

Extreme Cleverness

Functional Data Structures in Scala

Agenda



- Functional data structures
- Implementations
 - Sequential
 - Associative
- Modern computer architecture

Functional Data Struct.

• Immutable, immutable, immutable

Functional Data Struct.

- Immutable, immutable, immutable
- What we want...
 - Comparable asymptotic performance
 - Non-degraded versions
 - (full persistence)

Functional Data Struct.

- Immutable, immutable, immutable
- What we want...
 - Comparable asymptotic performance
 - Non-degraded versions
 - (full persistence)
- Structural sharing

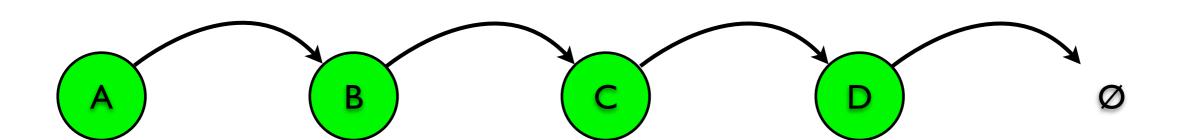
Sequential

- Singly-Linked List
- Banker's Queue
- 2-3 Finger Tree



Singly-Linked List

List(a, b, c, d)



Complexity

O(1)	$O(\log n)$	O(n)
first		append
prepend		concat
		insert
		last
		nth

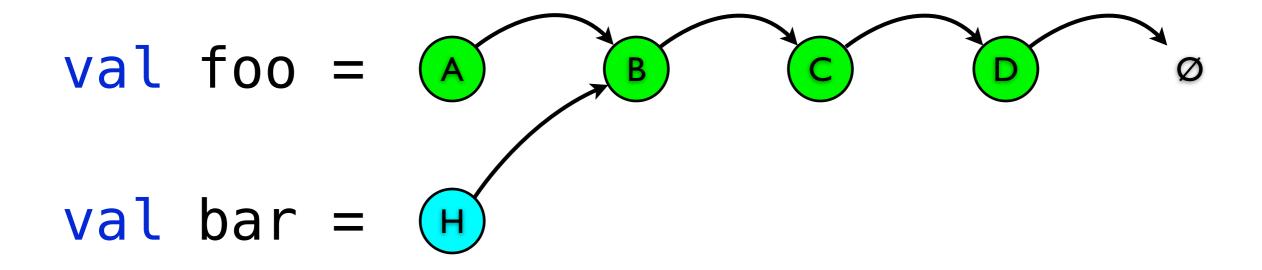
Anatomy

- A list is either...
 - A "cons" cell with a value and a tail
 - An empty list, called "nil"
- These are the only cases!

```
sealed trait List[+A] {
  def ::[B >: A](b: B): List[B] =
    new ::(b, this)
}

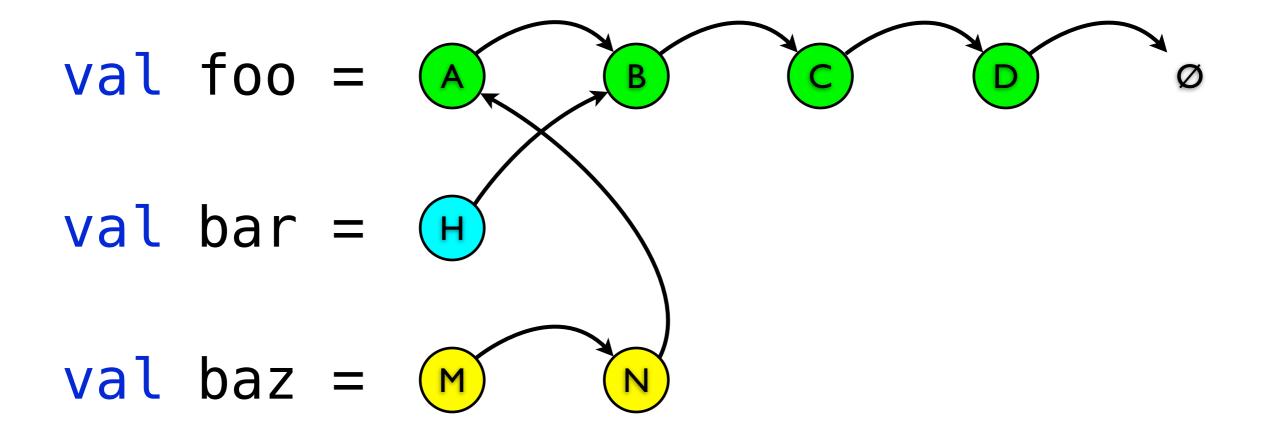
case class ::[+A](hd: A, tail: List[A]) extends List[A]
case object Nil extends List[Nothing]
```

```
val foo = a :: b :: c :: d :: Nil
```

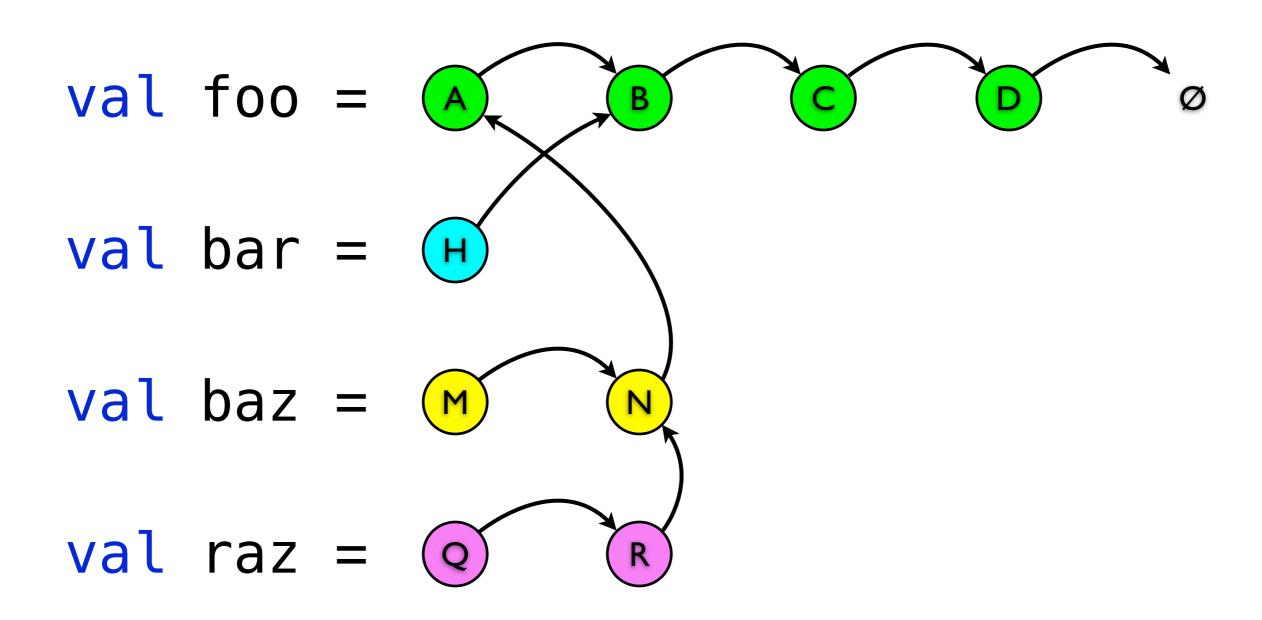


```
val foo = A B C D Ø
val bar = H
```

val baz = m :: n :: foo

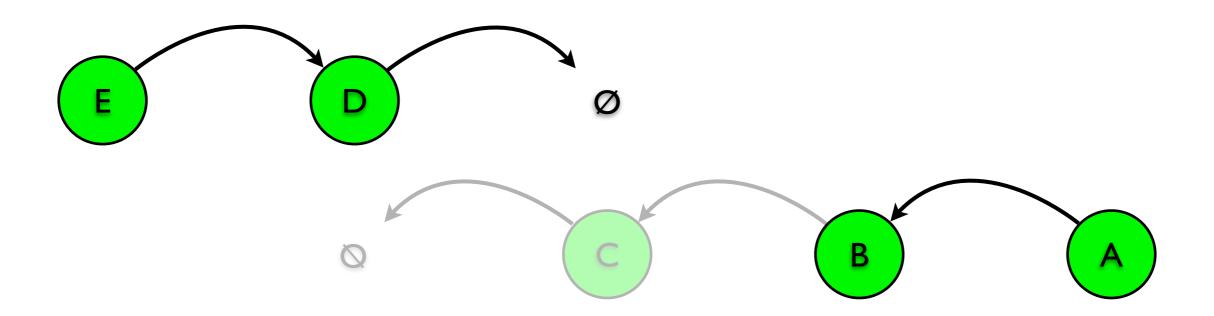


```
val foo = (A
val bar = (H
val baz = (M
val raz = q :: r :: baz.tail
```



Banker's Queue [1]

Queue(a, b, c, d, e)



Motivation

- We want a functional queue
- Linked list is obvious
 - prepend and last are opposing
 - One will be O(1), the other O(n)
- Can we have our cake and eat it too?

