

CAN Interface (MCMCAN)

Note: The rising edge detection at the event trigger is enabled with the start of each basic cycle. The first rising edge triggers the compare of the actual cycle time with *TTGTP0.CTP*. All further edges until the beginning of the next basic cycle are ignored.

40.4 Registers

This section describes the registers within the MCMCAN module. All the registers are prefixed as CAN0_, CAN1_ or CAN2_ for MCMCAN modules, if the corresponding module exist for a particular product variant (Refer Appendix). The registers are grouped as three different sections:

- General Configuration Registers
- User Interface Registers
- Registers within M_CAN

The registers listed in [Figure 604](#) are not included in the MCMCAN module kernel (part of general module IP blocks), some registers must be programmed for proper operation of the MCMCAN module.

The additional ACCEN registers, are MCMCAN specific.

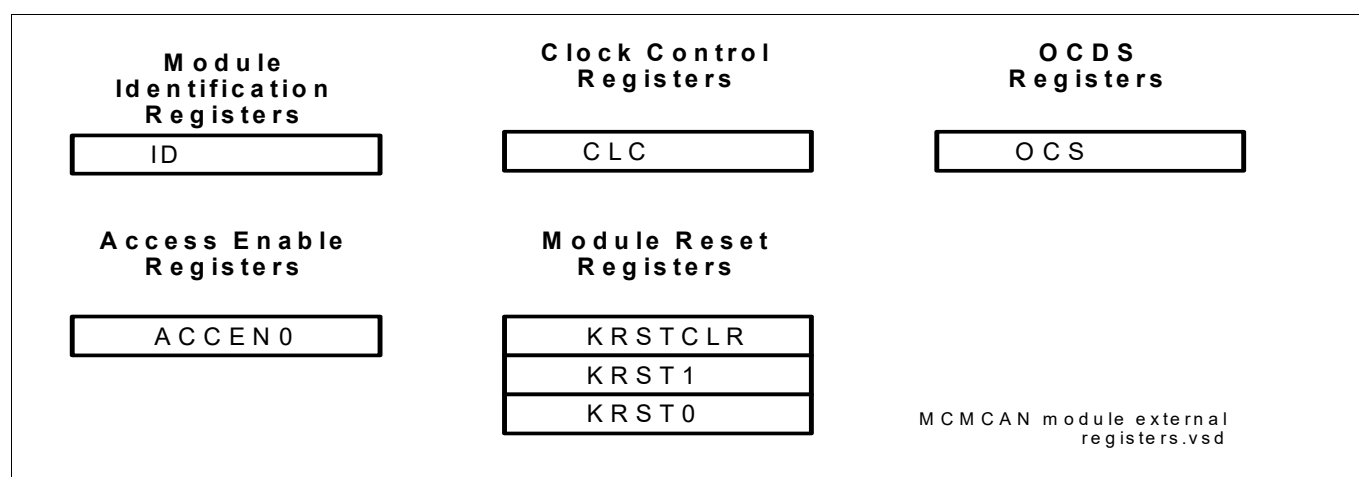


Figure 604 CAN Implementation-specific Special Function Registers

40.4.1 MCMCAN RAM address space

Table 378 Register Address Space - MCMCAN RAM

Module	Base Address	End Address	Note
CANRAM0	F020 0000 _H	F020 7FFF _H	RAM Area CAN0
CANRAM1	F021 0000 _H	F021 3FFF _H	RAM Area CAN1
CANRAM2	F022 0000 _H	F022 3FFF _H	RAM Area CAN2

Note: Refer Appendix of a product variant for the register address space of MCMCAN and available RAM modules.

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40.4.2 MCMCAN register overview

Table 379 Register Overview - CAN (ascending Offset Address)

Short Name	Long Name	Offset Address	Access Mode		Reset	Page Number
			Read	Write		
RAM	Embedded SRAM for messages (008000 _H Byte)	000000 _H				
CLC	CAN Clock Control Register	008000 _H	U,SV	SV,E,P	Application Reset	83
ID	Module Identification Register	008008 _H	U,SV	nBE	Application Reset	70
MCR	Module Control Register	008030 _H	U,SV	SV,U,P	Application Reset	70
BUFADR	Buffer receive address and transmit address	008034 _H	U,SV	SV,U,P	Application Reset	73
MECR	Measure Control Register	008040 _H	U,SV	SV,U,P	Application Reset	74
MESTAT	Measure Status Register	008044 _H	U,SV	SV,U,P	Application Reset	75
ACCENCTR0	Access Enable Register Control 0	0080DC _H	U,SV	SV,SE,P	Application Reset	79
OCS	OCDS Control and Status	0080E8 _H	U,SV	SV,P,OEN	Debug Reset	76
KRSTCLR	Kernel Reset Status Clear Register	0080EC _H	U,SV	SV,E,P	Application Reset	81
KRST1	Kernel Reset Register 1	0080F0 _H	U,SV	SV,E,P	Application Reset	81
KRST0	Kernel Reset Register 0	0080F4 _H	U,SV	SV,E,P	Application Reset	80
ACCEN0	Access Enable Register 0	0080FC _H	U,SV	SV,SE	Application Reset	78
ACCENNODEi0	Access Enable Register CAN Node i 0	008100 _H +i*400 _H	U,SV	SV,SE,P	Application Reset	79
STARTADRI	Start Address Node i	008108 _H +i*400 _H	U,SV	SV,SE,P	Application Reset	89
ENDADRI	End Address Node i	00810C _H +i*400 _H	U,SV	SV,SE,P	Application Reset	89
ISREGi	Interrupt Signalling Register i	008110 _H +i*400 _H	U,SV	nBE	Application Reset	86
GRINT1i	Interrupt routing for Groups 1 i	008114 _H +i*400 _H	U,SV	SV,U,P	Application Reset	83
GRINT2i	Interrupt routing for Groups 2 i	008118 _H +i*400 _H	U,SV	SV,U,P	Application Reset	85

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Table 379 Register Overview - CAN (ascending Offset Address) (cont'd)

Short Name	Long Name	Offset Address	Access Mode		Reset	Page Number
			Read	Write		
NTCCRI	Node i Timer Clock Control Register	008120 _H +i*400 _H	U,SV	SV,U,P	Application Reset	90
NTATTRI	Node i Timer A Transmit Trigger Register	008124 _H +i*400 _H	U,SV	SV,U,P	Application Reset	91
NTBTTRI	Node i Timer B Transmit Trigger Register	008128 _H +i*400 _H	U,SV	SV,U,P	Application Reset	92
NTCTTRI	Node i Timer C Transmit Trigger Register	00812C _H +i*400 _H	U,SV	SV,U,P	Application Reset	92
NTRTRI	Node i Timer Receive Timeout Register	008130 _H +i*400 _H	U,SV	SV,U,P	Application Reset	93
NPCRi	Node i Port Control Register	008140 _H +i*400 _H	U,SV	SV,U,P	Application Reset	87
TTCRI	Time Trigger Control Register	0081F0 _H	U,SV	SV,U,P	Application Reset	88
CRELi	Core Release Register i	008200 _H +i*400 _H	U,SV	nBE	See page 95	95
ENDNi	Endian Register i	008204 _H +i*400 _H	U,SV	nBE	Application Reset	95
DBTPi	Data Bit Timing & Prescaler Register i	00820C _H +i*400 _H	U,SV	SV,U,P	Application Reset	96
TESTi	Test Register i	008210 _H +i*400 _H	U,SV	SV,U,P	Application Reset	97
RWDi	RAM Watchdog i	008214 _H +i*400 _H	U,SV	SV,U,P	Application Reset	98
CCCRi	CC Control Register i	008218 _H +i*400 _H	U,SV	SV,U,P	Application Reset	99
NBTPi	Nominal Bit Timing & Prescaler Register i	00821C _H +i*400 _H	U,SV	SV,U,P	Application Reset	101
TSCCi	Timestamp Counter Configuration i	008220 _H +i*400 _H	U,SV	SV,U,P	Application Reset	103
TSCVi	Timestamp Counter Value i	008224 _H +i*400 _H	U,SV	SV,U,P	Application Reset	104
TOCCi	Timeout Counter Configuration i	008228 _H +i*400 _H	U,SV	SV,U,P	Application Reset	104
TOCVi	Timeout Counter Value i	00822C _H +i*400 _H	U,SV	SV,U,P	Application Reset	105
ECRI	Error Counter Register i	008240 _H +i*400 _H	U,SV	nBE	Application Reset	106
PSRi	Protocol Status Register i	008244 _H +i*400 _H	U,SV	nBE	Application Reset	107

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Table 379 Register Overview - CAN (ascending Offset Address) (cont'd)

Short Name	Long Name	Offset Address	Access Mode		Reset	Page Number
			Read	Write		
TDCRi	Transmitter Delay Compensation Register i	008248 _H +i*400 _H	U,SV	SV,U,P	Application Reset	111
IRi	Interrupt Register i	008250 _H +i*400 _H	U,SV	SV,U,P	Application Reset	112
IEi	Interrupt Enable i	008254 _H +i*400 _H	U,SV	SV,U,P	Application Reset	115
GFCi	Global Filter Configuration i	008280 _H +i*400 _H	U,SV	SV,U,P	Application Reset	117
SIDFCi	Standard ID Filter Configuration i	008284 _H +i*400 _H	U,SV	SV,U,P	Application Reset	118
XIDFCi	Extended ID Filter Configuration i	008288 _H +i*400 _H	U,SV	SV,U,P	Application Reset	119
XIDAMi	Extended ID AND Mask i	008290 _H +i*400 _H	U,SV	SV,U,P	Application Reset	120
HPMSi	High Priority Message Status i	008294 _H +i*400 _H	U,SV	nBE	Application Reset	120
NDAT1i	New Data 1 i	008298 _H +i*400 _H	U,SV	SV,U,P	Application Reset	121
NDAT2i	New Data 2 i	00829C _H +i*400 _H	U,SV	SV,U,P	Application Reset	122
RXF0Ci	Rx FIFO 0 Configuration i	0082A0 _H +i*400 _H	U,SV	SV,U,P	Application Reset	122
RXF0Si	Rx FIFO 0 Status i	0082A4 _H +i*400 _H	U,SV	nBE	Application Reset	123
RXF0Ai	Rx FIFO 0 Acknowledge i	0082A8 _H +i*400 _H	U,SV	SV,U,P	Application Reset	124
RXBCi	Rx Buffer Configuration i	0082AC _H +i*400 _H	U,SV	SV,U,P	Application Reset	125
RXF1Ci	Rx FIFO 1 Configuration i	0082B0 _H +i*400 _H	U,SV	SV,U,P	Application Reset	125
RXF1Si	Rx FIFO 1 Status i	0082B4 _H +i*400 _H	U,SV	nBE	Application Reset	126
RXF1Ai	Rx FIFO 1 Acknowledge i	0082B8 _H +i*400 _H	U,SV	SV,U,P	Application Reset	127
RXESCi	Rx Buffer/FIFO Element Size Configuration i	0082BC _H +i*400 _H	U,SV	SV,U,P	Application Reset	127
TXBCi	Tx Buffer Configuration i	0082C0 _H +i*400 _H	U,SV	SV,U,P	Application Reset	129
TXFQSi	Tx FIFO/Queue Status i	0082C4 _H +i*400 _H	U,SV	nBE	Application Reset	130

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Table 379 Register Overview - CAN (ascending Offset Address) (cont'd)

Short Name	Long Name	Offset Address	Access Mode		Reset	Page Number
			Read	Write		
TXESCI	Tx Buffer Element Size Configuration i	0082C8 _H +i*400 _H	U,SV	SV,U,P	Application Reset	131
TXBRPI	Tx Buffer Request Pending i	0082CC _H +i*400 _H	U,SV	SV,U,P	Application Reset	132
TXBARI	Tx Buffer Add Request i	0082D0 _H +i*400 _H	U,SV	SV,U,P	Application Reset	132
TXBCRI	Tx Buffer Cancellation Request i	0082D4 _H +i*400 _H	U,SV	SV,U,P	Application Reset	133
TXBTOI	Tx Buffer Transmission Occurred i	0082D8 _H +i*400 _H	U,SV	nBE	Application Reset	134
TXBCFI	Tx Buffer Cancellation Finished i	0082DC _H +i*400 _H	U,SV	nBE	Application Reset	134
TXBTIEI	Tx Buffer Transmission Interrupt Enable i	0082E0 _H +i*400 _H	U,SV	SV,U,P	Application Reset	135
TXBCIEI	Tx Buffer Cancellation Finished Interrupt Enable i	0082E4 _H +i*400 _H	U,SV	SV,U,P	Application Reset	135
TXEFCI	Tx Event FIFO Configuration i	0082F0 _H +i*400 _H	U,SV	SV,U,P	Application Reset	136
TXEFSI	Tx Event FIFO Status i	0082F4 _H +i*400 _H	U,SV	nBE	Application Reset	137
TXEFAI	Tx Event FIFO Acknowledge i	0082F8 _H +i*400 _H	U,SV	SV,U,P	Application Reset	137
TTTMCi	TT Trigger Memory Configuration i	008300 _H	U,SV	SV,U,P	Application Reset	138
TTRMCi	TT Reference Message Configuration i	008304 _H	U,SV	SV,U,P	Application Reset	138
TTOCFi	TT Operation Configuration i	008308 _H	U,SV	SV,U,P	Application Reset	139
TTMLMi	TT Matrix Limits i	00830C _H	U,SV	SV,U,P	Application Reset	141
TURCFi	TUR Configuration i	008310 _H	U,SV	SV,U,P	Application Reset	142
TTOCNi	TT Operation Control i	008314 _H	U,SV	SV,U,P	Application Reset	144
TTGTPi	TT Global Time Preset i	008318 _H	U,SV	SV,U,P	Application Reset	146
TTTMKi	TT Time Mark i	00831C _H	U,SV	SV,U,P	Application Reset	147
TTIRi	TT Interrupt Register i	008320 _H	U,SV	SV,U,P	Application Reset	148

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Table 379 Register Overview - CAN (ascending Offset Address) (cont'd)

Short Name	Long Name	Offset Address	Access Mode		Reset	Page Number
			Read	Write		
TTIEi	TT Interrupt Enable i	008324 _H	U,SV	SV,U,P	Application Reset	151
TTOSTi	TT Operation Status i	00832C _H	U,SV	nBE	Application Reset	153
TURNAi	TUR Numerator Actual i	008330 _H	U,SV	nBE	Application Reset	155
TTLGTi	TT Local & Global Time i	008334 _H	U,SV	nBE	Application Reset	156
TTCTCi	TT Cycle Time & Count i	008338 _H	U,SV	nBE	Application Reset	156
TTCPTi	TT Capture Time i	00833C _H	U,SV	nBE	Application Reset	157
TTCSMi	TT Cycle Sync Mark i	008340 _H	U,SV	nBE	Application Reset	157

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40.4.3 General Configuration Registers

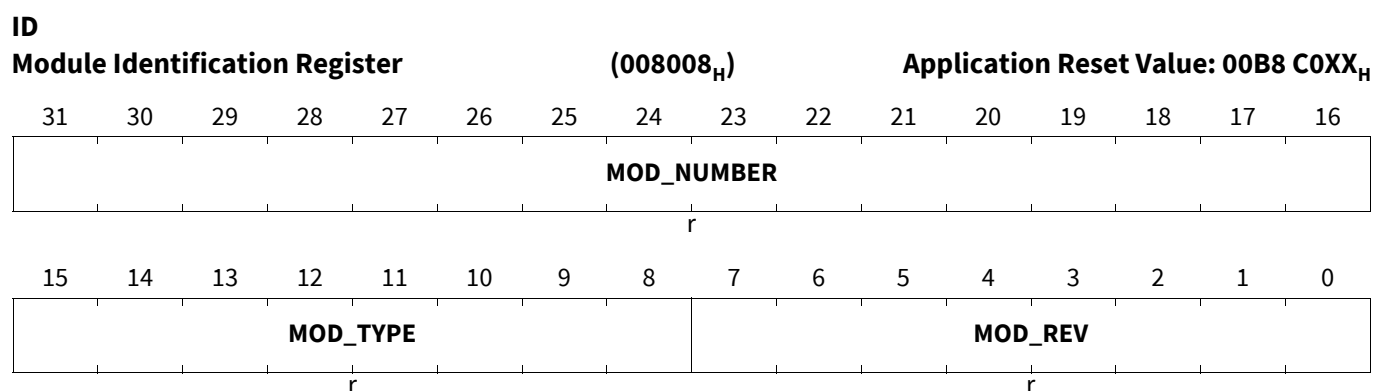
This section describes the global module registers, system registers, access enable registers and kernel reset registers.

40.4.3.1 Global Module Registers

Global Module Registers, are registers, which are not part of M_CAN nodes.

Module Identification Register

The Module Identification Register ID contains read-only information about the module version.



Field	Bits	Type	Description
MOD_REV	7:0	r	Module Revision Number MOD_REV defines the revision number. The value of a module revision starts with 01 _H (first revision).
MOD_TYPE	15:8	r	Module Type C0 _H Define the module as a 32-bit module.
MOD_NUMBER	31:16	r	Module Number Value This bit field defines the MCMCAN module identification number 00B8 _H .

Module Control Register

The Module Control Register MCR contains basic settings that determine the operation of the MCMCAN module. The write access to the lowest byte of the MCR register becomes only valid, if and only if, MCR.CCCE and MCR.CI are already set during write access. To switch the clocks on or off, the bits of MCR.CCCE and MCR.CI have to be reset afterwards. Before this sequence hasn't taken place, no write access to the corresponding nodes, can be done.

Note: If the baud rate logic is supplied from an unstable clock source, or no clock at all, the CAN functionality is not guaranteed.

To be able to change the clock settings the following programming sequence needs to be met:

```
uwTemp = CANn_MCR.U;
uwTemp |= (0xC0000000 | CLKSELx);
CANn_MCR.U = uwTemp;
uwTemp &= ~0xC0000000;
```

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CANn_MCR.U = uwTemp;

The clock settings for CAN nodes becomes active.

To be able to start the RAM initialization, the following programming sequence need to be met:

CANn_MCR |= 0xC0000000;

Wait until CANn_MCR.RBUSY is 0b

Set CANn_MCR.RINIT to 0b

Set CANn_MCR.RINIT to 1b

Dummy read CANn_MCR

Wait until CANn_MCR.RBUSY is 0b

Set CANn_MCR.RINIT to 0b

CANn_MCR &= ~0xC0000000;

RAM initialization is finished

MCR

Module Control Register

(008030_H)

Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
CCCE	CI	RINIT	RBUSY	DXCM	NODE		0								
rw	rw	rw	rh	rw	rw		r								
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0					CLKSEL3			CLKSEL2		CLKSEL1		CLKSEL0			
r					rw			rw		rw		rw			

Field	Bits	Type	Description
CLKSEL0	1:0	rw	Clock Select 0 This bitfield is MCR.CI and MCR.CCCE protected. 00 _B No clock supplied 01 _B The asynchronous clock source is switched on 10 _B The synchronous clock source is switched on 11 _B Both clock sources are switched on
CLKSEL1	3:2	rw	Clock Select 1 This bitfield is MCR.CI and MCR.CCCE protected. 00 _B No clock supplied 01 _B The asynchronous clock source is switched on 10 _B The synchronous clock source is switched on 11 _B Both clock sources are switched on
CLKSEL2	5:4	rw	Clock Select 2 This bitfield is MCR.CI and MCR.CCCE protected. 00 _B No clock supplied 01 _B The asynchronous clock source is switched on 10 _B The synchronous clock source is switched on 11 _B Both clock sources are switched on

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Field	Bits	Type	Description
CLKSEL3	7:6	rw	Clock Select 3 This bitfield is MCR.CI and MCR.CCCE protected. 00 _B No clock supplied 01 _B The asynchronous clock source is switched on 10 _B The synchronous clock source is switched on 11 _B Both clock sources are switched on
NODE	26:24	rw	Node This bit field determines the CAN node i which is used for debug over CAN. This bitfield only exists on CAN0. 000 _B Node 0 ... 011 _B Node 3
DXCM	27	rw	Debug Over CAN Messages Enable This bit enables the debug over serial connections between DAP and CAN0 module. If enabled the lowest receive/transmit message buffer is reserved for debugger communication. DXCM is described in detail in the OCDS chapter. This bit only exists on CAN0. 0 _B DXCM disabled 1 _B DXCM enabled
RBUSY	28	rh	RAM BUSY This bit shows that the RAM Initialization is running. This bit is set back to 0b by hardware when the RAM initialization is completed.
RINIT	29	rw	RAM Init This bit is MCR.CI and MCR.CCCE protected. This bit starts the initialization of the RAM block to all 0x0. The RAM initialization is started only when this bit is changed from 0b to 1b and also RBUSY is 0b.
CI	30	rw	Change Init Needs to be set to enable and disable clocks. 0 _B Change Init disabled 1 _B Change Init enabled (takes effect with CCCE:=1)
CCCE	31	rw	Clock and RAM Change Enable Needs to be set to enable and disable the clocks. 0 _B Clock and RAM Change disabled 1 _B Clock and RAM Change enabled (takes effect with CI:=1)
0	23:8	r	Reserved Shall read 0; shall be written with 0.

Debug over CAN (DXCM feature)

The MCMCAN controller supports debugging using standard CAN tool access in parallel to regular CAN bus traffic. This is achieved by transmitting DAP telegrams and replies as regular CAN messages (DXCM DAP over CAN Messages). DXCM uses the lowest message buffers and it is strongly recommended to use also the same CAN pins as for DXCPL (DAP over CAN Physical Layer). DXCM is enabled with the MCR.DXCM bit. Please refer to the OCDS chapter for more information about DAP, DXCM and DXCPL.

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Debug over CAN shall be only available on CAN0. TX Buffer 0 will be the sending transmit object. For receive at least one message buffer has to be configured. Meaning that RX Buffer 0 will be used for receiving DAP telegrams. The starting address of the message buffer and the receiving address of the message buffer have to be configured within BUFADR register.

Assigning the buffer start address

The following register assigns the start address to all features needing the message buffers inside the corresponding M_CAN, which are for receive and transmit.

Buffer receive address and transmit address

BUFADR

Buffer receive address and transmit address (008034_H)

Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0		RXBUF													
r		rw													
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0		TXBUF													
r		rw													

Field	Bits	Type	Description
TXBUF	13:0	rw	Transmit Buffer start address This is the start address of the first dedicated transmit buffer.
RXBUF	29:16	rw	Receive Buffer start address This is the start address of the first dedicated receive buffer.
0	15:14, 31:30	r	Reserved Shall read 0; shall be written with 0.

Pretended Networking

The registers above are intended to support Pretended Networking. As an application example, the SPB bus is clocked at 40MHz. The asynchronous module part is clocked either with 40MHz as well or even more power saving with direct drive from the oscillator. The cores are in idle mode.

