Erdem Bıyık

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CURRENT POSITION

University of Southern California

Assistant Professor of Computer Science

Los Angeles, CA, USA

Aug 2023 - present

EDUCATION

Stanford University

• Doctor of Philosophy in Electrical Engineering; GPA: 4.07/4.00 Advisor: Prof. Dorsa Sadigh Stanford, CA, USA

Sep 2017 - Jun 2022

Stanford University

Master of Science in Electrical Engineering; GPA: 4.08/4.00

Stanford, CA, USA Sep 2017 - Apr 2019

Bilkent University

• Bachelor of Science in Electrical and Electronics Engineering; GPA: 4.00/4.00 Rank: 1/170 based on GPA Ankara, Turkey

Aug 2012 - Jun 2017

National University of Singapore

Exchange Student in Electrical and Computer Engineering

Singapore
Aug 2015 - Dec 2015

WORK EXPERIENCE

UC Berkeley, Center for Human-Compatible Artificial Intelligence (CHAI)

Berkeley, CA, USA Jul 2022 - Jul 2023

 $Postdoctoral\ Researcher$

- Reward Learning: Working on various active reward learning projects for robotics under the supervision of Prof. Stuart Russell and Prof. Anca Dragan
- Reinforcement Learning for Brain Co-processors: Working on the applications of reinforcement learning algorithms for brain co-processors under the supervision of Prof. Anca Dragan

Google Research

Research Intern

Mountain View, CA, USA

Jun 2021 - Sep 2021

- Recommender Systems: Working on active preference elicitation for recommender systems under the supervision of Dr. Yinlam Chow, Dr. Mohammad Ghavamzadeh, and Prof. Craig Boutilier
- **Preference-based Reinforcement Learning**: Working on relaxing initial state assumptions in preference-based reinforcement learning under the supervision of Dr. Yinlam Chow and Dr. Mohammad Ghavamzadeh

National Magnetic Resonance Research Center (UMRAM)

Ankara, Turkey

Undergraduate Researcher & Research Intern

Apr 2016 - Sep 2017

- o csMRI: Developing compressed sensing methods for accelerated MRI under the supervision of Prof. Tolga Çukur
- **SSFP Imaging**: Developing coil compression methods and artifact suppression techniques for balanced SSFP under the supervision of Prof. Tolga Çukur

ASELSAN Ankara, Turkey

Intern (2015), Research Engineer (2017)

Jun 2015 - Jul 2015, Apr 2017 - Aug 2017

- Military Communications (2015): Developing a C++ program to decode and encode data in MIL-STD-3014 protocol with an easy-to-use interface
- Algorithms Design (2015): Designing algorithms to solve composite launch acceptability region problem
- SSFP Imaging (2017): R&D projects related to field inhomogeneity, banding profile estimation, coil compression and banding suppression in bSSFP MRI under the supervision of Dr. Aykut Koç

École polytechnique fédérale de Lausanne (EPFL)

Research Intern via Summer@EPFL Program

Lausanne, Switzerland

Jun 2016 - Sep 2016

• Approximate Message Passing: Research about approximate message passing algorithms as an intern in the Information Processing Group under the supervision of Prof. Rüdiger Urbanke

Anadolu Agency

Ankara, Turkey

Intern

Jun 2014 - Jul 2014

• Image Processing: Developing a Java, C++ and MySQL based program that uses image registration, matching and comparison techniques to detect copyright infringements

TEACHING EXPERIENCE

University of Southern California

Los Angeles, CA

Instructor

Fall 2023

o CSCI699 Robot Learning: Designing and teaching the course

Stanford University

Stanford, CA

Teaching Assistant

Winter 2020, Winter 2021

• CS237B / EE260B / AA174B / AA274B Principles of Robot Autonomy II: Holding office hours and sections, preparing and grading homeworks and exams

Awarded "outstanding course assistant" by the CS department (top 5%) in Winter 2021

Bilkent University

Ankara, Turkey

Teaching Assistant

Spring 2014, Fall 2016

- CS114 Introduction to Programming for Engineers (2014): Teaching in the weekly tutorials & recitations
- EEE211 Analog Electronics (2016): Teaching, interviewing and grading students in the laboratory sessions