Complexity

O(1)	$O(\log n)$	O(n)
append		concat
last		first
prepend		insert
		nth

Complexity

amortized

O(1)	$O(\log n)$	O(n)
append		concat
last		first
prepend		insert
		nth

Anatomy

- Naïve persistent queue
- Two lazy singly-linked lists
 - Front list (for dequeue)
 - Rear list (for enqueue)
- Periodically reverse rear into the front
- Lazy amortization

Amortization

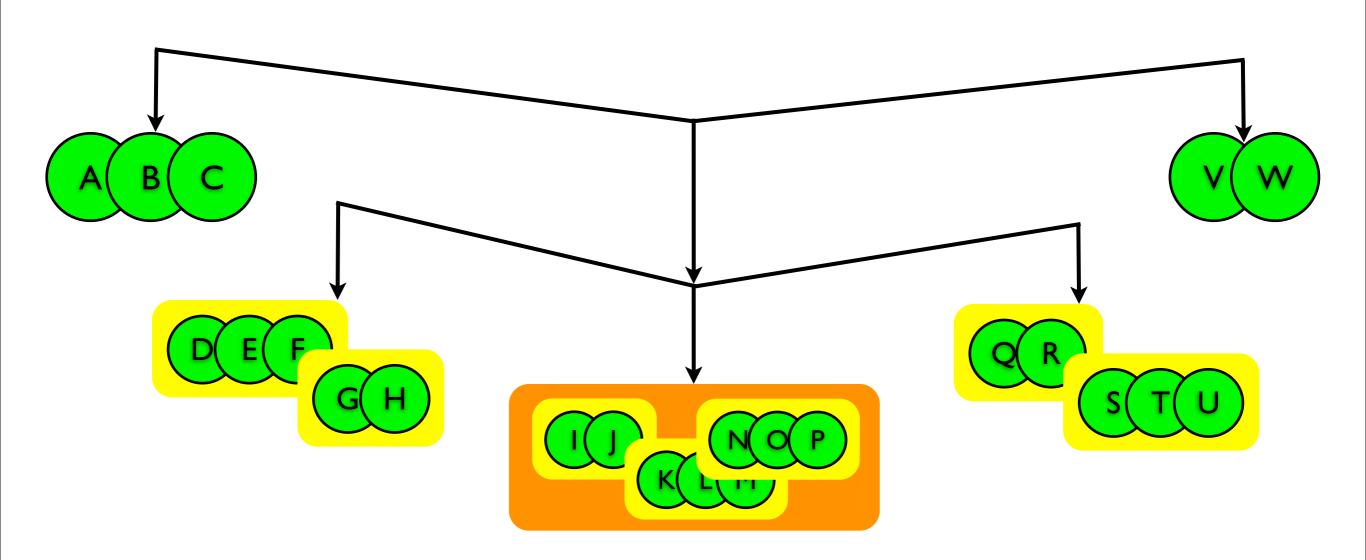
- Most operations are legitimately fast
 - Few operations are very slow
- Laziness distributes the work
- Net result: constant factor degradation
 - Translation: the net average is fast
- Also works without laziness!

```
class BankersQueue[+A](fsize: Int, front: Stream[A],
                        rsize: Int, rear: Stream[A]) {
object BankersQueue {
  def check[A](q: BankersQueue[A]) = {
    if (q.rsize <= q.fsize) {</pre>
                   // already valid
    } else {
      val fsize2 = q.fsize + q.rsize
      val front2 = q.front ++ q.rear.reverse
      new BankersQueue(fsize2, front2, 0, Stream())
```

```
class BankersQueue[+A](fsize: Int, front: Stream[A],
                       rsize: Int, rear: Stream[A]) {
  def enqueue[B >: A](b: B) =
    check(new BankersQueue(fsize, front,
                           rsize + 1, b #:: rear))
 def dequeue = front match {
    case hd #:: tail => {
      val rem = new BankersQueue(fsize - 1, tail,
                                  rsize, rear)
      (hd, check(rem))
    case _ => throw new NoSuchElementException
```

2-3 Finger Tree ^[4]

FingerTree('A' to 'W': _*)

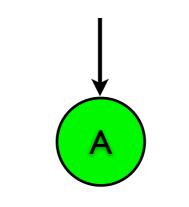


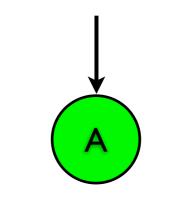
Complexity

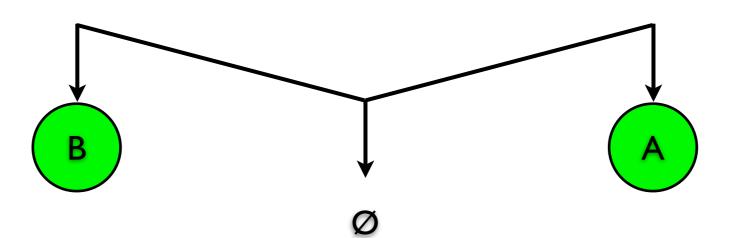
O(1)	$O(\log n)$	O(n)
append	insert	concat
first	nth	
last		
prepend		

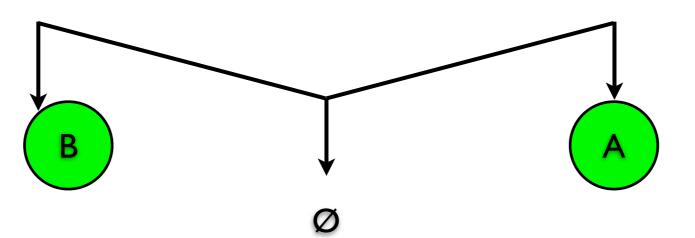
Anatomy

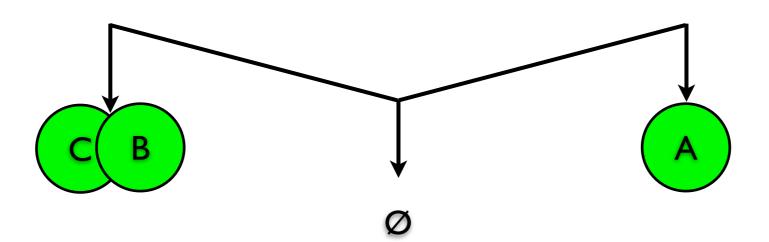
- Ideal persistent deque
- Digits of length 1, 2, 3 or 4
 - Head and tail
- Branching factor of 2 or 3
- Recursive tree body

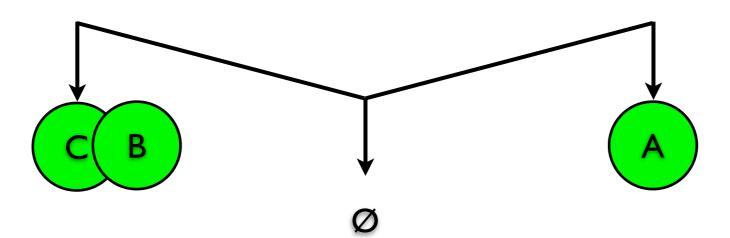


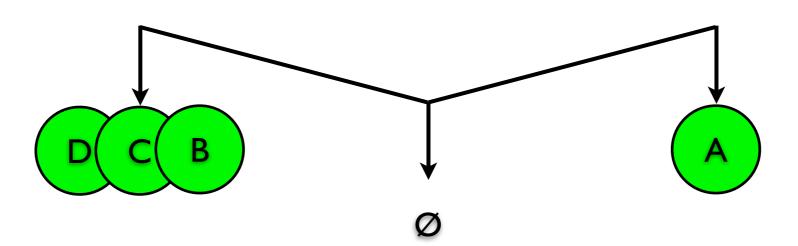


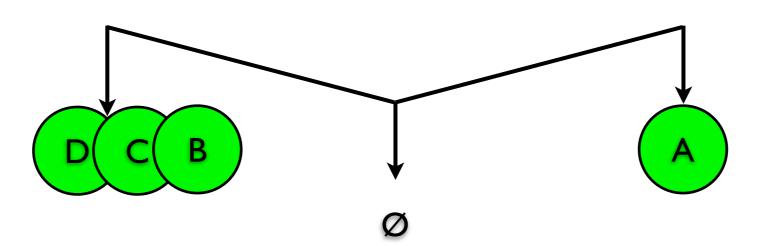


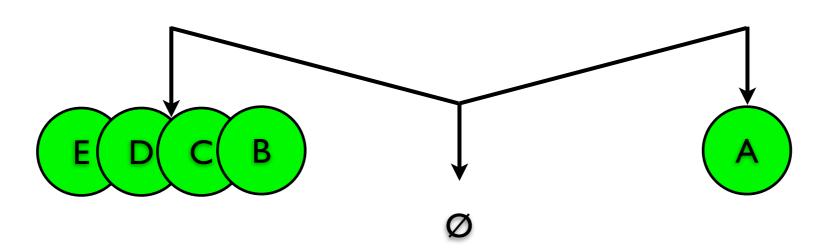


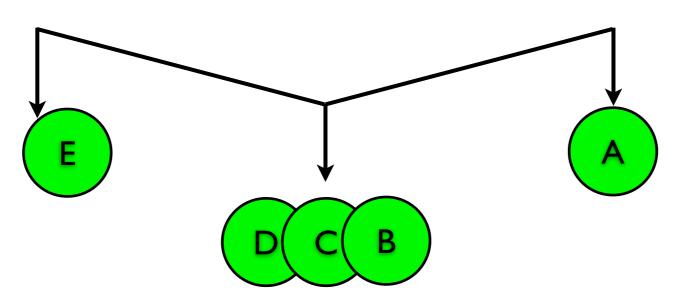


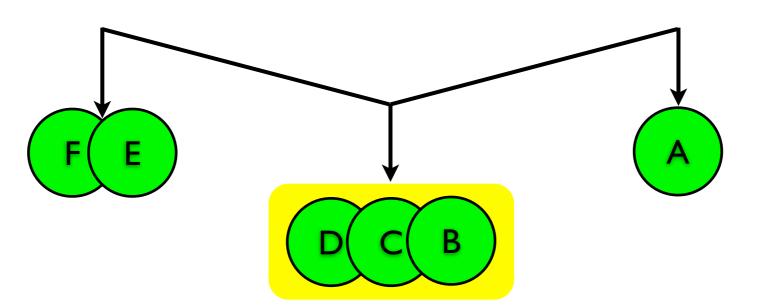


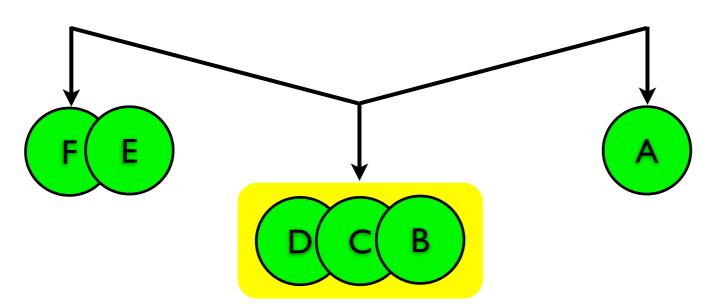


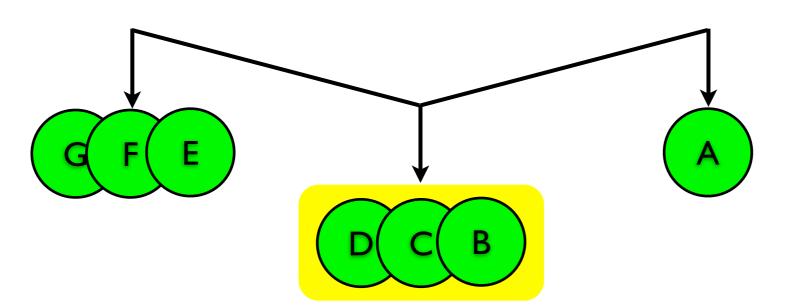












```
sealed trait FingerTree[+A] {
case class Single[+A](a: A) extends FingerTree[A] {
case class Deep[+A](prefix: Digit[A],
                    tree: FingerTree[Node[A]],
                    suffix: Digit[A])
    extends FingerTree[A] {
case object Empty extends FingerTree[Nothing] {
```

```
case class One[+A](a1: A) extends Digit[A]
case class Two[+A](a1: A, a2: A) extends Digit[A]
case class Three[+A](a1: A, a2: A, a3: A) extends Digit[A]
case class Four[+A](a1: A, a2: A, a3: A, a4: A)
        extends Digit[A]
```

