

Differential Operators and their Adjoint Operators

Differential Operators Linear functions from E^n to E^m may be described, once bases have been selected in both spaces (ordinarily one uses the standard unit vectors), by means of $n \times m$ matrices \mathbf{A} ; we write $Y = \mathbf{A} X$. This operation is linear because

$$\mathbf{A}(c_1 X_1 + c_2 X_2) = c_1 \mathbf{A} X_1 + c_2 \mathbf{A} X_2.$$

When $m = n$ we often use the term *linear transformation* for this operation because it then transforms E^n into itself.

We will use the symbol $PC_2[a, b]$, or $PC_2^0[a, b]$ to stand for the set of piecewise continuous functions on the interval $[a, b]$; supplied with the inner product and norm

$$\langle f, g \rangle = \int_a^b f(x) \overline{g(x)} dx; \quad \|f\| = \sqrt{\int_a^b |f(x)|^2 dx}.$$

This inner product and norm is ordinarily associated with the larger space $L^2[a, b]$, consisting of square Lebesgue integrable functions on the interval $[a, b]$, but we don't want to get into the details of that at the present. Since for any two functions f and g in $PC_2[a, b]$ it is easily verified that a linear combination $c_1 f + c_2 g$ continues to belong to that set, it follows that $PC_2[a, b]$ is a linear vector space; supplied with the inner product and norm we have just indicated it becomes an *inner product space*. Unlike the larger space $L^2[a, b]$ it is not *complete*; sequences of functions $f_k(x) \in PC_2[a, b]$ which have the *Cauchy property* $\lim_{j,k \rightarrow \infty} \|f_j - f_k\| = 0$ do not necessarily converge to a limit in $PC_2[a, b]$; the limit does exist in the larger, complete space $L^2[a, b]$ (which, being a complete inner product space is a *Hilbert space*) but it may not be piecewise continuous.

A linear transformation on $PC_2[a, b]$ is simply a linear function from that space into itself. It is very easy to cite examples. One may take a

fixed function, $h(x)$, piecewise continuous on $[a, b]$ and define

$$H : PC_2[a, b] \rightarrow PC_2[a, b]; \quad H(f)(x) = h(x)f(x).$$

It is straightforward to see that for each $f \in PC_2[a, b]$ this “operation” H gives another function in that space and it is easy to verify the linearity of the operation since $h(x)(c_1 f(x) + c_2 g(x)) = c_1 h(x)f(x) + c_2 h(x)g(x)$. Another example of a linear transformation on $PC_2[a, b]$ is given by

$$K(f)(x) = \int_a^b k(x, y)f(y) dy, \quad x \in [a, b],$$

where the “kernel” $k(x, y)$ satisfies the conditions indicated in the section on linear transforms (in particular, $k(x, y)$ continuous on $[a, b] \times [a, b]$ would suffice).

There is little precision in the terminology for these linear transformations; the terms *linear function*, *linear transformation*, *linear operator* are all used with no clear distinction between them. In these notes we will reserve the word “operator” for use in the term *linear differential operator* (the term linear differential operator is standard but “operator” by itself is often used in other contexts in the general literature). For our purposes here an n -th order linear differential operator on $[a, b]$ takes the form

$$\mathcal{D} = a_0(x) \frac{d^n}{dx^n} + a_1(x) \frac{d^{n-1}}{dx^{n-1}} + \dots + a_{n-1}(x) \frac{d}{dx} + a_n(x),$$

where each $a_{n-k}(x)$ is a piecewise continuous function on $[a, b]$ (we often add further requirements). The “operation” of \mathcal{D} on a piecewise n times continuously differentiable function $y(x)$ defined for $x \in [a, b]$ is simply

$$\mathcal{D}(y)(x) = a_0(x) \frac{d^n y}{dx^n} + a_1(x) \frac{d^{n-1} y}{dx^{n-1}} + \dots + a_{n-1}(x) \frac{dy}{dx} + a_n(x) y(x).$$

Most, but not all, of the examples we will cite correspond to $a_k(x) \equiv a_k$, constant. As x is allowed to vary in $[a, b]$ this process gives another

function, $\mathcal{D}(y)(x)$ and it is a simple matter to verify that the process is a linear one.