Stanford University

Stanford, CA

Guest Lecturer

Winter 2022

o CS333 Safe and Interactive Robotics: Teaching "learning from human preferences"

MENTORING

- Current Ph.D. Students: Ayush Jain (co-advised with Joseph Lim), Sumedh Sontakke (co-advised with Laurent Itti), Anthony Liang (co-advised with Jesse Thomason), Jesse Zhang (co-advised with Jesse Thomason and Joseph Lim), Pavel Czempin, Yigit Korkmaz
- Current M.Sc. Students: Xinhu Li, Chen Liu, Dhanush Kumar Varma Penmetsa, Thomas Reeves, Zhaojing Yang
- Current Undergraduate Students: Miru Jun

Honors & Awards

- Stanford CS Outstanding Course Assistant: Awarded to the top 5% of CAs in the department. Awarded for the "Principles of Robot Autonomy II" course in Winter 2021
- Qualcomm Innovation Fellowship 2020 North America: Finalist (as a group of two PhD students)
- HRI 2020 Honorable Mention: Awarded for the paper "When Humans Aren't Optimal: Robots that Collaborate with Risk-Aware Humans"
- Qualcomm Innovation Fellowship 2019 North America: Finalist (as a group of two PhD students)
- Stanford University James D. Plummer Graduate Fellowship (2017-2018): Full tuition waiver & stipend during the first year of PhD program
- Bilkent University Electrical and Electronics Engineering Department, Graduation Awards (2017): Academic Excellence, Research Excellence, Voluntary Professional Activities, Social Awareness and Activities

- Scholarship of the Turkish Prime Ministry (2012-2017): Awarded monthly stipend during the BSc program (given to those who rank in first 100 among 1.8 million students in nationwide university entrance exam)
- Bilkent University Comprehensive Scholarship (2012-2017): Full tuition waiver & stipend during the BSc program
- IEEExtreme Programming Competitions: 2nd in Turkey, 78th among all participants, 2015. 1st in Turkey, 73rd among all participants, 2014. 1st in Turkey, 100th among all participants, 2013 (All as a group of three students)
- Turkish Intelligence Foundation (TZV) Marathon: Ranked twice in top 25 and once 6th, 2012-2014
- İşbank Golden Youth Award (2012): Granted for outstanding performance in the nationwide university entrance exam
- Nationwide University Entrance Exam (LYS): Ranked 13th among 1.8 million students in Turkey, 2012

Invited Talks & Poster Presentations

- Data-Efficient Learning from Human Feedback and Large Pretrained Models for Robotics
 - o Arizona State University, School of Computing and Augmented Intelligence (2023)
- Open Problems in Reinforcement Learning from Human Feedback and Potential Solutions for Data-Efficiency
 - o University of Amsterdam, The Amsterdam Machine Learning Lab (2023)
- Efficient Robot Learning via Interaction with Humans
 - o Southern California Robotics (SCR) Symposium 2023
- ViSaRL: Visual Reinforcement Learning Guided by Human Saliency
 - o 7th Annual Center for Human-Compatible Artificial Intelligence (CHAI) Workshop (2023 poster)
- Learning Preferences for Interactive Autonomy
 - o Middle East Technical University, Robotics and AI Technologies Application and Research Center (2022)
 - Sonoma State University, Engineering Colloquium (2022)
 - o Cornell University, Robotics Seminar (2022)
 - University of Wisconsin-Madison, Computer Science, Department Seminar (2022)
 - o University of Illinois Urbana-Champaign, Computer Science, Department Seminar (2022)
 - o University of Michigan, Robotics Institute, Department Seminar (2022)
 - o University of Southern California, Computer Science, Department Seminar (2022)
 - o Imperial College London, Department of Aeronautics, Aerodynamics & Control Seminar (2022)
 - o Carnegie Mellon University, Robotics Institute, Department Seminar (2022)
 - UCLA, Electrical and Computer Engineering, Department Seminar (2022)
 - o Bilkent University, Electrical and Electronics Engineering, Graduate Seminar (2021)
 - o UC Berkeley, Center for Human-Compatible Artificial Intelligence (CHAI), Beneficial AI Seminar (2021)
 - Sabancı University, Computer Science & Engineering, Department Seminar (2021)
 - Koc University, AI Meetings (2021)
 - Bay Area Robotics Symposium (BARS) 2021 (poster)
 - o Virginia Tech, Mechanical Engineering, Department Seminar (2021)
 - Caltech Yue Lab (2021)
 - UT Austin Personal Autonomous Robotics Lab (2021)
 - UC Berkeley InterACT Lab (2021)
- Learning Multimodal Rewards from Rankings

