Chapter 1

Bridge

Module BRIDGE.

1.1 Contexte : constantes et axiomes

```
Module CONTEXT.

Parameter max\_nb\_cars: nat.

Axiom max\_nb\_cars\_not\_zero: max\_nb\_cars > O.

End CONTEXT.
```

1.2 Etat de la machine

```
Record State : Set :=
  mkState {
     nb_cars_to_island: nat;
     nb_cars_to_mainland: nat;
     nb_cars_on_island: nat
     }.

Definition total_nb_cars (B:State) : nat :=
     B.(nb_cars_to_island)
     + B.(nb_cars_to_mainland)
     + B.(nb_cars_on_island).
```

1.2.1 Invariants

```
Definition Inv_1 (B: State) : Prop :=
```

```
total_nb_cars B \leq Context.max_nb_cars.
Definition Inv_2 (B:State) : Prop :=
  B.(\mathsf{nb\_cars\_to\_island}) = 0
  \vee B.(nb_cars_to_mainland) = 0.
          Evénement: initialisation
1.2.2
Module INIT.
Definition Guard (limit:nat) : Prop :=
  Context.max\_nb\_cars = limit.
Definition action (limit:nat) : State :=
  mkState 0 0 0.
Obligation de preuve : sûreté
Lemma PO_Safety_Inv_1:
  \forall lim : nat,
     Guard lim

ightarrow let B:= action \lim
        in lnv_1 B.
Lemma PO_Safety_Inv_2:
  \forall lim : nat,
     Guard lim

ightarrow let B:= action \lim
        in lnv_2 B.
Lemma PO_Safety:
  \forall lim : nat,
     \mathsf{Guard}\ \mathit{lim}
     \rightarrow let B := action lim
```

in $lnv_1 B \wedge lnv_2 B$.

End INIT.

1.2.3 Evénement : entrée depuis le continent

```
Module CARENTERFROMMAINLAND.
Definition Guard (B: State) : Prop :=
  B.(\mathsf{nb\_cars\_to\_mainland}) = 0
  \land B.(nb\_cars\_to\_island) + B.(nb\_cars\_on\_island) < Context.max\_nb\_cars.
Definition action (B:State): State :=
  mkState (S B.(nb_cars_to_island))
              B.(\mathsf{nb\_cars\_to\_mainland})
                    B.(\mathsf{nb\_cars\_on\_island}).
Obligation de preuve : sûreté
Lemma PO_Safety_Inv_1:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
         in lnv_1 B.
Lemma PO_Safety_Inv_2:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B

ightarrow let B':= action B
         in lnv_2 B.
Theorem PO_Safety:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
         in lnv_1 B' \wedge lnv_2 B'.
```

```
Obligation de preuve : convergence
```

```
Definition variant (B:\mathbf{State}): \mathbf{nat} := Context.max\_nb\_cars - (B.(nb\_cars\_to\_island) + B.(nb\_cars\_on\_island)).
Lemma minus_S:
\forall n \ m: \mathbf{nat}, \\ m < n \rightarrow n - \mathbf{S} \ m < n - m.
Theorem PO_Convergence:
\forall B: \mathbf{State}, \\ \mathsf{Inv}\_1 \ B \rightarrow \mathsf{Inv}\_2 \ B \\ \rightarrow \mathsf{Guard} \ B \\ \rightarrow \mathsf{1et} \ B':= \mathsf{action} \ B \\ \mathsf{in} \\ \mathsf{variant} \ B' < \mathsf{variant} \ B.
```

End CARENTERFROMMAINLAND.

1.2.4 Evénement : sortie vers l'île

```
Module CarLeaveToIsland.
```

Obligation de preuve : sûreté

```
in lnv_2 B.
Lemma PO_Safety:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
         in lnv_1 B' \wedge lnv_2 B'.
End CARLEAVETOISLAND.
          Evénement : entrée depuis l'île
1.2.5
Module CARENTERFROMISLAND.
Definition Guard (B: State) : Prop :=
  B.(\mathsf{nb\_cars\_on\_island}) > 0
  \land B.(nb\_cars\_to\_island) = 0.
Definition action (B:State) : State :=
  mkState B.(nb_cars_to_island)
             (S B.(nb\_cars\_to\_mainland))
             (pred B.(nb\_cars\_on\_island)).
Obligation de preuve : sûreté
Lemma PO_Safety_Inv_1:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
         in lnv_1 B.
Lemma PO_Safety_Inv_2:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
         in lnv_2 B.
Lemma PO_Safety:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
```

in $lnv_1 B' \wedge lnv_2 B'$.

1.2.6 Evénement : sortie vers le continent

```
Module CARLEAVETOMAINLAND.
Definition Guard (B: State) : Prop :=
  B.(\mathsf{nb\_cars\_to\_mainland}) > 0.
Definition action (B:State) : State :=
  mkState B.(nb_cars_to_island)
             (pred B.(nb_cars_to_mainland))
             B.(\mathsf{nb\_cars\_on\_island}).
Obligation de preuve : sûreté
Lemma PO_Safety_Inv_1:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
         in lnv_1 B.
Lemma PO_Safety_Inv_2:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
         in lnv_2 B.
Lemma PO_Safety:
  \forall (B:State),
     lnv_1 B \rightarrow lnv_2 B
     \rightarrow Guard B
     \rightarrow let B' := action B
         in lnv_1 B' \wedge lnv_2 B'.
```

End CARLEAVETOMAINLAND.

1.2.7 Obligation de preuve : absence de deadlock

End Bridge.