It is clear that the operator \mathcal{D} cannot be applied to an arbitrary function $y(x) \in PC_2[a, b]$ because, in general, functions in that space may not have the required derivatives. Unlike linear transformations on finite dimensional spaces, we here encounter a transformation, associated with the operator \mathcal{D} , for which we have to specify a *domain subspace*; a subspace of the basic space in which we are operating, in this case $PC_2[a, b] = PC_2^0[a, b]$, consisting of those elements of the basic space to which the operation is to be applied. For the differential operator \mathcal{D} as just defined, one begins by restricting the operation of \mathcal{D} to the subspace $PC_2^n[a, b]$, which consists of functions $y(x)$ for which the n -th derivative $y^{(n)}(x)$ is defined and piecewise continuous on $[a, b]$. This implies that $y(x)$ and the lower order derivatives $y^{(k)}(x)$, $k = 1, 2, \dots, n-1$ are all continuous and, in fact, $y^{(k)}(x)$ must have derivatives up to order $n - k$.

In addition, the domain subspace for \mathcal{D} , which we will call \mathcal{S} , needs to be further restricted by imposing n boundary conditions at the endpoints, a and b , of the interval in question. In many cases $n = 2m$ is even and m boundary conditions are applied at each of these endpoints; exactly which boundary conditions depends on the specific operator and will become clearer as we discuss some of the examples to follow.

Our main interest lies in *eigenvalues* and *eigenfunctions* of differential operators. A function $\phi(x)$, not equivalent to the zero function, in the domain subspace \mathcal{S} of the differential operator \mathcal{D} is an *eigenfunction* of \mathcal{D} corresponding to the (possibly complex) *eigenvalue* λ of \mathcal{D} if

$$(\mathcal{D}\phi)(x) - \lambda \phi(x) \equiv 0, \quad x \in [a, b].$$

This means that $\phi(x)$ satisfies, for $x \in [a, b]$, the differential equation

$$a_0(x) \frac{d^n \phi}{dx^n} + a_1(x) \frac{d^{n-1} \phi}{dx^{n-1}} + \dots + a_{n-1} \frac{d\phi}{dx} + a_n(x) \phi(x) - \lambda \phi(x) \equiv 0.$$

If we assume the eigenvalue λ is known, the general solution of this differential equation will involve n arbitrary constants. The purpose of the boundary conditions completing the definition of \mathcal{S} , which we described earlier, is to determine these arbitrary constants. In general this specification of boundary conditions cannot be done in an entirely arbitrary way; it has to be done with due regard to the structure of the operator \mathcal{D} .

Definition 1 *If \mathcal{D}^* is a differential operator with domain subspace (we will normally just say “domain” from this point on) \mathcal{S}^* and for all $y(x) \in \mathcal{S}$ and all $z(x) \in \mathcal{S}^*$ we have*

$$\langle \mathcal{D}y, z \rangle = \langle y, \mathcal{D}^*z \rangle,$$

then \mathcal{D}^ is the adjoint operator for \mathcal{D} . If $\mathcal{D} = \mathcal{D}^*$ and $\mathcal{S} = \mathcal{S}^*$ we say that \mathcal{D} is self-adjoint.*

Remark Strictly speaking we should say that \mathcal{D}^* is *an* adjoint operator for \mathcal{D} but it turns out that in virtually all cases of practical interest the adjoint operator \mathcal{D}^* is unique if the domains \mathcal{S} and \mathcal{S}^* are chosen correctly.

Example 1 Consider the differential operator defined by

$$(\mathcal{D}y)(x) = y'(x), \quad x \in [0, 1]; \quad \mathcal{S} = \{y(x) \in PC_2^1[a, b] \mid y(0) = 0\}.$$

For $z(x)$ also in $PC_2^1[0, 1]$ we compute

$$\langle \mathcal{D}y, z \rangle = \int_0^1 y'(x) \overline{z(x)} dx = y(x) \overline{z(x)} \Big|_0^1 - \int_0^1 y(x) \overline{z'(x)} dx$$

$$= y(1)\overline{z(1)} - \int_0^1 y(x)\overline{z'(x)} dx.$$

Clearly, then, if we take $(\mathcal{D}^*z)(x) = -z'(x)$ and take \mathcal{S}^* to consist of functions $z(x) \in PC_2^1[0,1]$ such that $z(1) = 0$ we will have

$$\langle \mathcal{D}y, z \rangle = \int_0^1 y'(x)\overline{z(x)} dx = - \int_0^1 y(x)\overline{z'(x)} dx = \langle y, \mathcal{D}^*z \rangle$$

and we see that \mathcal{D}^* as defined on \mathcal{S}^* is the adjoint operator for \mathcal{D} .