- o 6th Annual Center for Human-Compatible Artificial Intelligence (CHAI) Workshop (2022)
- o CoRL 2021
- Learning from Humans for Adaptive Interaction
 - HRI Pioneers 2022
- APReL: A Library for Active Preference-based Reward Learning Algorithms
 - o Human-Interactive Robot Learning (HIRL) (Workshop at HRI 2022)
 - o HRI 2022
 - AI-HRI 2021 at AAAI Fall Symposium Series
- Partner-Aware Algorithms in Decentralized Cooperative Bandit Teams
 - o AAAI 2022
 - o AI-HRI 2021 at AAAI Fall Symposium Series
- The Role of Representations in Human-Aware Learning and Control (with Dorsa Sadigh)
 - o "Aware-Learning: How to Benefit from Priors" Workshop @ CDC 2021
- Interactive Robotics through the Lens of Learning (with Dorsa Sadigh)
 - NCCR (The National Centre of Competence in Research, Switzerland) Automation Seminar, 2021
- Leveraging Smooth Attention Prior for Multi-Agent Trajectory Prediction
 - Center for Automotive Research at Stanford (CARS) Annual Meeting (2021 poster)
- Learning Reward Functions from Scale Feedback
 - o CoRL 2021 (poster)
- Learning how to Dynamically Route Autonomous Vehicles on Shared Roads
 - ETH Zurich, Institute for Dynamic Systems and Control, Autonomy Talks (2021)
 - The 32nd IEEE Intelligent Vehicles Symposium Workshop (2021)
 - 3rd NorCal Control Workshop (2021)
 - Stanford Robotics Lunch (2019)
 - Center for Automotive Research at Stanford (CARS) Annual Meeting (2020 poster)
- Walking the Boundary of Learning and Interaction (with Dorsa Sadigh)
 - 3rd Robot Learning Workshop: Grounding Machine Learning Development in the Real World @ NeurIPS 2020
- When Humans Aren't Optimal: Robots that Collaborate with Risk-Aware Humans (with Minae Kwon)
 - o University of Chicago, Graduate Seminar on Topics in Human-Robot Interaction (2020)
- Active Preference-Based Gaussian Process Regression for Reward Learning
 - o RSS 2020
- The Green Choice: Learning and Influencing Human Decisions on Shared Roads
 - o CDC 2019
- Active Learning of Reward Dynamics from Hierarchical Queries
 - o IROS 2019
- Asking Easy Questions: A User-Friendly Approach to Active Reward Learning

- o CoRL 2019 (poster)
- Efficient and Safe Exploration in Deterministic Markov Decision Processes with Unknown Transition Models
 - o ACC 2019
 - Stanford AI Safety Retreat 2019 (poster)
- Batch Active Preference-Based Learning of Reward Functions
 - o CoRL 2018
 - Stanford HAI 2019 (poster)
 - TRI Joint University Workshop 2019 (poster)
 - Stanford SystemX Fall 2018 (poster)
 - o BARS Bay Area Robotics Symposium (BARS) 2018 (poster)

Professional Activities

• Conferences Organized

- o Finance Chair, Conference on Robot Learning (CoRL), 2024
- o Local Arrangements Chair, Bay Area Robotics Symposium (BARS), 2021
- o Local Arrangements Chair, Bay Area Robotics Symposium (BARS), 2020
- Organizer, Emergent Behaviors in Human-Robot Systems (Workshop at Robotics: Science and Systems (RSS)), 2020
- o Local Arrangements Chair, Bay Area Robotics Symposium (BARS), 2018

