaptability to different users and environments. Addressing these challenges can broaden the technology's applicability and improve its robustness.

1.2 Problem Statement

1.2.1 Computational Demands

Hand gesture recognition systems require significant computational resources to process and interpret hand movements accurately and in real-time. This poses a challenge for devices with limited processing power, such as smartphones and embedded systems. The high computational demand can result in latency issues, affecting the user experience. Optimizing algorithms to reduce computational load while maintaining accuracy is essential to overcome this challenge. Achieving this balance will enable the deployment of gesture recognition technology on a wider range of devices, making it more accessible and practical.

1.2.2 Generalization Across Users and Environments

Achieving consistent performance across different users and environments is a significant challenge for hand gesture recognition systems. Variations in hand shapes, sizes, and movement styles among users can lead to inaccuracies. Additionally, environmental factors like lighting and background noise can interfere with the system's ability to recognize gestures accurately. Developing models that can generalize well across diverse conditions is crucial. This requires extensive training data and robust algorithms capable of handling variability. Ensuring consistent performance will enhance the reliability and user satisfaction of gesture recognition systems.

1.2.3 Lack of Adaptability

Traditional hand gesture recognition systems often lack the adaptability needed to function effectively in dynamic environments. They struggle to learn new gestures or adapt to user-specific movements without undergoing extensive retraining. This rigidity limits their effectiveness in applications requiring flexibility, such as interactive gaming or assistive technologies. Developing adaptive learning algorithms that can continuously improve and adjust to new gestures and user behaviors is critical. Such adaptability will make gesture recognition systems more versatile and user-friendly, catering to a broader range of applications and user needs.

1.3 Project Objectives

1.3.1 Real-Time Performance

A primary objective of this project is to achieve real-time performance in hand gesture recognition. This involves developing algorithms capable of processing

and interpreting hand movements instantaneously, providing immediate feedback. Real-time performance is essential for applications such as virtual and augmented reality, where any delay can disrupt the user experience. By optimizing the processing pipeline and utilizing advanced machine learning techniques, the project aims to create a system that can recognize gestures without noticeable latency, ensuring a seamless and interactive user experience.

1.3.2 High Accuracy

Ensuring high accuracy in gesture recognition is a crucial objective. Accurate interpretation of hand gestures is vital for reliable interaction and user satisfaction. The project aims to develop models that can accurately recognize a wide range of gestures with minimal errors. This involves using comprehensive datasets for training and employing sophisticated machine learning algorithms to enhance the model's predictive capabilities. High accuracy is particularly important in applications such as sign language interpretation, where precise recognition is necessary for effective communication.

1.3.3 Adaptability

Adaptability is a key focus of this project, emphasizing the system's ability to adjust to new gestures and user behaviors over time. This includes creating models that can learn from ongoing interactions and refine their recognition capabilities without requiring extensive retraining. Adaptability ensures the system remains effective in dynamic environments and can cater to individual user preferences. By incorporating adaptive learning techniques, the project aims to develop a more flexible and user-friendly gesture recognition system that can evolve with its users.

1.3.4 Practical Application

Developing a hand gesture recognition system that is not only theoretically robust but also practically applicable is a significant objective. This involves creating a user-friendly interface and ensuring compatibility with various devices, such as smartphones, tablets, and PCs. Practical application also includes addressing potential security and privacy concerns associated with gesture recognition technology. By focusing on practical implementation, the project seeks to create a solution that can be readily adopted across various industries and use cases, providing real-world benefits and improving user interactions with technology.

1.4 Significance of the Project

1.4.1 Enhancing Human-Computer Interaction

The significance of this project lies in its potential to transform human-computer interaction. By enabling more natural and intuitive communication methods, gesture recognition technology can significantly enhance user experiences across various applications. This technology can make interactions more efficient and enjoyable, reducing the reliance on traditional input devices such as keyboards and mice. In sectors like gaming, healthcare, and smart homes, improved interaction can lead to more immersive and accessible experiences, providing users with a more intuitive way to interact with digital systems.

1.4.2 Applications in Various Fields

Hand gesture recognition has wide-ranging applications across numerous fields. In healthcare, it can facilitate touchless control of medical devices, improving hygiene and convenience. In the automotive industry, gesture recognition can

enhance driver safety by enabling hands-free control of infotainment systems. The technology also holds potential in virtual and augmented reality, providing users with more immersive and interactive experiences. This project aims to explore and expand these applications, demonstrating the versatility and impact of gesture recognition technology in various industries.

1.5 Scope of the Project

The scope of this project encompasses several key areas critical to the development and deployment of a robust hand gesture recognition system. First, extensive data collection and preprocessing will be undertaken to ensure a diverse and comprehensive dataset. This will involve gathering hand gesture data from various users and environments, followed by normalization and augmentation to improve the dataset's quality and variability.

Secondly, designing an effective model architecture will be a focus, selecting and implementing neural network structures that balance complexity and efficiency. Training and optimization will follow, using advanced machine learning techniques to fine-tune the model for optimal performance. Evaluation metrics, such as accuracy, precision, and recall, will be employed to rigorously assess the system's effectiveness.

Finally, developing a user-friendly application interface will ensure practical applicability, integrating real-time feedback and customization options while addressing security and privacy concerns. User testing and feedback will be integral to refining the system, ensuring it meets user needs and expectations. Through these comprehensive efforts, the project aims to create a versatile, accurate, and user-friendly hand gesture recognition system.

CHAPTER 2

LITERATURE REVIEW

The following literature survey summarizes recent advancements in sign language gesture recognition, focusing on deep learning techniques, algorithmic innovations, and application developments.

2.1 Deep Learning For Hand Gesture Recognition On Skeletal Data

Gesture recognition has increasingly relied on skeletal data representations to enhance performance in various applications, including human-computer interaction and gaming. Devineau et al. (2018) explore deep learning techniques specifically tailored for recognizing hand gestures using skeletal data. Their approach employs a hierarchical model that captures both global and local features of hand movements, allowing for improved classification accuracy. The authors conduct extensive experiments demonstrating that their deep learning model surpasses conventional techniques in recognizing gestures from skeletal data. The results indicate that this method is particularly effective in scenarios where visual data may be obscured or limited, underscoring the significance of skeletal representations in gesture recognition systems. The study lays the groundwork for future research in gesture-based interfaces and applications.

