

Generic Timer Module (GTM)

Please note, that the debug mechanism should not be used by the application, when a HW-Debugger is used to trace the ARU communication. In that case, the debug registers are used by the HW-Debugger to specify the ARU streams that should be traced.

28.5.4 ARU dynamic routing

A dynamic routing feature of the ARU is implemented and can be configured using the additional AEI registers:

- **ARU_CTRL**
- **ARU_[x]_DYN_CTRL**
- **ARU_[x]_DYN_RDADDR**
- **ARU_[x]_DYN_ROUTE_LOW**
- **ARU_[x]_DYN_ROUTE_HIGH**
- **ARU_[x]_DYN_ROUTE_SR_LOW**
- **ARU_[x]_DYN_ROUTE_SR_HIGH**

For further information see the register part of this chapter.

28.5.4.1 Dynamic routing - CPU controlled

The dynamic routing feature can be enabled separately for ARU-0 and ARU-1 by setting the corresponding bit fields of the register **ARU_CTRL**.

The enabling of the dynamic routing feature is synchronized to the normal routing scheme if ARU master ID-0 is addressed. The dynamic route will started with additional ARU master DYN_READ_ID0.

With the dynamic routing feature it is possible to insert additional ARU master ID's, DYN_READ_IDy (y:0-5), in a defined manner into the normal ARU routing scheme.

While inserting additional ARU master ID's the normal ARU routing scheme is paused. Therefore please consider that inserting additional ARU master ID's will lengthen the normal routing scheme.

It is possible to configure 6 additional ARU master ID's in the **ARU_[x]_DYN_ROUTE_LOW/_HIGH** registers for both ARU-0 and ARU-1.

In the bit field **DYN_CLK_WAIT** of **ARU_[x]_DYN_ROUTE_HIGH** register the number of clock cycles has to be configured, after which one of the additional ARU master ID's will be inserted.

After each configured number of clock cycles the defined ARU master ID's will be inserted cyclic one after each other in the following manner:

... -> DYN_READ_ID0 -> DYN_READ_ID1 -> DYN_READ_ID2 -> DYN_READ_ID3 -> DYN_READ_ID4 -> DYN_READ_ID5 -> DYN_READ_ID0 -> ...

In the shadow registers **ARU_[x]_DYN_ROUTE_SR_LOW/_HIGH** further 6 ARU master, DYN_READ_IDy (y:6-11), can be configured.

The bit **DYN_UPDATE_EN** in the **ARU_[x]_DYN_ROUTE_SR_HIGH** register controls whether the **ARU_[x]_DYN_ROUTE_LOW/_HIGH** registers are updated from its shadow registers except **DYN_UPDATE_EN**, it is not updated. The update is executed once after writing **ARU_[x]_DYN_ROUTE_SR_HIGH**. If update started **DYN_UPDATE_EN** is reset.

With the **DYN_ROUTE_SWAP** option in the **ARU_[x]_DYN_CTRL** register it is possible to swap the registers **ARU_[x]_DYN_ROUTE_LOW/HIGH** with its shadow registers **ARU_[x]_DYN_ROUTE_SR_LOW/HIGH**. The swapping is executed always after the 6 ARU master DYN_READ_ID's are inserted. So it is possible to insert a maximum of 12 ARU master DYN_READ_ID's cyclic after each configured number of clock cycles. If swap started **DYN_UPDATE_EN** is reset.

Setting the bit field **DYN_CLK_WAIT** of **ARU_[x]_DYN_ROUTE_HIGH** register to zero, only the defined ARU master DYN_READ_ID's will be executed. The normal ARU routing scheme is stopped.

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Setting the bit field **DYN_CLK_WAIT** of **ARU_[x]_DYN_ROUTE_HIGH** register to 15, only the normal ARU routing scheme is executed. Inserting of additional ID's is stopped.

To reset the ARU caddr counter and ARU dynamic route counter set bit **ARU_ADDR_RSTGLB** of **CMU_GLB_CTRL** following by a write access to register **CMU_CLK_EN**.

28.5.4.1.1 Dynamic routing ring mode

In dynamic routing ring mode it is possible to use all 24 **DYN_READ_ID**'s from both ARU-0 and ARU-1 by setting bit field **ARU_DYN_RING_MODE** in **ARU_CTRL** register to 1. In this mode all 4 registers **ARU_[x]_DYN_ROUTE_LOW/_HIGH** and **ARU_[x]_DYN_ROUTE_SR_LOW/_HIGH** are connected as a ring, so all 24 **DYN_READ_ID**'s can be used from both ARU's. The ring structure is shown in **Figure 24**. The data register shift direction is shown by the arrows in the ring.