Example 2 Let \mathcal{D} be the (first order) differentiation operator of Example 1 but, in specifying \mathcal{S} , we replace the boundary condition used there by the periodic condition $y(0) = y(1)$. Essentially the same calculations as carried out in Example 1 then show that $\mathcal{D}^* = -\mathcal{D}$ with $\mathcal{S}^* = \mathcal{S}$. (In this situation, where the adjoint of \mathcal{D} is $-\mathcal{D}$ with the same domain, we say that \mathcal{D} is *skew-adjoint* or *anti-hermitian*.) The eigenvalue - eigenfunction equation is

$$\frac{d\phi}{dx} = \lambda \phi$$

for which the general solution is $\phi(x, \lambda) = c e^{\lambda x}$, c being an arbitrary constant. Using the periodic boundary condition which is part of the definition of $\mathcal{S}^* = \mathcal{S}$ we have

$$c e^{\lambda \cdot 0} = c = e^{\lambda \cdot 1} = c e^{\lambda}.$$

This is satisfied for $c \neq 0$ just in case $\lambda = 2k\pi i$ for some integer k , $-\infty < k < \infty$. These eigenvalues are clearly complex, as are the eigenfunctions, which we may take to be $\phi_k(x) = e^{2k\pi i x}$, $-\infty < k < \infty$.

Example 3 We consider the constant coefficient, second order, differential operator

$$(\mathcal{D}y)(x) = \frac{\partial^2 y}{\partial x^2} - c y(x), \quad c \text{ real},$$

defined on the domain

$$\mathcal{S} = \{y(x) \in PC_2^2([0, L]) \mid a_0 y(0) + b_0 y'(0) = 0, a_L y(L) + b_L y'(L) = 0\}$$

with a_0, b_0, a_L, b_L all real, a_0, b_0 not both zero, a_L, b_L not both zero.

We claim that \mathcal{D} is self-adjoint. This assertion rests on the calculation, for $y, z \in \mathcal{S}$,

$$\begin{aligned} \langle \mathcal{D}y, z \rangle &= \int_0^L (y''(x) - cy(x)) \overline{z(x)} dx \\ &= y'(x) \overline{z(x)} \Big|_0^L - \int_0^L (y'(x) \overline{z'(x)} + cy(x) \overline{z(x)}) dx \\ &= (y'(x) \overline{z(x)} - y(x) \overline{z'(x)}) \Big|_0^L + \int_0^L y(x) \overline{(z''(x) - cz(x))} dx \\ &= (y'(x) \overline{z(x)} - y(x) \overline{z'(x)}) \Big|_0^L + \langle y, \mathcal{D}z \rangle. \end{aligned}$$

Clearly we have the self-adjointness property just in case

$$(y'(x) \overline{z(x)} - y(x) \overline{z'(x)}) \Big|_0^L = 0.$$

Suppose, first of all, that $a_L \neq 0$. Then, still for $y, z \in \mathcal{S}$, we compute

$$\begin{aligned} y'(L) \overline{z(L)} - y(L) \overline{z'(L)} &= y'(L) \left(\overline{z(L)} + \frac{b_L}{a_L} \overline{z'(L)} \right) \\ &\quad - \left(\frac{b_L}{a_L} y'(L) + y(L) \right) \overline{z'(L)} = 0. \end{aligned}$$

A similar result is obtained at $x = 0$ if $a_0 \neq 0$. If $a_L = 0$ then $b_L \neq 0$ and the boundary condition at $x = L$ gives $y'(L) = 0$, $z'(L) = 0$, in which case we again have $y'(L) \overline{z(L)} - y(L) \overline{z'(L)} = 0$. A similar result is obtained at $x = 0$ if $a_0 = 0$. The self-adjointness of \mathcal{D} is proved.

Our final example for this section shows how we deal with a second order differential operator with coefficients depending on x .