Authors: G. Devineau, F. Moutarde, W. Xi, J. Yang

Year: 2018

Location: 2018 13th IEEE International Conference on Automatic Face & Gesture Recognition

2.2 Challenges And Solutions For Vision-Based Hand Gesture Interpretation: A Review

Hand gesture interpretation remains a challenging task due to the variability of gestures and environmental factors. In their comprehensive review, Gao et al. (2024) identify key challenges in vision-based hand gesture recognition, including occlusion, illumination changes, and the complexity of gestures. The authors discuss various solutions proposed in the literature, such as the integration of machine learning techniques and hybrid systems that combine visual and depth information. They also highlight the role of data augmentation and transfer learning in improving model robustness. By synthesizing current research, this review serves as a valuable resource for researchers and practitioners aiming to enhance gesture recognition systems in real-world applications. The insights provided by the authors point towards future directions in developing more adaptive and resilient gesture interpretation frameworks.

Authors: K. Gao, H. Zhang, X. Liu, X. Wang, L. Xie, B. Ji, Y. Yan, E. Yin

Year: 2024

Location: Computer Vision and Image Understanding

2.3 Dynamic Gesture Recognition Algorithm Combining Global Gesture Motion And Local Finger Motion For Interactive Teaching

The advancement of interactive teaching tools has necessitated the development of effective gesture recognition algorithms. Jiashan and Zhonghua (2024) propose a dynamic gesture recognition algorithm that integrates global gesture motion with local finger motion, tailored specifically for educational environments. Their method employs a dual-stream architecture that processes both global hand movement and detailed finger articulation. The authors

demonstrate that this approach significantly improves recognition accuracy in real-time scenarios, making it suitable for interactive teaching applications. Experimental validation reveals that their algorithm achieves high precision in recognizing complex gestures, thereby enhancing the interactivity of educational tools. This research highlights the potential of gesture recognition in facilitating more engaging learning experiences.

Authors: L. I. Jiashan, L. I. Zhonghua

Year: 2024

Location: IEEE Access: Practical Innovations, Open Solutions

2.4 An Adaptive, Affordable, Open-Source Robotic Hand For Deaf And Deaf-Blind Communication Using Tactile American Sign Language

The communication needs of the deaf and deaf-blind communities are often unmet due to a lack of accessible technologies. Johnson et al. (2021) introduce an adaptive, open-source robotic hand designed to facilitate communication through tactile American Sign Language (ASL). The authors outline the development process, focusing on affordability and adaptability to various users' needs. By integrating sensors and actuators, the robotic hand can convey tactile signs, allowing for effective communication with both deaf and deaf-blind individuals. This work represents a significant step toward inclusive communication technologies and emphasizes the importance of accessibility in assistive devices. The potential for customization and community involvement in the development of this technology further enhances its impact on users.

Authors: S. Johnson, G. Gao, T. Johnson, M. Liarokapis, C. Bellini

Year: 2021

Location: 2021 43rd Annual International Conference of the IEEE Engineering in Medicine & Biology Society

2.5 Indian Sign Language Recognition System Using Surf With SVM And CNN

The recognition of Indian Sign Language (ISL) has become increasingly relevant in promoting accessibility and communication for the deaf community in India. Katoch et al. (2022) present an ISL recognition system that utilizes Speeded Up Robust Features (SURF) in combination with Support Vector Machines (SVM) and Convolutional Neural Networks (CNN). Their approach effectively captures hand movement features while addressing challenges related to variability in sign execution. Through rigorous testing, the authors demonstrate that their hybrid model achieves high recognition accuracy, significantly outperforming traditional techniques. The findings underscore the potential of integrating feature extraction and classification methods to enhance the effectiveness of sign language recognition systems, paving the way for broader applications in accessibility technologies.

Authors: S. Katoch, V. Singh, U. S. Tiwary

Year: 2022

Location: Array (New York, N.Y.)

2.6 Silent Expressions Unveiled: Deep Learning For British And American Sign Language Detection

The intersection of deep learning and sign language recognition is an emerging field that promises to enhance communication for the deaf and hard-of-hearing populations. Koyineni et al. (2024) explore the application of deep learning

techniques for the detection of both British and American Sign Languages. Their study emphasizes the development of a unified model that accommodates the linguistic differences between the two sign languages. By leveraging large datasets and advanced neural network architectures, the authors achieve substantial improvements in recognition accuracy. This research contributes to the ongoing efforts to bridge communication gaps and foster inclusivity, emphasizing the need for adaptable models in multilingual sign language recognition systems.

Authors: S. N. Koyineni, G. K. Sai, K. Anvesh, T. Anjali

Year: 2024

Location: Procedia Computer Science

2.7 Development Of An End-To-End Deep Learning Framework For Sign Language Recognition, Translation, And Video Generation

The advancement of deep learning technologies has transformed sign language recognition and translation, enabling more effective communication for the deaf community. Natarajan et al. (2022) introduce an end-to-end deep learning framework designed for sign language recognition, translation, and video generation. Their framework integrates multiple stages of processing, including gesture recognition, linguistic translation, and visual synthesis, to create a seamless communication tool. The authors emphasize the importance of using large-scale datasets to train their models, demonstrating significant improvements in both recognition accuracy and translation quality. This comprehensive approach highlights the potential for deep learning to facilitate real-time communication and bridge language barriers for sign language users.

Authors: B. Natarajan, E. Rajalakshmi, R. Elakkiya, K. Kotecha, A. Abraham, L. A. Gabralla, V. Subramaniaswamy

Year: 2022

Location: IEEE Access: Practical Innovations, Open Solutions

2.8 3d-Cnn Based Dynamic Gesture Recognition For Indian Sign Language Modeling

Modeling Indian Sign Language (ISL) using advanced recognition techniques has garnered attention for its potential to enhance communication access. Singh (2021) presents a 3D-CNN-based dynamic gesture recognition model specifically designed for ISL. The study emphasizes the significance of spatial and temporal features in accurately recognizing dynamic gestures. By utilizing a 3D convolutional architecture, the author achieves significant improvements in gesture classification accuracy compared to conventional methods. The findings illustrate the effectiveness of employing 3D-CNNs for dynamic gesture recognition tasks and provide insights into the future development of ISL recognition systems, underscoring the importance of tailored approaches for different sign languages.