Messages can be received and a receive interrupt can be generated. It is possible to trigger messages with or without changing the content by the timers provided. For example the network management message and two related messages can be triggered without any CPU interaction.

As mostly the operating system is still running, messages can be changed without any problem during the time, where the operating system is active.

Oscillator calibration

The following registers support the oscillator calibration on which the decision is taken to increase or decrease the frequency. A detailed description will be provided as Application Node.

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Measure Control Register

The Measure Control Register MECR controls the CAN edge timing measurement function for calibration purposes. This feature only exists on CAN0.

MECR

Measure Control Register

(008040_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0	SOF	DEPTH			0	CAPEIE	ANYED	0	NODE			INP			
r	rw	rw			r	rw	rw	r	rw			rw			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TH															
rw															

Field	Bits	Type	Description
TH	15:0	rw	Threshold This bit field contains the threshold value for the measurement timer. If TH = 0000 _H , the timer is stopped and the capture function is disabled.
INP	19:16	rw	Interrupt Node Pointer INP selects the interrupt output line INT_Om (m = 0-15) for a capture event interrupt. 0 _H Interrupt output line INT_O0 is selected ... F _H Interrupt output line INT_O15 is selected
NODE	22:20	rw	Node This bit field determines the CAN node i whose input line RXDCANi is used for start and capture of the measurement timer. 000 _B Node 0 ... 011 _B Node 3
ANYED	24	rw	Any Edge This bit enables capture on any edge of CAN input line specified by NODE. 0 _B Capture on falling (dominant) edge only 1 _B Capture on rising (recessive) or falling (dominant) edge
CAPEIE	25	rw	Capture Event Interrupt Enable This bit enables the capture event interrupt. Bit field INP selects the interrupt output line which becomes activated at this type of interrupt. 0 _B Capture event interrupt is disabled 1 _B Capture event interrupt is enabled

CAN Interface (MCMCAN)

Field	Bits	Type	Description
DEPTH	29:27	rw	Digital Glitch Filter Depth DEPTH determines the number of input samples clocked with $f_{\text{SYN}i}$ that are taken into account for the calculation of the floating average. The higher DEPTH is chosen to be, the longer the glitches that are suppressed and the longer the delay of the input signal introduced by this filter. 000 _B off, default 001 _B Filter depth of 8 cycles 010 _B Filter depth of 16 cycles 011 _B Filter depth of 32 cycles 100 _B Filter depth of 64 cycles 101 _B Filter depth of 128 cycles 110 _B Filter depth of 255 cycles 111 _B not allowed, reserved
SOF	30	rw	Start Of Frame This bit selects falling edge or any edge as measurement for start of frame detection. 0 _B Measurement starts with any falling edge 1 _B Measurement starts with falling Start of Frame edge. i.e any falling edge that occurs while the CAN node is in idle state
0	23, 26, 31	r	Reserved Shall read 0; shall be written with 0.

Measure Status Register

The Measure Status Register MESTAT contains the status information of the CAN edge timing measurement. This feature only exists on CAN0.

MESTAT

Measure Status Register

(008044_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0														CAPE	CAPRE D
r														rwh	rh
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CAPT															
rh															

CAN Interface (MCMCAN)

Field	Bits	Type	Description
CAPT	15:0	rh	<p>Captured Timer</p> <p>This bit field contains the captured measurement timer content. The timer itself is cleared and started by the first falling (dominant) edge of a CAN frame on the input line of the CAN node specified by MECR.NODE. The timer is incremented by the module control clock f_{SYNI} and will be stopped when $FFFF_H$ is reached. If $MECR.TH = 0000_H$, the timer is always stopped.</p> <p>A capture will take place if all the following conditions are met:</p> <ol style="list-style-type: none"> 1. $MECR.TH > 0000_H$ 2. Timer is cleared and started by new frame 3. Timer reaches MECR.TH 4. This node is not sending and first edge (as specified by MECR.ANYED) after 3. occurs on input line <p>Capture will be repeated for the following CAN frames until MECR.TH is cleared.</p>
CAPRED	16	rh	<p>Captured Rising Edge</p> <p>This bit indicates the type of edge that caused the last capture event.</p> <p>0_B Capture occurred on falling (dominant) edge</p> <p>1_B Capture occurred on rising (recessive) edge</p>
CAPE	17	rwh	<p>Capture Event</p> <p>This flag is set on a capture event. It must be reset by software. An interrupt request is generated if $MECR.CAPEIE = 1$. If $CAPE=1$ then no further measurement results are posted to MESTAT.CAPT and MESTAT.CAPRED. CAPE bit has to be cleared to re-enable update of MESTAT.CAPT and MESTAT.CAPRED.</p> <p>0_B No capture event has occurred since last flag reset</p> <p>1_B Capture event has occurred since last flag reset</p>
0	31:18	r	<p>Reserved</p> <p>Shall read 0; shall be written with 0.</p>

40.4.3.2 System Registers

OCDS Control and Status

OCDS Trigger Bus (OTGB) The OCDS Control and Status (OCS) register is cleared by Debug Reset. The OCS register can only be written when the OCDS is enabled. If OCDS is being disabled, the OCS register value will not change. When OCDS is disabled the OCS suspend control is ineffective. Write access requires Supervisor Mode.

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OCS

OCDS Control and Status

(0080E8_H)Debug Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0		SUSSTA	SUS_P				SUS					0			
r		rh	w				rw					r			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							0					TG_P	TGB	TGS	
							r					w	rw	rw	

Field	Bits	Type	Description
TGS	1:0	rw	Trigger Set for OTGB0/1 00 _B No Trigger Set output 01 _B TS16_CAN others , reserved
TGB	2	rw	OTGB0/1 Bus Select 0 _B Trigger Set is output on OTGB0 1 _B Trigger Set is output on OTGB1
TG_P	3	w	TGS, TGB Write Protection TGS and TGB are only written when TG_P is 1, otherwise unchanged. Read as 0.
SUS	27:24	rw	OCDS Suspend Control Controls the sensitivity to the suspend signal coming from the OCDS Trigger Switch (OTGS) 0 _H Will not suspend 1 _H Hard suspend. Clock is off immediately. Do not use this mode in normal CAN applications, this mode is meant for debugging the peripheral IP. 2 _H Soft suspend of CAN nodes. others , reserved
SUS_P	28	w	SUS Write Protection SUS is only written when SUS_P is 1, otherwise unchanged. Read as 0.
SUSSTA	29	rh	Suspend State 0 _B CAN nodes are not (yet) suspended 1 _B All CAN nodes are suspended
0	23:4, 31:30	r	Reserved Shall read 0; shall be written with 0.

OCDS Trigger Bus (OTGB) Interface

The MCMCAN Trigger Set is shown in [Table 380](#). Its output is on OTGB0 or OTGB1 controlled by the **OCDS Control and Status** register. Links are only for CAN0, but the feature is available for all CAN modules.

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Table 380 TS16_CAN Trigger Set MCMCAN

Value s	Name	Description
i	AF	Acceptance filtering done for node i
i + 4	MR	Message successfully received on node i
i + 8	FDR	Fast Data Phase reception on node i
i + 12	FDT	Fast Data Phase transmission on node i.

40.4.3.3 Access Enable Registers ACCEN

The access enable bits control the access on the module itself.

Access Enable Register 0

The Access Enable Register 0 controls write access¹⁾ for transactions with the on chip bus master TAG ID 000000_B to 011111_B (see On Chip Bus chapter for the products TAG ID <-> master peripheral mapping). The BPI_FPI is prepared for a 6-bit TAG ID. The registers ACCEN0 provides one enable bit for each possible 6-bit TAG ID encoding. Mapping of TAG IDs to ACCEN0.ENy: EN0 -> TAG ID 000000_B, EN1 -> TAG ID 000001_B, ..., EN31 -> TAG ID 011111_B.

ACCEN0

Access Enable Register 0

(0080FC_H)Application Reset Value: FFFF FFFF_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
EN31	EN30	EN29	EN28	EN27	EN26	EN25	EN24	EN23	EN22	EN21	EN20	EN19	EN18	EN17	EN16
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
EN15	EN14	EN13	EN12	EN11	EN10	EN9	EN8	EN7	EN6	EN5	EN4	EN3	EN2	EN1	EN0
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
ENy (y=0-31)	y	rw	Access Enable for Master TAG ID y This bit enables write access to the module kernel addresses for transactions with the Master TAG ID y. 0 _B Write access will not be executed 1 _B Write access will be executed

40.4.3.4 Additional Access Enable Registers ACCENCTR and ACCENNODEi

The access enable bits help the application to control the access rights via bus master TAG ID. Inside the CAN node registers, an additional address range can be defined, called STARTADR and ENDADR.

The ACCENNODEi registers are protecting node i and the memory range defined in the STARTADRI and ENDADRI register. To disable the mechanism the STARTADRI has to be higher than the corresponding ENDADRI of the node.

1) The BPI_FPI Access Enable functionality controls only write transactions. Read transactions are not influenced. SW has to take care for destructive/modifying read functionality in kernel registers-

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Access Enable Register Control 0

The Access Enable Register Control 0 controls write access for transactions with the on chip bus master TAG ID 000000_B to 011111_B (see On Chip Bus chapter for the products TAG ID ↔ master peripheral mapping). The BPI_FPI is prepared for a 6-bit TAG ID. The registers ACCENCTR0 provides one enable bit for each possible 6-bit TAG ID encoding. The control registers (address range 8020_H to 804F_H) are protected by this register.

Mapping of TAG IDs to ACCENCTR0.ENy: EN0 → TAG ID 000000_B, EN1 → TAG ID 000001_B, ..., EN31 → TAG ID 011111_B.

ACCENCTR0

Access Enable Register Control 0

(0080DC_H)

Application Reset Value: FFFF FFFF_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
EN31	EN30	EN29	EN28	EN27	EN26	EN25	EN24	EN23	EN22	EN21	EN20	EN19	EN18	EN17	EN16
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
EN15	EN14	EN13	EN12	EN11	EN10	EN9	EN8	EN7	EN6	EN5	EN4	EN3	EN2	EN1	EN0
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
ENy (y=0-31)	y	rw	Access Enable for Master TAG ID y This bit enables write access to the module kernel addresses for transactions with the Master TAG ID y 0 _B Write access will not be executed 1 _B Write access will be executed

Access Enable Register CAN Node i 0

The Access Enable Register CAN Node i Control 0 controls write access for transactions with the on chip bus master TAG ID 000000_B to 011111_B (see On Chip Bus chapter for the products TAG ID ↔ master peripheral mapping). The BPI_FPI is prepared for a 6-bit TAG ID. The registers ACCENNODEi0 provides one enable bit for each possible 6-bit TAG ID encoding. This register controls node y registers, including the STARTADR0 and ENDADR0 register included in the node control area (8100_H+i*0400_H to 8400_H+i*0400_H-1). This means, that this area is including these registers and also the STARTADRI and ENDADRI. If the programming of the CPU leads to the fact, that it is disabling its own access, it will not be able to correct such a setting afterwards.

Mapping of TAG IDs to ACCENNODEi0.ENy: EN0 → TAG ID 000000_B, EN1 → TAG ID 000001_B, ..., EN31 → TAG ID 011111_B.

ACCENNODEi0 (i=0-3)

Access Enable Register CAN Node i 0

(008100_H+i*400_H)

Application Reset Value: FFFF FFFF_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
EN31	EN30	EN29	EN28	EN27	EN26	EN25	EN24	EN23	EN22	EN21	EN20	EN19	EN18	EN17	EN16
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
EN15	EN14	EN13	EN12	EN11	EN10	EN9	EN8	EN7	EN6	EN5	EN4	EN3	EN2	EN1	EN0
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

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Field	Bits	Type	Description
ENy (y=0-31)	y	rw	Access Enable for Master TAG ID y This bit enables write access to the module kernel addresses for transactions with the Master TAG ID y 0 _B Write access will not be executed 1 _B Write access will be executed

40.4.3.5 Kernel Reset Registers

The Kernel Reset Registers give the user the possibility to reset the module without resetting the device.

Kernel Reset Register 0

The Kernel Reset Register 0 is used to reset the related module kernel. Kernel registers related to the Debug Reset (Class 1) are not influenced. To reset a module kernel it is necessary to set the RST bits by writing with '1' in both Kernel Reset Registers related to the module kernel reset. The RST bit will be reset by the BPI with the end of the BPI kernel reset sequence.

Kernel Reset Register 0 includes a kernel reset status bit that is set to '1' by the BPI_FPI in the same clock cycle the RST bit is reset by the BPI_FPI. This bit can be used to detect that a kernel reset was processed. The bit can be reset to '0' by writing to KRSTCLR.CLR with '1'.

During the execution of the kernel reset until RSTSTAT is set, access to the kernel registers will result in an error acknowledge.

KRST0

Kernel Reset Register 0

(0080F4_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0														RSTSTAT	RST
r														rh	rwh

Field	Bits	Type	Description
RST	0	rwh	Kernel Reset This reset bit can be used to request for a kernel reset. The kernel reset will be executed if the reset bits of both kernel registers are set. The RST bit will be cleared (reset to '0') by the BPI_FPI after the kernel reset was executed. 0 _B No kernel reset was requested 1 _B A kernel reset was requested

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Field	Bits	Type	Description
RSTSTAT	1	rh	Kernel Reset Status This bit indicates whether a kernel reset was executed or not. This bit is set by the BPI_FPI after the execution of a kernel reset in the same clock cycle both reset bits. This bit can be cleared by writing with '1' to the CLR bit in the related KRSTCLR register. 0 _B No kernel reset was executed 1 _B Kernel reset was executed
0	31:2	r	Reserved Shall read 0; shall be written with 0.

Kernel Reset Register 1

The Kernel Reset Register 1 is used to reset the related module kernel. To reset a module kernel it is necessary to set the RST bits by writing with '1' in both Kernel Reset Registers (KRST1.RST and KRST0.RST) related to the module kernel reset. The RST bit will be reset (cleared to '0') by the BPI with the end of the BPI kernel reset sequence.

KRST1

Kernel Reset Register 1

(0080F0_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
							0								
							r								
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							0								
							r								RST
															rwh

Field	Bits	Type	Description
RST	0	rwh	Kernel Reset This reset bit can be used to request for a kernel reset. The kernel reset will be executed if the reset bits of both kernel reset registers is set. The RST bit will be cleared (reset to '0') by the BPI_FPI after the kernel reset was executed. 0 _B No kernel reset was requested 1 _B A kernel reset was requested
0	31:1	r	Reserved Shall read 0; shall be written with 0.

Kernel Reset Status Clear Register

The Kernel Reset Clear Register is used to clear the Kernel Reset Status bit (KRST0.RSTSTAT).

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KRSTCLR

Kernel Reset Status Clear Register

(0080EC_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
							0								
							r								
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							0								
							r								w

Field	Bits	Type	Description
CLR	0	w	Kernel Reset Status Clear Read always as 0. 0 _B No action 1 _B Clear Kernel Reset Status KRST0.RSTSTAT
0	31:1	r	Reserved Shall read 0; shall be written with 0.

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40.4.4 MCMCAN User Interface Registers

This section describes the registers for clock control, port connections, interrupt control, and address decoding.

40.4.4.1 The Clock Control Register

CAN Clock Control Register

The Clock Control Register CLC allows the programmer to adapt the functionality and power consumption of the module to the requirements of the application. The description below shows the clock control register functionality which is implemented in the standard interface for the module. Where a module kernel is connected to the CLC clock control interface, CLC controls the f_{SYN} and f_{ASYN} module clock signal, sleep mode and fast shut-off mode for the module.

CLC

CAN Clock Control Register

(008000_H)Application Reset Value: 0000 0003_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0												EDIS	0	DISS	DISR
r												rw	r	rh	rw

Field	Bits	Type	Description
DISR	0	rw	Module Disable Request Bit Used for enable/disable control of the module. The synchronous and asynchronous clock is switched on/off Note that no register access is possible to any register while module is disabled. A disable request is granted, if the M_CAN clock is disabled, or all M_CAN nodes acknowledge the disable request.
DISS	1	rh	Module Disable Status Bit Bit indicates the current status of the module.
EDIS	3	rw	Sleep Mode Disable Control Used to control module's sleep mode.
0	2, 31:4	r	Reserved Shall read 0; shall be written with 0.

40.4.4.2 Interrupt Grouping and Signalling Registers

Interrupt routing for Groups 1 i

GRINT1i is the first of two grouping registers. In this register, the interrupt line within the module is fixed. Please be reminded, that the interrupt sources need to be enabled to be mapped. The total module has 16 interrupts and the interrupt node can be chosen within GRINT1i and GRINT2i.

Meaning:

0000_B Interrupt output line INT_O0 is selected.

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0001_B Interrupt output line INT_O1 is selected.

...B...

1110_B Interrupt output line INT_O14 is selected.

1111_B Interrupt output line INT_O15 is selected.

GRINT1i (i=0-3)

Interrupt routing for Groups 1 i

(008114_H+i*400_H)

Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
LOI				BOFF				SAFE				MOER			
rw				rw				rw				rw			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ALRT				WATI				HPE				TEFIFO			
rw				rw				rw				rw			

Field	Bits	Type	Description
TEFIFO	3:0	rw	Transmit Event FIFO Incidents are mapped here. IR.TEFF (Transmit Event FIFO Full) and IR.TEFN (Transmit Event FIFO New Entry)
HPE	7:4	rw	High Priority Events are mapped here, giving IR.HPM an interrupt level
WATI	11:8	rw	Watermark interrupts are mapped here: IR.TEFW (Transmit FIFO warning interrupt reached), IR.RF1W (Receive FIFO 1 warning interrupt reached). IR.RF0W (Receive FIFO 0 warning interrupt reached)
ALRT	15:12	rw	ALERTS All kind of alerts are mapped here. IR.EW (warning status), IR.EP (error passive), IR.TSW (timestamp wrap around), IR.TEFL (Transmit Event FIFO Element Lost), IR.RF0L (Receive FIFO 0 Message Lost), IR.RF1L (Receive FIFO 1 Message Lost). The following TTCAN error messages and warnings are also shown here: TTIR.CER (Configuration Error), TTIR.AW Application Watchdog, TTIR.WT (Watch Trigger), TTIR.IWT Initialization Watch Trigger, TTIR.ELC (Error Level Changed), TTIR.SE2 (Scheduling Error 2), TTIR.SE1 (Scheduling Error), TTIR.TXO (Tx Count Overflow), TTIR.TXU (TX Count Underflow), TTIR.GTE (Global Time Error), TTIR.GTD (Global Time Discontinuity) and TTIR.GTW (Global Time Wrap)
MOER	19:16	rw	Module errors IR.WDI (watchdog interrupt) and IR.MRAF (message RAM access failure) are mapped here.
SAFE	23:20	rw	Safety counter overflow The interrupt node for IR.ELO showing a safety counter overflow
BOFF	27:24	rw	Bus Off has been reached Mapped to IRi.BO flag indication the change in Bus_Off status. To get out of bus off, the CCCRN.INIT bit has to be reset.

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Field	Bits	Type	Description
LOI	31:28	rw	Last Error Interrupts The interrupt sources IR.PED (Protocol Error in Data Phase) and IR.PEA (Protocol Error in Arbitration Phase) are signalled here.

Interrupt routing for Groups 2 i

GRINT2i has the same functionality as GRINT1i, but for other interrupt sources. The interrupt sources need to be enabled to be mapped.

GRINT2i (i=0-3)

Interrupt routing for Groups 2 i

(008118_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
TRACO				TRAQ				RETI				RxF0N			
rw				rw				rw				rw			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RxF1N				RxF0F				RxF1F				REINT			
rw				rw				rw				rw			

Field	Bits	Type	Description
REINT	3:0	rw	Message stored in dedicated receive buffer interrupt (IR.DRX) is assigned to interrupt node.
RxF1F	7:4	rw	IR.RF1F Receive FIFO1 full interrupt assigned to an interrupt node
RxF0F	11:8	rw	IR.RF0F Receive FIFO0 full interrupt assigned to an interrupt node
RxF1N	15:12	rw	IR.RF1N Receive FIFO1 new message assigned to an interrupt node
RxF0N	19:16	rw	IR.RF0N Receive FIFO0 new message assigned to an interrupt node
RETI	23:20	rw	Receive Timeouts can be assigned here. IR.TOO (time-out event) and TE (Timer Event)
TRAQ	27:24	rw	Transmission Queue Events can be assigned here. IR.TFE Transmission FIFO Empty
TRACO	31:28	rw	Interrupts of the transmission control can be assigned here. IR.TCF (Transmission Cancellation Finished) and IR.TF (Transmission Completed). As an additional information the copy of a local time event is shown here with TTIR.SWT (Stop Watch Event). Further on the TTIR.TTMI Trigger Time Event Internal, TTIR.RTMI (Register Time Mark), TTIR.SOG (Start of Gap), TTIR.CSM (Change of Synchronization Mode), TTIR.SMC (Start Matrix Cycle) and TTIR.SBC (Start of Basic Cycle) are shown here.

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Interrupt Signalling Register i

The groups by the GRINT registers are also shown inside the ISREG (interrupt signalling register) register. Inside the interrupt signalling register a 1 means, that one of the corresponding bits inside the interrupt (status) register of the corresponding M_CAN node, at least one group member is showing an interrupt. ISREG is purely ORing the interrupt status bits of the group to enable SW to have proper handling of the bits. Writing to ISREGi has no effect. If ISREGi is written, this shall have no effect on the interrupt status inside the M_CAN nodes. The bits have to be reset inside the corresponding M_CAN nodes, see register CANn_IRi.

ISREGi (i=0-3)

Interrupt Signalling Register i (008110 _H +i*400 _H)																Application Reset Value: 0000 0000 _H	
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16		
0																	
r																	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
LOI	BOFF	SAFE	MOER	ALRT	WATI	HPE	TEFIFO	TRACO	TRAQ	RETI	RxF0N	RxF1N	RxF0F	RxF1F	REINT		
rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh		

Field	Bits	Type	Description
REINT	0	rh	A message stored in a receive buffer interrupt
RxF1F	1	rh	Receive FIFO1 is full interrupt
RxF0F	2	rh	Receive FIFO0 is full interrupt
RxF1N	3	rh	Receive FIFO1 got a new message interrupt
RxF0N	4	rh	Receive FIFO0 got a new message interrupt
RETI	5	rh	A receive timeout event interrupt
TRAQ	6	rh	A transmission queue event interrupt
TRACO	7	rh	A transmission control event interrupt
TEFIFO	8	rh	A Transmit Event FIFO Incident interrupt
HPE	9	rh	A high priority event interrupt
WATI	10	rh	A watermark interrupt has been reached
ALRT	11	rh	An alert interrupt
MOER	12	rh	Module error interrupt
SAFE	13	rh	The safety counter interrupt ELO
BOFF	14	rh	Bus Off Interrupt
LOI	15	rh	Last Error Interrupt
0	31:16	r	Reserved Shall read 0; shall be written with 0.