case class Node3[+A](a1: A, a2: A, a3: A) extends Node[A]

case class Node2[+A](a1: A, a2: A) extends Node[A]

sealed trait Node[+A]

```
case class Deep[+A](...) extends FingerTree[A] {
  def +:[B >: A](b: B) = prefix match {
    case Four(d, e, f, g) =>
      Deep(Two(b, d), Node3(e, f, g) +: tree, suffix)
    case _ => Deep(b +: prefix, tree, suffix)
  }
  def :+[B >: A](b: B) = suffix match {
    case Four(g, f, e, d) =>
      Deep(prefix, tree :+ Node3(g, f, e), Two(d, b))
    case _ => Deep(prefix, tree, suffix :+ b)
```

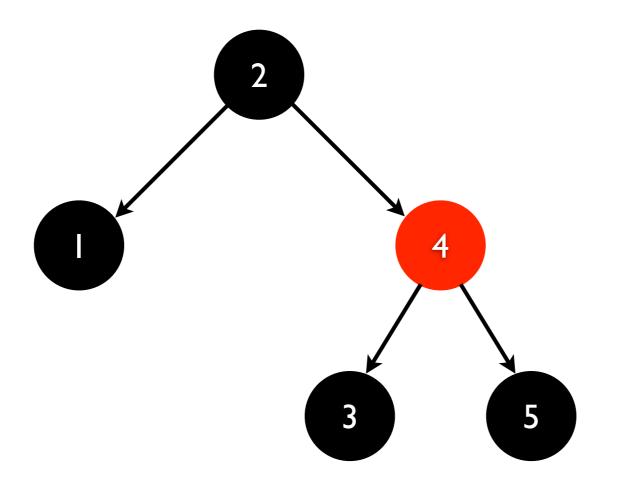
Associative

- Red-Black Tree
- Patricia Trie



Red-Black Tree [2]

RedBlack(1, 2, 3, 4, 5)



Complexity

O(1)	$O(\log n)$	O(n)
	get	intersect
	insert	union
	update	

Anatomy

- Balanced binary search tree
- Invariants...
 - Every path from root to a leaf contains the same number of black nodes
 - No red node has a red parent
- Need to rebalance after any "update"

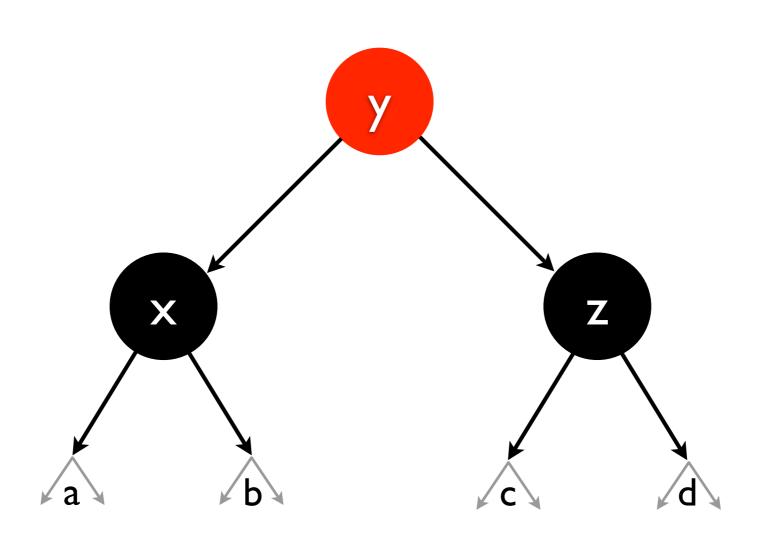
```
sealed abstract class Tree[K : Ordering, +V] {
  val isBlack: Boolean

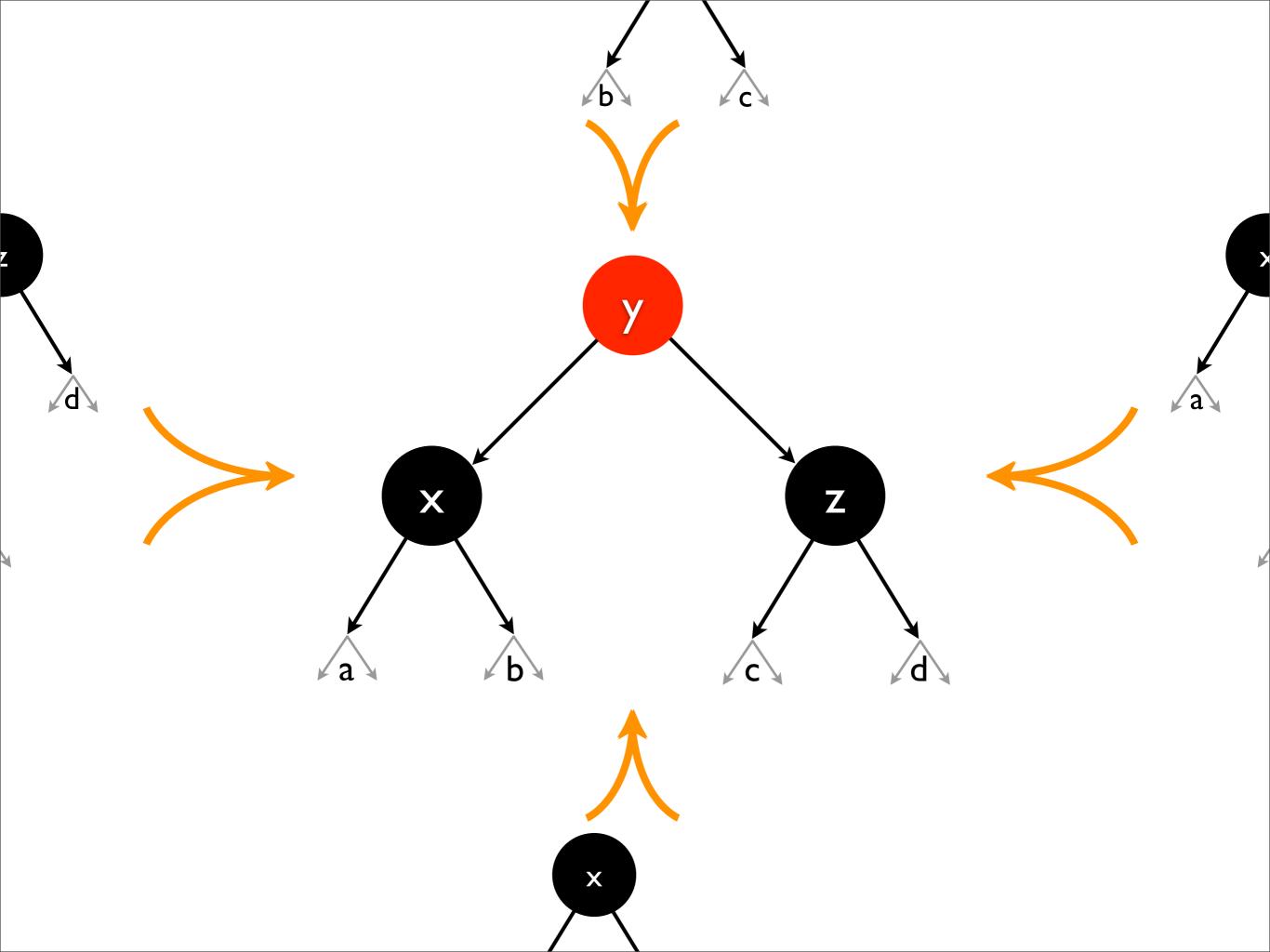
  def left: Tree[K, V]

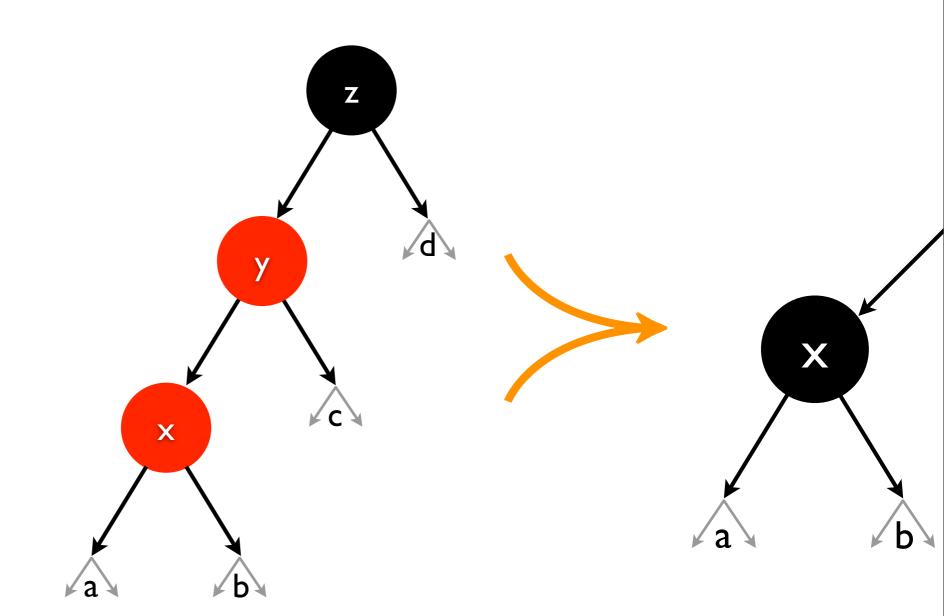
  def key: K
  def value: V

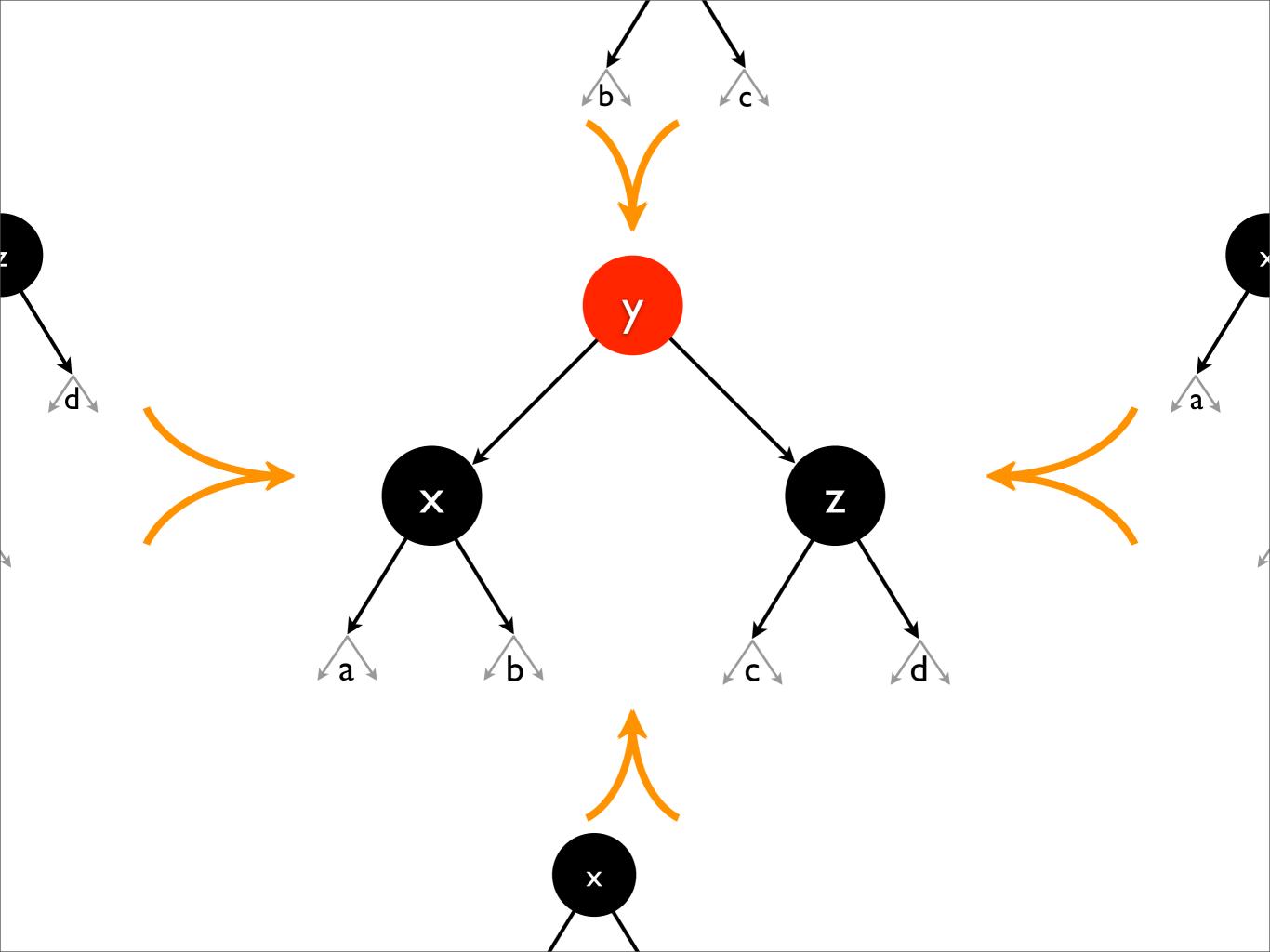
  def right: Tree[K, V]
}
```