• Program Committee Member

o Center for Human-Compatible Artificial Intelligence (CHAI) Workshop, 2023

• Area Chair

Responsible AI (RAI) (Workshop at International Conference on Learning Representations (ICLR)),
 2021

• Reviewer for Journals

- ACM Transactions on Human-Robot Interaction (THRI)
- Artificial Intelligence
- Autonomous Robots (AURO)
- o Cognitive Systems Research
- o Frontiers in Robotics and AI
- Nature Communications
- IEEE Control System Letters (L-CSS)
- IEEE Robotics and Automation Letters (RA-L)
- IEEE Robotics and Automation Magazine (RAM)
- IEEE Transactions on Automatic Control (TAC)
- IEEE Transactions on Control Systems Technology (TCST)
- IEEE Transactions on Human-Machine Systems (THMS)
- IEEE Transactions on Intelligent Transportation Systems (T-ITS)
- IEEE Transactions on Neural Networks and Learning Systems (TNNLS)
- IEEE Transactions on Robotics (T-RO)

- Journal of Machine Learning Research (JMLR)
- o Proceedings of the Royal Society A
- Robotics
- The International Journal of Robotics Research (IJRR)

• Reviewer for Conferences

- IEEE International Conference on Robotics and Automation (ICRA), 2021–2024
- ACM/IEEE International Conference on Human-Robot Interaction (HRI), 2020–2024
- o Conference on Neural Information Processing Systems (NeurIPS), 2023
- o IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2020, 2022–2023
- o IEEE Conference on Decision and Control (CDC), 2019–2020, 2023
- $\circ\,$ Conference on Robot Learning (CoRL), 2019–2023
- o Robotics: Science and Systems (RSS), 2020–2021, 2023
- o Conference on Uncertainty in Artificial Intelligence (UAI), 2023
- o Learning for Dynamics & Control (L4DC), 2020, 2023
- o International Joint Conference on Artificial Intelligence (IJCAI), 2023
- American Control Conference (ACC), 2019, 2021–2022
- IEEE Conference on Control Technology and Applications (CCTA), 2021
- o IEEE-RAS International Conference on Humanoid Robots (Humanoids), 2020
- o International Conference on Computer-Aided Verification (CAV), 2019
- o ACM International Conference on Hybrid Systems: Computation and Control (HSCC), 2019

• Reviewer for Workshops

- o HRI Pioneers Workshop 2023–2024
- o Interactive Learning with Implicit Human Feedback Workshop (ILHF) at ICML 2023
- AAMAS Workshop on Rebellious and Disobedient AI (RaD-AI), 2022–2023
- o RSS Pioneers Workshop 2023
- o CoRL Workshop on Aligning Robot Representations with Humans, 2022
- NeurIPS Workshop on Foundation Models for Decision Making (FMDM), 2022
- o NeurIPS Workshop on Progress and Challenges in Building Trustworthy Embodied AI (TEA), 2022
- NeurIPS Workshop on Machine Learning Safety, 2022
- RSS Workshop on Learning from Diverse, Offline Data (L-DOD), 2022
- o RSS Workshop on Social Intelligence in Humans and Robots, 2022
- Artificial Intelligence for Human-Robot Interaction Symposium (AI-HRI) at AAAI Fall Symposium Series, 2021
- o ICRA Workshop on Social Intelligence in Humans and Robots, 2021
- Bridging AI and Cognitive Science (BAICS) (Workshop at International Conference on Learning Representations (ICLR)), 2020

- Berkeley Artificial Intelligence Safety Initiative for Students, 2023-present Berkeley, CA, USA
 - Mentor at Supervised Program for Alignment Research: Mentoring three undergraduate students on a multi-agent inverse reinforcement learning research project
- Berkeley Artificial Intelligence Research Lab (BAIR), 2022-2023

Berkeley, CA, USA

- BAIR Undergraduate Mentoring Program Mentor: Mentoring undergraduate students about their future career, getting involved in AI research, and applying for industry or graduate school
- Stanford University Department of Computer Science, 2020-2022