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40.4.4.3 Node Port Control Register

Node i Port Control Register

The Node Port Control Register NPCR_i configures the CAN bus transmit/receive ports.

NPCR_i (i=0-3)

Node i Port Control Register (008140_H+i*400_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0				DELE		LOUT	LBM	0				RXSEL			
r				rw		rw	rw	r				rw			

Field	Bits	Type	Description
RXSEL	2:0	rw	Receive Select RXSEL selects one out of 8 possible receive inputs. The CAN receive signal is performed by the selected input. (see the device related chapter for RXSEL)
LBM	8	rw	Loop-Back Mode 0 _B Loop-Back Mode is disabled. 1 _B Loop-Back Mode is enabled. This node is connected to an internal (virtual) loop-back CAN bus. All CAN nodes which are in Loop-Back Mode are connected to this virtual CAN bus so that they can communicate with each other internally. The external transmit line is forced recessive in Loop-Back Mode.
LOUT	9	rw	Loop Back Mode Out The loop back bus is switched to the external CAN bus of the node.
DELE	10	rw	Enable destructive read on ECR_i.CEL If this bit is set, the destructive read on ECR _i .CEL and on the PSR register takes place. Meaning, that with read access on ECR _i , the CEL is reset. The same is true for the PSR register, for the bits PXE, RFDF, RBRS, RESI, LEC and DLEC. After the destructive read it is advised to reset the bit again.
0	7:3, 31:11	r	Reserved Shall read 0; shall be written with 0.

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40.4.4.4 Time Trigger Control Register

Time Trigger Control Register

TTCR0

Time Trigger Control Register

(0081F0_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
							0								
							r								
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0				TTCTSS		0		ETSSEL		ETESSEL			0	
	r				rw		r		rw		rw			r	

Field	Bits	Type	Description
ETESSEL	3:2	rw	External Trigger Event Selection This bit field defines the external trigger event that can be used to trigger the transmission of the reference message. The event causes the Event Trigger to be triggered. Control settings for this will not be influenced. 00 _B The external event ECTTx does not trigger the transmission of the reference message. 01 _B The reference message will be transmitted when a negative edge is detected at the selected input line ECTTx. 10 _B The reference message will be transmitted when a positive edge is detected at the input line ECTTx. 11 _B The reference message will be transmitted when a negative edge or a positive edge is detected at the input line ECTTx.
ETSSEL	6:4	rw	External Trigger Source Selection This bit fields selects the input source for the external reference message trigger. 000 _B External trigger input line ECTT1 selected 001 _B External trigger input line ECTT2 selected 010 _B External trigger input line ECTT3 selected 011 _B External trigger input line ECTT4 selected 100 _B External trigger input line ECTT5 selected 101 _B External trigger input line ECTT6 selected 110 _B External trigger input line ECTT7 selected 111 _B External trigger input line ECTT8 selected
TTCTSS	11:9	rw	TTCapture Time Trigger Source Select This bit selects the input source for the TT Capture Time (TTCPT) trigger. This register influences the stop watch event trigger 000 _B No TTCPT trigger input allowed 001 _B Local time register capture trigger input TTCPT_TRIG1 selected ... 100 _B Local time register capture trigger input TTCPT_TRIG4 selected others , Reserved; do not use this combination

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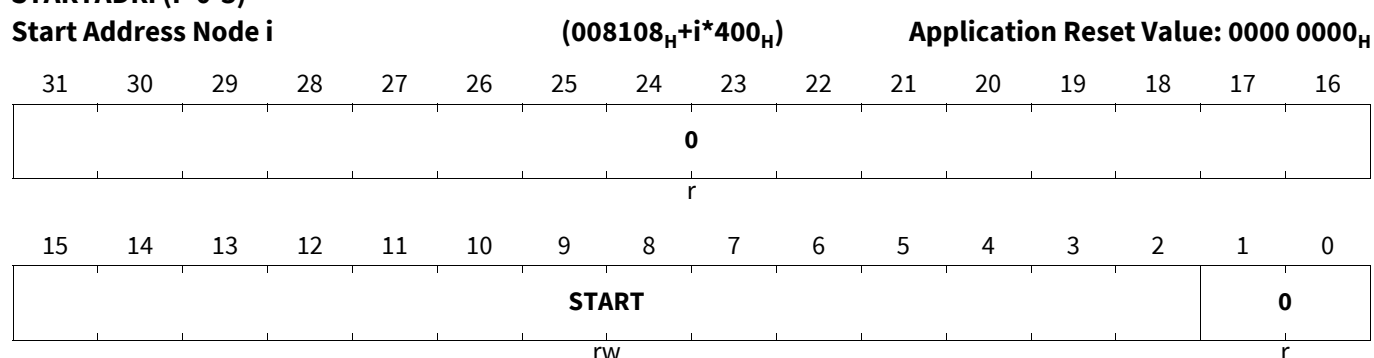
Field	Bits	Type	Description
0	1:0, 8:7, 31:12	r	Reserved Shall read 0; shall be written with 0.

40.4.4.5 Message RAM start address register

Start Address Node i

In case the RAM shall not be protected, the STARTADR has to be higher than the corresponding ENDADR of the node.

STARTADRI (i=0-3)

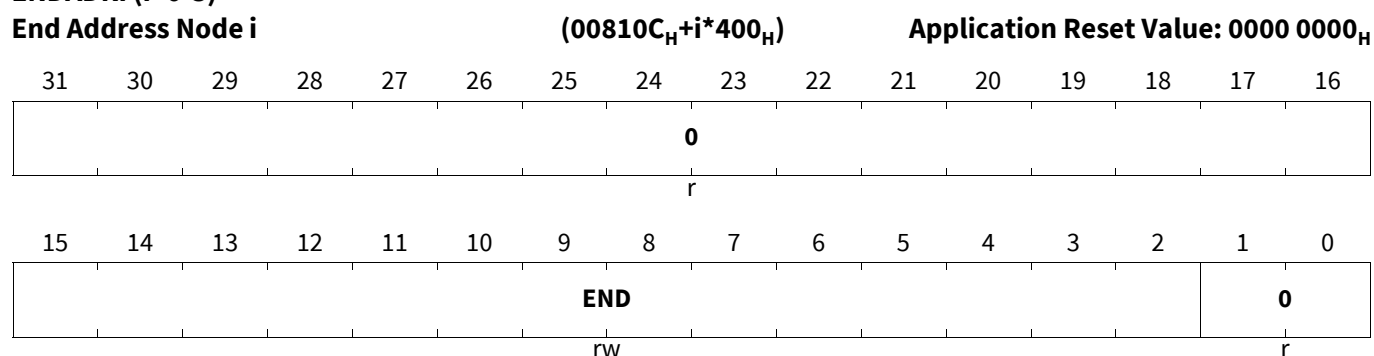


Field	Bits	Type	Description
START	15:2	rw	Message RAM start The address within the RAM area of the MCMCAN, of node i, where the message RAM to be protected starts
0	1:0, 31:16	r	Reserved Shall read 0; shall be written with 0.

40.4.4.6 Message RAM end address register

End Address Node i

ENDADRI (i=0-3)



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Field	Bits	Type	Description
END	15:2	rw	Message RAM end The address within the RAM area of the MCMCAN, of node i, where the message RAM to be protected ends
0	1:0, 31:16	r	Reserved Shall read 0; shall be written with 0.

40.4.4.7 NTCCR

The Node i Timer Clock Control and Node i Timer A/B/C Transmit Trigger Registers offer additional timing functions for the node.

Node i Timer Clock Control Register

The Node i Timer Clock Control Register NTCCRi controls the functions of the node timer.

NTCCRi (i=0-3)

Node i Timer Clock Control Register (008120_H+i*400_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0											TRIGSRC			0	
r											rw			r	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
STSTA RT	STRES ET	0		TPSC				0							
rw	rw	r		rw				r							

Field	Bits	Type	Description
TPSC	11:8	rw	Timer Prescaler The duration of one timer clock is given by (TPSC + 1) CAN bit times for all NTCCRi.TRIGSRC settings.
STRESET	14	rw	Stamping Reset This bit gives the possibility to reset the time stamp for CAN FD messages.
STSTART	15	rw	Stamping Start This bit starts the external timer used for CAN FD messages. The source and the prescaler are identical to the timers A/B/C.

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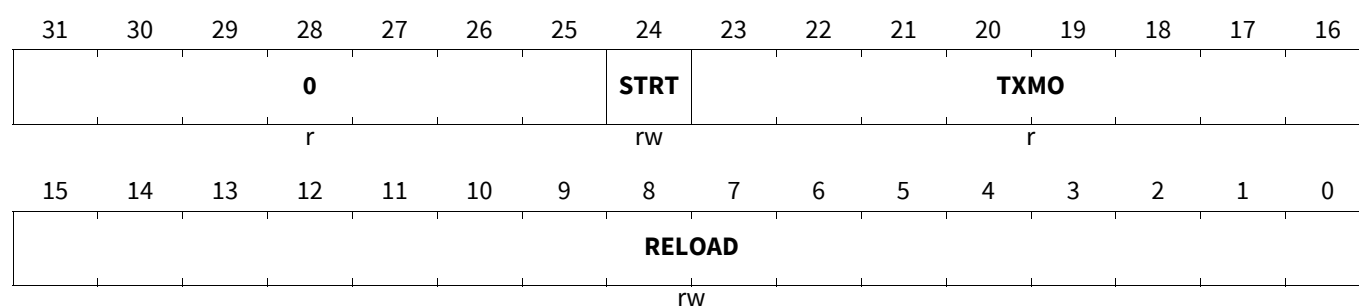
Field	Bits	Type	Description
TRIGSRC	20:18	rw	Trigger Source This bit selects the trigger source for the different modes in the node timer. 000 _B Node i Timer is decremented per f_{SYNi} prescaled by (TPSC + 1) timing to 0. 001 _B System Timer (STM) trigger event enabled Node i Timer is decremented per STM trigger event prescaled by (TPSC + 1). 010 _B General Timer (GTM) trigger event enabled Node i Timer is decremented per GTM trigger event prescaled by (TPSC + 1). others , Reserved, do not use
0	7:0, 13:12, 17:16, 31:21	r	Reserved Shall read 0; shall be written with 0.

40.4.4.8 CAN Node timers for pretended networking

Node i Timer A Transmit Trigger Register

The Node i Timer A Transmit Trigger Register NTATTRi controls the node timing functions for Transmit Trigger Mode.

NTATTRi (i=0-3)

Node i Timer A Transmit Trigger Register (008124_H+i*400_H)Application Reset Value: 0001 0000_H

Field	Bits	Type	Description
RELOAD	15:0	rw	Reload Value This bit field contains the reload value for the timer. The timer will restart when RELOAD is written.
TXMO	23:16	r	Transmit Message Object This transmit trigger is fixed to transmit buffer 1
STRT	24	rw	Timer Start This bit field controls the operation of the timer. 0 _B Timer is stopped. 1 _B Timer is started.

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Field	Bits	Type	Description
0	31:25	r	Reserved Shall read 0; shall be written with 0.

Node i Timer B Transmit Trigger Register

The Node i Timer B Transmit Trigger Register NTBTRi controls the node timing functions for Transmit Trigger Mode.

NTBTRi (i=0-3)**Node i Timer B Transmit Trigger Register (008128_H+i*400_H)****Application Reset Value: 0002 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0							STRT	TXMO							
r							rw	r							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RELOAD															
rw															

Field	Bits	Type	Description
RELOAD	15:0	rw	Reload Value This bit field contains the reload value for the timer. The timer will restart when RELOAD is written.
TXMO	23:16	r	Transmit Message Object This transmit object is fixed to transmit buffer 2
STRT	24	rw	Timer Start This bit field controls the operation of the timer. 0 _B Timer is stopped. 1 _B Timer is started.
0	31:25	r	Reserved Shall read 0; shall be written with 0.

Node i Timer C Transmit Trigger Register

The Node i Timer C Transmit Trigger Register NTCTTRi controls the node timing functions for Transmit Trigger Mode.

NTCTTRi (i=0-3)**Node i Timer C Transmit Trigger Register (00812C_H+i*400_H)****Application Reset Value: 0003 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0							STRT	TXMO							
r							rw	r							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RELOAD															
rw															

CAN Interface (MCMCAN)

Field	Bits	Type	Description
RELOAD	15:0	rw	Reload Value This bit field contains the reload value for the timer. The timer will restart when RELOAD is written.
TXMO	23:16	r	Transmit Message Object This transmit trigger is fixed to transmit buffer 3
STRT	24	rw	Timer Start This bit field controls the operation of the timer. 0 _B Timer is stopped. 1 _B Timer is started.
0	31:25	r	Reserved Shall read 0; shall be written with 0.

40.4.4.9 Node Timer Receive Timeout Register

Node i Timer Receive Timeout Register

The Node i Timer Receive Timeout Register NTRTRi controls the node timing functions for Receive Timeout Mode. This feature is independent of Classical CAN and CAN FD.

This mode exists, to have for example network management supervision.

NTRTRi (i=0-3)

Node i Timer Receive Timeout Register (008130_H+i*400_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	
0								TE	TEIE	0						
r								rwh		rw	r					
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
RELOAD																
rw																

Field	Bits	Type	Description
RELOAD	15:0	rw	Reload Value This bit field contains the reload value for the timer. The timer will start when RELOAD ≠ 0 is written. After half the time of the RELOAD value, the interrupt flags of the receive buffers will be cleared automatically, to ensure, that no message receive will be missed.
TEIE	22	rw	Timer Event Interrupt Enable This bit enables the node timer event interrupt of CAN node i. Bit field GRINT2.RETI selects the interrupt output line which becomes activated at this type of interrupt. 0 _B Timer event interrupt is disabled 1 _B Timer event interrupt is enabled

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TE	23	rwh	Timer Event This flag is set on a node timer transition from 1 to 0 in Receive Timeout Mode. This bit must be reset (i.e Write to '0') by software, writing a '1' has no effect. An interrupt request is generated if TEIE = 1. 0 _B No timer event has occurred since last flag reset 1 _B Timer event has occurred since last flag reset
0	21:16, 31:24	r	Reserved Shall read 0; shall be written with 0.

40.4.5 Registers within M_CAN

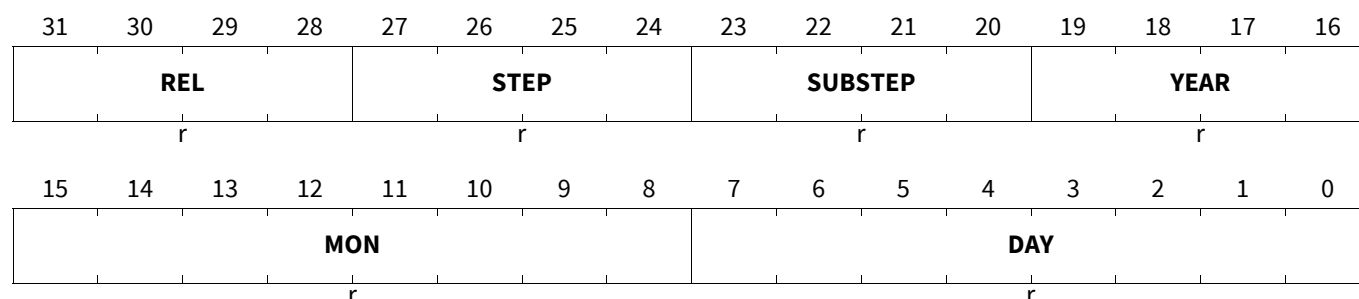
CAN Interface (MCMCAN)

40.4.5.1 Standard Registers

Core Release Register i

CRELi (i=0-3)

Core Release Register i

(008200_H+i*400_H)Reset Value: [Table 381](#)

Field	Bits	Type	Description
DAY	7:0	r	Time Stamp Day
MON	15:8	r	Time Stamp Month
YEAR	19:16	r	Time Stamp Year
SUBSTEP	23:20	r	Sub-step of Core Release One digit, BCD-coded.
STEP	27:24	r	Step of Core Release One digit, BCD-coded.
REL	31:28	r	Core Release One digit, BCD-coded.

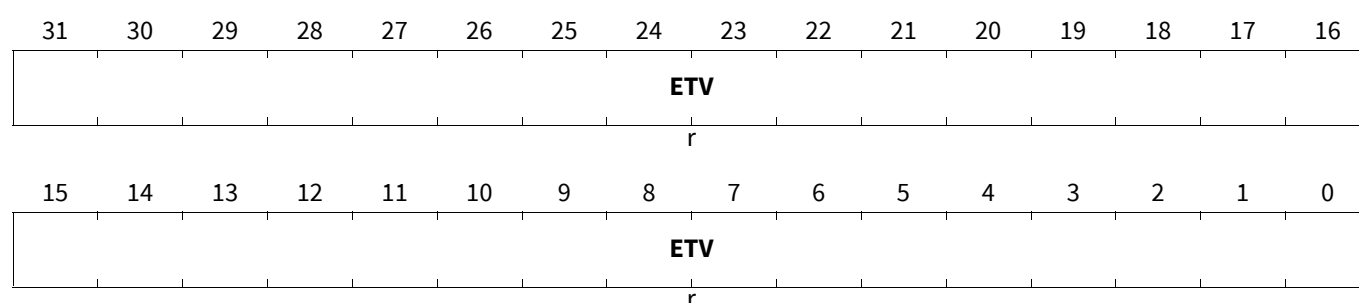
Table 381 Reset Values of CRELi (i=0-3)

Reset Type	Reset Value	Note
Application Reset	3215 0323 _H	Node (i = 0) with TTCAN
Application Reset	3215 0320 _H	Nodes (i > 0) without TTCAN

Endian Register i

ENDNi (i=0-3)

Endian Register i

(008204_H+i*400_H)Application Reset Value: 8765 4321_H

CAN Interface (MCMCAN)

Field	Bits	Type	Description
ETV	31:0	r	Endianness Test Value The endianness test value is 0x87654321.

Data Bit Timing & Prescaler Register i

This register is only writable if bits CCCR.CCE and CCCR.INIT are set. The CAN bit time may be programmed in the range of 4 to 49 time quanta. The CAN time quantum may be programmed in the range of 1 to 32 clock cycles. $t_q = (\text{DBRP} + 1)$ clock cycles.

DTSEG1 is the sum of Prop_Seg and Phase_Seg1. DTSEG2 is Phase_Seg2.

Therefore the length of the bit time is (programmed values) $[\text{DTSEG1} + \text{DTSEG2} + 3] t_q$ or (functional values) $[\text{Sync_Seg} + \text{Prop_Seg} + \text{Phase_Seg1} + \text{Phase_Seg2}] t_q$.

The Information Processing Time (IPT) is zero, meaning the data for the next bit is available at the first clock edge after the sample point.

Notes

1. With a CAN clock of 8 MHz, the reset value of 0x00000A33 configures the M_CAN for a fast bit rate of 500 kbit/s.
2. The bit rate configured for the CAN FD data phase via DBTP must be higher or equal to the bit rate configured for the arbitration phase via NBTP.

DBTPi (i=0-3)

Data Bit Timing & Prescaler Register i (00820C_H+i*400_H) **Application Reset Value: 0000 0A33_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16		
0								TDC	0		DBRP						
r								rw		r		rw					
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
0			DTSEG1					DTSEG2				DSJW					
r			rw					rw				rw					

Field	Bits	Type	Description
DSJW	3:0	rw	Data (Re) Synchronization Jump Width This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Valid values are 0 to 15. The actual interpretation by the hardware of this value is such that one more than the value programmed here is used.
DTSEG2	7:4	rw	Data time segment after sample point This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Valid values are 0 to 15. The actual interpretation by the hardware of this value is such that one more than the programmed value is used.

CAN Interface (MCMCAN)

Field	Bits	Type	Description
DTSEG1	12:8	rw	Data time segment before sample point This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Valid values are 0 to 31. The actual interpretation by the hardware of this value is such that one more than the programmed value is used.
DBRP	20:16	rw	Data Baud Rate Prescaler This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. The value by which the oscillator frequency is divided for generating the bit time quanta. The bit time is built up from a multiple of this quanta. Valid values for the Baud Rate Prescaler are 0 to 31. The actual interpretation by the hardware of this value is such that one more than the value programmed here is used.
TDC	23	rw	Transmitter Delay Compensation This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Transmitter Delay Compensation disabled 1 _B Transmitter Delay Compensation enabled
0	15:13, 22:21, 31:24	r	Reserved Shall read 0, shall be written with 0.

Test Register i

Write access to the Test Register has to be enabled by setting bit CCCR.TEST to '1'. All Test Register functions are set to their reset values when bit CCCR.TEST is reset.

Loop Back Mode and software control of transmit pin are hardware test modes. Programming of TEST.TX ≠ "00" may disturb the message transfer on the CAN bus.

TESTi (i=0-3)

Test Register i															
(008210 _H + i * 400 _H)															
Application Reset Value: 0000 00X0 _H															
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0								RX	TX		LBCK	0	0	0	0
r								rh	rwh		rwh	r	r	r	r

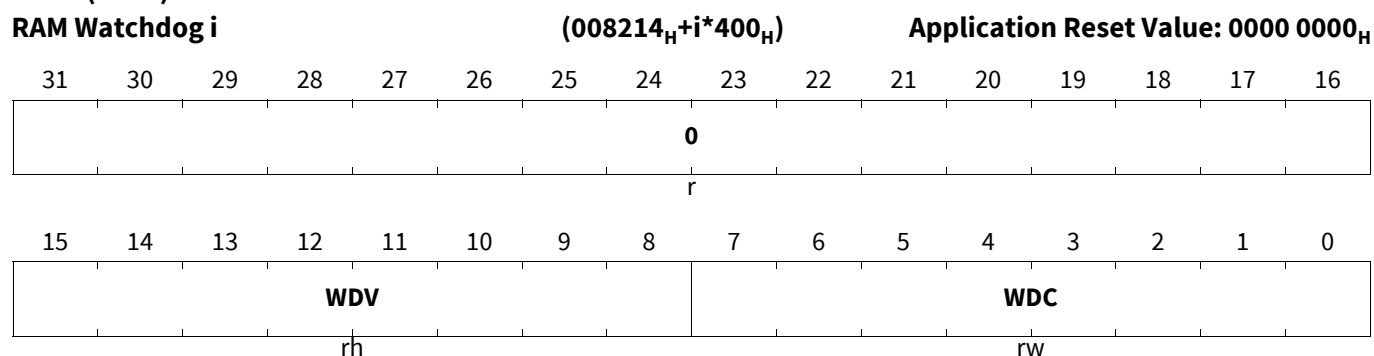
CAN Interface (MCMCAN)

Field	Bits	Type	Description
LBCK	4	rwh	Loop Back Mode This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. This is the external loop back mode, visible on the outside. 0 _B Reset value, Loop Back Mode is disabled 1 _B Loop Back Mode is enabled
TX	6:5	rwh	Control of Transmit Pin This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 00 _B Reset value, TX pin controlled by the CAN Core, updated at the end of the CAN bit time 01 _B Sample Point can be monitored at the TX pin 10 _B Dominant ('0') level at TX pin. 11 _B Recessive ('1') at RX pin.
RX	7	rh	Receive Pin Monitors the actual value of RX pin. 0 _B The CAN bus is dominant (RXD = '0') 1 _B The CAN bus is recessive (RXD = '1')
0	0, 1, 2, 3, 31:8	r	Reserved Shall read 0, shall be written with 0.