Authors: S. Singh

Year: 2021

Location: 2021 IEEE Calcutta Conference (CALCON)

CHAPTER 3

SYSTEM ANALYSIS

3.1 Existing System

The landscape of sign language gesture recognition is characterized by a multitude of innovative systems that leverage different techniques to improve accuracy and efficiency. Al-Hammadi et al. (2020) introduced a deep learning-based approach that emphasizes efficient hand gesture representation through convolutional neural networks (CNNs). Their system is designed to operate in real-time, making it suitable for practical applications in communication aids, significantly enhancing the interaction experience for users. Similarly, Devineau et al. (2018) focused on skeletal data for hand gesture recognition, employing pose estimation technology to identify gestures based on skeletal movements. This method not only minimizes computational load but also accelerates recognition speed, thus promoting its usability in interactive environments.

In addition to these approaches, Gao et al. (2024) conducted a comprehensive review of vision-based gesture interpretation systems, detailing the challenges and advancements in this area. Their findings underscore the importance of computer vision techniques in analyzing video data for gesture recognition, leading to improvements in accuracy and processing time. Moreover, Jiashan and Zhonghua (2024) introduced a dynamic gesture recognition algorithm that merges global gesture motion with local finger motion, catering specifically to interactive teaching scenarios. This dual focus enhances the system's ability to recognize complex sign language gestures effectively, thus enriching the learning experience.

Furthermore, the exploration of tactile communication systems, such as the one developed by Johnson et al. (2021), highlights an innovative application of gesture recognition technology for deaf and deaf-blind individuals. This robotic hand system interprets tactile American Sign Language (ASL) gestures, showcasing how gesture recognition can extend beyond visual systems. Meanwhile, the end-to-end deep learning framework presented by Natarajan et al. (2022) integrates recognition, translation, and video generation into a cohesive model, streamlining the conversion process for sign language. Collectively, these systems demonstrate the ongoing evolution of sign language gesture recognition technologies, emphasizing the need for diversity in methodologies to address various user requirements and contexts.

3.2 Proposed System

To improve gesture recognition, our suggested method does the following:

Using CNNs for Spatial Feature Extraction: CNNs are used to recognize hand landmarks in video frames and extract spatial features from them. Important information for gesture identification is provided by these features, which record the hand's shape and direction.

Using Long Short-Term Memory (LSTM) to Record Temporal Dependencies: LSTMs are employed to simulate the movements of hands across time. Through the processing of video frame sequences, LSTMs are able to recognize dynamic gestures by learning the temporal correlations between subsequent hand movements.

Including Bidirectional Layers to Take Forward and Backward Temporal Information Into Account: The model incorporates bidirectional LSTM layers to analyze data both forward and backward. This method improves the model's

capacity to identify gestures that might contain intricate movements by offering a more thorough grasp of temporal sequences.

Utilizing Regularization Techniques to Reduce Overfitting: To improve model generalization and resilience, regularization techniques like dropout and L2 regularization are used. To avoid relying too much on particular traits, dropout randomly deactivates a portion of neurons during training. Large weights are penalized by L2 regularization, which pushes the model to pick up more broadly applicable characteristics.

Creating an Easy-to-Use Interface for Speech Synthesis, Multilingual Translation, and Real-Time Interaction: Flask is used to create a web-based interface that enables real-time gesture recognition. The system is usable by a wide range of users thanks to the interface's capability for speech synthesis and multilingual translation. The technology can be used by users to convert text to speech, translate detected text into other languages, and recognize gestures.

By combining these elements, our suggested system seeks to offer a reliable and effective real-time hand gesture detection solution, overcoming the drawbacks of conventional approaches and improving user engagement with cutting-edge deep learning algorithms and an intuitive user interface.

3.3 Feasibility Study

A feasibility study is crucial for evaluating the viability of the proposed gesture recognition system, assessing its technical, economic, operational, and legal aspects to ensure successful implementation.

1. Technical Feasibility:

The proposed system relies on advanced deep learning techniques, primarily Convolutional Neural Networks (CNNs) and Long Short-Term Memory (LSTM) networks, which are well-established in the fields of computer vision and sequence prediction. With existing frameworks like TensorFlow and PyTorch, the development of the system is feasible, given the availability of pre-trained models and robust libraries for implementation. Furthermore, the integration of regularization techniques to prevent overfitting and enhance model generalization is technically sound, ensuring that the system can handle various user inputs effectively. The hardware requirements for processing video frames and running deep learning models are manageable with modern GPUs, making the system feasible for deployment in real-time applications.

2. Economic Feasibility:

The economic viability of the system can be assessed through a cost-benefit analysis. While the initial investment in hardware and development may be significant, the potential benefits include improved communication for users who are deaf or hard of hearing, thereby enhancing accessibility and inclusion. The web-based interface can facilitate easy access for various users, leading to wider adoption and potential revenue generation through subscriptions or institutional partnerships. Additionally, funding opportunities from government and non-profit organizations focused on accessibility technology could further support economic feasibility. A detailed projection of operational costs versus expected benefits will be essential in determining the overall economic viability of the project.

3. Operational Feasibility:

The operational aspect focuses on the implementation and adoption of the system in real-world environments. User acceptance is a key factor; thus, conducting usability testing with target user groups, such as deaf and hard-of-hearing individuals, will be crucial for refining the interface and functionalities. Training and support for users will also need to be established to ensure effective use of the system. Moreover, collaboration with educational institutions and organizations serving individuals with disabilities can promote awareness and facilitate the system's integration into existing communication tools. Finally, ongoing maintenance and updates will be necessary to adapt to user feedback and technological advancements, ensuring the system remains relevant and effective.

3.3.4 Legal Feasibility:

Compliance with regulations regarding accessibility and data privacy is imperative. The system must adhere to laws such as the Americans with Disabilities Act (ADA) and the General Data Protection Regulation (GDPR) if deployed in regions where these laws apply. This involves implementing robust data protection measures, especially if user data is collected for improving system performance. Engaging legal counsel to navigate these requirements during development will be essential to mitigate any potential legal issues and ensure the system's legitimacy and trustworthiness in the eyes of users and stakeholders.