Stanford, CA, USA

- o CS Mentorship Program Organizer: Organizing the CS mentorship program and the related social events
- CS Mentorship Program Mentor: Mentoring first and second-year undergraduate students about their future career, getting involved in research projects, and applying for industry or graduate school
- Stanford University AI Laboratory (SAIL), 2018-2020

Stanford, CA, USA

- o AI Mentorship Program Organizer: Organizing the AI mentorship program and the related social events
- AI Mentorship Program Mentor: Mentoring first and second-year undergraduate students about their future career, getting involved in AI research, and applying for industry or graduate school
- Robotics Lunch Organizer (2019-2020): Organizing bi-weekly robotics lunch sessions where invited professors, postdoctoral researchers and Ph.D. candidates present their research
- Stanford STEM to SHTEM Summer Internship Program, 2019

Stanford, CA, USA

- o Mentor: Mentoring high school students in a research project about decision making under risk / time constraints
- IEEE Bilkent Student Branch, 2012-2017

Ankara, Turkey

- Road to University Volunteer (2013-2017): Introducing engineering and campus life to high school students from all around Turkey
- Vice Chair (2014-2015): Managing and organizing the technical trainings and social events
- Robotics and Automation Society Member (2012-2015): Assistantship in the electronics and robotics focused tutorials
- Web Team Member (2012-2014) and Webmaster (2013-2014): Designing and managing the website of IEEE Bilkent SB, its communities and events; teaching in web design tutorials and in MATLAB tutorials; organizing a Java programming competition and weekly brain teasers
- GazeteBilkent, 2014-2017

Ankara, Turkey

- o Online Operations Manager: Managing the website of GazeteBilkent, an online newspaper
- Bilkent University, 2014-2017

Ankara, Turkey

- Webmaster of Electrical and Electronics Engineering (2013-2017), Mechanical Engineering (2015-2017), Economics (2016-2017) Departments: Designing, developing and managing the websites of the departments and developing necessary web tools
- 1st and 2nd Industrial Design Projects Fairs Student Coordinator and Webmaster (2015, 2016): Organizing the fair in which the senior students of Bilkent EEE present their industry projects
- Graduate Research Conference '15 Student Coordinator (2015): Organizing the conference series in which graduate students of Bilkent EEE present their research and projects
- Graduate Research Conference '14 Webmaster and Organization Team Member (2014): Organizing the conference series in which graduate students of Bilkent EEE present their research and projects
- Bilkent Chess Society, 2013-2014

Ankara, Turkey

- Vice Chair: Organizing tournaments on campus, participating in local events as a team
- Bilkent Academic Career Club, 2013

Ankara, Turkey

o Physics Olympiads Volunteer: Organizing a physics competition among high school students

 Z Cao, E Bıyık, WZ Wang, A Raventos, A Gaidon, G Rosman, D Sadigh. "Reinforcement Learning Based Control of Imitative Policies for Autonomous Driving", US Patent Application No. US17/002,650.