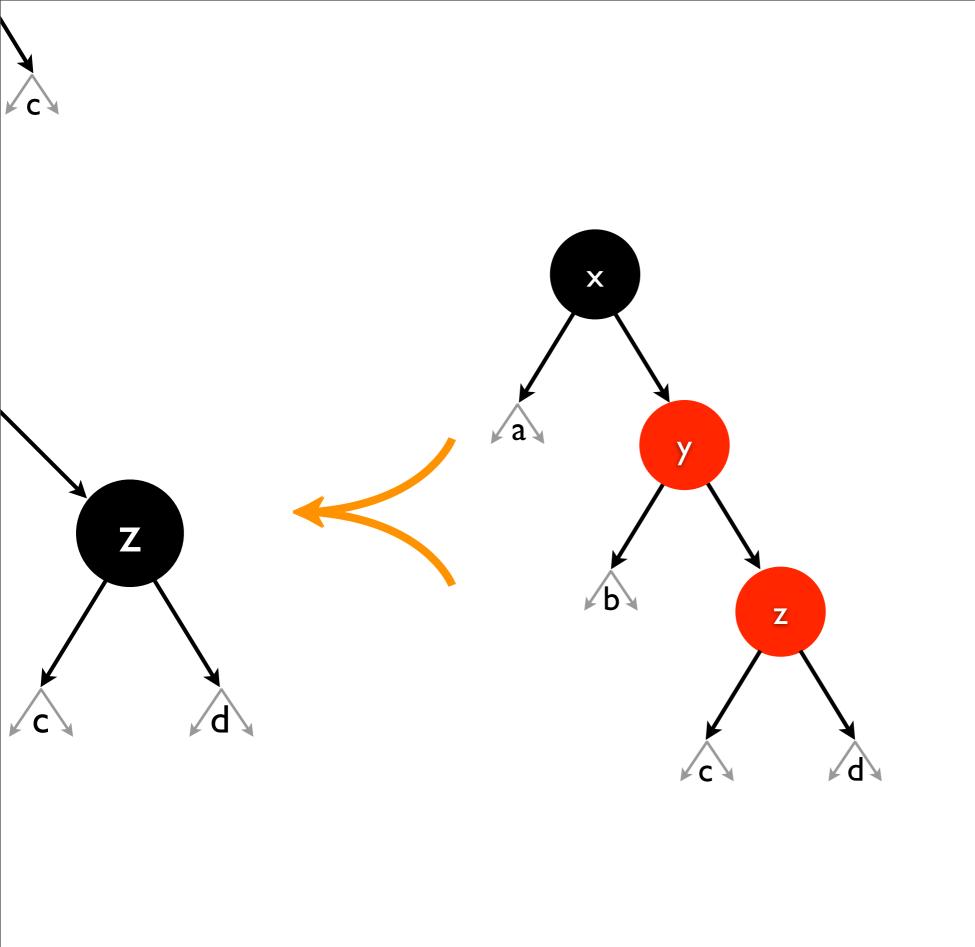
```
case class Node[K : Ordering, +V](isBlack: Boolean,
                                   left: Tree[K, V],
                                   key: K, value: V,
                                   right: Tree[K, V])
   extends Tree[K, V] {
case class Leaf[K : Ordering]()
    extends Tree[K, Nothing] {
  val isBlack = true
```