RAM Watchdog i

The RAM Watchdog monitors the READY output of the Message RAM. A Message RAM access via the M_CAN's Generic Master Interface starts the Message RAM Watchdog Counter with the value configured by RWD.WDC. The counter is reloaded with RWD.WDC when the Message RAM signals successful completion. In case there is no response from the Message RAM until the counter has counted down to zero, the counter stops and interrupt flag IR.WDI is set. The RAM Watchdog Counter is clocked by the Host clock.

RWDi (i=0-3)



CAN Interface (MCMCAN)

Field	Bits	Type	Description
WDC	7:0	rw	Watchdog Configuration This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Start value of the Message RAM Watchdog Counter. With the reset value of "00" the counter is disabled. 00 _H Watchdog disabled others , Start value of the Message RAM Watchdog Counter
WDV	15:8	rh	Watchdog Value Actual Message RAM Watchdog Counter Value.
0	31:16	r	Reserved Shall read 0, shall be written with 0.

CC Control Register i

The CCCRi register enables and disables CAN bus participation and basic protocol functions. Due to synchronization mechanisms between the clock domains, after a write operation to CCCRi, the register shall be read back, until the set values are written to the register. Please keep in mind, that the register also includes hardware influenced bits.

Note: After enabling the CAN clocks in MCR register, the application software has to wait for 10 hostclock cycles before accessing the kernel registers.

Note: LDMST or SWAPMSK.W instructions should be used only with bit mask enabled for rwh bits in this register.

CCCRi (i=0-3)

CC Control Register i

(008218_H+i*400_H)Application Reset Value: 0000 0001_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
NISO	TXP	EFBI	PXHD	0	BRSE	FDOE	TEST	DAR	MON	CSR	CSA	ASM	CCE	INIT	
rw	rw	rw	rw	r	rw	rw	rw	rw	rwh	rw	rh	rwh	rw	rwh	

CAN Interface (MCMCAN)

Field	Bits	Type	Description
INIT	0	rwh	Initialization <i>Note:</i> Due to the synchronization mechanism between the two clock domains, there may be a delay until the value written to INIT can be read back. Therefore the programmer has to assure that the previous value written to INIT has been accepted by reading INIT before setting INIT to a new value. 0 _B Normal Operation 1 _B Initialization is started
CCE	1	rw	Configuration Change Enable 0 _B The CPU has no write access to the protected configuration registers 1 _B The CPU has write access to the protected configuration registers (while CCCR.INIT = '1')
ASM	2	rwh	Restricted Operation Mode Bit ASM can only be set by the Host when both CCE and INIT are set to '1'. In can also be set by the M_CAN. The bit can be reset by the Host at any time. For a description of the Restricted Operation Mode see paragraph Restricted Operation Mode. 0 _B Normal CAN operation 1 _B Restricted Operation Mode active
CSA	3	rh	Clock Stop Acknowledge 0 _B No clock stop acknowledged 1 _B M_CAN may be set in power down by stopping the synchronous and the asynchronous clock source
CSR	4	rw	Clock Stop Request 0 _B No clock stop is requested 1 _B Clock stop requested. When clock stop is requested, first INIT and then CSA will be set after all pending transfer requests have been completed and the CAN bus reached idle.
MON	5	rwh	Bus Monitoring Mode Bit MON can only be set by the Host when both CCE and INIT are set to '1'. The bit can be reset by the Host at any time. 0 _B Bus Monitoring Mode is disabled 1 _B Bus Monitoring Mode is enabled
DAR	6	rw	Disable Automatic Retransmission This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Automatic retransmission of messages not transmitted successfully enabled 1 _B Automatic retransmission disabled

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TEST	7	rw	Test Mode Enable The TEST register can only be set, if CCE, INIT and TEST are set. Writes to test will only have effect, if all three bits are set. 0 _B Normal operation, register TEST holds reset values 1 _B Test Mode, write access to register TEST enabled
FDOE	8	rw	FD Operation Enable This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B CAN FD frame format disabled. 1 _B CAN FD frame format enabled.
BRSE	9	rw	Bit Rate Switch Enable This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Bit rate switching for transmission disabled. 1 _B Bit rate switching for transmission enabled.
PXHD	12	rw	Protocol Exception Handling Disable This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Protocol exception handling enabled. 1 _B Protocol exception handling disabled. (When protocol exception handling is disabled, the M_CAN will transmit an error frame when it detects a protocol exception condition.
EFBI	13	rw	Edge Filtering during Bus Integration This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Edge filter disabled 1 _B Two consecutive dominant tq required to detect an edge for hard synchronization.
TXP	14	rw	Transmit Pause This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. If this bit is set, the M_CAN pauses for two CAN bit times before starting the next transmission after itself has successfully transmitted a frame (see Tx Handling). 0 _B Transmit pause disabled 1 _B Transmit pause enabled
NISO	15	rw	Non ISO Operation If this bit is set, the M_CAN uses the CAN FD frame format as specified by the Bosch CAN FD Specification V1.0. 0 _B CAN FD frame format according to ISO11898-1 1 _B CAN FD frame format according to Bosch CAN FD Specification V1.0
0	11:10, 31:16	r	Reserved Shall read 0, shall be written with 0.

Nominal Bit Timing & Prescaler Register i

This register is only writable if bits CCCR.CCE and CCCR.INIT are set.

CAN Interface (MCMCAN)

The CAN bit time may be programmed in the range of 4 to 385 time quanta. The CAN time quantum may be programmed in the range of 1 to 512 clock periods. $t_q = (NBRP + 1)$ clock periods.

NTSEG1 is the sum of Prop_Seg and Phase_Seg1. NTSEG2 is Phase_Seg2.

Therefore the length of the bit time is (programmed values) $[NTSEG1 + NTSEG2 + 3] t_q$ or (functional values) $[Sync_Seg + Prop_Seg + Phase_Seg1 + Phase_Seg2] t_q$.

The Information Processing Time (IPT) is zero, meaning the data for the next bit is available at the first clock edge after the sample point.

Note: With a CAN clock of 8 MHz, the reset value of 0600_H0A03 configures the M_CAN for a bit rate of 500 kbit/s.

NBTPI (i=0-3)

Nominal Bit Timing & Prescaler Register i (00821C_H+i*400_H)

Application Reset Value: 0600 0A03_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
NSJW								NBRP							
rw								rw							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
NTSEG1								0	NTSEG2						
rw								r	rw						

Field	Bits	Type	Description
NTSEG2	6:0	rw	Nominal Time segment after sample point This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Valid values are 1 to 127. The actual interpretation by the hardware of this value is such that one more than the programmed value is used.
NTSEG1	15:8	rw	Nominal Time segment before sample point This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Valid values are 1 to 255. The actual interpretation by the hardware of this value is such that one more than the programmed value is used.
NBRP	24:16	rw	Baud Rate Prescaler This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. The value by which the oscillator frequency is divided for generating the bit time quanta. The bit time is built up from a multiple of this quanta. Valid values for the Baud Rate Prescaler are 0 to 511. The actual interpretation by the hardware of this value is such that one more than the value programmed here is used.
NSJW	31:25	rw	(Re) Synchronization Jump Width This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Valid values are 0 to 127. The actual interpretation by the hardware of this value is such that one more than the value programmed here is used.

CAN Interface (MCMCAN)

Field	Bits	Type	Description
0	7	r	Reserved Shall read 0, shall be written with 0.

Timestamp Counter Configuration i

For a description of the Timestamp Counter see chapter Timestamp Generation

TSCCi (i=0-3)

Timestamp Counter Configuration i (008220_H+i*400_H) **Application Reset Value: 0000 0000_H**

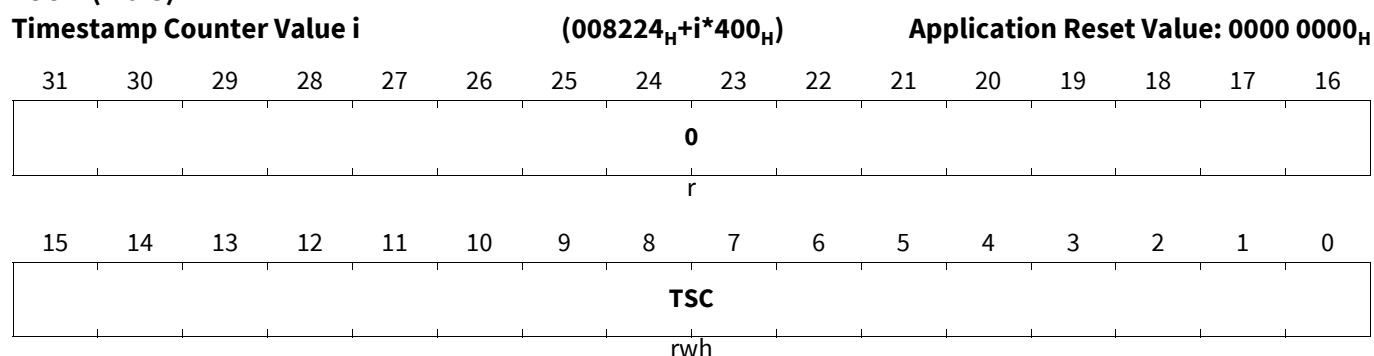
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0												TCP			
r												rw			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0												TSS			
r												rw			

Field	Bits	Type	Description
TSS	1:0	rw	Time segment before sample point This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 01 _B Timestamp counter value incremented according to TCP 10 _B External timestamp counter value used, timer to be started in NTCCRy, the clock source as well as the chosen prescaler has to be configured before using this feature. others , Timestamp counter value always 0x0000
TCP	19:16	rw	Timestamp Counter Prescaler This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Configures the timestamp and timeout counters time unit in multiples of CAN bit times [1...16]. The actual interpretation by the hardware of this value is such that one more than the value programmed here is used. <i>Note: With CAN FD an external counter is required for timestamp generation (TSS = "10")</i>
0	15:2, 31:20	r	Reserved Shall read 0, shall be written with 0.

CAN Interface (MCMCAN)

Timestamp Counter Value i

TSCVi (i=0-3)

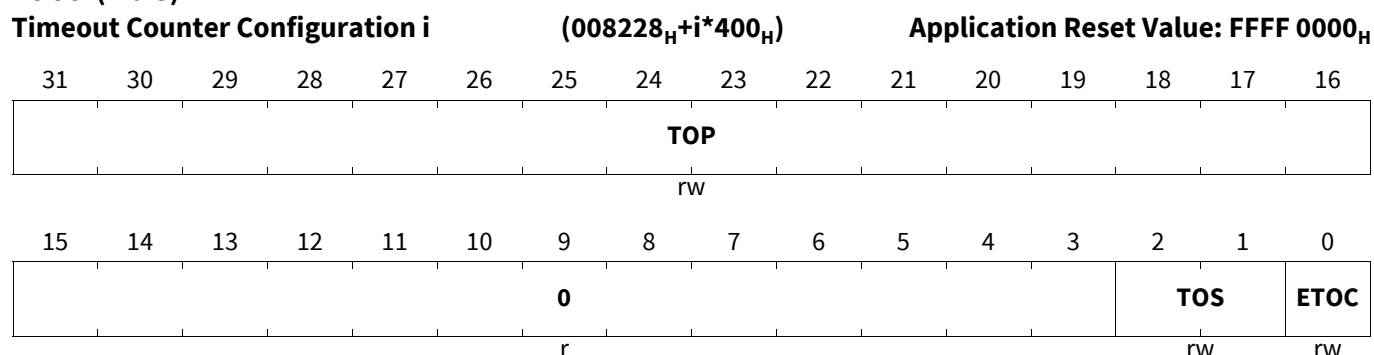


Field	Bits	Type	Description
TSC	15:0	rwh	Timestamp Counter The internal/external Timestamp Counter value is captured on start of frame (both Rx and Tx). When TSCC.TSS = "01", the Timestamp Counter is incremented in multiples of CAN bit times [1...16] depending on the configuration of TSCC.TCP. A wrap around sets interrupt flag IR.TSW. Write access resets the counter to zero. When TSCC.TSS = "10", TSC reflects the external Timestamp Counter value. A write access has no impact. <i>Note:</i> A "wrap around" is a change of the Timestamp Counter value from non-zero to zero not caused by write access to TSCV.
0	31:16	r	Reserved Shall read 0, shall be written with 0.

Timeout Counter Configuration i

For a description of the Timeout Counter see [Timeout Counter](#)

TOCCi (i=0-3)



CAN Interface (MCMCAN)

Field	Bits	Type	Description
ETOC	0	rw	Enable Timeout Counter This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. <i>Note:</i> For use of timeout function with CAN FD see chapter Timeout Counter. 0 _B Timeout Counter disabled 1 _B Timeout Counter enabled
TOS	2:1	rw	Timeout Select This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. When operating in Continuous mode, a write to TOCV presets the counter to the value configured by TOCC.TOP and continues down-counting. When the Timeout Counter is controlled by one of the FIFOs, an empty FIFO presets the counter to the value configured by TOCC.TOP. Down-counting is started when the first FIFO element is stored. 00 _B Continuous operation 01 _B Timeout controlled by Tx Event FIFO 10 _B Timeout controlled by Rx FIFO 0 11 _B Timeout controlled by Rx FIFO 1
TOP	31:16	rw	Timeout Period This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Start value of the Timeout Counter (down-counter). Configures the Timeout Period.
0	15:3	r	Reserved Shall read 0, shall be written with 0.

Timeout Counter Value i

TOCVi (i=0-3)

Timeout Counter Value i															
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TOC															
rwh															

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TOC	15:0	rwh	Timeout Counter The Timeout Counter is decremented in multiples of CAN bit times [1...16] depending on the configuration of TSCC.TCP. When decremented to zero, interrupt flag IR.TOO is set and the Timeout Counter is stopped. Start and reset/restart conditions are configured via TOCC.TOS. Any write access will lead to clearing of the counter.
0	31:16	r	Reserved Shall read 0, shall be written with 0.

Error Counter Register i

ECRi (i=0-3)

Error Counter Register i

(008240_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0								CEL							
r								rh							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RP	REC						TEC								
rh	rh						rh								

Field	Bits	Type	Description
TEC	7:0	rh	Transmit Error Counter Actual state of the Transmit Error Counter, values between 0 and 255 <i>Note:</i> When CCCR.ASM is set, the CAN protocol controller does not increment TEC and REC when a CAN protocol error is detected, but CEL is still incremented.
REC	14:8	rh	Receive Error Counter Actual state of the Receive Error Counter, values between 0 and 127 <i>Note:</i> When CCCR.ASM is set, the CAN protocol controller does not increment TEC and REC when a CAN protocol error is detected, but CEL is still incremented.
RP	15	rh	Receive Error Passive 0 _B The Receive Error Counter is below the error passive level of 128 1 _B The Receive Error Counter has reached the error passive level of 128

CAN Interface (MCMCAN)

Field	Bits	Type	Description
CEL	23:16	rh	CAN Error Logging The counter is incremented each time when a CAN protocol error causes the Transmit Error Counter or the Receive Error Counter to be incremented. It is reset by read access to CEL. The counter stops at 0xFF; the next increment of TEC or REC sets interrupt flag IR.ELO. The counter is reset on read, if the bit NPCRi.DELE is set for the node.
0	31:24	r	Reserved Shall read 0, shall be written with 0.

Protocol Status Register i

PSRi (i=0-3)

Protocol Status Register i

(008244_H+i*400_H)Application Reset Value: 0000 0707_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0									TDCV						
r									r						
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	PXE	RFDF	RBRS	RESI	DLEC			BO	EW	EP	ACT		LEC		
r	rh	rh	rh	rh	rh			rh	rh	rh	rh		rh		

CAN Interface (MCMCAN)

Field	Bits	Type	Description
LEC	2:0	rh	<p>Last Error Code</p> <p>The LEC indicates the type of the last error to occur on the CAN bus. This field will be cleared to '0' when a message has been transferred (reception or transmission) without error. This bit field is set to 0x7 on read, if NPCRi.DELE is set.</p> <p><i>Note: The Bus_Off recovery sequence (see ISO11898-1) cannot be shortened by setting or resetting CCCR.INIT. If the device goes Bus_Off, it will set CCCR.INIT of its own accord, stopping all bus activities. Once CCCR.INIT has been cleared by the CPU, the device will then wait for 129 occurrences of Bus Idle (129 * 11 consecutive recessive bits) before resuming normal operation. At the end of the Bus_Off recovery sequence, the Error Management Counters will be reset. During the waiting time after the resetting of CCCR.INIT, each time a sequence of 11 recessive bits has been monitored, a Bit0Error code is written to PSR.LEC, enabling the CPU to readily check up whether the CAN bus is stuck at dominant or continuously disturbed and to monitor the Bus_Off recovery sequence. ECR.REC is used to count these sequences.</i></p> <p>000_B No Error: No error occurred since LEC has been reset by successful reception or transmission.</p> <p>001_B Stuff Error: More than 5 equal bits in a sequence have occurred in a part of a received message where this is not allowed.</p> <p>010_B Form Error: A fixed format part of a received frame has the wrong format.</p> <p>011_B Ack Error: The message transmitted by the M_CAN was not acknowledged by another node.</p> <p>100_B Bit1 Error: During the transmission of a message (with the exception of the arbitration field), the device wanted to send a recessive level (bit of logical value '1'), but the monitored bus value was dominant.</p> <p>101_B Bit0 Error: During the transmission of a message (or acknowledge bit, or active error flag, or overload flag), the device wanted to send a dominant level (data or identifier bit logical value '0'), but the monitored bus value was recessive. During Bus_Off recovery this status is set each time a sequence of 11 recessive bits has been monitored. This enables the CPU to monitor the proceeding of the Bus_Off recovery sequence (indicating the bus is not stuck at dominant or continuously disturbed).</p> <p>110_B CRC Error: The CRC check sum of a received message was incorrect. The CRC of an incoming message does not match with the CRC calculated from the received data.</p> <p>111_B No Change: Any read access to the Protocol Status Register re-initializes the LEC to '7'. When the LEC shows the value '7', no CAN bus event was detected since the last CPU read access to the Protocol Status Register.</p>

CAN Interface (MCMCAN)

Field	Bits	Type	Description
ACT	4:3	rh	Activity Monitors the module's CAN communication state. <i>Note:</i> <i>ACT is set to "00" by a Protocol Exception Event.</i> 00 _B Synchronizing - node is synchronizing on CAN communication 01 _B Idle - node is neither receiver nor transmitter 10 _B Receiver - node is operating as receiver 11 _B Transmitter - node is operating as transmitter
EP	5	rh	Error Passive 0 _B The M_CAN is in the Error_Active state. It normally takes part in bus communication and sends an active error flag when an error has been detected 1 _B The M_CAN is in the Error_Passive state
EW	6	rh	Warning Status 0 _B Both error counters are below the Error_Warning limit of 96 1 _B At least one of error counter has reached the Error_Warning limit of 96
BO	7	rh	Bus_Off Status 0 _B The M_CAN is not in Bus_Off ¹⁾ 1 _B The M_CAN is in Bus_Off state
DLEC	10:8	rh	Data Phase Last Error Code Type of last error that occurred in the data phase of a CAN FD format frame with its BRS flag set. Coding is the same as for LEC. This field will be cleared to zero when a CAN FD format frame with its BRS flag set has been transferred (reception or transmission) without error. This bit field is set to 0x7 on read, if NPCRi.DELE is set. <i>Note:</i> <i>When a frame in CAN FD format has reached the data phase with BRS flag set, the next CAN event (error or valid frame) will be shown in DLEC instead of LEC. An error in a fixed stuff bit of a CAN FD CRC sequence will be shown as a Form Error, not Stuff Error.</i>
RESI	11	rh	ESI flag of last received CAN FD Message This bit is set together with REDF, independent of acceptance filtering. This bit is reset after read access, if NPCRi.DELE is set. 0 _B Last received CAN FD message did not have its ESI flag set 1 _B Last received CAN FD message had its ESI flag set
RBRS	12	rh	BRS flag of last received CAN FD Message This bit is set together with REDF, independent of acceptance filtering. This bit is reset after read access, if NPCRi.DELE is set. 0 _B Last received CAN FD message did not have its BRS flag set 1 _B Last received CAN FD message had its BRS flag set

CAN Interface (MCMCAN)

Field	Bits	Type	Description
RFDF	13	rh	Received a CAN FD Message This bit is set independent of acceptance filtering. This bit is reset after read access, if NPCRi.DELE is set. 0 _B Since this bit was reset by the CPU, no CAN FD message has been received 1 _B Message in CAN FD format with FDF flag set, has been received
PXE	14	rh	Protocol Exception Event This bit is reset after read access, if NPCRi.DELE is set. 0 _B No protocol exception event occurred since last read access 1 _B Protocol exception event occurred
TDCV	22:16	r	Transmitter Delay Compensation Value Position of the secondary sample point, defined by the sum of the measured delay from TX to RX and TDCR.TDCO. The SSP position is, in the data phase, the number of mtq between the start of the transmitted bit and the secondary sample point. Valid values are 0 to 127 mtq.
0	15, 31:23	r	Reserved Shall read 0, shall be written with 0.

- 1) The Bus_Off recovery sequence (see ISO11898-1) cannot be shortened by setting or resetting CCCR.INIT. If the device goes Bus_Off, it will set CCCR.INIT of its own accord, stopping all bus activities. Once CCCR.INIT has been cleared by the CPU, the device will then wait for 129 occurrences of Bus Idle (129 * 11 consecutive recessive bits) before resuming normal operation. At the end of the Bus_Off recovery sequence, the Error Management Counters will be reset. During the waiting time after the resetting of CCCR.INIT, each time a sequence of 11 recessive bits has been monitored, a Bit0Error code is written to PSR.LEC, enabling the CPU to readily check up whether the CAN bus is stuck at dominant or continuously disturbed and to monitor the Bus_Off recovery sequence. ECR.REC is used to count these sequences.