JOURNAL PUBLICATIONS

- E Bıyık, N Huynh, MJ Kochenderfer, D Sadigh. "Active Preference-Based Gaussian Process Regression for Reward Learning and Optimization", The International Journal of Robotics Research (IJRR), 2023; doi: 10.1177/02783649231208729.
- 2. **E Biyik**, N Anari, D Sadigh. "Batch Active Learning of Reward Functions from Human Preferences", ACM Transactions on Human-Robot Interaction (THRI), 2022. (Submitted)
- 3. M Tucker, K Li, E Novoseller, M Pétriaux, G Burger, **E Bıyık**, M Masselin, D Sadigh, JW Burdick, Y Yue, AD Ames. *Anonymous Submission*, Nature Machine Intelligence, 2022. (Submitted)
- 4. E Bıyık, DP Losey, M Palan, NC Landolfi, G Shevchuk, D Sadigh. "Learning Reward Functions from Diverse Sources of Human Feedback: Optimally Integrating Demonstrations and Preferences", The International Journal of Robotics Research (IJRR), 2022; doi:10.1177/02783649211041652
- 5. DA Lazar*, **E Bıyık***, D Sadigh, R Pedarsani (*equal contribution). "Learning How to Dynamically Route Autonomous Vehicles on Shared Roads", Transportation Research Part C: Emerging Technologies (TR_C), 2021; doi: 10.1016/j.trc.2021.103258
- E Bıyık*, DA Lazar*, R Pedarsani, D Sadigh (*equal contribution). "Incentivizing Efficient Equilibria in Traffic Networks with Mixed Autonomy", IEEE Transactions on Control of Network Systems (TCNS), 2021; doi: 10.1109/TCNS.2021.3084045.
- 7. E Biyik*, K Keskin*, SUH Dar, A Koc, T Çukur (*equal contribution). "Factorized sensitivity estimation for artifact suppression in phase-cycled bSSFP MRI", NMR in Biomedicine, 2020; doi: 10.1002/nbm.4228.
- 8. **E Biyik**, E Ilicak, T Çukur. "Reconstruction by Calibration over Tensors for Multi-Coil Multi-Acquisition Balanced SSFP Imaging", Magnetic Resonance in Medicine (MRM), 2017; doi: 10.1002/mrm.26902.
- 9. E Ilicak, LK Senel, **E Biyik**, T Çukur. "Profile-encoding reconstruction for multiple-acquisition balanced steady-state free precession imaging", Magnetic Resonance in Medicine (MRM), 2016; doi: 10.1002/mrm.26507.

REFEREED CONFERENCE PUBLICATIONS

- 10. A Liang, J Thomason, E Biyik. ViSaRL: Visual Reinforcement Learning Guided by Human Saliency, 2024 IEEE International Conference on Robotics and Automation (ICRA), Yokohama, Japan, May 2024. (Submitted)
- 11. E Ellis, SJ Russell, A Dragan, **E Biyik**. Self-Supervision Improves Data Efficiency in Reinforcement Learning from Human Feedback, 2024 IEEE International Conference on Robotics and Automation (ICRA), Yokohama, Japan, May 2024. (Submitted)
- 12. E Ellis, GR Ghosal, SJ Russell, A Dragan, **E Biyik**. A Generalized Acquisition Function for Preference-based Reward Learning, 2024 IEEE International Conference on Robotics and Automation (ICRA), Yokohama, Japan, May 2024. (Submitted)
- 13. S Sontakke, S Arnold, J Zhang, K Pertsch, **E Biyik**, D Sadigh, C Finn, L Itti. *RoboCLIP: One Demonstration is Enough to Learn Robot Policies*, 37th Conference on Neural Information Processing Systems (NeurIPS), New Orleans, Louisiana, USA, Nov. 2023.
- 14. V Myers, **E Biyik**, D Sadigh. Asking Preference Questions Online in Active Reward Learning, 2023 IEEE International Conference on Robotics and Automation (ICRA), London, United Kingdom, May 2023.
- 15. M Srivastava, **E Biyik**, S Mirchandani, ND Goodman, D Sadigh. Assistive Teaching of Motor Control Tasks to Humans, 36th Conference on Neural Information Processing Systems (NeurIPS), New Orleans, Louisiana, USA, Nov. 2022.
- 16. E Brockbank, H Wang, J Yang, S Mirchandani, **E Bıyık**, D Sadigh, J Fan. *How do People Incorporate Advice from Artificial Agents when Making Physical Judgments?*, 44th Annual Meeting of the Cognitive Science Society (CogSci), Toronto, Ontario, Canada, Jul. 2022.
- 17. Z Cao, **E Bıyık**, G Rosman, D Sadigh. "Leveraging Smooth Attention Prior for Multi-Agent Trajectory Prediction", 2022 IEEE International Conference on Robotics and Automation (ICRA), Philadelphia, Pennsylvania, USA, May 2022; doi: 10.1109/ICRA46639.2022.9811718.
- 18. **E Biyik**, A Talati, D Sadigh. *APReL: A Library for Active Preference-based Reward Learning Algorithms*, ACM/IEEE International Conference on Human-Robot Interaction (HRI), Sapporo, Hokkaido, Japan, Mar. 2022.