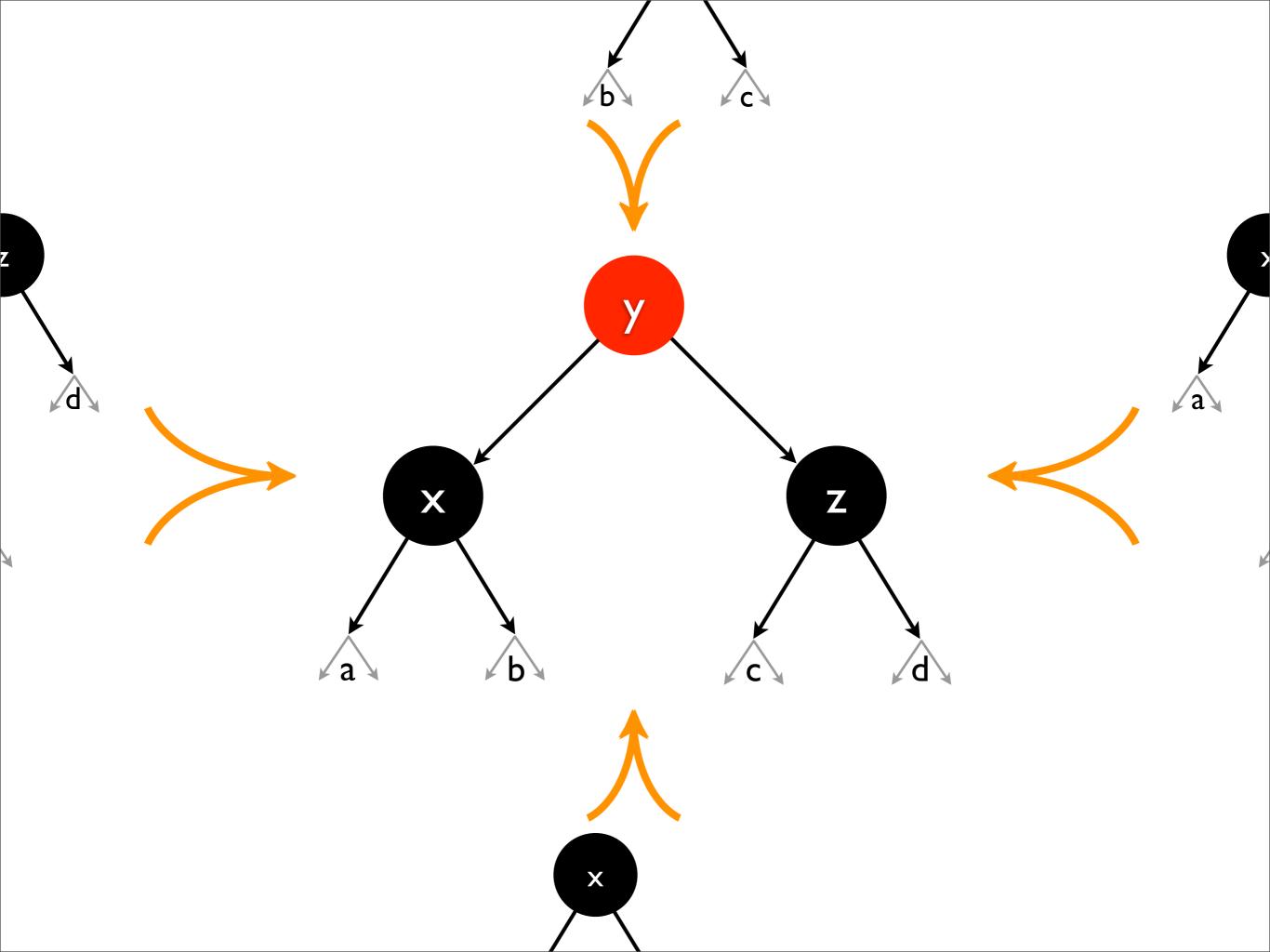


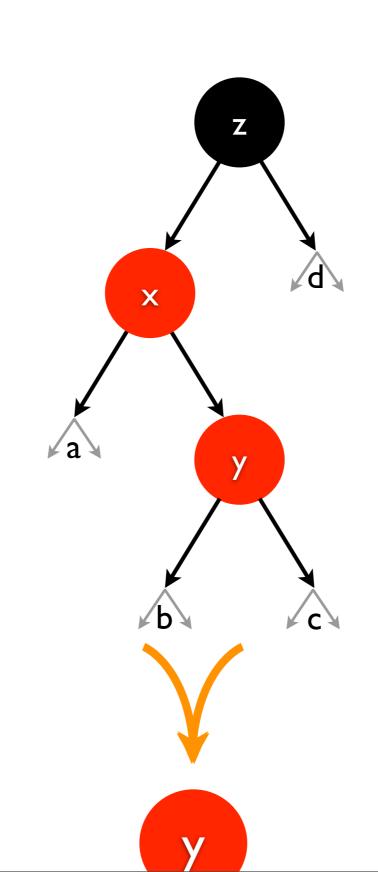


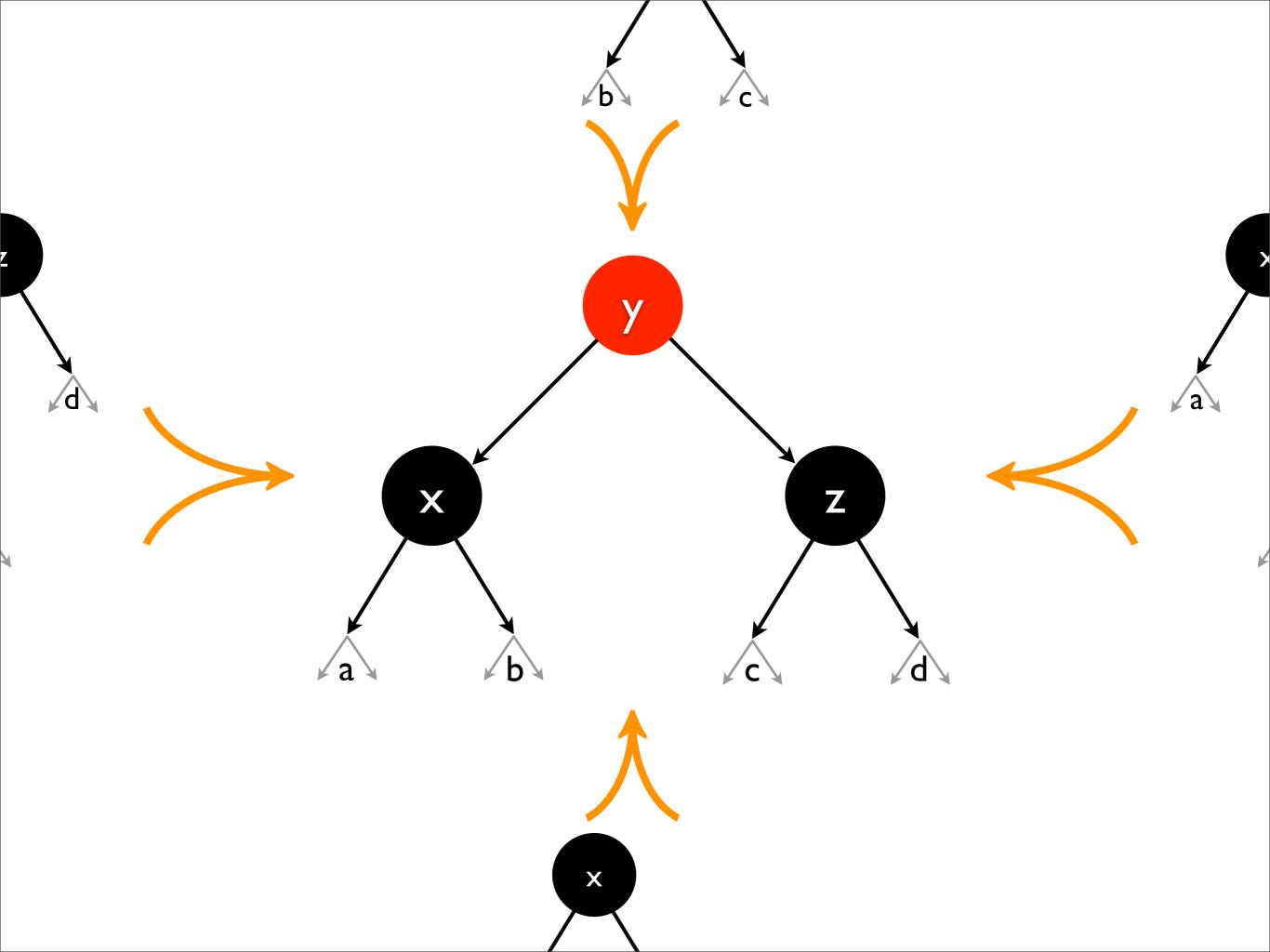


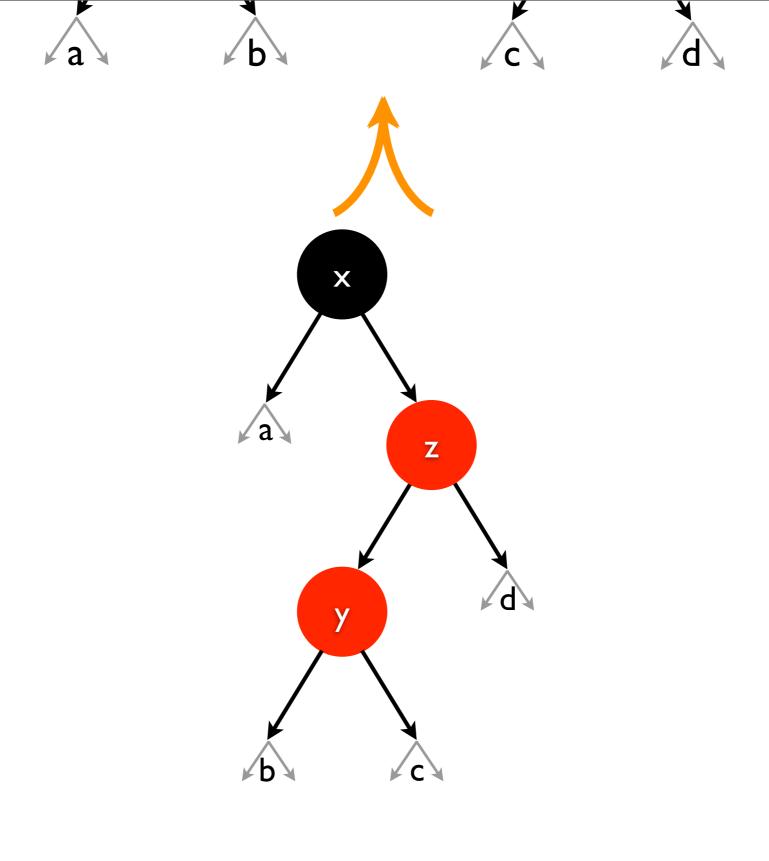


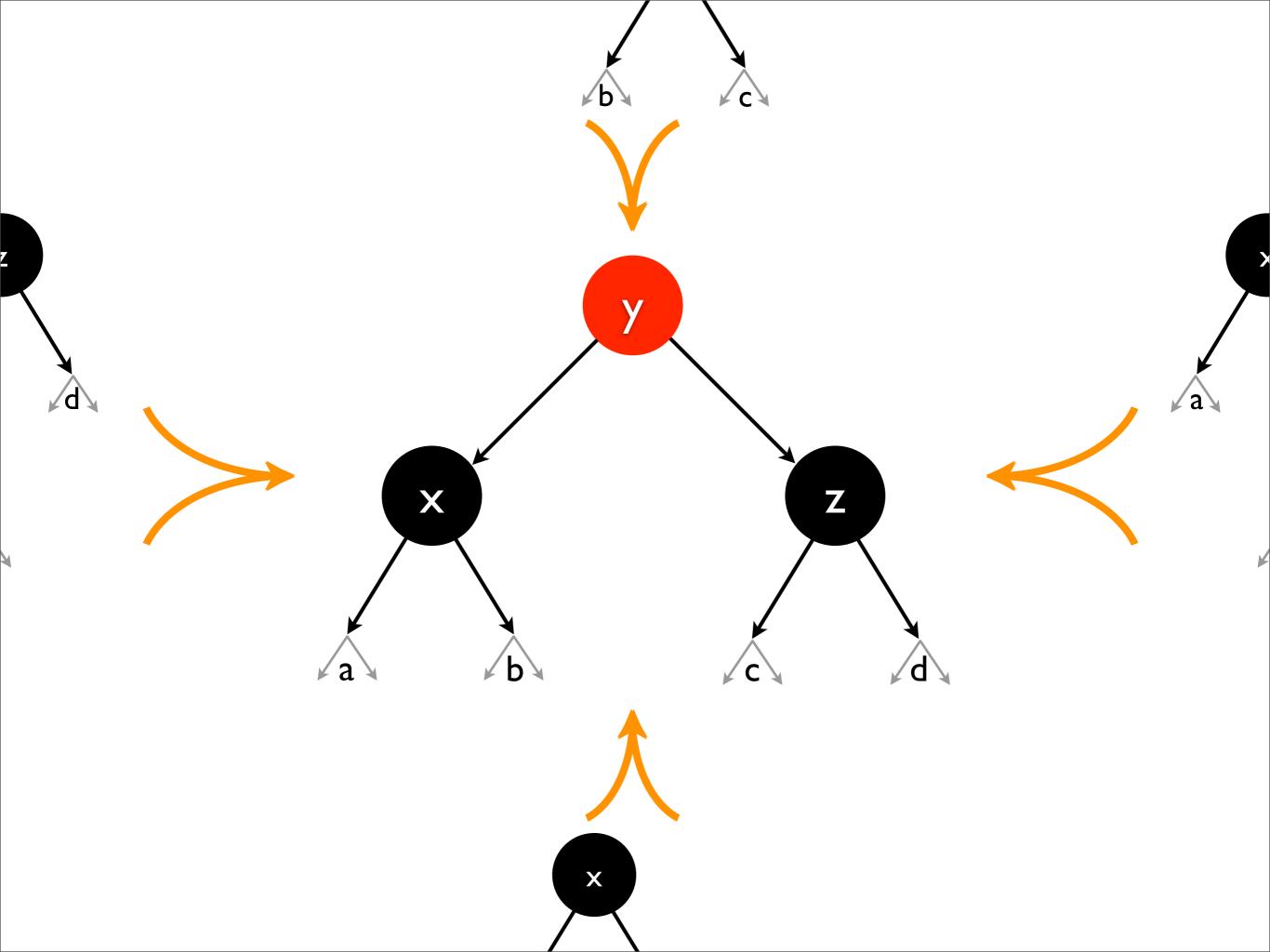












```
def balance[K : Ordering, V](isBlack: Boolean, left: Tree[K, V], key: K,
                                               value: V, right: Tree[K, V]) = {
  (isBlack, left, key, value, right) match {
    case (true, Node(false, Node(false, a, xk, xv, b), yk, yv, c), zk, zv, d) =>
     Node(false, Node(true, a, xk, xv, b), yk, yv, Node(true, c, zk, zv, d))
   case (true, Node(false, a, xk, xv, Node(false, b, yk, yv, c)), zk, zv, d) =>
     Node(false, Node(true, a, xk, xv, b), yk, yv, Node(true, c, zk, zv, d))
   case (true, a, xk, xv, Node(false, Node(false, b, yk, yv, c), zk, zv, d)) =>
     Node(false, Node(true, a, xk, xv, b), yk, yv, Node(true, c, zk, zv, d))
   case (true, a, xk, xv, Node(false, b, yk, yv, Node(false, c, zk, zv, d))) =>
     Node(false, Node(true, a, xk, xv, b), yk, yv, Node(true, c, zk, zv, d))
   case (isBlack, a, xk, xv, b) => Node(isBlack, a, xk, xv, b)
```

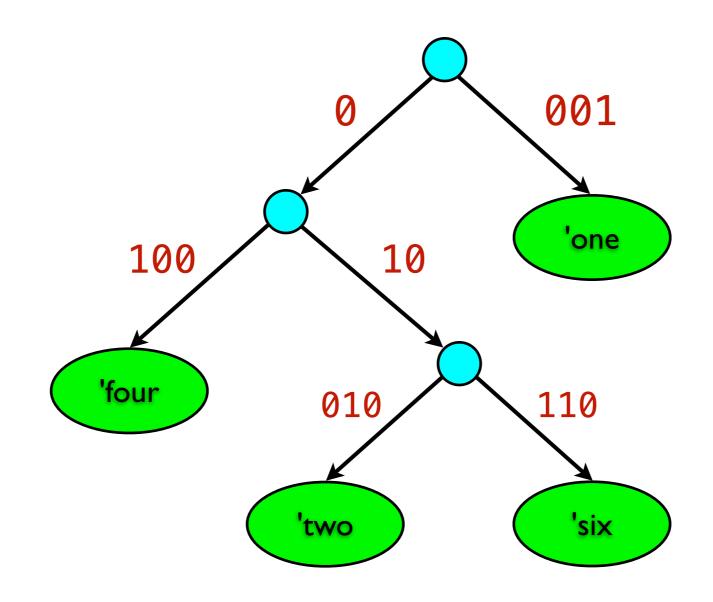
```
isBlack: Boolean, left: Tree[K, V], key: K,
                  value: V, right: Tree[K, V]) = {
right) match {