CHAPTER 4

SYSTEM DESIGN

4.1 System Architecture

The system architecture is designed to facilitate real-time gesture recognition using advanced deep learning techniques. It comprises multiple integrated modules that work collaboratively to capture, process, and translate hand gestures into text and speech, enabling interactive communication for users. This architecture leverages technologies such as CNNs and Bi-LSTMs for efficient gesture recognition and provides a user-friendly interface for output.

4.1.1 List of Modules:

1. Data Collection Module
2. Data Preparation Module
3. Model Training Module
4. Evaluation Module
5. Inference Module
6. Translation Module
7. Output Module

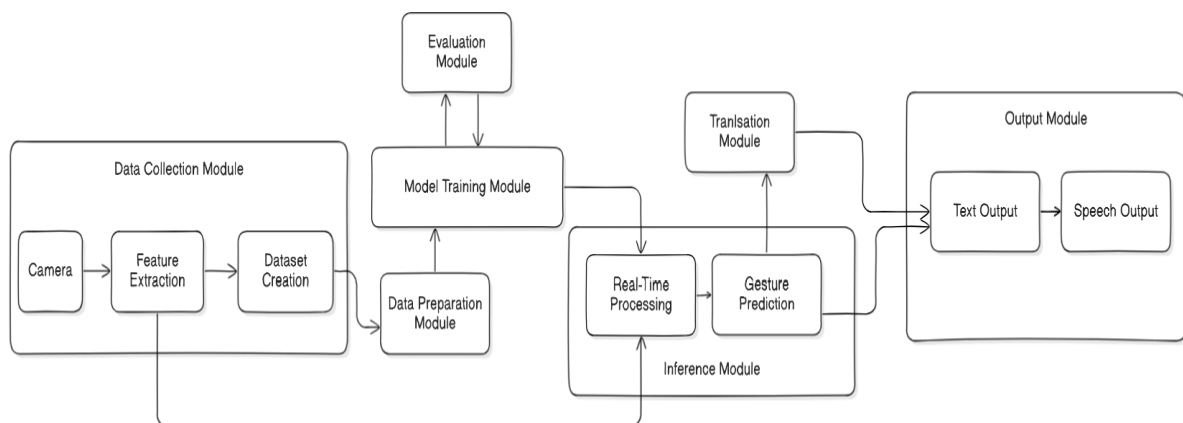


Fig 4.1 : System Architecture Diagram

4.2 Module Descriptions

1. Data Collection Module:

The Data Collection Module is the initial step in the gesture recognition system, primarily responsible for gathering raw video data. A camera captures real-time video frames, which serve as the primary input for feature extraction. Utilizing MediaPipe, this module efficiently extracts critical hand landmarks and movement features, which are essential for accurately identifying various gestures.

Following the extraction, the module creates a comprehensive dataset comprising sequences of gestures. Each gesture is represented by 30 sequences, each containing 30 frames of extracted features. These sequences are saved as .npy files, facilitating easy access and manipulation for subsequent processing stages. This structured approach ensures a rich dataset that enhances model training and performance.

2. Data Preparation Module:

The Data Preparation Module processes the raw data collected from the previous module, ensuring that it is suitable for training the machine learning model. This includes normalization techniques to standardize the data, making it easier for the model to learn from the input. Data augmentation is also applied to artificially increase the diversity of the dataset, simulating variations in gestures that can occur in real-world scenarios.

Furthermore, this module segments the data into individual gestures and splits it into training and testing subsets. This division is crucial, as it allows the model to

learn from a portion of the data while validating its performance on unseen data. By preparing the dataset in this manner, the module helps improve the robustness and accuracy of the model during training.

3. Model Training Module:

The Model Training Module employs a hybrid approach using Convolutional Neural Networks (CNNs) and Bidirectional Long Short-Term Memory (Bi-LSTM) networks. This combination allows for effective learning from both spatial and temporal features within the gesture data. During this phase, the model is trained on the prepared dataset, optimizing its parameters through techniques like gradient descent and backpropagation.

The training process involves feeding the model sequences of gestures, enabling it to learn the patterns associated with each gesture. By adjusting the weights based on the errors observed during training, the model gradually improves its accuracy in gesture recognition. This module plays a critical role in ensuring that the final model can reliably predict gestures in real-time scenarios.

4. Evaluation Module:

The Evaluation Module is essential for assessing the performance of the trained model. It utilizes various metrics such as accuracy, precision, recall, and F1-score to gauge the model's effectiveness in recognizing gestures. By evaluating the model on the test dataset, this module provides insights into its strengths and weaknesses, highlighting areas for improvement.

This evaluation process not only helps in fine-tuning the model but also ensures that it meets the required performance standards for real-time applications. By analyzing the results and iterating on the model based on feedback from this

module, developers can enhance the system's reliability and accuracy before deploying it for user interaction.

5. Inference Module:

The Inference Module is crucial for the real-time operation of the gesture recognition system. It processes video frames captured by the camera, extracting the features necessary for gesture analysis. Once the system has captured a sequence of 30 frames, it prepares the data for prediction by inputting it into the trained model.

Upon processing, the module predicts the gesture based on the extracted features and the learned patterns from the training phase. This real-time analysis enables immediate feedback to users, enhancing interaction and responsiveness. The Inference Module is pivotal in translating visual input into meaningful gesture predictions, making it an integral part of the architecture.

6. Translation Module:

The Translation Module follows the Inference Module and is responsible for converting the predicted gesture text into various languages. This functionality is essential for ensuring that the system is accessible to a wider audience, accommodating users who may not speak the language of the predicted gesture text.

By utilizing language translation algorithms, the module processes the predicted gestures and provides accurate translations based on user selection. This feature not only enhances user experience but also supports effective communication across different linguistic backgrounds. The Translation Module significantly broadens the usability of the gesture recognition system.

7. Output Module:

The Output Module is the final stage of the gesture recognition process, responsible for presenting the results to the user. It displays both the predicted gesture text and the translated text on a web interface, ensuring that users can easily understand the recognized gestures. The interface is designed to be user-friendly, providing a seamless interaction experience.

In addition to text output, this module also incorporates speech synthesis capabilities. Both the predicted gesture text and the translated text are converted into speech, providing auditory feedback for users. This dual output mechanism enhances accessibility, particularly for individuals with visual impairments or those who prefer auditory information, making the system more inclusive.