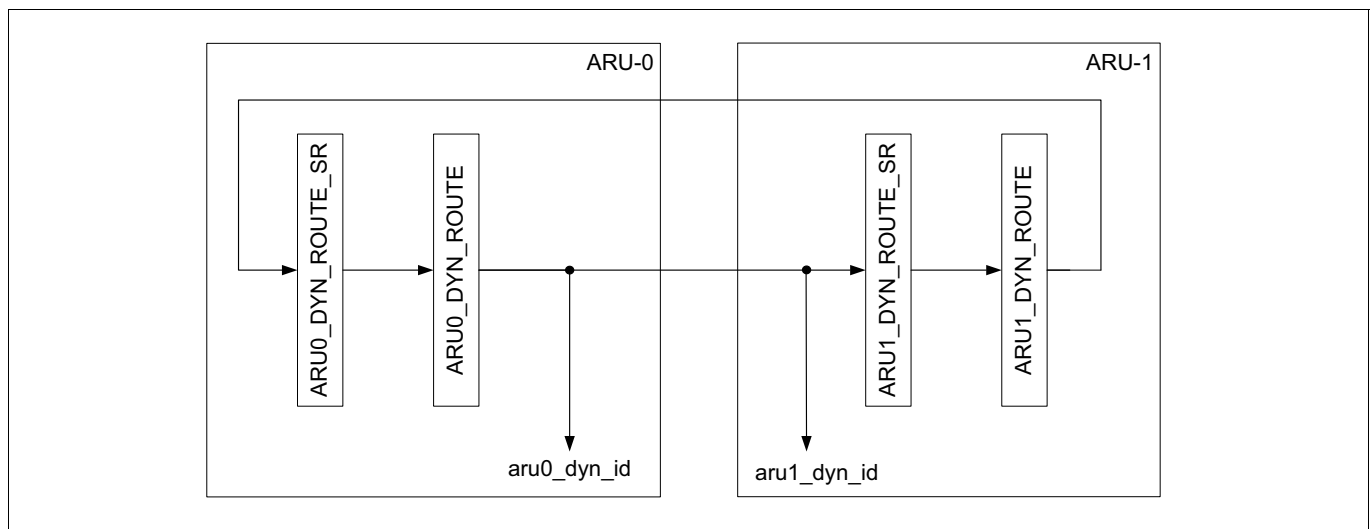


Figure 24 ARU dynamic routing - ring mode

Enabling the dynamic routing ring mode will automatically reset the caddr counter of both ARU-0 and ARU-1. This is necessary to synchronize both ARU's in this mode.

Enabling the dynamic routing ring mode will ignored **DYN_ROUTE_SWAP** and **DYN_UPDATE_EN**.

Note: **DYN_ARU_UPDATE_EN** should be disabled in dynamic routing ring mode.

It is possible to enable the dynamic routing ring mode for both ARU-0 and ARU-1 or only for one of the ARU's by setting the corresponding bit field **ARU_0_DYN_EN/ARU_1_DYN_EN** of the register **ARU_CTRL**.

Because of the fact that to each ARU port ARU-0 and ARU-1 with the same ARU read ID two different GTM sub-modules are served it may make sense to enable ARU dynamic routing only for one port ARU-0 or ARU-1 if configured to ring-mode. The other port is then served in the default round robin manner.

In dynamic routing ring mode **ARU_[x]_DYN_ROUTE_LOW/_HIGH** and **ARU_[x]_DYN_ROUTE_SR_LOW/_HIGH** are not write-protected. NOTE: Avoid modification of **ARU_[x]_DYN_ROUTE_LOW/_HIGH** and **ARU_[x]_DYN_ROUTE_SR_LOW/_HIGH** in active dynamic routing ring mode.

28.5.4.2 Dynamic routing - ARU controlled

Furthermore it is possible to reload the **ARU_[x]_DYN_ROUTE_SR_LOW/_HIGH** registers by ARU itself.

Therefore the ARU has its own master port which will be served in the normal ARU routing scheme. The ARU read address for this master port has to be configured in the register **ARU_[x]_DYN_RDADDR**.