ode(false, a, xk, xv, b), yk, yv, c), zk, zv, d) =>
a, xk, xv, b), yk, yv, Node(true, c, zk, zv, d))
, xk, xv, Node(false, b, yk, yv, c)), <math>zk, zv, d) =>
a, xk, xv, b), yk, yv, Node(true, c, zk, zv, d))
de(false, Node(false, b, yk, yv, c), zk, zv, d)) =>
a, xk, xv, b), yk, yv, Node(true, c, zk, zv, d))
de(false, b, yk, yv, Node(false, c, zk, zv, d))) =>
a, xk, xv, b), yk, yv, Node(true, c, zk, zv, d))
b) => Node(isBlack, a, xk, xv, b)
```

```
case class Node[K : Ordering, +V](...) extends ... {
 def +[A >: V](pair: (K, A)): Tree[K, V] = {
   val(k2, v2) = pair
    if (key > k2)
      balance(isBlack, left + pair, key, value, right)
    else if (key == k2)
     Node(isBlack, left, k2, v2, right)
    else
      balance(isBlack, left, key, value, right + pair)
```

```
case class Node[K : Ordering, +V](...) extends ... {
 def + [A >: V](pair: (K, A)): Tree[K, V] = {
   val(k2, v2) = pair
    if (key > k2)
   balance(isBlack, left + pair, key, value, right)
   else if (key == k2)
     Node(isBlack, left, k2, v2, right)
   else
   → balance(isBlack, left, key, value, right + pair)
```

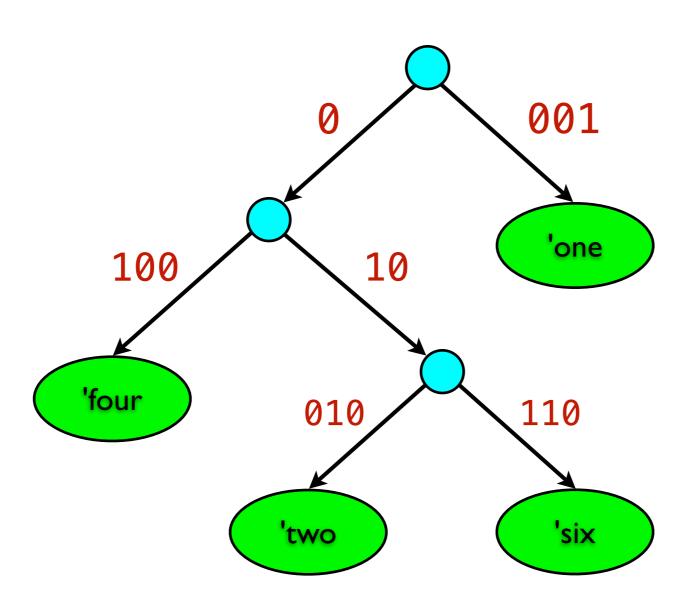
Patricia Trie [3]

```
Trie(2 -> 'two, 6 -> 'six, 4 -> 'four, 1 -> 'one)
```



fast mergeable integer trie


```
Trie(2 -> 'two, 6 -> 'six, 4 -> 'four, 1 -> 'one)
```