- 19. **E Bıyık**, A Lalitha, R Saha, A Goldsmith, D Sadigh. *Partner-Aware Algorithms in Decentralized Cooperative Bandit Teams*, Thirty-Sixth AAAI Conference on Artificial Intelligence (AAAI), Vancouver, British Columbia, Canada, Feb. 2022; doi: 10.1609/aaai.v36i9.21158.
- 20. N Wilde*, E Bıyık*, D Sadigh, SL Smith (*equal contribution). Learning Reward Functions from Scale Feedback, 5th Conference on Robot Learning (CoRL), London, United Kingdom, Nov. 2021.
- 21. V Myers, **E Bıyık**, N Anari, D Sadigh. *Learning Multimodal Rewards from Rankings*, 5th Conference on Robot Learning (CoRL), London, United Kingdom, Nov. 2021.
- 22. WZ Wang*, M Beliaev*, **E Biyik***, DA Lazar, R Pedarsani, D Sadigh (*equal contribution). *Emergent Prosociality in Multi-Agent Games Through Gifting*, 30th International Joint Conference on Artificial Intelligence (IJCAI), Montreal, Quebec, Canada, Aug. 2021; doi: 10.24963/ijcai.2021/61.
- 23. K Li, M Tucker, E Bıyık, E Novoseller, JW Burdick, Y Sui, D Sadigh, Y Yue, AD Ames. "ROIAL: Region of Interest Active Learning for Characterizing Exoskeleton Gait Preference Landscapes", 2021 IEEE International Conference on Robotics and Automation (ICRA), Xi'an, China, May 2021; doi: 10.1109/ICRA48506.2021.9560840.
- 24. M Beliaev, E Bıyık, DA Lazar, WZ Wang, D Sadigh, R Pedarsani. "Incentivizing Routing Choices for Safe and Efficient Transportation in the Face of the COVID-19 Pandemic", 12th ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS), Nashville, Tennessee, USA, May 2021; doi: 10.1145/3450267.3450546.
- 25. Z Zhu, E Bıyık, D Sadigh. "Multi-Agent Safe Planning with Gaussian Processes", IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Las Vegas, Nevada, USA, Oct. 2020; doi: 10.1109/IROS45743.2020.9341169.
- 26. **E Biyik***, N Huynh*, MJ Kochenderfer, D Sadigh (*equal contribution). "Active Preference-Based Gaussian Process Regression for Reward Learning", Robotics: Science and Systems (RSS), Corvallis, Oregon, USA, Jul. 2020; doi: 10.15607/rss.2020.xvi.041.
- 27. Z Cao*, E Bıyık*, WZ Wang, A Raventos, A Gaidon, G Rosman, D Sadigh (*equal contribution). "Reinforcement Learning based Control of Imitative Policies for Near-Accident Driving", Robotics: Science and Systems (RSS), Corvallis, Oregon, USA, Jul. 2020; doi: 10.15607/rss.2020.xvi.039
- 28. M Kwon, **E Biyik**, A Talati, K Bhasin, DP Losey, D Sadigh. "When Humans Aren't Optimal: Robots that Collaborate with Risk-Aware Humans", ACM/IEEE International Conference on Human-Robot Interaction (HRI), Cambridge, United Kingdom, Mar. 2020; doi: 10.1145/3319502.3374832. *Honorable mention award*.
- 29. **E Biyik**, DA Lazar, D Sadigh, R Pedarsani. "The Green Choice: Learning and Influencing Human Decisions on Shared Roads", 58th IEEE Conference on Decision and Control (CDC), Nice, France, Dec. 2019; doi: 10.1109/CDC40024.2019.9030169.
- 30. C Basu, E Bıyık, Z He, M Singhal, D Sadigh. "Active Learning of Reward Dynamics with Hierarchical Queries", IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Macau, China, Nov. 2019; doi: 10.1109/IROS40897.2019.8968522.
- 31. **E Biyik**, M Palan, NC Landolfi, DP Losey, D Sadigh. "Asking Easy Questions: A User-Friendly Approach to Active Reward Learning", 3rd Conference on Robot Learning (CoRL), Osaka, Japan, Oct. 2019.
- 32. E Bıyık*, J Margoliash*, SR Alimo, D Sadigh (*equal contribution). "Efficient and Safe Exploration in Deterministic Markov Decision Processes with Unknown Transition Models", American Control Conference (ACC), Philadelphia, Pennsylvania, USA, Jul. 2019; doi: 10.23919/ACC.2019.8815276.
- 33. E Bıyık*, DA Lazar*, R Pedarsani, D Sadigh (*equal contribution). "Altruistic Autonomy: Beating Congestion in Shared Roads", Workshop on Algorithmic Foundations of Robotics (WAFR), Mérida, México, Dec. 2018; doi: 10.1007/978-3-030-44051-0_51
- 34. **E Biyik**, D Sadigh. "Batch Active Preference-Based Learning of Reward Functions", 2nd Conference on Robot Learning (CoRL), Zürich, Switzerland, Oct. 2018.
- 35. HC Baykara*, **E Biyik***, G Gül*, D Onural*, AS Öztürk*, İ Yıldız* (*equal contribution). "Real-Time Detection, Tracking and Classification of Multiple Moving Objects in UAV Videos", 29th IEEE International Conference on Tools with Artificial Intelligence (ICTAI), Boston, Massachusetts, USA, Nov. 2017; doi: 10.1109/ICTAI.2017.00145.
- 36. **E Biyik**, J Barbier, M Dia. "Generalized Approximate Message-Passing Decoder for Universal Sparse Superposition Codes", IEEE International Symposium on Information Theory (ISIT), Aachen, Germany, Jun. 2017; doi: 10.1109/ISIT.2017.8006798.