Transmitter Delay Compensation Register i

TDCRi (i=0-3)

Transmitter Delay Compensation Register i(008248_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	TDCO						0	TDCF							
r	rw						r	rw							

Field	Bits	Type	Description
TDCF	6:0	rw	Transmitter Delay Compensation Filter Window Length This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Defines the minimum value for the Secondary Sample Point position, dominant edges on RX that would result in an earlier Secondary Sample Point position are ignored for transmitter delay measurement. This feature is enabled when TDCF is configured to a value greater than TDCO. Valid values are from 0 to 127 mtq.

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TDCO	14:8	rw	Transmitter Delay Compensation Offset This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Offset value defining the distance between the measured delay from TX to RX and the secondary sample point. Valid values are 0 to 127 mtq. The duration of one mtq is equal to the fASYNi clock period.
0	7, 31:15	r	Reserved Shall read 0, shall be written with 0.

Interrupt Register i

The flags are set when one of the listed conditions is detected (edge-sensitive). The flags remain set until the Host clears them. A flag is cleared by writing a “1” to the corresponding bit position. Writing a “0” has no effect. The configuration of IE controls whether an interrupt is generated.

Note: LDMST or SWAPMSK.W instructions should be used only with bit mask enabled for all rwh bits in this register.

IRi (i=0-3)

Interrupt Register i (008250_H+i*400_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0	0	PED	PEA	WDI	BO	EW	EP	ELO	0	0	DRX	TOO	MRAF	TSW	
r	r	rwh	rwh	rwh	rwh	rwh	rwh	rwh	r	r	rwh	rwh	rwh	rwh	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TEFL	TEFF	TEFW	TEFN	TFE	TCF	TC	HPM	RF1L	RF1F	RF1W	RF1N	RF0L	RF0F	RF0W	RF0N
rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh

Field	Bits	Type	Description
RF0N	0	rwh	Rx FIFO 0 New Message 0 _B No new message written to Rx FIFO 0 1 _B New message written to Rx FIFO 0
RF0W	1	rwh	Rx FIFO 0 Watermark Reached 0 _B Rx FIFO 0 fill level below watermark 1 _B Rx FIFO 0 fill level reached watermark
RF0F	2	rwh	Rx FIFO 0 Full 0 _B Rx FIFO 0 not full 1 _B Rx FIFO 0 full
RF0L	3	rwh	Rx FIFO 0 Message Lost 0 _B No Rx FIFO 0 message lost 1 _B Rx FIFO 0 message lost, also set after write attempt to Rx FIFO 0 of size zero
RF1N	4	rwh	Rx FIFO 1 New Message 0 _B No new message written to Rx FIFO 1 1 _B New message written to Rx FIFO 1

CAN Interface (MCMCAN)

Field	Bits	Type	Description
RF1W	5	rwh	Rx FIFO 1 Watermark Reached 0 _B Rx FIFO 1 fill level below watermark 1 _B Rx FIFO 1 fill level reached watermark
RF1F	6	rwh	Rx FIFO 1 Full 0 _B Rx FIFO 1 not full 1 _B Rx FIFO 1 full
RF1L	7	rwh	Rx FIFO 1 Message Lost 0 _B No Rx FIFO 1 message lost 1 _B Rx FIFO 1 message lost, also set after write attempt to Rx FIFO 1 of size zero
HPM	8	rwh	High Priority Message 0 _B No high priority message received 1 _B High priority message received
TC	9	rwh	Transmission Completed 0 _B No transmission completed 1 _B Transmission completed
TCF	10	rwh	Transmission Cancellation Finished 0 _B No transmission cancellation finished 1 _B Transmission cancellation finished
TFE	11	rwh	Tx FIFO Empty 0 _B Tx FIFO non-empty 1 _B Tx FIFO empty
TEFN	12	rwh	Tx Event FIFO New Entry 0 _B Tx Event FIFO unchanged 1 _B Tx Handler wrote Tx Event FIFO element
TEFW	13	rwh	Tx Event FIFO Watermark Reached 0 _B Tx Event FIFO fill level below watermark 1 _B Tx Event FIFO fill level reached watermark
TEFF	14	rwh	Tx Event FIFO Full 0 _B Tx Event FIFO not full 1 _B Tx Event FIFO full
TEFL	15	rwh	Tx Event FIFO Element Lost 0 _B No Tx Event FIFO element lost 1 _B Tx Event FIFO element lost, also set after write attempt to Tx Event FIFO of size zero
TSW	16	rwh	Timestamp Wraparound 0 _B No timestamp counter wrap-around 1 _B Timestamp counter wrapped around

CAN Interface (MCMCAN)

Field	Bits	Type	Description
MRAF	17	rwh	<p>Message RAM Access Failure</p> <p>The flag is set, when the Rx Handler</p> <ul style="list-style-type: none"> has not completed acceptance filtering or storage of an accepted message until the arbitration field of the following message has been received. In this case acceptance filtering or message storage is aborted and the Rx Handler starts processing of the following message. was not able to write a message to the Message RAM. In this case message storage is aborted. <p>In both cases the FIFO put index is not updated resp. the New Data flag for a dedicated Rx Buffer is not set, a partly stored message is overwritten when the next message is stored to this location. The flag is also set when the Tx Handler was not able to read a message from the Message RAM in time. In this case message transmission is aborted. In case of a Tx Handler access failure the M_CAN is switched into Restricted Operation Mode. To leave Restricted Operation Mode, the Host CPU has to reset CCCR.ASM.</p> <p>0_B No Message RAM access failure occurred 1_B Message RAM access failure occurred</p>
TOO	18	rwh	<p>Timeout Occurred</p> <p>0_B No timeout 1_B Timeout reached</p>
DRX	19	rwh	<p>Message stored to Dedicated Rx Buffer</p> <p>The flag is set whenever a received message has been stored into a dedicated Rx Buffer.</p> <p>0_B No Rx Buffer updated 1_B At least one received message stored into an Rx Buffer</p>
ELO	22	rwh	<p>Error Logging Overflow</p> <p>0_B CAN Error Logging Counter did not overflow 1_B Overflow of CAN Error Logging Counter occurred</p>
EP	23	rwh	<p>Error Passive</p> <p>0_B Error_Passive status unchanged 1_B Error_Passive status changed</p>
EW	24	rwh	<p>Warning Status</p> <p>0_B Error_Warning status unchanged 1_B Error_Warning status changed</p>
BO	25	rwh	<p>Bus_Off Status</p> <p>0_B Bus_Off status unchanged 1_B Bus_Off status changed</p>
WDI	26	rwh	<p>Watchdog Interrupt</p> <p>0_B No Message RAM Watchdog event occurred 1_B Message RAM Watchdog event due to missing READY</p>

CAN Interface (MCMCAN)

Field	Bits	Type	Description
PEA	27	rwh	Protocol Error in Arbitration Phase (Nominal Bit Time is used) 0 _B No protocol error in arbitration phase 1 _B Protocol error in arbitration phase detected (PSR.LEC ≠ 0,7)
PED	28	rwh	Protocol Error in Data Phase (Data Bit Time is used) 0 _B No protocol error in data phase detected 1 _B Protocol error in data phase detected (PSR.DLEC ≠ 0,7)
0	20, 21, 29, 31:30	r	Reserved Shall read 0, shall be written with 0.

Interrupt Enable i

The settings in the Interrupt Enable register determine which status changes in the Interrupt Register will be signalled on an interrupt line.

IEi (i=0-3)

Interrupt Enable i (008254_H+i*400_H) Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0	0	PEDE	PEAE	WDIE	BOE	EWE	EPE	ELOE	0	0	DRXE	TOOE	MRAF E	TSWE	
r	r	rw	rw	rw	rw	rw	rw	rw	r	r	rw	rw	rw	rw	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TEFLE	TEFFE	TEFW E	TEFNE	TFEE	TCFE	TCE	HPME	RF1LE	RF1FE	RF1W E	RF1NE	RF0LE	RF0FE	RF0W E	RF0NE
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
RF0NE	0	rw	Rx FIFO 0 New Message Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
RF0WE	1	rw	Rx FIFO 0 Watermark Reached Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
RF0FE	2	rw	Rx FIFO 0 Full Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
RF0LE	3	rw	Rx FIFO 0 Message Lost Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled

CAN Interface (MCMCAN)

Field	Bits	Type	Description
RF1NE	4	rw	Rx FIFO 1 New Message Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
RF1WE	5	rw	Rx FIFO 1 Watermark Reached Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
RF1FE	6	rw	Rx FIFO 1 Full Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
RF1LE	7	rw	Rx FIFO 1 Message Lost Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
HPME	8	rw	High Priority Message Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TCE	9	rw	Transmission Completed Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TCFE	10	rw	Transmission Cancellation Finished Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TFEE	11	rw	Tx FIFO Empty Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TEFNE	12	rw	Tx Event FIFO New Entry Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TEFWE	13	rw	Tx Event FIFO Watermark Reached Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TEFFE	14	rw	Tx Event FIFO Full Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TEFLE	15	rw	Tx Event FIFO Element Lost Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TSWE	16	rw	Timestamp Wraparound Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
MRAFE	17	rw	Message RAM Access Failure Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
TOOE	18	rw	Timeout Occurred Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled

CAN Interface (MCMCAN)

Field	Bits	Type	Description
DRXE	19	rw	Message stored to Dedicated Rx Buffer Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
ELOE	22	rw	Error Logging Overflow Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
EPE	23	rw	Error Passive Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
EWE	24	rw	Warning Status Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
BOE	25	rw	Bus_Off Status Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
WDIE	26	rw	Watchdog Interrupt Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
PEAE	27	rw	Protocol Error in Arbitration Phase Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
PEDE	28	rw	Protocol Error in Data Phase Enable 0 _B Interrupt disabled 1 _B Interrupt enabled
0	20, 21, 29, 31:30	r	Reserved Shall read 0, shall be written with 0.

Global Filter Configuration i

Global settings for Message ID filtering. The Global Filter Configuration controls the filter path for standard and extended messages as described in [Figure 594](#) and [Figure 595](#).

GFCi (i=0-3)

Global Filter Configuration i (008280 _H +i*400 _H)										Application Reset Value: 0000 0000 _H					
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0										ANFS	ANFE	RRFS	RRFE		
r										rw	rw	rw	rw		

CAN Interface (MCMCAN)

Field	Bits	Type	Description
RRFE	0	rw	Reject Remote Frames Extended This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Filter remote frames with 29-bit extended IDs 1 _B Reject all remote frames with 29-bit extended IDs
RRFS	1	rw	Reject Remote Frames Standard This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Filter remote frames with 11-bit standard IDs 1 _B Reject all remote frames with 11-bit standard IDs
ANFE	3:2	rw	Accept Non-matching Frames Extended This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Defines how received messages with 29-bit IDs that do not match any element of the filter list are treated. 00 _B Accept in Rx FIFO 0 01 _B Accept in Rx FIFO 1 10 _B Reject 11 _B Reject
ANFS	5:4	rw	Accept Non-matching Frames Standard This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Defines how received messages with 11-bit IDs that do not match any element of the filter list are treated. 00 _B Accept in Rx FIFO 0 01 _B Accept in Rx FIFO 1 10 _B Reject 11 _B Reject
0	31:6	r	Reserved Shall read 0, shall be written with 0.

Standard ID Filter Configuration i

Settings for 11-bit standard Message ID filtering. The Standard ID Filter Configuration controls the filter path for standard messages.

SIDFCi (i=0-3)

Standard ID Filter Configuration i

(008284_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0								LSS							
r								rw							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
FLSSA														0	
rw														r	

CAN Interface (MCMCAN)

Field	Bits	Type	Description
FLSSA	15:2	rw	Filter List Standard Start Address This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Start address of standard Message ID filter list (32-bit word address).
LSS	23:16	rw	List Size Standard This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 00 _H No standard Message ID filter 01 _H 1 Message ID filter elements ... 80 _H 128 Message ID filter elements others , 128 Message ID filter elements
0	1:0, 31:24	r	Reserved Shall read 0, shall be written with 0.

Extended ID Filter Configuration i

Settings for 29-bit extended Message ID filtering. The Extended ID Filter Configuration controls the filter path for standard messages as described in [Figure 595](#).

XIDFCi (i=0-3)

Extended ID Filter Configuration i (008288_H+i*400_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0									LSE						
r									rw						
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
FLESA													0		
rw													r		

Field	Bits	Type	Description
FLESA	15:2	rw	Filter List Extended Start Address This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Start address of extended Message ID filter list (32-bit word address).
LSE	22:16	rw	List Size Extended This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 00 _H No standard Message ID filter 01 _H 1 extended Message ID filter element ... 40 _H 64 extended Message ID filter element others , 64 extended Message ID filter elements

CAN Interface (MCMCAN)

Field	Bits	Type	Description
0	1:0, 31:23	r	Reserved Shall read 0, shall be written with 0.

Extended ID AND Mask i

XIDAMi (i=0-3)

Extended ID AND Mask i				(008290 _H +i*400 _H)						Application Reset Value: 1FFF FFFF _H					
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0			EIDM												
r			rw												
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
EIDM															
rw															

Field	Bits	Type	Description
EIDM	28:0	rw	Extended ID Mask This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. For acceptance filtering of extended frames the Extended ID AND Mask is ANDed with the Message ID of a received frame. Intended for masking of 29-bit IDs in SAE J1939. With the reset value of all bits set to one the mask is not active.
0	31:29	r	Reserved Shall read 0, shall be written with 0.

High Priority Message Status i

This register is updated every time a Message ID filter element configured to generate a priority event matches. This can be used to monitor the status of incoming high priority messages and to enable fast access to these messages.

HPMSi (i=0-3)

High Priority Message Status i								(008294 _H +i*400 _H)				Application Reset Value: 0000 0000 _H					
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16		
								0									
								r									
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
FLST		FIDX						MSI		BIDX							
rh		rh						rh		rh							

CAN Interface (MCMCAN)

Field	Bits	Type	Description
BIDX	5:0	rh	Buffer Index Index of Rx FIFO element to which the message was stored. Only valid when MSI[1] = '1'.
MSI	7:6	rh	Message Storage Indicator 00 _B No FIFO selected 01 _B FIFO message lost 10 _B Message stored in FIFO 0 11 _B Message stored in FIFO 1
FIDX	14:8	rh	Filter Index Index of matching filter element. Range is 0 to SIDFC.LSS - 1 resp. XIDFC.LSE - 1.
FLST	15	rh	Filter List Indicates the filter list of the matching filter element. 0 _B Standard Filter List 1 _B Extended Filter List
0	31:16	r	Reserved Shall read 0, shall be written with 0.

New Data 1 i

The register holds the New Data flags of Rx Buffers 0 to 31.

Note: LDMST or SWAPMSK.W instructions should be used only with bit mask enabled for all rwh bits in this register.

NDAT1i (i=0-3)

New Data 1 i (008298 _H +i*400 _H)																Application Reset Value: 0000 0000 _H													
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16														
ND31	ND30	ND29	ND28	ND27	ND26	ND25	ND24	ND23	ND22	ND21	ND20	ND19	ND18	ND17	ND16														
rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh														
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0														
ND15	ND14	ND13	ND12	ND11	ND10	ND9	ND8	ND7	ND6	ND5	ND4	ND3	ND2	ND1	ND0														
rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh														

Field	Bits	Type	Description
NDy (y=0-31)	y	rwh	New Data in Rx Buffer y - ND The flag is set when the respective Rx Buffer has been updated from a received frame. The flags remain set until the Host clears them. A flag is cleared by writing a "1" to the corresponding bit position. Writing a "0" has no effect. 0 _B Rx Buffer not updated 1 _B Rx Buffer updated from new message

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CAN Interface (MCMCAN)

Field	Bits	Type	Description
F0S	22:16	rw	Rx FIFO 0 Size This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 00 _H No Rx FIFO 0 01 _H 1 Rx FIFO 0 elements ... 40 _H 64 Rx FIFO 0 elements others , 64 Rx FIFO 0 elements
F0WM	30:24	rw	Rx FIFO 0 Watermark This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 01 _H Level for Rx FIFO 0 watermark interrupt (IR.RF0W) ... 40 _H Level for Rx FIFO 0 watermark interrupt (IR.RF0W) others , Watermark interrupt disabled
F0OM	31	rw	FIFO 0 Operation Mode This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. FIFO 0 can be operated in blocking or in overwrite mode (see Rx FIFOs). 0 _B FIFO 0 blocking mode 1 _B FIFO 0 overwrite mode
0	1:0, 23	r	Reserved Shall read 0, shall be written with 0.

Rx FIFO 0 Status i

RXF0Si (i=0-3)

Rx FIFO 0 Status i																(0082A4 _H +i*400 _H)				Application Reset Value: 0000 0000 _H							
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16												
0						RF0L	F0F	0		F0PI																	
r						rh	rh	r		rh																	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0												
0		F0GI						0		F0FL																	
r		rh						r		rh																	

Field	Bits	Type	Description
F0FL	6:0	rh	Rx FIFO 0 Fill Level Number of elements stored in Rx FIFO 0, range 0 to 64.
F0GI	13:8	rh	Rx FIFO 0 Get Index Rx FIFO 0 read index pointer, range 0 to 63.
F0PI	21:16	rh	Rx FIFO 0 Put Index Rx FIFO 0 write index pointer, range 0 to 63.

CAN Interface (MCMCAN)

Field	Bits	Type	Description
F0F	24	rh	Rx FIFO 0 Full 0 _B Rx FIFO 0 not full 1 _B Rx FIFO 0 full
RF0L	25	rh	Rx FIFO 0 Message Lost This bit is a copy of interrupt flag IR.RF0L. When IR.RF0L is reset, this bit is also reset. <i>Note: Overwriting the oldest message when RXF0C.F0OM = '1' will not set this flag.</i> 0 _B No Rx FIFO 0 message lost 1 _B Rx FIFO 0 message lost, also set after write attempt to Rx FIFO 0 of size zero
0	7, 15:14, 23:22, 31:26	r	Reserved Shall read 0, shall be written with 0.

Rx FIFO 0 Acknowledge i

RXF0Ai (i=0-3)

Rx FIFO 0 Acknowledge i

(0082A8_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0										F0AI					
r										rw					

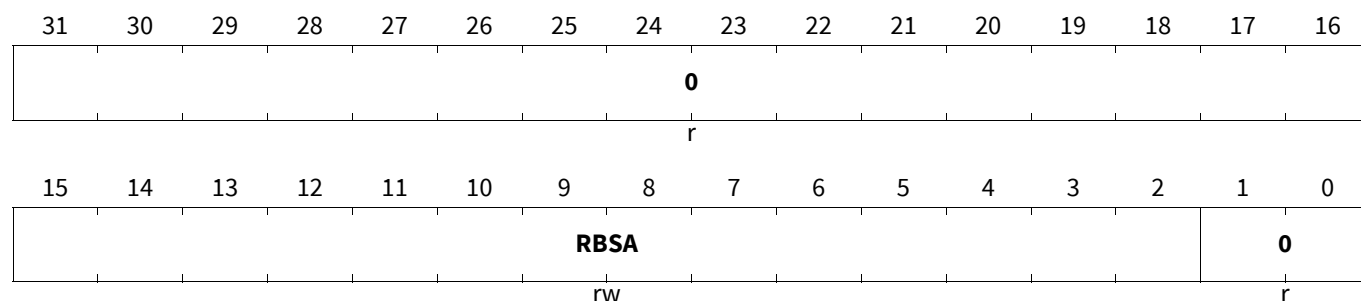
Field	Bits	Type	Description
F0AI	5:0	rw	Rx FIFO 0 Acknowledge Index After the Host has read a message or a sequence of messages from Rx FIFO 0 it has to write the buffer index of the last element read from Rx FIFO 0 to F0AI. This will set the Rx FIFO 0 Get Index RXF0S.F0GI to F0AI + 1 and update the FIFO 0 Fill Level RXF0S.F0FL.
0	31:6	r	Reserved Shall read 0, shall be written with 0.

CAN Interface (MCMCAN)

Rx Buffer Configuration i

RXBCi (i=0-3)

Rx Buffer Configuration i

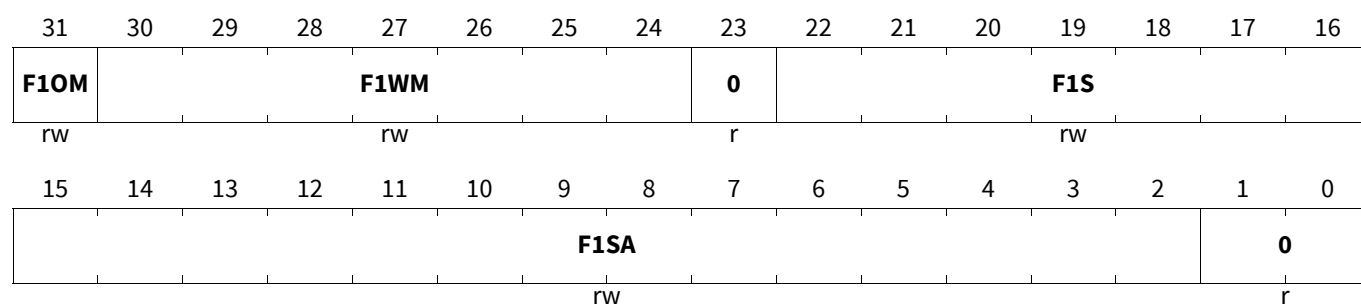
(0082AC_H+i*400_H)Application Reset Value: 0000 0000_H

Field	Bits	Type	Description
RBSA	15:2	rw	Rx Buffer Start Address This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Configures the start address of the Rx Buffers section in the Message RAM (32-bit word address).
0	1:0, 31:16	r	Reserved Shall read 0, shall be written with 0.

Rx FIFO 1 Configuration i

RXF1Ci (i=0-3)

Rx FIFO 1 Configuration i

(0082B0_H+i*400_H)Application Reset Value: 0000 0000_H

Field	Bits	Type	Description
F1SA	15:2	rw	Rx FIFO 1 Start Address This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Start address of Rx FIFO 1 in Message RAM (32-bit word address).

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Field	Bits	Type	Description
F1S	22:16	rw	Rx FIFO 1 Size This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 00 _H No Rx FIFO 1 01 _H 1 Rx FIFO 1 elements ... 40 _H 64 Rx FIFO 1 elements others , 64 Rx FIFO 1 elements
F1WM	30:24	rw	Rx FIFO 1 Watermark This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 01 _H Level for Rx FIFO 1 watermark interrupt (IR.RF1W) ... 40 _H Level for Rx FIFO 1 watermark interrupt (IR.RF1W) others , Watermark interrupt disabled
F1OM	31	rw	FIFO 1 Operation Mode This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. FIFO 1 can be operated in blocking or in overwrite mode. 0 _B FIFO 1 blocking mode 1 _B FIFO 1 overwrite mode
0	1:0, 23	r	Reserved Shall read 0, shall be written with 0.