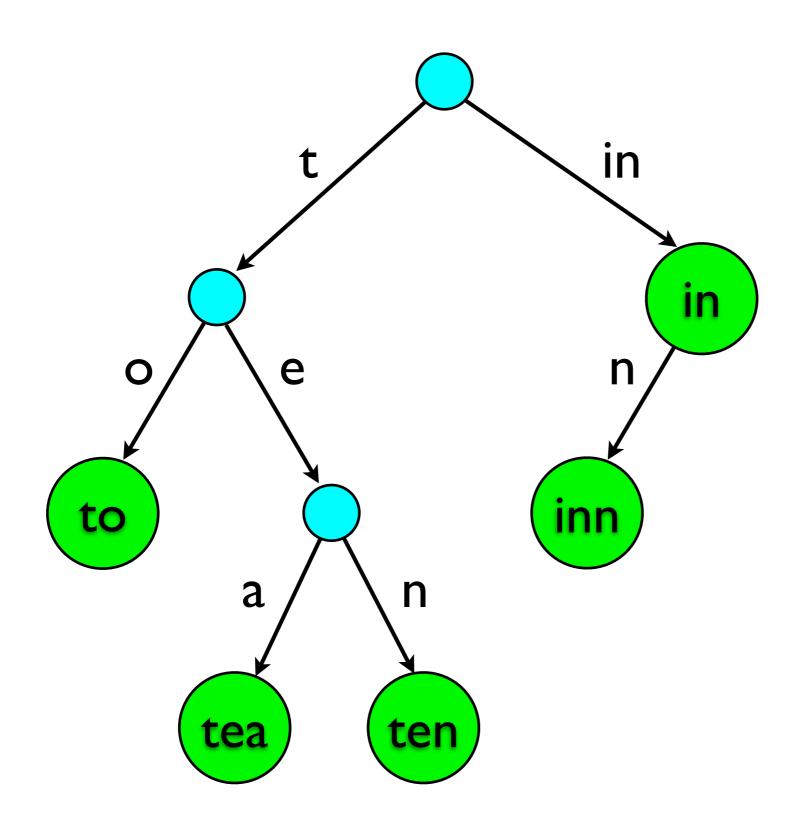


Complexity

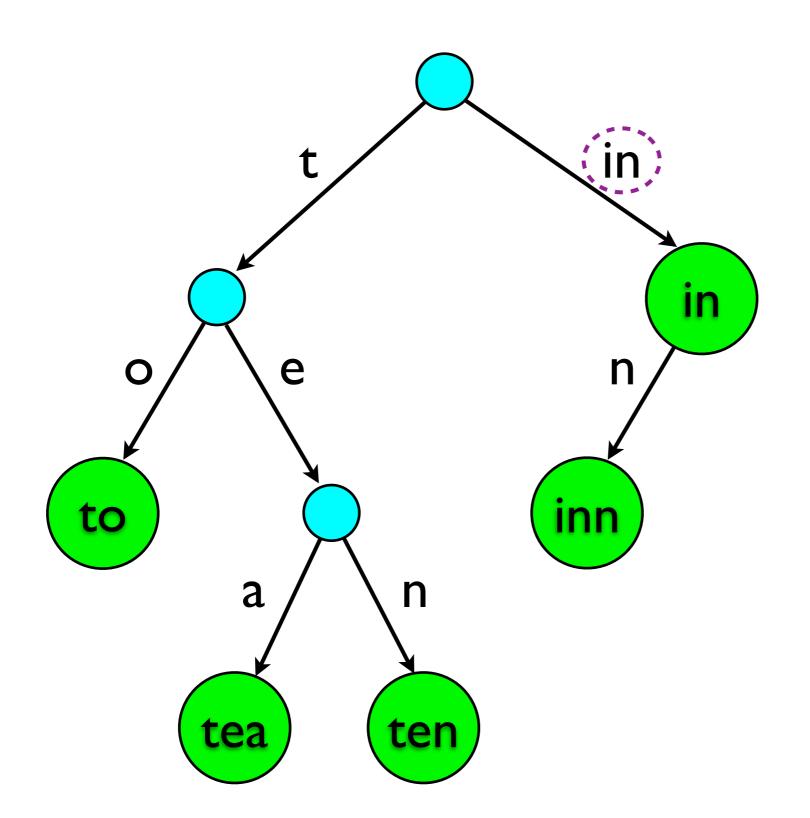
O(1)	$O(\log n)$	O(n)
	get	intersect
	insert	
	update	
	union	

Anatomy

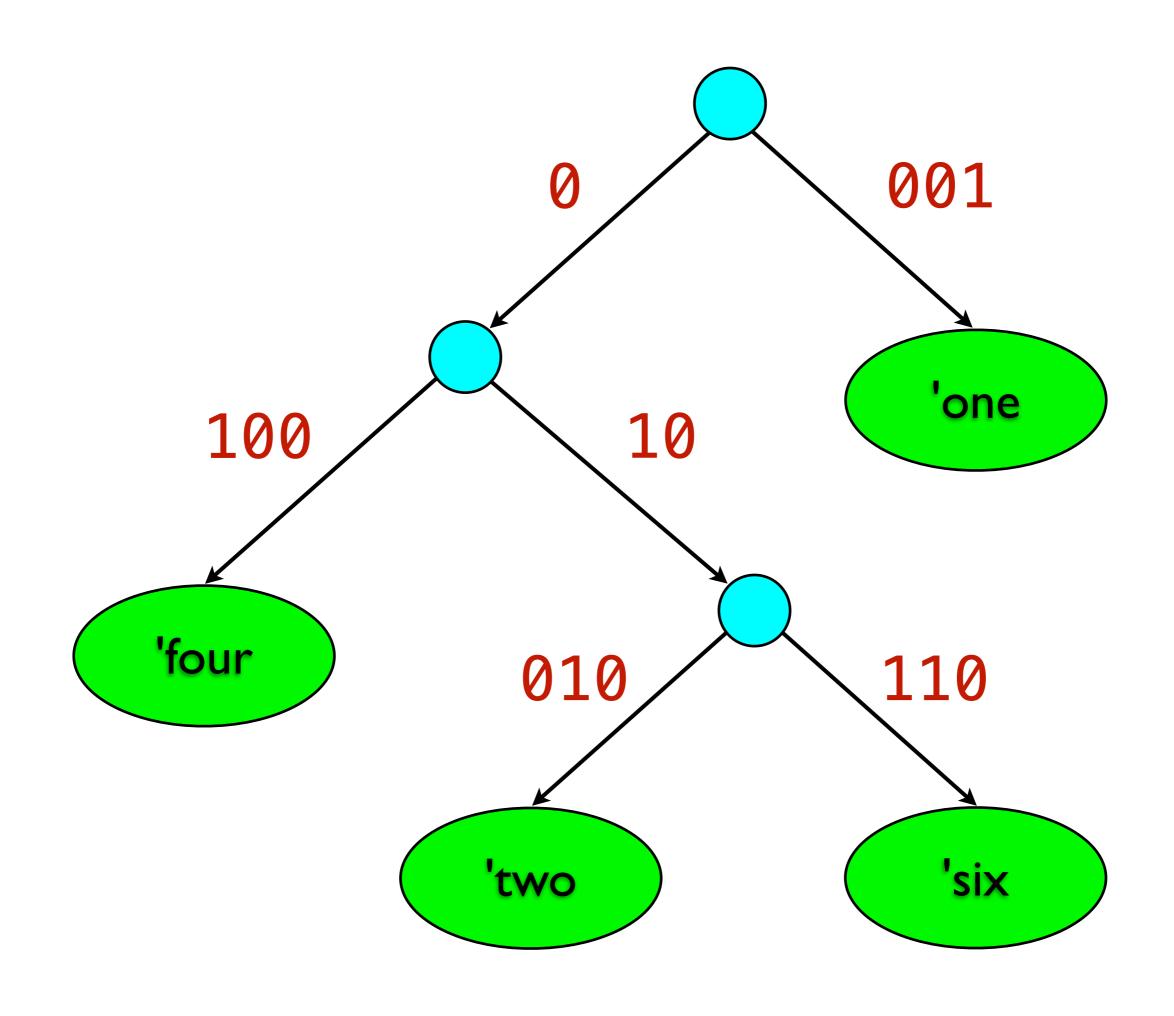
- "Trie" is short for "data is in the leaves"
- Branches each contain a part of the key
 - Integer bits
- Branches may contain more than one bit
- Patricia Trie ⇔ Radix Trie

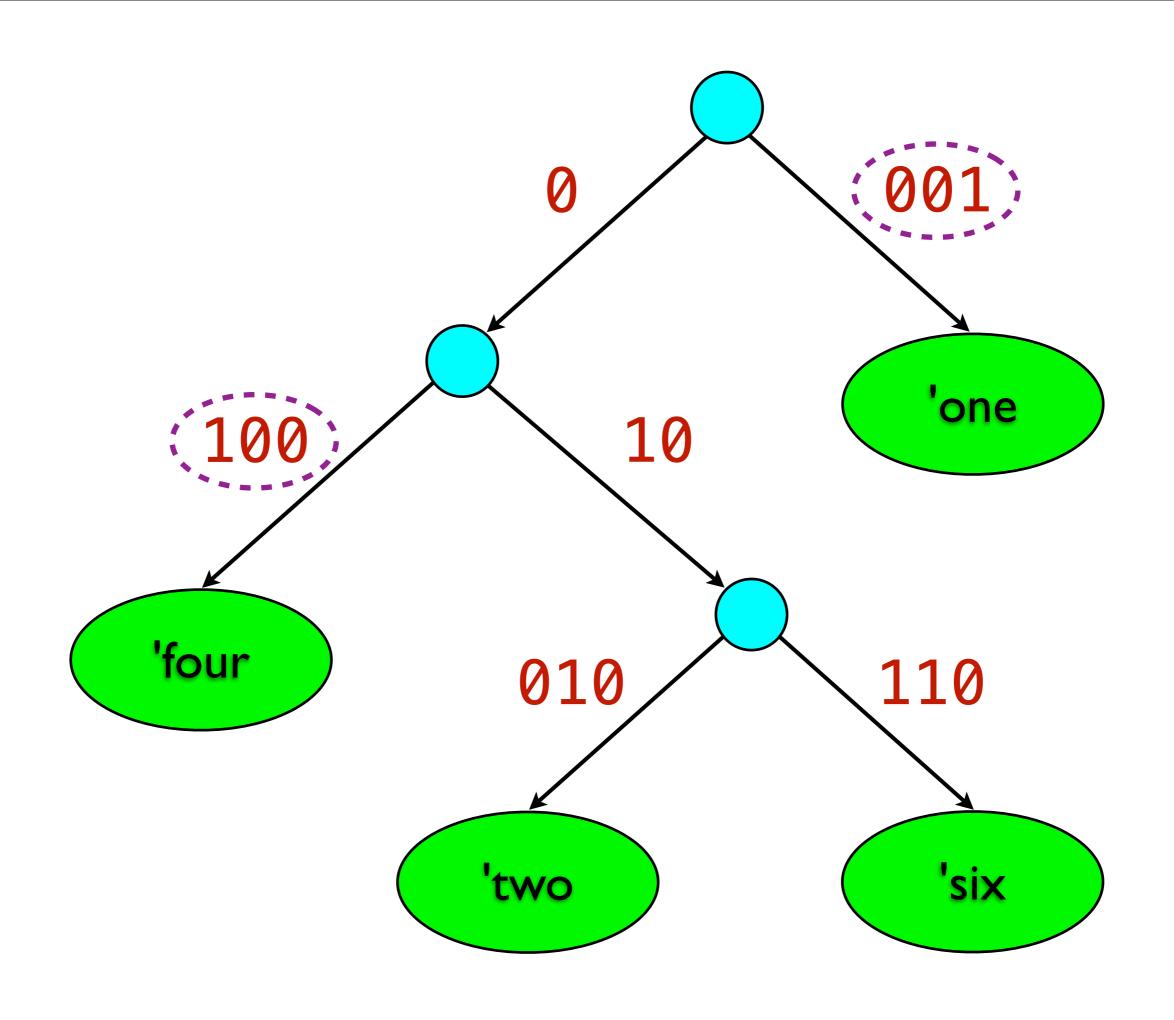


in inn to tea ten



in inn to tea ten





```
case class Leaf[+A](key: Int, a: A) extends Trie[A] {
  def apply(key: Int) =
    if (this key == key) Some(a) else None
case class Branch[+A](...) extends Trie[A] {
  def apply(key: Int) =
    if ((key & mask) == 0) left(key) else right(key)
case object Empty extends Trie[Nothing] {
  def apply(key: Int) = None
```