4.3 Work Flow Diagram

1. **Start:** Initiate the system workflow.
2. **Data Collection:** Gather raw hand gesture data from cameras or sensors.
3. **Preprocessing:** Clean and standardize the data.
4. **Model Training:** Train the CNN-LSTM model with preprocessed data.
5. **Inference:** Apply the trained model to new data for real-time predictions.
6. **Translation:** Convert recognized gestures into text or commands.
7. **Output (Text or Speech):** Generate user-friendly outputs.
8. **Evaluation:** Assess model performance and identify improvements.
9. **Suggest Improvements:** Propose adjustments based on evaluation.
10. **End:** Conclude the workflow, ready for real-time detection.

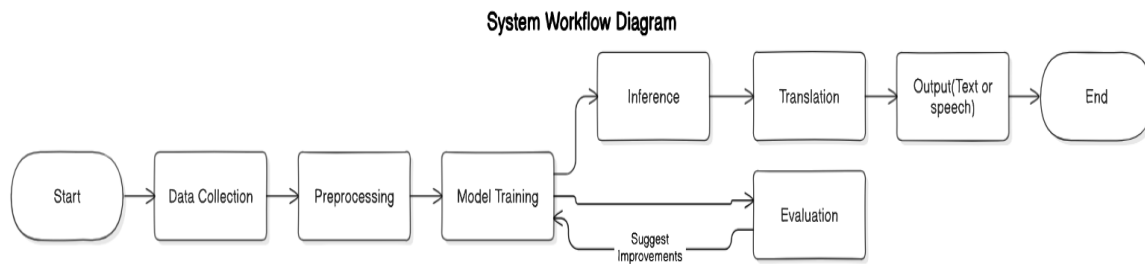


Fig 4.2 : Work Flow Diagram

CHAPTER 5

PROJECT MODULES

5 MODULES

The project consists of seven modules. They are as follows,

1. Data Collection Module
2. Data Preparation Module
3. Model Training Module
4. Evaluation Module
5. Inference Module
6. Translation Module
7. Output Module

5.1 Module Purposes and Usage in the Project

5.1.1 Data Collection Module:

Purpose: The Data Collection Module is designed to capture raw data needed for training the gesture recognition system. Its primary goal is to gather high-quality visual input that reflects the variations and complexities of hand gestures.

Usage in the Project: This module employs a camera to capture real-time video frames of hand movements. MediaPipe is then used to extract key hand features, such as landmark positions and movements. The extracted features are saved as .npy files to create a structured dataset that serves as the foundation for training the machine learning model. By collecting diverse gestures in various conditions, the module ensures that the dataset is rich enough to train a robust recognition model.

5.1.2 Data Preparation Module

Purpose: The Data Preparation Module prepares the collected data for training by normalizing and enhancing it. This ensures that the model receives consistent and diverse input for learning.

Usage in the Project: This module processes the raw data by normalizing values to a common scale, applying data augmentation techniques (like rotation and flipping) to increase the dataset's variety, and segmenting the data into individual gestures. The prepared dataset is then split into training and testing sets, which is crucial for evaluating the model's performance and ensuring it generalizes well to new data. Proper data preparation is essential for effective model training, as it directly impacts the accuracy and reliability of the gesture recognition system.

5.1.3 Model Training Module

Purpose: The Model Training Module aims to build and optimize a machine learning model capable of recognizing gestures based on the prepared data.

Usage in the Project: This module utilizes a hybrid architecture that combines Convolutional Neural Networks (CNNs) and Bidirectional Long Short-Term

Memory (Bi-LSTM) networks. The CNN extracts spatial features from images, while the Bi-LSTM captures temporal dynamics from sequences of frames. By feeding the normalized and augmented dataset into this model, the module trains it through optimization techniques to accurately recognize various hand gestures. The training process is crucial for enabling the system to learn the patterns necessary for effective gesture recognition.

5.1.4 Evaluation Module

Purpose: The Evaluation Module is responsible for assessing the performance of the trained model, ensuring that it meets the desired accuracy and reliability standards.

Usage in the Project: After training, this module evaluates the model using metrics such as accuracy, precision, recall, and F1-score. By analyzing these metrics, the module identifies areas for improvement, such as overfitting or underfitting. This feedback is essential for refining the model further, whether through additional training, adjusting parameters, or improving data quality. Continuous evaluation helps maintain the model's effectiveness in real-world applications.

5.1.5 Inference Module

Purpose: The Inference Module provides real-time predictions of hand gestures based on live camera input, enabling interactive user experiences.

Usage in the Project: This module processes video frames captured by the camera in real time. Once a sequence of 30 frames is reached, the module extracts relevant features and predicts the corresponding gesture using the trained model.

This capability allows users to interact with the system instantly, receiving immediate feedback on their gestures. Real-time processing is essential for making the gesture recognition system responsive and engaging for users.

5.1.6 Translation Module

Purpose: The Translation Module translates recognized gestures into selected languages, enhancing the system's inclusivity and accessibility.

Usage in the Project: After a gesture is predicted, this module translates the corresponding text into the user's chosen language. This feature is particularly beneficial for non-native speakers, allowing them to communicate effectively through gestures. By supporting multiple languages, the Translation Module ensures that the system can cater to a diverse audience, making it more user-friendly and versatile.

5.1.7 Output Module

Purpose: The Output Module presents the results of the gesture recognition and translation processes to the user in an understandable format.

Usage in the Project: This module displays both the predicted gesture and its translation on a web interface. Additionally, it converts both texts to speech, providing auditory feedback for users. The output can be displayed as text in separate fields, ensuring clarity, while the speech output enhances the user experience, particularly for those with visual impairments. By effectively presenting results, the Output Module closes the loop of interaction, enabling users to receive comprehensive feedback from the gesture recognition system.

CHAPTER 6

SYSTEM REQUIREMENTS

6.1 Introduction

This chapter involves the technology used, the hardware requirements ,the software requirements and the environmental requirements for the project .

6.2 Requirements

6.2.1 Hardware Requirements

1. Camera: High-resolution webcam or built-in camera for capturing hand gestures in real-time, ensuring clear and precise input for the system. The camera must support at least 720p resolution to accurately capture the nuances of hand movements and gestures.