Rx FIFO 1 Status i

RXF1Si (i=0-3)

Rx FIFO 1 Status i																(0082B4 _H +i*400 _H)																Application Reset Value: 0000 0000 _H															
31		30		29		28		27		26		25		24		23		22		21		20		19		18		17		16																	
0				0								RF1L		F1F		0				F1PI																											
r		r								rh		rh		r				rh																													
15		14		13		12		11		10		9		8		7		6		5		4		3		2		1		0																	
0				F1GI												0				F1FL																											
r		rh												r				rh																													

Field	Bits	Type	Description
F1FL	6:0	rh	Rx FIFO 1 Fill Level Number of elements stored in Rx FIFO 1, range 0 to 64.
F1GI	13:8	rh	Rx FIFO 1 Get Index Rx FIFO 1 read index pointer, range 0 to 63.
F1PI	21:16	rh	Rx FIFO 1 Put Index Rx FIFO 1 write index pointer, range 0 to 63.

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Field	Bits	Type	Description
F1F	24	rh	Rx FIFO 1 Full 0 _B Rx FIFO 1 not full 1 _B Rx FIFO 1 full
RF1L	25	rh	Rx FIFO 1 Message Lost This bit is a copy of interrupt flag IR.RF1L. When IR.RF1L is reset, this bit is also reset. <i>Note: Overwriting the oldest message when RXF1C.F1OM = '1' will not set this flag.</i> 0 _B No Rx FIFO 1 message lost 1 _B Rx FIFO 1 message lost, also set after write attempt to Rx FIFO 1 of size zero
0	7, 15:14, 23:22, 29:26, 31:30	r	Reserved Shall read 0, shall be written with 0.

Rx FIFO 1 Acknowledge i

RXF1Ai (i=0-3)

Rx FIFO 1 Acknowledge i																(0082B8 _H +i*400 _H)																Application Reset Value: 0000 0000 _H															
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16																																
0																																															
r																																															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																
0																F1AI																															
r																rw																															

Field	Bits	Type	Description
F1AI	5:0	rw	Rx FIFO 1 Acknowledge Index After the Host has read a message or a sequence of messages from Rx FIFO 1 it has to write the buffer index of the last element read from Rx FIFO 1 to F1AI. This will set the Rx FIFO 1 Get Index RXF1S.F1GI to F1AI + 1 and update the FIFO 1 Fill Level RXF1S.F1FL
0	31:6	r	Reserved Shall read 0, shall be written with 0.

Rx Buffer/FIFO Element Size Configuration i

Configures the number of data bytes belonging to an Rx Buffer / Rx FIFO element. Data field sizes > 8 bytes are intended for CAN FD operation only.

CAN Interface (MCMCAN)

RXESCi (i=0-3)

Rx Buffer/FIFO Element Size Configuration i(0082BC_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0				RBDS				0	F1DS				0	F0DS	
r				rw				r	rw				r	rw	

Field	Bits	Type	Description
F0DS	2:0	rw	Rx FIFO 0 Data Field Size This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. <i>Note:</i> In case the data field size of an accepted CAN frame exceeds the data field size configured for the matching Rx Buffer or Rx FIFO, only the number of bytes as configured by RXESC are stored to the Rx Buffer resp. Rx FIFO element. The rest of the frame's data field is ignored. 000 _B 8-byte data field 001 _B 12-byte data field 010 _B 16-byte data field 011 _B 20-byte data field 100 _B 24-byte data field 101 _B 32-byte data field 110 _B 48-byte data field 111 _B 64-byte data field
F1DS	6:4	rw	Rx FIFO 1 Data Field Size This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 000 _B 8-byte data field 001 _B 12-byte data field 010 _B 16-byte data field 011 _B 20-byte data field 100 _B 24-byte data field 101 _B 32-byte data field 110 _B 48-byte data field 111 _B 64-byte data field

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Field	Bits	Type	Description
RBDS	10:8	rw	Rx Buffer Data Field Size This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 000 _B 8-byte data field 001 _B 12-byte data field 010 _B 16-byte data field 011 _B 20-byte data field 100 _B 24-byte data field 101 _B 32-byte data field 110 _B 48-byte data field 111 _B 64-byte data field
0	3, 7, 31:11	r	Reserved Shall read 0, shall be written with 0.

Tx Buffer Configuration i

TXBCi (i=0-3)

Tx Buffer Configuration i

(0082C0_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0	TFQM							0					NDTB		
r	rw							r					rw		
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
															0
															r

Field	Bits	Type	Description
TBSA	15:2	rw	Tx Buffers Start Address This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Start address of Tx Buffers section in Message RAM (32-bit word address).
NDTB	21:16	rw	Number of Dedicated Transmit Buffers This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. <i>Note: Be aware that the sum of TFQS and NDTB may be not greater than 32. There is no check for erroneous configurations. The Tx Buffers section in the Message RAM starts with the dedicated Tx Buffers.</i> 00 _H No Dedicated Tx Buffers 01 _H 1 Dedicated Tx Buffers ... 20 _H 32 Dedicated Tx Buffers others, 32 Dedicated Tx Buffers

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TFQS	29:24	rw	Transmit FIFO/Queue Size This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 00 _H No Tx FIFO/Queue 01 _H 1 Tx Buffers used for Tx FIFO/Queue ... 20 _H 32 Tx Buffers used for Tx FIFO/Queue others , 32 Tx Buffers used for Tx FIFO/Queue
TFQM	30	rw	Tx FIFO/Queue Mode This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Tx FIFO operation 1 _B Tx Queue operation
0	1:0, 23:22, 31	r	Reserved Shall read 0, shall be written with 0.

Tx FIFO/Queue Status i

The Tx FIFO/Queue status is related to the pending Tx requests listed in register TXBRP. Therefore the effect of Add/Cancellation requests may be delayed due to a running Tx scan (TXBRP not yet updated).

TXFQSi (i=0-3)

Tx FIFO/Queue Status i (0082C4 _H +i*400 _H)										Application Reset Value: 0000 0000 _H					
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0										TFQF	TFQPI				
r										rh	rh				
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0			TFGI				0			TFFL					
r			rh				r			rh					

Field	Bits	Type	Description
TFFL	5:0	rh	Tx FIFO Free Level Number of consecutive free Tx FIFO elements starting from TFGI, range 0 to 32. Read as zero when Tx Queue operation is configured (TXBC.TFQM = '1') <i>Note: In case of mixed configurations where dedicated Tx Buffers are combined with a Tx FIFO or a Tx Queue, the Put and Get Indices indicate the number of the Tx Buffer starting with the first dedicated Tx Buffers. Example: For a configuration of 12 dedicated Tx Buffers and a Tx FIFO of 20 Buffers a Put Index of 15 points to the fourth buffer of the Tx FIFO.</i>

CAN Interface (MCMCAN)

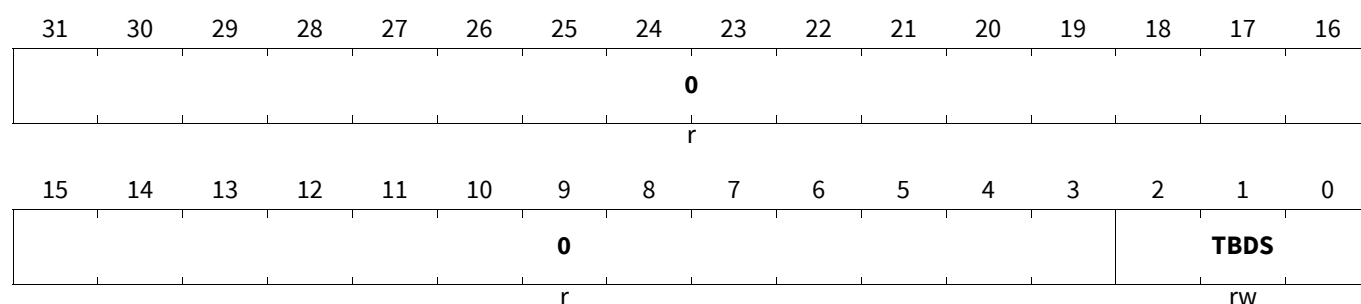
Field	Bits	Type	Description
TFGI	12:8	rh	Tx FIFO Get Index Tx FIFO read index pointer, range 0 to 31. Read as zero when Tx Queue operation is configured (TXBC.TFQM = '1').
TFQPI	20:16	rh	Tx FIFO/Queue Put Index Tx FIFO/Queue write index pointer, range 0 to 31.
TFQF	21	rh	Tx FIFO/Queue Full 0 _B Tx FIFO/Queue not full 1 _B Tx FIFO/Queue full
0	7:6, 15:13, 31:22	r	Reserved Shall read 0, shall be written with 0.

Tx Buffer Element Size Configuration i

Configures the number of data bytes belonging to a Tx Buffer element. Data field sizes > 8 bytes are intended for CAN FD operation only.

TXESCI (i=0-3)

Tx Buffer Element Size Configuration i (0082C8_H+i*400_H) **Application Reset Value: 0000 0000_H**



Field	Bits	Type	Description
TBDS	2:0	rw	Tx Buffer Data Field Size This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. <i>Note:</i> In case the data length code DLC of a Tx Buffer element is configured to a value higher than the Tx Buffer data field size TXESC.TBDS, the bytes not defined by the Tx Buffer are transmitted as "0xCC" (padding bytes). 000 _B 8-byte data field 001 _B 12-byte data field 010 _B 16-byte data field 011 _B 20-byte data field 100 _B 24-byte data field 101 _B 32-byte data field 110 _B 48-byte data field 111 _B 64-byte data field

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Field	Bits	Type	Description
0	31:3	r	Reserved Shall read 0, shall be written with 0.

Tx Buffer Request Pending i

Each Tx Buffer has its own Transmission Request Pending bit. The bits are set via register TXBAR. The bits are reset after a requested transmission has completed or has been cancelled via register TXBCR.

TXBRP bits are set only for those Tx Buffers configured via TXBC. After a TXBRP bit has been set, a Tx scan (Tx Handling) is started to check for the pending Tx request with the highest priority (Tx Buffer with lowest Message ID).

A cancellation request resets the corresponding transmission request pending bit of register TXBRP. In case a transmission has already been started when a cancellation is requested, this is done at the end of the transmission, regardless whether the transmission was successful or not. The cancellation request bits are reset directly after the corresponding TXBRP bit has been reset.

After a cancellation has been requested, a finished cancellation is signalled via TXBCF

- after successful transmission together with the corresponding TXBTO bit
- when the transmission has not yet been started at the point of cancellation
- when the transmission has been aborted due to lost arbitration
- when an error occurred during frame transmission

In DAR mode all transmissions are automatically cancelled if they are not successful. The corresponding TXBCF bit is set for all unsuccessful transmissions.

Note: TXBRP bits which are set while a Tx scan is in progress are not considered during this particular Tx scan. In case a cancellation is requested for such a Tx Buffer, this "Add Request" is cancelled immediately, the corresponding TXBRP bit is reset.

TXBRPi (i=0-3)

Tx Buffer Request Pending i (0082CC_H+i*400_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
TRP31	TRP30	TRP29	TRP28	TRP27	TRP26	TRP25	TRP24	TRP23	TRP22	TRP21	TRP20	TRP19	TRP18	TRP17	TRP16
rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TRP15	TRP14	TRP13	TRP12	TRP11	TRP10	TRP9	TRP8	TRP7	TRP6	TRP5	TRP4	TRP3	TRP2	TRP1	TRP0
rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh

Field	Bits	Type	Description
TRPz (z=0-31)	z	rh	Transmission Request Pending Tx Buffer z - TRP 0 _B No transmission request pending 1 _B Transmission request pending

Tx Buffer Add Request i

Each Tx Buffer has its own "Add Request" bit. Writing a '1' will set the corresponding "Add Request" bit; writing a '0' has no impact. This enables the Host to set transmission requests for multiple Tx Buffers with one write to

CAN Interface (MCMCAN)

TXBAR. TXBAR bits are set only for those Tx Buffers configured via TXBC. When no Tx scan is running, the bits are reset immediately, else the bits remain set until the Tx scan process has completed.

Note: If an add request is applied for a Tx Buffer with pending transmission request (corresponding TXBRP bit already set), this add request is ignored. LDMST or SWAPMSK.W instructions should be used only with bit mask enabled for all rwh bits in this register.

TXBARi (i=0-3)

Tx Buffer Add Request i (0082D0 _H +i*400 _H)															
Application Reset Value: 0000 0000 _H															
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
AR31	AR30	AR29	AR28	AR27	AR26	AR25	AR24	AR23	AR22	AR21	AR20	AR19	AR18	AR17	AR16
rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
AR15	AR14	AR13	AR12	AR11	AR10	AR9	AR8	AR7	AR6	AR5	AR4	AR3	AR2	AR1	AR0
rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh

Field	Bits	Type	Description
ARz (z=0-31)	z	rwh	Add Request Tx Buffer z - AR 0 _B No transmission request added 1 _B Transmission requested added

Tx Buffer Cancellation Request i

Each Tx Buffer has its own Cancellation Request bit. Writing a '1' will set the corresponding Cancellation Request bit; writing a '0' has no impact. This enables the Host to set cancellation requests for multiple Tx Buffers with one write to TXBCR. TXBCR bits are set only for those Tx Buffers configured via TXBC. The bits remain set until the corresponding bit of TXBRP is reset.

Note: LDMST or SWAPMSK.W instructions should be used only with bit mask enabled for all rwh bits in this register.

TXBCRi (i=0-3)

Tx Buffer Cancellation Request i (0082D4 _H +i*400 _H)															
Application Reset Value: 0000 0000 _H															
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
CR31	CR30	CR29	CR28	CR27	CR26	CR25	CR24	CR23	CR22	CR21	CR20	CR19	CR18	CR17	CR16
rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CR15	CR14	CR13	CR12	CR11	CR10	CR9	CR8	CR7	CR6	CR5	CR4	CR3	CR2	CR1	CR0
rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh

CAN Interface (MCMCAN)

Field	Bits	Type	Description
CRz (z=0-31)	z	rwh	Cancellation Request Tx Buffer z - CR 0_B No cancellation pending 1_B Cancellation pending

Tx Buffer Transmission Occurred i

Each Tx Buffer has its own Transmission Occurred bit. The bits are set when the corresponding TXBRP bit is cleared after a successful transmission. The bits are reset when a new transmission is requested by writing a '1' to the corresponding bit of register TXBAR.

TXBTOi (i=0-3)

Tx Buffer Transmission Occurred i (0082D8_H+i*400_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
TO31	TO30	TO29	TO28	TO27	TO26	TO25	TO24	TO23	TO22	TO21	TO20	TO19	TO18	TO17	TO16
rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TO15	TO14	TO13	TO12	TO11	TO10	TO9	TO8	TO7	TO6	TO5	TO4	TO3	TO2	TO1	TO0
rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh

Field	Bits	Type	Description
TOz (z=0-31)	z	rh	Transmission Occurred Tx Buffer z - TO 0_B No transmission occurred 1_B Transmission occurred

Tx Buffer Cancellation Finished i

Each Tx Buffer has its own Cancellation Finished bit. The bits are set when the corresponding TXBRP bit is cleared after a cancellation was requested via TXBCR. In case the corresponding TXBRP bit was not set at the point of cancellation, CF is set immediately. The bits are reset when a new transmission is requested by writing a '1' to the corresponding bit of register TXBAR.

TXBCFi (i=0-3)

Tx Buffer Cancellation Finished i (0082DC_H+i*400_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
CF31	CF30	CF29	CF28	CF27	CF26	CF25	CF24	CF23	CF22	CF21	CF20	CF19	CF18	CF17	CF16
rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CF15	CF14	CF13	CF12	CF11	CF10	CF9	CF8	CF7	CF6	CF5	CF4	CF3	CF2	CF1	CF0
rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh	rh

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Field	Bits	Type	Description
CFz (z=0-31)	z	rh	Cancellation Finished Tx Buffer z - CF 0 _B No transmit buffer cancellation 1 _B Transmit buffer cancellation finished

Tx Buffer Transmission Interrupt Enable i

Each Tx Buffer has its own Transmission Interrupt Enable bit.

TXBTIEi (i=0-3)**Tx Buffer Transmission Interrupt Enable i (0082E0_H+i*400_H)**Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
TIE31	TIE30	TIE29	TIE28	TIE27	TIE26	TIE25	TIE24	TIE23	TIE22	TIE21	TIE20	TIE19	TIE18	TIE17	TIE16
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TIE15	TIE14	TIE13	TIE12	TIE11	TIE10	TIE9	TIE8	TIE7	TIE6	TIE5	TIE4	TIE3	TIE2	TIE1	TIE0
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
TIEz (z=0-31)	z	rw	Transmission Interrupt Enable Tx Buffer z - TIE 0 _B Transmission interrupt disabled 1 _B Transmission interrupt enable

Tx Buffer Cancellation Finished Interrupt Enable i

Each Tx Buffer has its own Cancellation Finished Interrupt Enable bit.

TXBCIEi (i=0-3)**Tx Buffer Cancellation Finished Interrupt Enable i(0082E4_H+i*400_H)**Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
CFIE3 1	CFIE3 0	CFIE2 9	CFIE2 8	CFIE2 7	CFIE2 6	CFIE2 5	CFIE2 4	CFIE2 3	CFIE2 2	CFIE2 1	CFIE2 0	CFIE1 9	CFIE1 8	CFIE1 7	CFIE1 6
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CFIE1 5	CFIE1 4	CFIE1 3	CFIE1 2	CFIE1 1	CFIE1 0	CFIE9	CFIE8	CFIE7	CFIE6	CFIE5	CFIE4	CFIE3	CFIE2	CFIE1	CFIE0
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
CFIEz (z=0-31)	z	rw	Cancellation Finished Interrupt Enable Tx Buffer z - CFIE 0 _B Cancellation finished interrupt disabled 1 _B Cancellation finished interrupt enabled

CAN Interface (MCMCAN)

Tx Event FIFO Configuration i

TXEFCi (i=0-3)

Tx Event FIFO Configuration i

(0082F0_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0								0							
r					rw			r					rw		
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
															0
															r

Field	Bits	Type	Description
EFSA	15:2	rw	Event FIFO Start Address This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Start address of Tx Event FIFO in Message RAM (32-bit word address).
EFS	21:16	rw	Event FIFO Size This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. The Tx Event FIFO elements are indexed from 0 to EFS - 1 00 _H Tx Event FIFO disabled 01 _H 1 Tx Event FIFO elements ... 20 _H 32 Tx Event FIFO elements others , 32 Tx Event FIFO elements
EFWM	29:24	rw	Event FIFO Watermark This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 01 _H Level for Tx Event FIFO watermark interrupt (IR.TEFW) ... 20 _H Level for Tx Event FIFO watermark interrupt (IR.TEFW) others , Watermark interrupt disabled
0	1:0, 23:22, 31:30	r	Reserved Shall read 0, shall be written with 0.

CAN Interface (MCMCAN)

Tx Event FIFO Status i

TXEFSi (i=0-3)

Tx Event FIFO Status i

(0082F4_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0						TEFL	EFF	0			EFPI				
r						rh	rh	r			rh				
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0			EFGI				0			EFFL					
r			rh				r			rh					

Field	Bits	Type	Description
EFFL	5:0	rh	Event FIFO Fill Level Number of elements stored in Tx Event FIFO, range 0 to 32.
EFGI	12:8	rh	Event FIFO Get Index Tx Event FIFO read index pointer, range 0 to 31.
EFPI	20:16	rh	Event FIFO Put Index Tx Event FIFO write index pointer, range 0 to 31.
EFF	24	rh	Event FIFO Full 0 _B Tx Event FIFO not full 1 _B Tx Event FIFO full
TEFL	25	rh	Tx Event FIFO Element Lost This bit is a copy of interrupt flag IR.TEFL. When IR.TEFL is reset, this bit is also reset. 0 _B No Tx Event FIFO element lost 1 _B Tx Event FIFO element lost, also set after write attempt to Tx Event FIFO of size zero.
0	7:6, 15:13, 23:21, 31:26	r	Reserved Shall read 0, shall be written with 0.

Tx Event FIFO Acknowledge i

TXEFAi (i=0-3)

Tx Event FIFO Acknowledge i

(0082F8_H+i*400_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0											EFAI				
r											rw				

CAN Interface (MCMCAN)

Field	Bits	Type	Description
EFAI	4:0	rw	Event FIFO Acknowledge Index After the Host has read an element or a sequence of elements from the Tx Event FIFO it has to write the index of the last element read from Tx Event FIFO to EFAI. This will set the Tx Event FIFO Get Index TXEFS.EFGI to EFAI + 1 and update the FIFO 0 Fill Level TXEFS.EFFL.
0	31:5	r	Reserved Shall read 0, shall be written with 0.

TT Trigger Memory Configuration 0

The TTCAN function exists only on CAN0 node 0.

TTTMC0

TT Trigger Memory Configuration 0

(008300_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0									TME						
r									rw						
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TMSA														0	
rw														r	

Field	Bits	Type	Description
TMSA	15:2	rw	Trigger Memory Start Address This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Start address of Trigger Memory in Message RAM.
TME	22:16	rw	Trigger Memory Elements This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 00 _H No Trigger Memory 01 _H 1 Trigger Memory element ... 40 _H 64 Trigger Memory element others , 64 Trigger Memory elements
0	1:0, 31:23	r	Reserved Shall read 0, shall be written with 0.

TT Reference Message Configuration 0

The TTCAN function exists only on CAN0 node 0. For details about handling of reference messages.

CAN Interface (MCMCAN)

TTRMCO

TT Reference Message Configuration 0

(008304_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
RMPS	XTD	0							RID						
rw	rw	r							rw						
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
									RID						
									rw						

Field	Bits	Type	Description
RID	28:0	rw	Reference Identifier This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Identifier transmitted with reference message and used for reference message filtering. Standard or extended reference identifier depending on bit XTD. A standard identifier has to be written to ID[28:18].
XTD	30	rw	Extended Identifier This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B 11-bit standard identifier 1 _B 29-bit extended identifier
RMPS	31	rw	Reference Message Payload Select This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Ignored in case of time slaves. 0 _B Reference message has no additional payload 1 _B The following elements are taken from Tx Buffer 0: Message Marker MM, Event FIFO Control EFC, Data Length Code DLC, Data Bytes DB (Level 1: bytes 2-8, Level 0,2: bytes 5-8)
0	29	r	Reserved Shall read 0, shall be written with 0.

TT Operation Configuration 0

The TTCAN function exists only on CAN0 node 0.