Workshop Proceedings

- 37. A Liang, J Thomason, **E Biyik**. ViSaRL: Visual Reinforcement Learning Guided by Human Saliency, Pretraining for Robotics (PT4R) Workshop at the 2023 International Conference on Robotics and Automation (ICRA), London, United Kingdom, May 2023.
- 38. **E Biyik**. Learning from Humans for Adaptive Interaction, 17th Annual Human-Robot Interaction Pioneers Workshop (HRI Pioneers), Sapporo, Hokkaido, Japan, Mar. 2022.
- 39. M Kwon, **E Biyik**, A Talati, K Bhasin, DP Losey, D Sadigh. When Humans Aren't Optimal: Robots that Collaborate with Risk-Aware Humans, Cooperative AI NeurIPS Workshop 2021, Virtual, Dec. 2021.
- 40. E Bıyık, A Lalitha, R Saha, A Goldsmith, D Sadigh. Partner-Aware Algorithms in Decentralized Cooperative Bandit Teams, Artificial Intelligence for Human-Robot Interaction Symposium (AI-HRI) at AAAI Fall Symposium Series, Washington DC, USA, Nov. 2021.
- 41. **E Bıyık**, A Talati, D Sadigh. *APReL: A Library for Active Preference-based Reward Learning Algorithms*, Artificial Intelligence for Human-Robot Interaction Symposium (AI-HRI) at AAAI Fall Symposium Series, Washington DC, USA, Nov. 2021.
- 42. M Beliaev*, WZ Wang*, DA Lazar, **E Biyik**, D Sadigh, R Pedarsani (*equal contribution). "Emergent Correlated Equilibrium through Synchronized Exploration", RSS 2020 Workshop on Emergent Behaviors in Human-Robot Systems, Corvallis, Oregon, USA, Jul. 2020.

PH.D. DISSERTATION

43. E Bıyık. "Learning Preferences for Interactive Autonomy", Ph.D. Dissertation, Department of Electrical Engineering, Stanford University, May 2022.

PREPRINTS

- 44. E Bıyık, F Yao, Y Chow, A Haig, C Hsu, M Ghavamzadeh, C Boutilier. "Preference Elicitation with Soft Attributes in Interactive Recommendation", arXiv preprint, Nov. 2023.
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