2. Processor: Multi-core processor (Intel i5 or above) to handle the computational load of real-time video processing and machine learning model inference efficiently. A higher-end processor (e.g., Intel i7 or AMD Ryzen 7) is recommended for better performance during intensive tasks such as model training and real-time inference.

3. Memory: Minimum 8GB RAM to ensure smooth data handling and processing, accommodating the needs of video data and machine learning operations. For more intensive use cases or larger datasets, 16GB or more is recommended to prevent memory bottlenecks.

4. Storage: SSD with at least 256GB capacity for storing datasets, model weights, and other necessary files, ensuring fast read/write speeds and adequate storage space. Additional storage may be required based on the size of datasets and the number of models being developed and tested.

5. Graphics Card: Dedicated GPU (NVIDIA GTX 1050 or higher) for accelerating model training and inference, providing the necessary computational power for deep learning tasks. A higher-end GPU such as the NVIDIA RTX series will significantly reduce training times and improve real-time inference performance.

6. Internet Connection: Stable internet connection for accessing online resources, cloud services, and potential updates to the software and models. High-speed internet is recommended for faster download and upload speeds, especially when working with cloud-based resources or large datasets.

6.2.2 Software Requirements

1. Operating System: Compatible with multiple OS options such as Windows 10 or later, macOS 10.15 or later, and Ubuntu 18.04 or later, offering flexibility in deployment environments. The operating system should be kept up-to-date with the latest patches and updates to ensure security and compatibility.

2. Programming Languages: Python 3.7 or later for development and implementation, chosen for its extensive libraries and community support. Other languages such as JavaScript (for front-end development) may also be required.

3. Development Environment: Jupyter Notebook or any other Python IDE (like PyCharm, VSCode) for coding and experimentation, providing a user-friendly

interface for development. Integrated development environments should support debugging, version control, and project management features.

4. Browser: Modern web browser (Google Chrome, Mozilla Firefox, Microsoft Edge) for accessing the web-based user interface, ensuring compatibility and ease of use. Browsers should be kept up-to-date to ensure support for the latest web standards and security features.

5. Libraries and Frameworks:

- **TensorFlow/Keras:** For building and training deep learning models, providing robust tools for neural network development.
- **OpenCV:** For video capture and image processing, enabling efficient handling of video frames and feature extraction.
- **MediaPipe:** For hand landmark detection, offering advanced and reliable hand tracking capabilities.
- **NumPy:** For numerical computations and data manipulation, essential for preprocessing steps.
- **Flask:** For developing the web-based user interface, allowing for real-time interaction with the system.
- **SpeechRecognition:** For converting text to speech, enhancing the accessibility of the system.
- **scikit-learn:** For additional machine learning utilities and evaluation metrics.

6.2.3 Environmental Requirements

1. Physical Environment: Adequate lighting to ensure clear video capture, reducing shadows and improving the accuracy of hand landmark detection.

Proper lighting minimizes noise and enhances the system's performance. A stable and non-distracting background to minimize noise in video frames, enhancing the reliability of gesture recognition. A clean background ensures that the hand landmarks are easily distinguishable.

2. Operational Environment: Temperature-controlled setting to ensure the consistent performance of hardware components, especially important for long-term use. Overheating can cause hardware malfunctions and degrade performance. Secure environment to protect the hardware and data from unauthorized access and potential damage. Security measures should include physical locks, access controls, and regular monitoring.

CHAPTER 7

PERFORMANCE ANALYSIS

The performance analysis of the gesture recognition model is critical for evaluating its effectiveness and identifying areas for improvement. This analysis encompasses various metrics and visualizations that provide insights into how well the model performs on unseen data.

7.1 Model Evaluation Metrics

The model's performance is initially assessed through test loss and accuracy calculated on the test dataset. Test loss indicates how well the model predicts the output, while accuracy reflects the proportion of correct predictions among all predictions made. Together, these metrics provide a clear overview of the model's generalization capability.

$$\text{Accuracy} = 0.9667 \ \& \ \text{Loss} = 0.3127$$

7.2 Confusion Matrix

The confusion matrix serves as a vital tool for visualizing the performance of the classification model. It displays the counts of true positive, true negative, false positive, and false negative predictions for each gesture class. This matrix allows for detailed inspection of which gestures are being correctly identified and which are frequently misclassified, providing valuable insights for further model training and refinement.

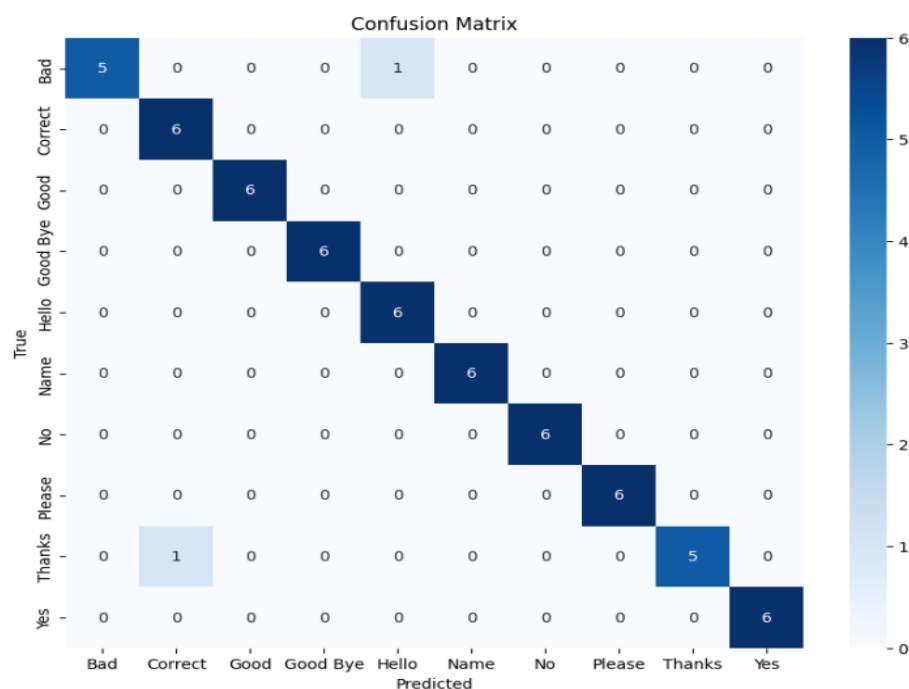


Fig 7.1 Confusion Matrix

7.3 Classification Report

A comprehensive classification report is generated, detailing precision, recall, and F1-score for each gesture class. Precision indicates the accuracy of positive predictions, recall reflects the model's ability to find all relevant instances, and the F1-score provides a balance between precision and recall. This report is essential for understanding the model's performance beyond mere accuracy,

especially in scenarios with multiple gesture classes where certain classes may be more challenging to predict accurately.