CAN Interface (MCMCAN)

TTOCF0

TT Operation Configuration 0

(008308_H)Application Reset Value: 0001 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0					EVTP	ECC	EGTF	AWL							
r					rw	rw	rw	rw							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
EECS	IRTO					LDSDL			TM	GEN	0	OM			
rw	rw					rw			rw	rw	rw	r	rw		

Field	Bits	Type	Description
OM	1:0	rw	Operation Mode This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 00 _B Event-driven CAN communication, default 01 _B TTCAN level 1 10 _B TTCAN level 2 11 _B TTCAN level 0
GEN	3	rw	Gap Enable This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Strictly time-triggered operation 1 _B External event-synchronized time-triggered operation
TM	4	rw	Time Master This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Time Master function disabled 1 _B Potential Time Master
LDSDL	7:5	rw	LD of Synchronization Deviation Limit This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. The Synchronization Deviation Limit SDL is configured by its dual logarithm LDSDL with $SDL = 2^{(LDSDL + 5)}$. It should not exceed the clock tolerance given by the CAN bit timing configuration. LD of Synchronization Deviation Limit ($SDL \leq 32 \dots 4096$)
IRTO	14:8	rw	Initial Reference Trigger Offset This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Positive offset, range from 0 to 127

CAN Interface (MCMCAN)

Field	Bits	Type	Description
EECS	15	rw	Enable External Clock Synchronization This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. If enabled, TUR configuration (TURCF.NCL only) may be updated during TTCAN operation. 0 _B External clock synchronization in TTCAN Level 0,2 disabled 1 _B External clock synchronization in TTCAN Level 0,2 enabled
AWL	23:16	rw	Application Watchdog Limit This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. The application watchdog can be disabled by programming AWL to 0x00. Maximum time after which the application has to serve the application watchdog. The application watchdog is incremented once each 256 NTUs.
EGTF	24	rw	Enable Global Time Filtering This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Global time filtering in TTCAN Level 0,2 is disabled 1 _B Global time filtering in TTCAN Level 0,2 is enabled
ECC	25	rw	Enable Clock Calibration This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Automatic clock calibration in TTCAN Level 0,2 is disabled 1 _B Automatic clock calibration in TTCAN Level 0,2 is enabled
EVTP	26	rw	Event Trigger Polarity This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. 0 _B Rising edge trigger 1 _B Falling edge trigger
0	2, 31:27	r	Reserved Shall read 0, shall be written with 0.

TT Matrix Limits 0

The TTCAN function exists only on CAN0 node 0.

TTMLM0

TT Matrix Limits 0

(00830C_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0				ENTT											
r				rw											
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0				TXEW				CSS		CCM					
r				rw				rw		rw					

CAN Interface (MCMCAN)

Field	Bits	Type	Description
CCM	5:0	rw	Cycle Count Max This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. <i>Note: ISO 11898-4, 5.2.1 requires, that only the listed cycle count values are configured. Other values are possible but may lead to inconsistent matrix cycles.</i> 00 _H 1 Basic Cycle per Matrix Cycle 01 _H 2 Basic Cycles per Matrix Cycle 03 _H 4 Basic Cycles per Matrix Cycle 07 _H 8 Basic Cycles per Matrix Cycle 0F _H 16 Basic Cycles per Matrix Cycle 1F _H 32 Basic Cycles per Matrix Cycle 3F _H 64 Basic Cycles per Matrix Cycle others , Reserved
CSS	7:6	rw	Cycle Start Synchronization This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Enables sync pulse output at start of cycle. 00 _B No sync pulse 01 _B Sync pulse at start of basic cycle 10 _B Sync pulse at start of matrix cycle 11 _B Reserved
TXEW	11:8	rw	Tx Enable Window This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Length of Tx enable window, 1-16 NTU cycles
ENTT	27:16	rw	Expected Number of Tx Triggers This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. Expected number of Tx Triggers in one Matrix Cycle
0	15:12, 31:28	r	Reserved Shall read 0, shall be written with 0.

TUR Configuration 0

The TTCAN function exists only on CAN0 node 0.

The length of the NTU is given by: $NTU = \text{CAN Clock Period} \times NC / DC$

NC is an 18-bit value. Its high part, NCH[17:16] is hard wired to 0b01. Therefore the range of NC is 10000_H...1FFFF_H. The value configured by NCL is the initial value for TURNA.NAV[15:0]. DC is set to 1000_H by hardware reset and it may not be written to 0000_H.

Level 1: $NC \geq 4 \times DC$ and $NTU = \text{CAN bit time}$

Level 0,2: $NC \geq 8 \times DC$

The actual value of TUR may be changed by the clock drift compensation function of TTCAN Level 0 and Level 2 in order to adjust the node's local view of the NTU to the time master's view of the NTU. DC will not be changed

CAN Interface (MCMCAN)

by the automatic drift compensation, TURNA.NAV may be adjusted around NC in the range of the Synchronisation Deviation Limit given by TTOCF.LDSDL. NC and DC should be programmed to the largest suitable values in order to allow the best computational accuracy for the drift compensation process.

TURCF0

TUR Configuration 0

(008310_H)

Application Reset Value: 1000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
ELT	0	DC													
rw	r	rw													
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
NCL															
rw															

Field	Bits	Type	Description
NCL	15:0	rw	<p>Numerator Configuration Low</p> <p>This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set.</p> <p>Write access to the TUR Numerator Configuration Low is only possible during configuration with TURCF.ELT = '0' or if TTOCF.EECS (external clock synchronization enabled) is set. When a new value for NCL is written outside TT Configuration Mode, the new value takes effect when TTOST.WECS is cleared to '0'. NCL is locked TTOST.WECS is '1'.</p> <p><i>Note: If $NC < 7 \times DC$ in TTCAN Level 1, then it is required that subsequent time marks in the Trigger Memory must differ by at least 2 NTU.</i></p> <p>0000_HNumerator Configuration Low ... FFFF_HNumerator Configuration Low</p>
DC	29:16	rw	<p>Denominator Configuration</p> <p>This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set.</p> <p>0000_HIllegal value 0001_HDenominator Configuration ... 3FFF_HDenominator Configuration</p>

CAN Interface (MCMCAN)

Field	Bits	Type	Description
ELT	31	rw	Enable Local Time This bitfield is CCE and INIT protected. Writes will only have effect, if both bits are set. <i>Note:</i> Local time is started by setting ELT. It remains active until ELT is reset or until the next hardware reset. TURCF.DC is locked when TURCF.ELT = '1'. If ELT is written to '0', the readable value will stay at '1' until the new value has been synchronized into the CAN clock domain. During this time write access to the other bits of the register remains locked. 0 _B Local time is stopped, default 1 _B Local time is enabled
0	30	r	Reserved Shall read 0, shall be written with 0.

TT Operation Control 0

The TTCAN function exists only on CAN0 node 0.

TTOCN0

TT Operation Control 0

(008314_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0															
r															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
LCKC	0	ESCN	NIG	TMG	FGP	GCS	TTIE	TMC	RTIE	SWS	SWP	ECS	SGT		
rh	r	rw	rwh	rw	rwh	rw	rw	rw	rw	rw	rw	rw	rwh	rwh	

Field	Bits	Type	Description
SGT	0	rwh	Set Global time Writing a '1' to SGT sets TTOST.WGDT if the node is the actual Time Master. SGT is reset after one Host clock period. The global time preset takes effect when the node transmits the next reference message with the Master_Ref_Mark modified by the preset value written to TTGTP.
ECS	1	rwh	External Clock Synchronization Writing a '1' to ECS sets TTOST.WECS if the node is the actual Time Master. ECS is reset after one Host clock period. The external clock synchronization takes effect at the start of the next basic cycle.
SWP	2	rw	Stop Watch Polarity 0 _B Rising edge trigger 1 _B Falling edge trigger

CAN Interface (MCMCAN)

Field	Bits	Type	Description
SWS	4:3	rw	Stop Watch Source 00 _B Stop Watch disabled 01 _B Actual value of cycle time is copied to TTCPT.SWV 10 _B Actual value of local time is copied to TTCPT.SWV 11 _B Actual value of global time is copied to TTCPT.SWV
RTIE	5	rw	Register Time Mark Interrupt Pulse Enable Register time mark interrupts are configured by register TTTMK. A register time mark interrupt pulse with the length of one TTCAN clock period is generated when the time referenced by TTOCN.TMC (cycle, local, or global) equals TTTMK.TM, independent of the synchronization state. 0 _B Register Time Mark Interrupt output disabled 1 _B Register Time Mark Interrupt output enabled
TMC	7:6	rw	Register Time Mark Compare <i>Note: When changing the time mark reference (cycle, local, global time), it is recommended to first write TMC = "00", then reconfigure TTTMK, and finally set TMC to the intended time reference.</i> 00 _B No Register Time Mark Interrupt generated 01 _B Register Time Mark Interrupt if Time Mark = cycle time 10 _B Register Time Mark Interrupt if Time Mark = local time 11 _B Register Time Mark Interrupt if Time Mark = global time
TTIE	8	rw	Trigger Time Mark Interrupt Pulse Enable External time mark events are configured by trigger memory element TMEX. A trigger time mark interrupt pulse is generated when the trigger memory element becomes active, and the M_CAN is in synchronization state In_Schedule or In_Gap. 0 _B Trigger Time Mark Interrupt output disabled 1 _B Trigger Time Mark Interrupt output enabled
GCS	9	rw	Gap Control Select 0 _B Gap control independent from event trigger 1 _B Gap control by the event trigger
FGP	10	rwh	Finish Gap Set by the CPU, reset by each reference message 0 _B No reference message requested 1 _B Application requested start of reference message
TMG	11	rw	Time Mark Gap 0 _B Reset by each reference message 1 _B Next reference message started when Register Time Mark interrupt TTIR.RTMI is activated

CAN Interface (MCMCAN)

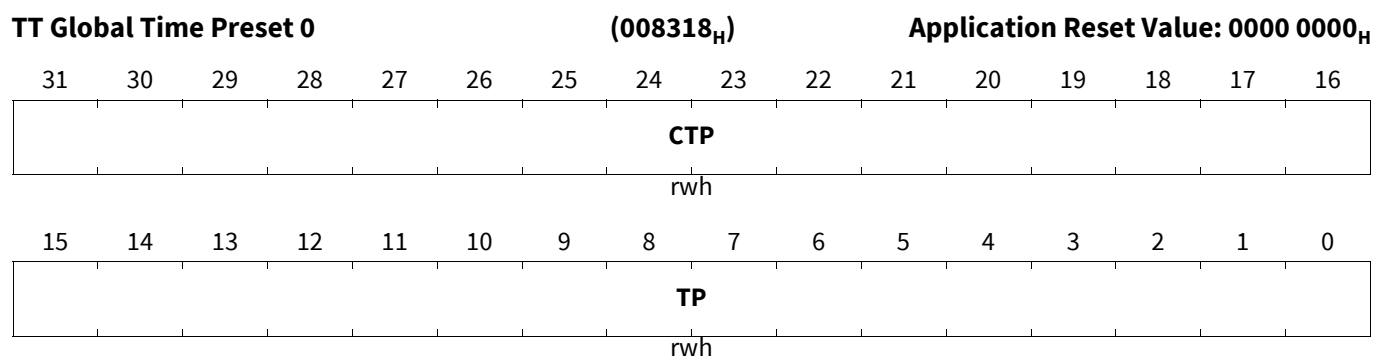
Field	Bits	Type	Description
NIG	12	rwh	Next is Gap This bit can only be set when the M_CAN is the actual Time Master and when it is configured for external event-synchronized time-triggered operation (TTOCF.GEN = '1') 0 _B No action, reset by reception of any reference message 1 _B Transmit next reference message with Next_is_Gap = '1'
ESCN	13	rw	External Synchronization Control If enabled the M_CAN synchronizes its cycle time phase to an external event signalled by a rising edge at the event trigger. 0 _B External synchronization disabled 1 _B External synchronization enabled
LCKC	15	rh	TT Operation Control Register Locked Set by a write access to register TTOCN. Reset when the updated configuration has been synchronized into the CAN clock domain. 0 _B Write access to TTOCN enabled 1 _B Write access to TTOCN locked
0	14, 31:16	r	Reserved Shall read 0, shall be written with 0.

TT Global Time Preset 0

If TTOST.WGDT is set, the next reference message will be transmitted with the Master_Ref_Mark modified by the preset value and with Disc_Bit = '1', presetting the global time in all nodes simultaneously.

TP is reset to 0x0000 each time a reference message with Disc_Bit = '1' becomes valid or if the node is not the current Time Master. TP is locked while TTOST.WGTD = '1' after setting TTOCN.SGT until the reference message with Disc_Bit = '1' becomes valid or until the node is no longer the current Time Master.

The TTCAN function exists only on CAN0 node 0.

TTGTP0

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TP	15:0	rwh	Time Preset CTP is write-protected while TTOCN.ESCN or TTOST.SPL are set. 0000 _H Next Master Reference Mark = Master Reference Mark + TP ... 7FFF _H Next Master Reference Mark = Master Reference Mark + TP 8000 _H Reserved 8001 _H Next Master Reference Mark = Master Reference Mark - (0x10000 - TP) ... FFFF _H Next Master Reference Mark = Master Reference Mark - (0x10000 - TP)
CTP	31:16	rwh	Cycle Time Target Phase CTP is write-protected while TTOCN.ESCN or TTOST.SPL are set. 0000 _H Defines target value of cycle time when a rising edge of the event trigger is expected ... FFFF _H Defines target value of cycle time when a rising edge of the event trigger is expected

TT Time Mark 0

A time mark interrupt (TTIR.RTMI = '1') is generated when the time base indicated by TTOCN.TMC (cycle time, local time, or global time) has the same value as TM.

The TTCAN function exists only on CAN0 node 0.

TTTMK0

TT Time Mark 0 (00831C _H)															
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
LCKM		0								TICC					
rh		r								rw					
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TM															
rw															

Field	Bits	Type	Description
TM	15:0	rw	Time Mark <i>Note: When using byte access to register TTTMK it is recommended to first disable the time mark compare function (TTOCN.TMC = "00") to avoid compares on inconsistent register values.</i> 0000 _H Time Mark ... FFFF _H Time Mark

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TICC	22:16	rw	Time Mark Cycle Code Cycle count for which the time mark is valid. 00 _H valid for all cycles 01 _H valid for all cycles 02 _H valid every second cycle at cycle count mod2 = 0 03 _H valid every second cycle at cycle count mod2 = 1 04 _H valid every fourth cycle at cycle count mod4 = 0 ... 07 _H valid every fourth cycle at cycle count mod4 = 3 08 _H valid every eighth cycle at cycle count mod8 = 0 ... 0F _H valid every eighth cycle at cycle count mod8 = 7 10 _H valid every sixteenth cycle at cycle count mod16 = 0 ... 1F _H valid every sixteenth cycle at cycle count mod16 = 15 20 _H valid every thirty-second cycle at cycle count mod32 = 0 ... 3F _H valid every thirty-second cycle at cycle count mod32 = 31 40 _H valid every sixty-fourth cycle at cycle count mod64 = 0 ... 7F _H valid every sixty-fourth cycle at cycle count mod64 = 63
LCKM	31	rh	TT Time Mark Register Locked Always set by a write access to registers TTOCN. Set by write access to register TTTMK when TTOCN.TMC ≠ "00". Reset when the registers have been synchronized into the CAN clock domain. 0 _B Write access to TTTMK enabled 1 _B Write access to TTTMK locked
0	30:23	r	Reserved Shall read 0, shall be written with 0.

TT Interrupt Register 0

The interrupt register for TTCAN related events.

Note: LDMST or SWAPMSK.W instructions should be used only with bit mask enabled for all rwh bits in this register.

The TTCAN function exists only on CAN0 node 0.

CAN Interface (MCMCAN)

TTIRO

TT Interrupt Register 0

(008320_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0													CER	AW	WT
r													rwh	rwh	rwh
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
IWT	ELC	SE2	SE1	TXO	TXU	GTE	GTD	GTW	SWE	TTMI	RTMI	SOG	CSM	SMC	SBC
rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh

Field	Bits	Type	Description
SBC	0	rwh	Start of Basic Cycle 0 _B No Basic Cycle started since bit has been reset 1 _B Basic Cycle started
SMC	1	rwh	Start of Matrix Cycle 0 _B No Matrix Cycle started since bit has been reset 1 _B Matrix Cycle started
CSM	2	rwh	Change of Synchronization Mode 0 _B No change in master to slave relation or schedule synchronization 1 _B Master to slave relation or schedule synchronization changed, also set when TTOST.SPL is reset
SOG	3	rwh	Start of Gap 0 _B No reference message seen with Next_is_Gap bit set 1 _B Reference message with Next_is_Gap bit set becomes valid
RTMI	4	rwh	Register Time Mark Interrupt Set when time referenced by TTOCN.TMC (cycle, local, or global) equals TTTMK.TM, independent of the synchronization state. 0 _B Time mark not reached 1 _B Time mark reached
TTMI	5	rwh	Trigger Time Mark Event Internal Internal time mark events are configured by trigger memory element TMIN. Set when the trigger memory element becomes active, and the M_CAN is in synchronization state In_Gap or In_Schedule. 0 _B Time mark not reached 1 _B Time mark reached (Level 0: cycle time TTOCF.IRTO · 0x200)
SWE	6	rwh	Stop Watch Polarity 0 _B No rising/falling edge at stop watch trigger detected 1 _B Rising/falling edge at stop watch trigger detected

CAN Interface (MCMCAN)

Field	Bits	Type	Description
GTW	7	rwh	Global Time Wrap 0 _B No global time wrap occurred 1 _B Global time wrap from 0xFFFF to 0x0000 occurred
GTD	8	rwh	Global Time Discontinuity 0 _B No discontinuity of global time 1 _B Discontinuity of global time
GTE	9	rwh	Global Time Error Synchronization deviation SD exceeds limit specified by TTOCF.LDSDL, TTCAN Level 0,2 only. 0 _B Synchronization deviation within limit 1 _B Synchronization deviation exceeded limit
TXU	10	rwh	Tx Count Underflow 0 _B Number of Tx Trigger as expected 1 _B Less Tx trigger than expected in one matrix cycle
TXO	11	rwh	Tx Count Overflow 0 _B Number of Tx Trigger as expected 1 _B More Tx trigger than expected in one matrix cycle
SE1	12	rwh	Scheduling Error 1 0 _B No scheduling error 1 1 _B Scheduling error 1 occurred
SE2	13	rwh	Scheduling Error 2 0 _B No scheduling error 2 1 _B Scheduling error 2 occurred
ELC	14	rwh	Error Level Changed Not set when error level changed during initialization. 0 _B No change in error level 1 _B Error level changed
IWT	15	rwh	Initialization Watch Trigger The initialization is restarted by resetting IWT. 0 _B No missing reference message during system startup 1 _B No system startup due to missing reference message
WT	16	rwh	Watch Trigger 0 _B No missing reference message 1 _B Missing reference message (Level 0: cycle time 0xFF00)
AW	17	rwh	Application Watchdog 0 _B Application watchdog served in time 1 _B Application watchdog not served in time

CAN Interface (MCMCAN)

Field	Bits	Type	Description
CER	18	rwh	Configuration Error Trigger out of order. 0 _B No error found in trigger list 1 _B Error found in trigger list
0	31:19	r	Reserved Shall read 0, shall be written with 0.

TT Interrupt Enable 0

The settings in the TT Interrupt Enable register determine which status changes in the TT Interrupt Register will result in an interrupt.

R = Read, W = Write; -n = value after reset

TTIE0

TT Interrupt Enable 0

(008324_H)Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0													CERE	AWE	WTE
r													rw	rw	rw
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
IWTE	ELCE	SE2E	SE1E	TXOE	TXUE	GTEE	GTDE	GTWE	SWEE	TTMIE	RTMIE	SOG	CSME	SMCE	SBCE
rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Field	Bits	Type	Description
SBCE	0	rw	Start of Basic Cycle Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
SMCE	1	rw	Start of Matrix Cycle Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
CSME	2	rw	Change of Synchronization Mode Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
SOG	3	rw	Start of Gap Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
RTMIE	4	rw	Register Time Mark Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TTMIE	5	rw	Trigger Time Mark Event Internal Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
SWEE	6	rw	Stop Watch Polarity Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
GTWE	7	rw	Global Time Wrap Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
GTDE	8	rw	Global Time Discontinuity Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
GTEE	9	rw	Global Time Error Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
TXUE	10	rw	Tx Count Underflow Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
TXOE	11	rw	Tx Count Overflow Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
SE1E	12	rw	Scheduling Error 1 Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
SE2E	13	rw	Scheduling Error 2 Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
ELCE	14	rw	Change Error Level Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
IWTE	15	rw	Initialization Watch Trigger Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled

CAN Interface (MCMCAN)

Field	Bits	Type	Description
WTE	16	rw	Watch Trigger Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
AWE	17	rw	Application Watchdog Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
CERE	18	rw	Configuration Error Interrupt Enable 0 _B TT interrupt disabled 1 _B TT interrupt enabled
0	31:19	r	Reserved Shall read 0, shall be written with 0.

TT Operation Status 0

R = Read, P = Protected write; -n = value after reset

The TTCAN function exists only on CAN0 node 0.