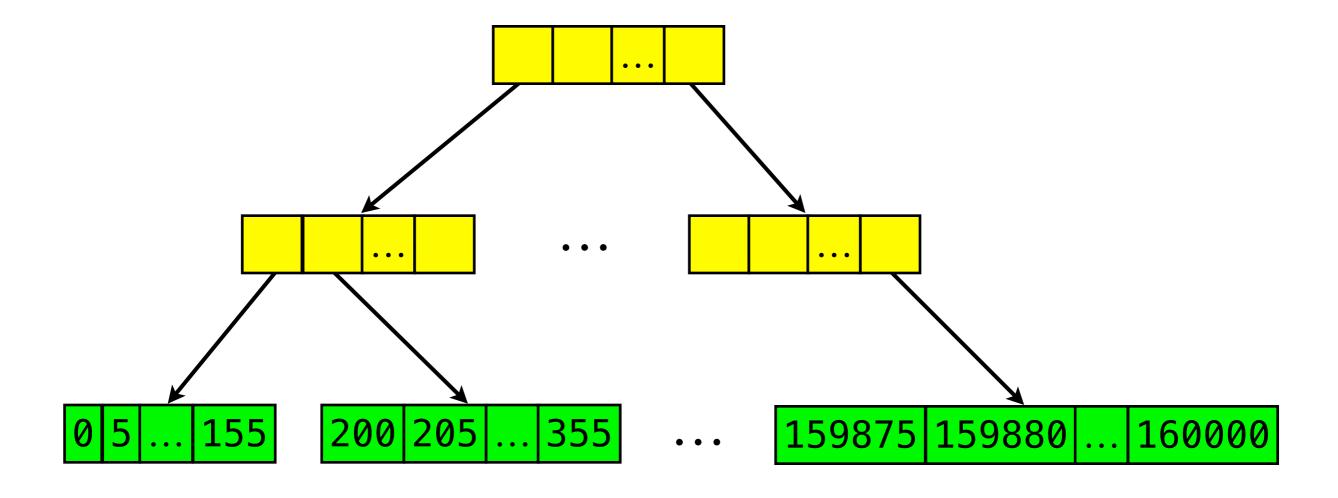
```
case class Branch[+A](...) extends Trie[A] {
  def +[B >: A](pair: (Int, B)): Trie[B] = {
   val (key, value) = pair
    if (matchPrefix(key, prefix, mask)) {
      if ((key & mask) == 0)
        Branch(prefix, mask, left + pair, right)
      else
        Branch(prefix, mask, left, right + pair)
    } else {
      merge(key, Leaf(key, value), prefix, this)
```

A little of both...



Bitmapped Vector Trie

Vector(0 to 160000 by 5: _*)



Complexity

O(1)	$O(\log n)$	O(n)
append		concat
first		insert
last		prepend
nth		
update		

$O(\log_{32} n)$

$O(\log_{32} n) \approx O(1)$

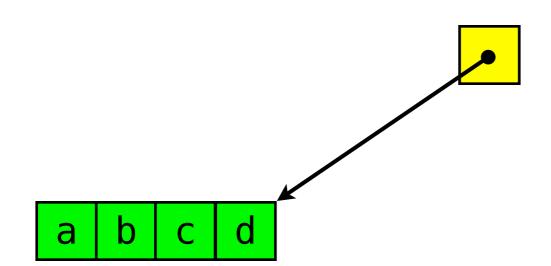
Anatomy

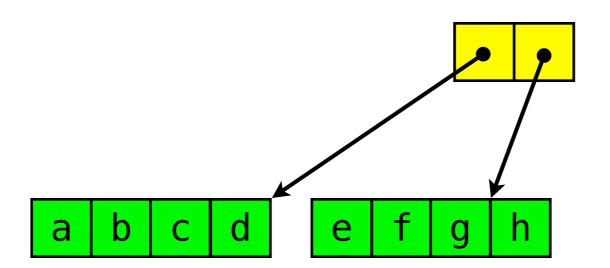
- Start with an array with max length 32
 - Copy on write
- Array of arrays, max length 32
 - Array of array of arrays, max length 32
 - ...
- Maximum depth is 7!

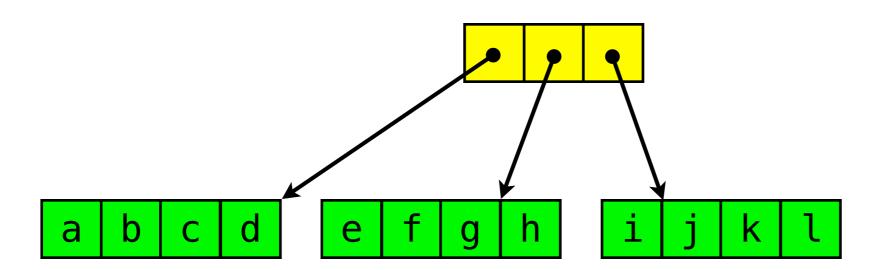
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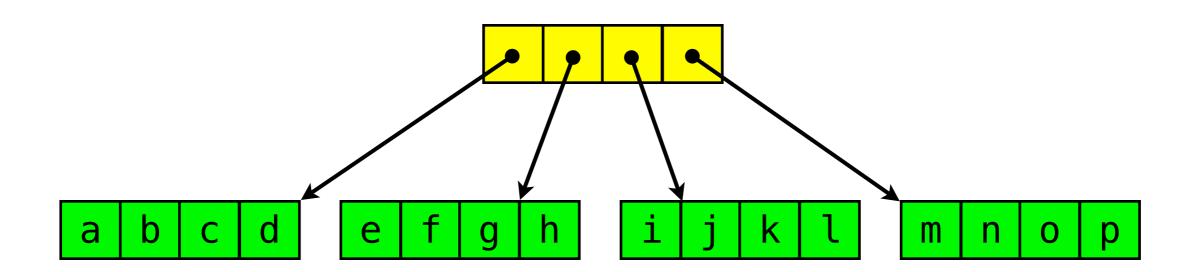
a b c d

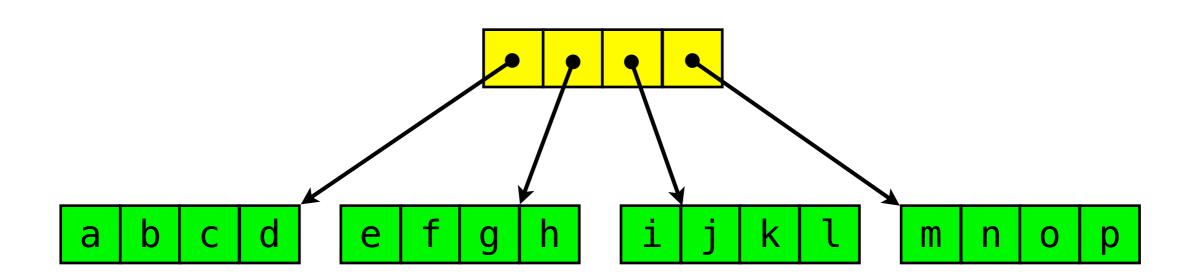
a b c d

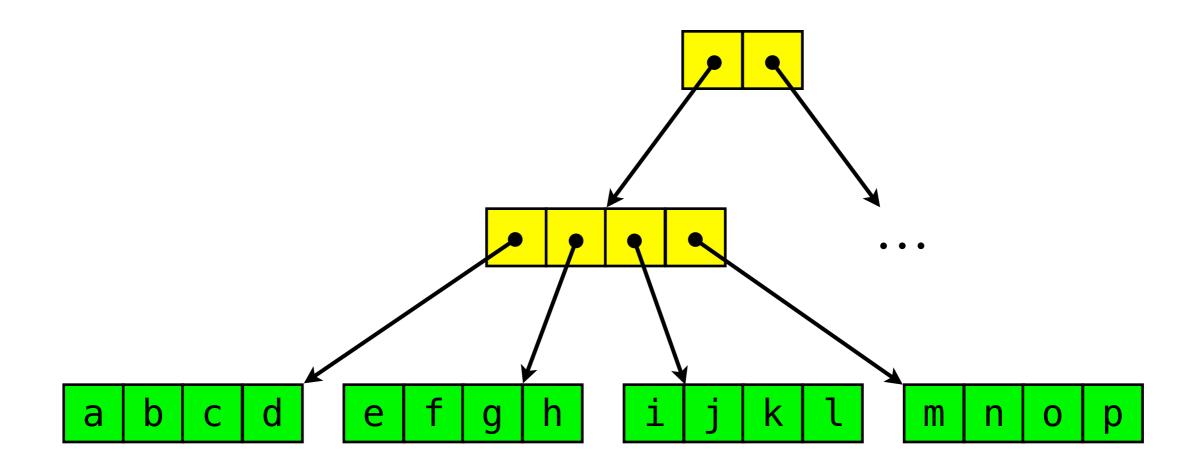












```
sealed trait Case {
  type Self <: Case

val shift: Int

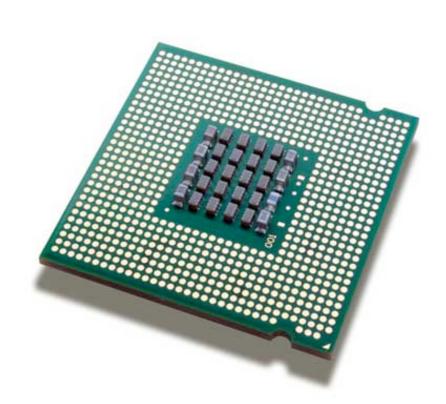
def apply(i: Int): Array[AnyRef]
  def updated(i: Int, obj: AnyRef): Self

def :+(node: Array[AnyRef]): Case
  def pop: (Case, Array[AnyRef])
}</pre>
```

```
case class One(trie: Array[AnyRef]) extends Case {
  type Self = One
 val shift = 0
  def apply(i: Int) = trie
 def updated(i: Int, obj: AnyRef) = {
   val trie2 = copy1(trie, new Array(trie.length))
    trie2(i \& 0x01f) = obj
   One(trie2)
  def :+(tail: Array[AnyRef]) = Two(Array(trie, tail))
 def pop = (Zero, trie)
```

Modern Architectures

- Locality of reference
- Caching
 - Bite-sized data chunks
- JVM considerations
 - Heap locality



References

- [1] Okasaki; Purely Functional Data Structures
- [2] Okasaki; Red-Black Trees in a Functional Setting
- [3] Okasaki & Gill; Fast Mergeable Integer Maps
- [4] Hinz & Paterson; Finger trees, a simple general-

purpose data structure

http://github.com/djspiewak/extreme-cleverness