Classification Report:				
	precision	recall	f1-score	support
Bad	1.00	0.83	0.91	6
Correct	0.86	1.00	0.92	6
Good	1.00	1.00	1.00	6
Good Bye	1.00	1.00	1.00	6
Hello	0.86	1.00	0.92	6
Name	1.00	1.00	1.00	6
No	1.00	1.00	1.00	6
Please	1.00	1.00	1.00	6
Thanks	1.00	0.83	0.91	6
Yes	1.00	1.00	1.00	6
accuracy			0.97	60
macro avg	0.97	0.97	0.97	60
weighted avg	0.97	0.97	0.97	60

Fig 7.2 Classification Report

7.4 Training and Validation Metrics

Training and validation metrics are visualized through plots that illustrate accuracy and loss over epochs. These visualizations reveal the model's learning behavior during training, indicating trends such as overfitting (where the model performs well on training data but poorly on validation data) or underfitting (where the model fails to capture underlying patterns in the data). Monitoring these metrics is crucial for making informed decisions regarding model adjustments and improvements.

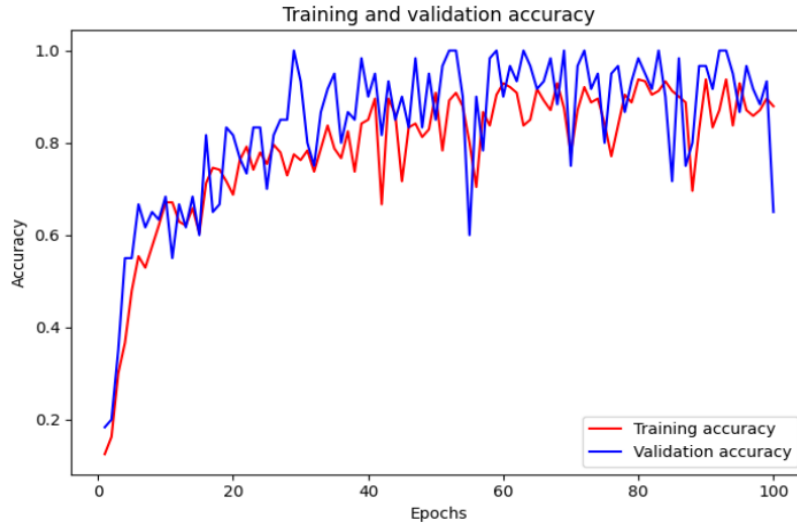


Fig 7.3 Training Accuracy Vs. Validation Accuracy Graph

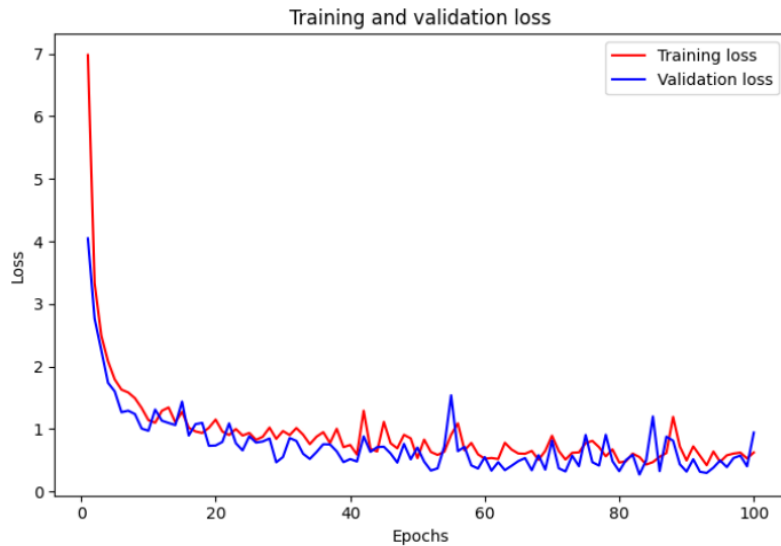


Fig 7.4 Training Loss Vs. Validation Loss Graph

7.5 ROC Curve Analysis

The Receiver Operating Characteristic (ROC) curve is plotted for each gesture class, illustrating the trade-off between sensitivity (true positive rate) and specificity (false positive rate) at various classification thresholds. The area under the ROC curve (AUC) quantifies the overall ability of the model to discriminate between classes. This analysis helps in selecting optimal classification thresholds based on the specific application requirements, enhancing model performance.

