

Matrix Transpose

1 Overview

1.1 Location \$<AMDAPPSDKSamplesInstallPath>\samples\opencl\cl\1.x

1.2 How to Run

See the Getting Started guide for how to build samples. You first must compile the sample.

Use the command line to change to the directory where the executable is located. The default executables are placed in $\$ are placed in $\$ and $\$ are placed in $\$

Type the following command(s).

- MatrixTranspose
 Transforms an abitrary array of 64.
- MatrixTranspose -h
 This prints the help message.

1.3 Command Line Options

Table 1 lists, and briefly describes, the command line options.

Table 1 Command Line Options

Short Form	Long Form	Description
-h	help	Shows all command options and their respective meaning.
	device	Devices on which the program is to be run. Acceptable values are cpu or gpu.
- q	quiet	Quiet mode. Suppresses all text output.
-e	verify	Verify results against reference implementation.
-t	timing	Print timing.
	dump	Dump binary image for all devices.
	load	Load binary image and execute on device.
	flags	Specify compiler flags to build the kernel.
-р	platformId	Select platformId to be used (0 to N-1, where N is the number of available platforms).
-d	deviceId	Select deviceId to be used (0 to N-1, where N is the number of available devices).
-v	version	AMD APP SDK version string.
-x	width	Width/height dimension of the square matrix.
-b	blockSize	Use local memory of dimensions blockSize x blockSize.
-i	iterations	Number of iterations for kernel execution.

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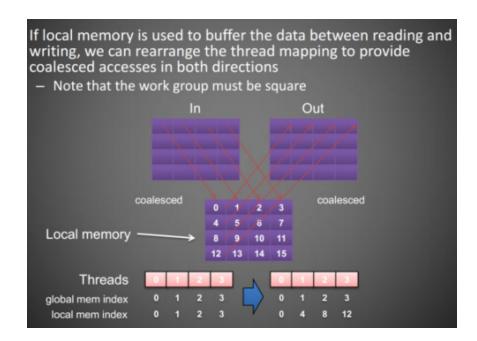
2 Introduction

In linear algebra, the transpose of a matrix A is another matrix A^T (also written A', A^{tr} or A^t). Formally, the i^{th} row, j^{th} column element of A^T is the j^{th} row, j^{th} column element of A.

If A is an m \times n matrix then A^{T} is an n \times m matrix.

3 Implementation

The implementation takes by default the workgroup of size 256 in 16 X 16 format. If the first row of work-items reads the input matrix in a coalesced manner, the elements read must be written into different rows but into the same column. Such an implementation will cause global memory channel conflicts and will be very slow.



To handle this situation, Local Data Share (LDS) is used as an intermediary buffer. A workgroup puts a block of memory from the input matrix into this LDS block. This write can occur in a coalesced manner. The elements of the block are transposed inside the LDS. Even this approach will cause LDS bank conflicts, but the conflicts are far less severe. The LDS block can now be written back to the global memory in a coalesced manner, as the matrix is already transposed.

4 References

- http://en.wikipedia.org/wiki/Transpose
- 2. https://www.cvg.ethz.ch/teaching/2011spring/gpgpu/GPU-Optimization.pdf

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