Example 4 Let \mathcal{D} be the differential operator defined by

$$\mathcal{D}y(x) = c_0(x) \frac{d^2y}{dx^2} + c_1(x) \frac{dy}{dx} + c_2(x) y(x),$$

where the real valued functions $c_k(x) \in PC^{2-k}$, $k = 0, 1, 2$. We will assume $c_0(x) \neq 0$, $x \in [a, b]$. We take the domain of \mathcal{D} to be the subspace of $PC_2[a, b]$ consisting of functions $y(x)$ which also lie in $PC^2[a, b]$ and satisfy boundary conditions, with real coefficients,

$$d_a y'(a) + e_a y(a) = 0, \quad d_b y'(b) + e_b y(b) = 0.$$

We assume that at least one of d_a , e_a and at least one of d_b , e_b are different from zero. Assuming that $z(x) \in PC^2[a, b]$, we use integration by parts to compute

$$\begin{aligned} \langle \mathcal{D}y, z \rangle &= \int_a^b \left(c_0(x) \frac{d^2y}{dx^2} + c_1(x) \frac{dy}{dx} + c_2(x) y(x) \right) \overline{z(x)} dx \\ &= \left(c_0(x) y'(x) \overline{z(x)} - y(x) \overline{(c_0(x) z'(x) + (c_1(x) - c_0'(x)) z(x))} \right) \Big|_a^b + \\ &\quad \int_a^b y(x) \overline{(c_0(x) z''(x) + (2c_0'(x) - c_1(x)) z'(x) + (c_0''(x) - c_1'(x) + c_2(x)) z(x))} dx. \end{aligned}$$

The last integral shows that the adjoint differential operator should be

$$\mathcal{D}^*z(x) = c_0(x) \frac{d^2z}{dx^2}(x) + (2c_0'(x) - c_1(x)) \frac{dz}{dx}(x) + (c_0''(x) - c_1'(x) + c_2(x)) z(x).$$

If $d_b \neq 0$ the boundary terms at $x = b$ can be rewritten as

$$\begin{aligned} &c_0(b) \left(y'(b) + \frac{e_b}{d_b} y(b) \right) \overline{z(b)} - \frac{c_0(b)e_b}{d_b} y(b) \overline{z(b)} \\ &\quad - y(b) \overline{(c_0(b) z'(b) + (c_1(b) - c_0'(b)) z(b))}. \end{aligned}$$

Applying the boundary condition satisfied by $y(x)$ at $x = b$, the boundary term at $x = b$ vanishes just in case

$$0 = - \frac{c_0(b)e_b}{d_b} y(b) \overline{z(b)} - y(b) \overline{(c_0(b) z'(b) + (c_1(b) - c_0'(b)) z(b))}$$

$$= -y(b) \overline{\left(c_0(b)z'(b) + \left(c_1(b) - c'_0(b) + \frac{c_0(b)e_b}{d_b} \right) z(b) \right)},$$

which is true if $z(x)$ satisfies the boundary condition

$$c_0(b)z'(b) + \left(c_1(b) - c'_0(b) + \frac{c_0(b)e_b}{d_b} \right) z(b) = 0.$$

If we assume $d_a \neq 0$ we similarly obtain

$$c_0(a)z'(a) + \left(c_1(a) - c'_0(a) + \frac{c_0(a)e_a}{d_a} \right) z(a) = 0.$$

The adjoint domain \mathcal{D}^* consists of functions in $PC^2[a, b]$ satisfying these boundary conditions. The cases wherein $d_a = 0$ and/or $d_b = 0$ (and hence $e_a \neq 0$ and/or $e_b \neq 0$) are left as exercises.

QuickCheck Exercises

1. Find the adjoint operator for $\mathcal{D}y(x) = \frac{d}{dx} \left((1+x) \frac{dy}{dx} \right)$, the domain of \mathcal{D} consisting of functions in $PC^2[0, 1]$ for which $y(0) = y(1) = 0$.
2. Find the adjoint operator for $\mathcal{D}y(x) = y'''(x)$, the domain consisting of functions in $PC^3[0, 1]$ for which $y(0) = y''(0) = 0$, $y'(1) = 0$.
3. Show that $-c$ is an eigenvalue of \mathcal{D} as defined in Example 3 if $a_0 = a_L = 0$.
4. Compute the eigenvalues of \mathcal{D} in Example 3 if $b_0 = b_L = 0$. What are the corresponding eigenfunctions?
5. How are the boundary conditions characterizing the domain of \mathcal{D}^* modified in the case of the operator \mathcal{D} of Example 4 if one or both of d_a, d_b is equal to zero?