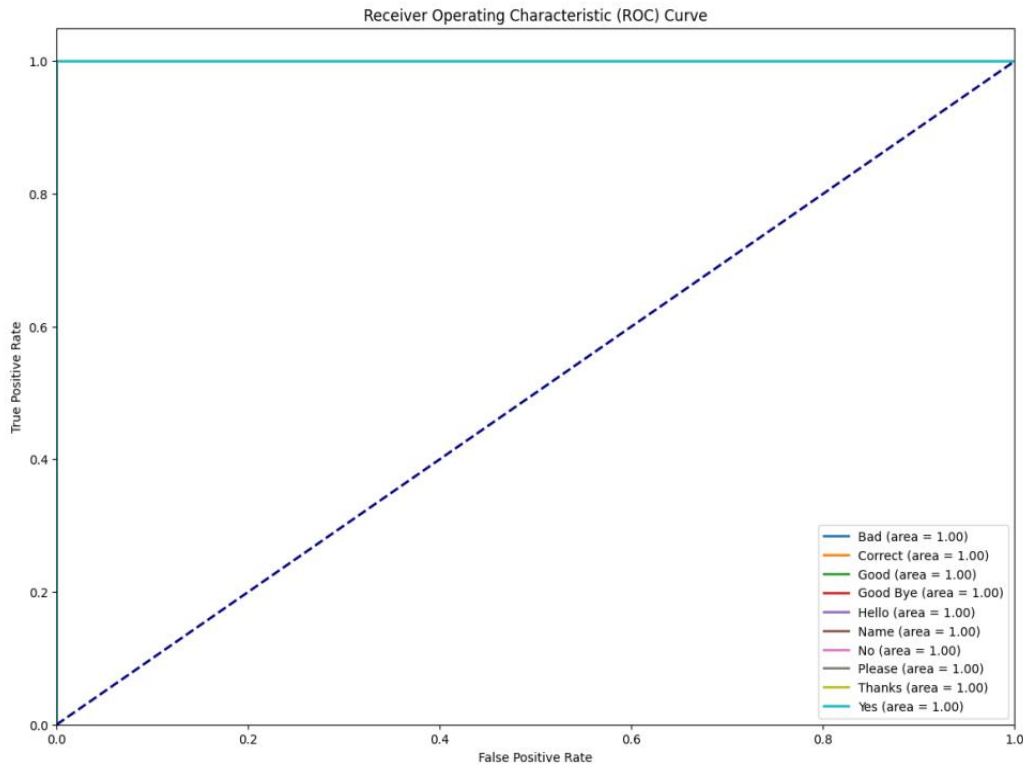


Fig 7.5 ROC Curve

7.6 Real-Time Analysis

The real-time gesture recognition system leverages advanced deep learning techniques to recognize hand gestures using a webcam feed. The application is built with Flask, utilizing several libraries such as OpenCV, TensorFlow, and MediaPipe for video processing and gesture detection. Below is an analysis of the key functionalities and features of the application, complemented by a screenshot of the web interface.

Key Features:

1. Real-Time Gesture Recognition: The application captures video frames from the webcam, detects hand movements, and recognizes gestures in real time using a trained CNN-LSTM model.

2. Gesture Translation: Recognized gestures are translated into text using the Google Translate API, allowing for a multilingual interface.

3. User Control: Users can start and stop the gesture recognition process through buttons on the web interface, enabling flexibility in operation.

4. Feedback Display: The recognized gestures are displayed in real time on the video feed, providing immediate feedback to the user.

5. Language Settings: Users can change the target language for translation, enhancing the system's usability across different languages.

6. Clear and Backspace Functions: The application includes functionality to clear recognized text or delete the last recognized gesture, allowing for better text management.

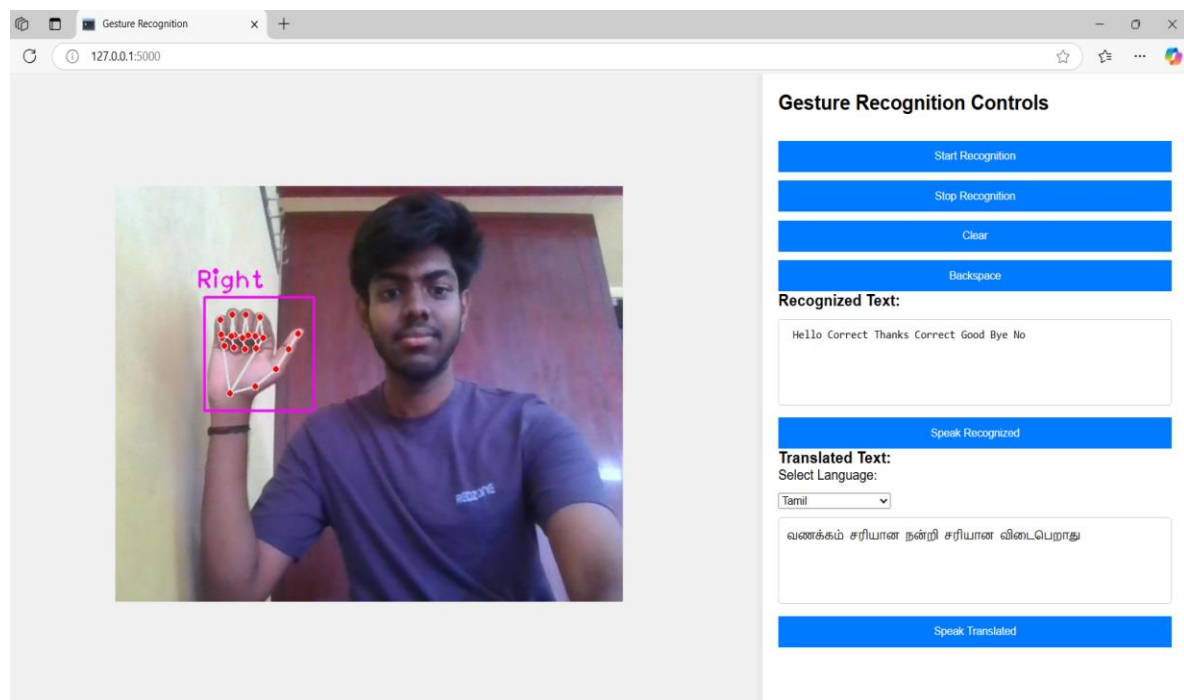


Fig 7.6 Real Time Web Page Interface

CHAPTER 8

CONCLUDING REMARKS

8.1 CONCLUSION

In this study, we successfully developed a real-time hand gesture detection system utilizing CNN-LSTM networks, effectively addressing the limitations of traditional gesture recognition methods. By integrating advanced CNN and LSTM architectures, we created a robust model capable of accurately identifying gestures in various scenarios. The incorporation of bidirectional layers and regularization techniques further enhanced the model's resilience, making it suitable for a diverse user base and highlighting its potential for applications in areas like virtual reality, sign language interpretation, and remote device control.

Our system features an intuitive user interface built with Flask, enabling real-time communication, multilingual translation, and speech synthesis. This design choice ensures accessibility for a wide range of users, enhancing overall user interaction. The combination of sophisticated deep learning models with a user-friendly interface exemplifies the system's versatility and opens up numerous possibilities for real-world implementation, including in educational and assistive technologies.

Looking ahead, we envision several enhancements to improve the system's capabilities. Integrating Natural Language Processing (NLP) can facilitate the conversion of recognized gestures into coherent sentences, enriching communication further. Additional features, such as multi-user support, gesture customization, and adaptability to varying environmental conditions, can

significantly broaden its application scope. By continuously expanding the gesture library and implementing enhanced security measures, we aim to create a more comprehensive and secure user experience, ultimately contributing to more inclusive technological solutions for all users.

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