TTOST0

TT Operation Status 0

(00832C_H)Application Reset Value: 2000 0080_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
SPL	WECS	AWE	WFE	GSI	TMP			GFI	WGTD	0					
rh	rh	rh	rh	rh	rh			rh	rh	r					
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RTO								QCS	QGTP	SYS	MS		EL		
rh								rh	rh	rh	rh		rh		rh

Field	Bits	Type	Description
EL	1:0	rh	Error Level 00 _B Severity 0 - No Error 01 _B Severity 1 - Warning 10 _B Severity 2 - Error 11 _B Severity 3 - Severe Error
MS	3:2	rh	Master State 00 _B Master_Off, no master properties relevant 01 _B Operating as Time Slave 10 _B Operating as Backup Time Master 11 _B Operating as current Time Master

CAN Interface (MCMCAN)

Field	Bits	Type	Description
SYS	5:4	rh	Synchronization State 00 _B Out of Synchronization 01 _B Synchronizing to TTCAN communication 10 _B Schedule suspended by Gap (In_Gap) 11 _B Synchronized to schedule (In_Schedule)
QGTP	6	rh	Quality of Global Time Phase Only relevant in TTCAN Level 0 and Level 2, otherwise fixed to '0'. 0 _B Global time not valid 1 _B Global time in phase with Time Master
QCS	7	rh	Quality of Clock Speed Only relevant in TTCAN Level 0 and Level 2, otherwise fixed to '1'. 0 _B Local clock speed not synchronized to Time Master clock speed 1 _B Synchronization Deviation ≤ SDL
RTO	15:8	rh	Reference Trigger Offset The Reference Trigger Offset value is a signed integer with a range from -127 (0x81) to 127 (0x7F). There is no notification when the lower limit of -127 is reached. In case the M_CAN becomes Time Master (MS[1:0] = "11"), the reset of RTO is delayed due to synchronization between Host and CAN clock domain. For time slaves the value configured by TTOCF.IRTH is read. Actual Reference Trigger offset value
WGTD	22	rh	Wait for Global Time Discontinuity 0 _B No global time preset pending 1 _B Node waits for the global time preset to take effect. The bit is reset when the node has transmitted a reference message with Disc_Bit = '1' or after it received a reference message.
GFI	23	rh	Gap Finished Indicator Set when the CPU writes TTOCN.FGP, or by a time mark interrupt if TMG = '1', or via event trigger input if TTOCN.GCS = '1'. Not set by Ref_Trigger_Gap or when Gap is finished by another node sending a reference message. 0 _B Reset at the end of each reference message 1 _B Gap finished by M_CAN
TMP	26:24	rh	Time Master Priority 000 _B Priority of actual Time Master ... 111 _B Priority of actual Time Master
GSI	27	rh	Gap Started Indicator 0 _B No Gap in schedule, reset by each reference message and for all time slaves 1 _B Gap time after Basic Cycle has started
WFE	28	rh	Wait for Event 0 _B No Gap announced, reset by a reference message with Next_is_Gap = '0' 1 _B Reference message with Next_is_Gap = '1' received

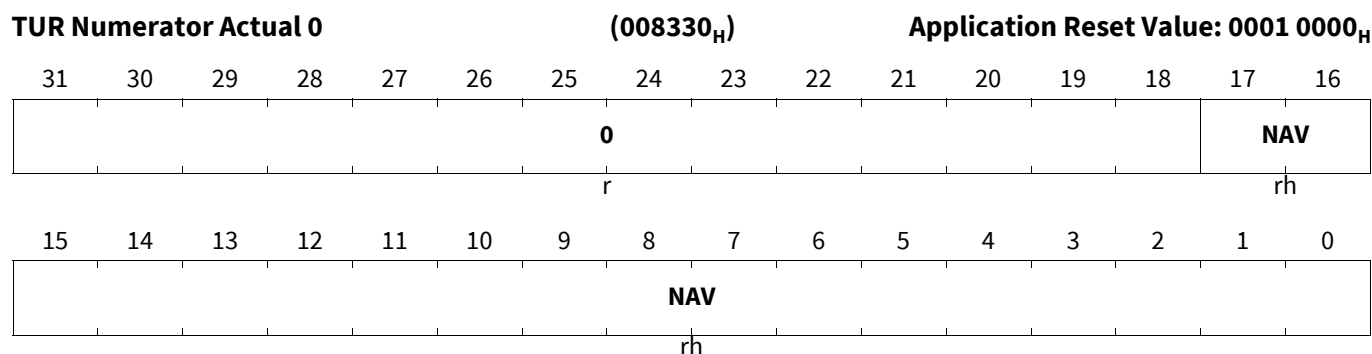
CAN Interface (MCMCAN)

Field	Bits	Type	Description
AWE	29	rh	Application Watchdog Event The application watchdog is served by reading TTOST. When the watchdog is not served in time, bit AWE is set, all TTCAN communication is stopped, and the M_CAN is set into Bus Monitoring Mode. 0 _B Application Watchdog served in time 1 _B Failed to serve Application Watchdog in time
WECS	30	rh	Wait for External Clock Synchronization 0 _B No external clock synchronization pending 1 _B Node waits for external clock synchronization to take effect. The bit is reset at the start of the next basic cycle.
SPL	31	rh	Schedule Phase Lock The bit is valid only when external synchronization is enabled (TTOCN.ESCN = '1'). In this case it signals that the difference between cycle time configured by TTGTP.CTP and the cycle time at the rising edge at the event trigger is less or equal 9 NTU. 0 _B Phase outside range 1 _B Phase inside range
0	21:16	r	Reserved Shall read 0, shall be written with 0.

TUR Numerator Actual 0

The TTCAN function exists only on CAN0 node 0.

There is no drift compensation in TTCAN Level 1 (NAV = NC). In TTCAN Level 0 and Level 2, the drift between the node's local clock and the time master's local clock is calculated. The drift is compensated when the Synchronisation Deviation (difference between NC and the calculated NAV) is not more than $2^{(TTOCF.LDSDL + 5)}$. With $TTOCF.LDSDL \leq 7$, this results in a maximum range for NAV of $(NC - 0x1000) \leq NAV \leq (NC + 0x1000)$.

TURNAO

Field	Bits	Type	Description
NAV	17:0	rh	Numerator Actual Value 0F000 _H Actual numerator value ... 20FFF _H Actual numerator value others , Illegal value

CAN Interface (MCMCAN)

Field	Bits	Type	Description
0	31:18	r	Reserved Shall read 0, shall be written with 0.

TT Local & Global Time 0

The TTCAN function exists only on CAN0 node 0.

TTLGT0

TT Local & Global Time 0 (008334_H) **Application Reset Value: 0000 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
GT															
rh															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
LT															
rh															

Field	Bits	Type	Description
LT	15:0	rh	Local Time Non-fractional part of local time, incremented once each local NTU. Local time value of TTCAN node
GT	31:16	rh	Global Time Non-fractional part of the sum of the node's local time and its local offset. Global time value of TTCAN network

TT Cycle Time & Count 0

The TTCAN function exists only on CAN0 node 0.

TTCTC0

TT Cycle Time & Count 0 (008338_H) **Application Reset Value: 003F 0000_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0										CC					
r										rh					
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CT															
rh															

Field	Bits	Type	Description
CT	15:0	rh	Cycle Time Non-fractional part of the difference of the node's local time and Ref_Mark. Cycle time value of TTCAN Basic Cycle

CAN Interface (MCMCAN)

Field	Bits	Type	Description
CC	21:16	rh	Cycle Count Number of actual Basic Cycle in the System Matrix
0	31:22	r	Reserved Shall read 0, shall be written with 0.

TT Capture Time 0

The TTCAN function exists only on CAN0 node 0.

TTCPT0

TT Capture Time 0 (00833C_H) Application Reset Value: 0000 0000_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
SWV															
rh															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0										CCV					
r										rh					

Field	Bits	Type	Description
CCV	5:0	rh	Cycle Count Value Cycle count value captured together with SWV. Captured cycle count value
SWV	31:16	rh	Stop Watch Value On a rising/falling edge (as configured via TTOCN.SWP) at the Stop Watch Trigger, when TTOCN.SWS is ≠ "00" and TTIR.SWE is '0', the actual time value as selected by TTOCN.SWS (cycle, local, global) is copied to SWV and TTIR.SWE will be set to '1'. Capturing of the next stop watch value is enabled by resetting TTIR.SWE. Captured Stop Watch value
0	15:6	r	Reserved Shall read 0, shall be written with 0.

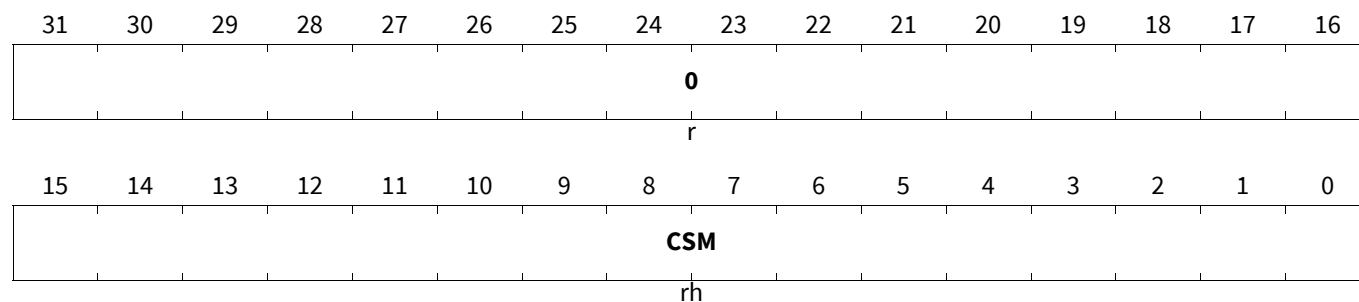
TT Cycle Sync Mark 0

The TTCAN function exists only on CAN0 node 0.

CAN Interface (MCMCAN)

TTCSM0

TT Cycle Sync Mark 0

(008340_H)Application Reset Value: 0000 0000_H

Field	Bits	Type	Description
CSM	15:0	rh	Cycle Sync Mark The Cycle Sync Mark is measured in cycle time. It is updated when the reference message becomes valid and retains its value until the next reference message becomes valid. Captured cycle time
0	31:16	r	Reserved Shall read 0, shall be written with 0.

CAN Interface (MCMCAN)

40.4.6 Message RAM

M_CAN

40.4.6.1 Message RAM Configuration

When operated in CAN FD mode the required Message RAM size strongly depends on the element size configured for Rx FIFO0, Rx FIFO1, Rx Buffers, and Tx Buffers via RXESCI.F0DS, RXESCI.F1DS, RXESCI.RBDS, and TXESCI.TBDS.

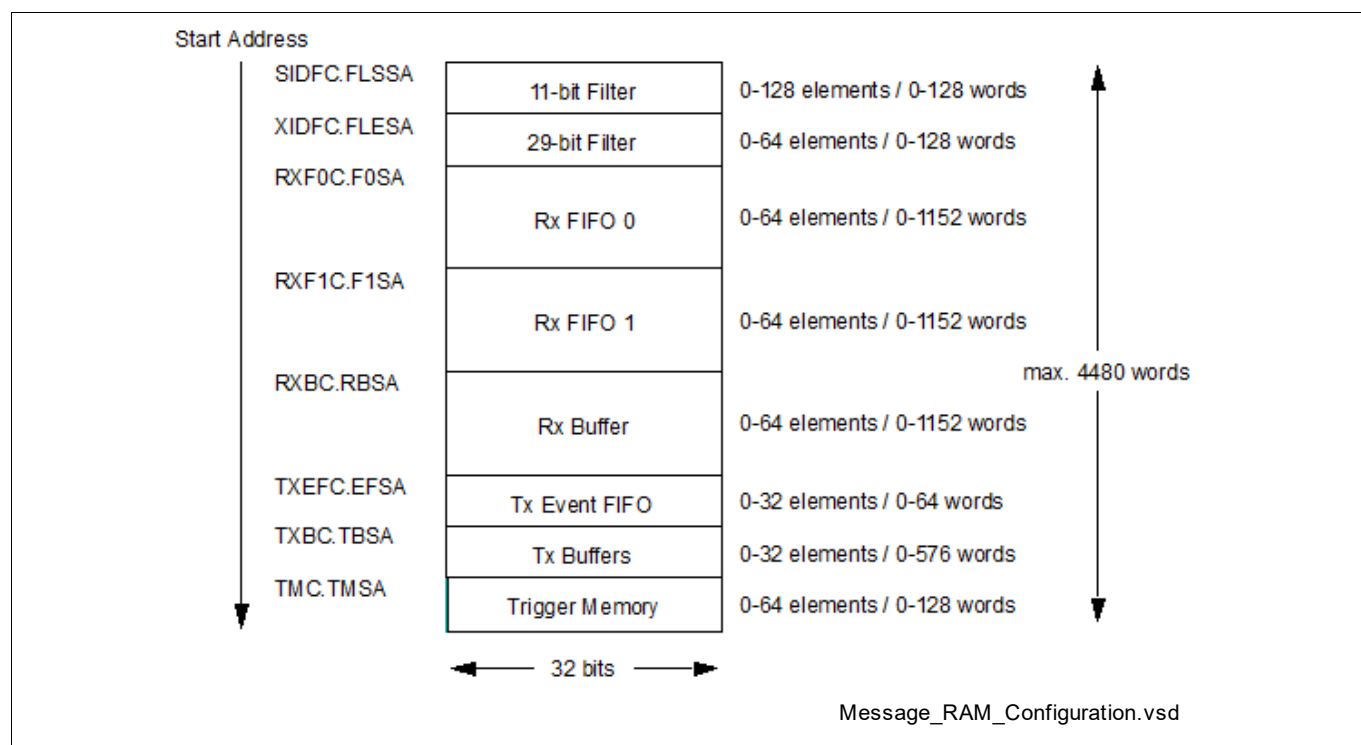


Figure 605 Message RAM Configuration

When the M_CAN addresses the Message RAM it addresses 32-bit words, not single bytes. The configurable start addresses are 32-bit word addresses i.e. only bits 15 to 2 are evaluated, the two least significant bits are ignored.

CAN Interface (MCMCAN)

40.4.6.2 Rx Buffer and FIFO Element

Up to 64 Rx Buffers and two Rx FIFOs can be configured in the Message RAM. Each Rx FIFO section can be configured to store up to 64 received messages. The structure of a Rx Buffer / FIFO element is shown in [Table 382](#) below. The element size can be configured for storage of CAN FD messages with up to 64 bytes data field via register RXESCI.

Table 382 Message Layout - Rx Buffer and FIFO Element

	3	2	2	1	1	8	7	0
	1	4	3	6	5			
R0	ESI	XTD	RTR	ID[28:0]				
R1	ANMF	FIDX[6:0]		0	EDF	BRS	DLC[3:0]	RXTS[15:0]
R2	DB3[7:0]		DB2[7:0]		DB1[7:0]		DB0[7:0]	
R3	DB7[7:0]		DB6[7:0]		DB5[7:0]		DB4[7:0]	
...	
Rn	DBm[7:0]		DBm-1[7:0]		DBm-2[7:0]		DBm-3[7:0]	

Register 0

See Message layout, [Table 382](#).

See Message layout.

RxMsgk_R0 (k=0-63)**Register 0****(000000_H + k*48_H)****Application Reset Value: XXXX XXXX_H**

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
ESI	XTD	RTR	ID												
rwh	rwh	rwh	rwh												
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID															
rwh															

Field	Bits	Type	Description
ID	28:0	rwh	Identifier Standard or extended identifier depending on bit XTD. A standard identifier is stored into ID[28:18].

CAN Interface (MCMCAN)

Field	Bits	Type	Description
RTR	29	rwh	Remote Transmission Request Signals to the Host whether the received frame is a data frame or a remote frame. <i>Note:</i> There are no remote frames in CAN FD format. In case a CAN FD frame was received ($FDF = 1$), bit RTR reflects the state of the reserved bit r1. 0_B Received frame is a data frame 1_B Received frame is a remote frame
XTD	30	rwh	Extended Identifier Signals to the Host whether the received frame has a standard or extended identifier. 0_B 11-bit standard identifier 1_B 29-bit extended identifier
ESI	31	rwh	Error State Indicator 0_B Transmitting node is error active 1_B Transmitting node is error passive

Register 1See Message layout, [Table 382](#).

See Message layout.

RxMsgk_R1 (k=0-63)**Register 1** $(000004_H + k \cdot 48_H)$ Application Reset Value: XXXX XXXX_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
ANMF				FIDX				0		FDF	BRS			DLC	
rwh				rwh				rwh		rwh	rwh			rwh	
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
								RXTS							
								rwh							

Field	Bits	Type	Description
RXTS	15:0	rwh	Rx Timestamp Timestamp Counter value captured on start of frame reception. Resolution depending on configuration of the Timestamp Counter Prescaler TSCC.TCP.

CAN Interface (MCMCAN)

Field	Bits	Type	Description
DLC	19:16	rwh	Data Length Code 0_H CAN + CAN FD: received frame has 0 data bytes ... 8_H CAN + CAN FD: received frame has 8 data bytes 9_H CAN FD: received frame has 12 ($9 \times 4 - 24$) data bytes CAN: received frame has 8 data bytes ... C_H CAN FD: received frame has 24 ($12 \times 4 - 24$) data bytes CAN: received frame has 8 data bytes D_H CAN FD: received frame has 32 ($13 \times 16 - 176$) data bytes CAN: received frame has 8 data bytes ... F_H CAN FD: received frame has 64 ($15 \times 16 - 176$) data bytes CAN: received frame has 8 data bytes
BRS	20	rwh	Bit Rate Switch 0_B Frame received without bit rate switching 1_B Frame received with bit rate switching
FDF	21	rwh	Frame Data Format 0_B Standard frame format 1_B CAN FD frame format (new DLC-coding and CRC)
FIDX	30:24	rwh	Filter Index 00_H Index of matching Rx acceptance filter element (invalid if ANMF = '1'). Range is 0 to SIDFC.LSS - 1 resp. XIDFC.LSE - 1. ... $7F_H$ Index of matching Rx acceptance filter element (invalid if ANMF = '1'). Range is 0 to SIDFC.LSS - 1 resp. XIDFC.LSE - 1.
ANMF	31	rwh	Accepted Non-matching Frame Acceptance of non-matching frames may be enabled via GFC.ANFS and GFC.ANFE. 0_B Received frame matching filter index FIDX 1_B Received frame did not match any Rx filter element
0	23:22	rwh	Reserved Shall read 0, shall be written with 0.

Data Byte m

RxMsgk_DBm ($k=0-63; m=0-63$)

Data Byte m	(000008 _H +k*48 _H +m)				Application Reset Value: XX _H		
7	6	5	4	3	2	1	0
DB							
rwh							

CAN Interface (MCMCAN)

Field	Bits	Type	Description
DB	7:0	rwh	Data Byte m

Note: Depending on the configuration of the element size (RXESC), between two and sixteen 32-bit words ($Rn = 3 \dots 17$) are used for storage of a CAN message's data field.

40.4.6.3 Tx Buffer Element

The Tx Buffers section can be configured to hold dedicated Tx Buffers as well as a Tx FIFO / Tx Queue. In case that the Tx Buffers section is shared by dedicated Tx buffers and a Tx FIFO / Tx Queue, the dedicated Tx Buffers start at the beginning of the Tx Buffers section followed by the buffers assigned to the Tx FIFO or Tx Queue. The Tx Handler distinguishes between dedicated Tx Buffers and Tx FIFO / Tx Queue by evaluating the Tx Buffer configuration TXBCi.TFQS and TXBCi.NDTB. The element size can be configured for storage of CAN FD messages with up to 64 bytes data field via register TXESCi.

Table 383 Message Layout - Tx Buffer Element

	3 1	2 4	2 3	1 6	1 5	8 7	0
T0	0	XTD	RTR	ID[28:0]			
T1	MM[7:0]		EFC	0	FDL	BRS	DLC[3:0]
T2	DB3[7:0]		DB2[7:0]		DB1[7:0]		DB0[7:0]
T3	DB7[7:0]		DB6[7:0]		DB5[7:0]		DB4[7:0]
...
Tn	DBm[7:0]		DBm-1[7:0]		DBm-2[7:0]		DBm-3[7:0]

Transmit Buffer 0

See Message layout.

TxMsgk_T0 (k=0-31)

Transmit Buffer 0

 $(000000_H + k \cdot 48_H)$
Application Reset Value: XXXX XXXX_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
ESI	XTD	RTR	ID												
rw	rw	rw	rw												
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID															
rw															

Field	Bits	Type	Description
ID	28:0	rw	Identifier Standard or extended identifier depending on bit XTD. A standard identifier has to be written to ID[28:18].

CAN Interface (MCMCAN)

Field	Bits	Type	Description
RTR	29	rw	Remote Transmission Request <i>Note:</i> When $RTR = 1$, the M_CAN transmits a remote frame according to ISO11898-1, even if $CCCR.FDOE$ enables the transmission in CAN FD format. 0_B Transmit data frame 1_B Transmit remote frame
XTD	30	rw	Extended Identifier 0_B 11-bit standard identifier 1_B 29-bit extended identifier
ESI	31	rw	Error State Indicator <i>Note:</i> The ESI bit of the transmit buffer is OR'ed with the error passive flag to decide the value of the ESI bit in the transmitted FD frame. As required by the CAN FD protocol specification, an error active node may optionally transmit the ESI bit recessive, but an error passive node will always transmit the ESI bit recessive. 0_B ESI bit in CAN FD format depends only on error passive flag 1_B ESI bit in CAN FD format transmitted recessive

Transmit Buffer 1

See Message layout.

TxMsgk_T1 (k=0-31)

Transmit Buffer 1

(000004_H+k*48_H)Application Reset Value: XXXX XXXX_H

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
MM								EFC	0	FDF	BRS	DLC			
rw								rw	rw	rw	rw	rw			
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0															
rw															

CAN Interface (MCMCAN)

Field	Bits	Type	Description
DLC	19:16	rw	Data Length Code 0_H CAN + CAN FD: received frame has 0 data bytes ... 8_H CAN + CAN FD: received frame has 8 data bytes 9_H CAN FD: received frame has 12 ($9 \times 4 - 24$) data bytes CAN: received frame has 8 data bytes ... C_H CAN FD: received frame has 24 ($12 \times 4 - 24$) data bytes CAN: received frame has 8 data bytes D_H CAN FD: received frame has 32 ($13 \times 16 - 176$) data bytes CAN: received frame has 8 data bytes ... F_H CAN FD: received frame has 64 ($15 \times 16 - 176$) data bytes CAN: received frame has 8 data bytes
BRS	20	rw	Bit Rate Switching <i>Note: Bits ESI, FDF, and BRS are only evaluated when CAN FD operation is enabled $CCCR.FDOE = 1$. Bit BRS is only evaluated when in addition $CCCR.BRSE = 1$.</i> 0_B CAN FD frames transmitted without bit rate switching 1_B CAN FD frames transmitted with bit rate switching
FDF	21	rw	FD Format 0_B Frame transmitted in Classical CAN format 1_B Frame transmitted in CAN FD format
EFC	23	rw	Event FIFO Control 0_B Don't store Tx events 1_B Store Tx events
MM	31:24	rw	Message Marker Written by CPU during Tx Buffer configuration. Copied into Tx Event FIFO element for identification of Tx message status.
0	15:0, 22	rw	Reserved Shall read 0, shall be written with 0.

Data Byte m

TxMsgk_DBm ($k=0-31; m=0-63$)

Data Byte m	($000008_H + k \times 48_H + m$)	Application Reset Value: XX_H
7 6 5 4 3 2 1 0		
DB		
rw		

Field	Bits	Type	Description
DB	7:0	rw	Data Byte m

CAN Interface (MCMCAN)

Note: Depending on the configuration of the element size (TXESC), between two and sixteen 32-bit words ($T_n = 3 \dots 17$) are used for storage of a CAN message's data field.

40.4.6.4 Tx Event FIFO Element

Each element stores information about transmitted messages. By reading the Tx Event FIFO the Host CPU gets this information in the order the messages were transmitted. Status information about the Tx Event FIFO can be obtained from register TXEFS.

Table 384 Message Layout - Tx Event FIFO Element

	3	2	2	1	1	8	7	0
	1	4	3	6	5			
E0	ESI	XTD	RTR	ID[28:0]				
E1	MM[7:0]			ET [1:0]	EDF BRS	DLC[3:0]	TXTS[15:0]	

Event 0

See Message layout.

TxEventk_E0 (k=0-31)

Event 0										(000000 _H + k*8)						Application Reset Value: XXXX XXXX _H					
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16						
ESI	XTD	RTR	ID																		
rwh	rwh	rwh	rwh																		
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0						
ID																					
rwh																					

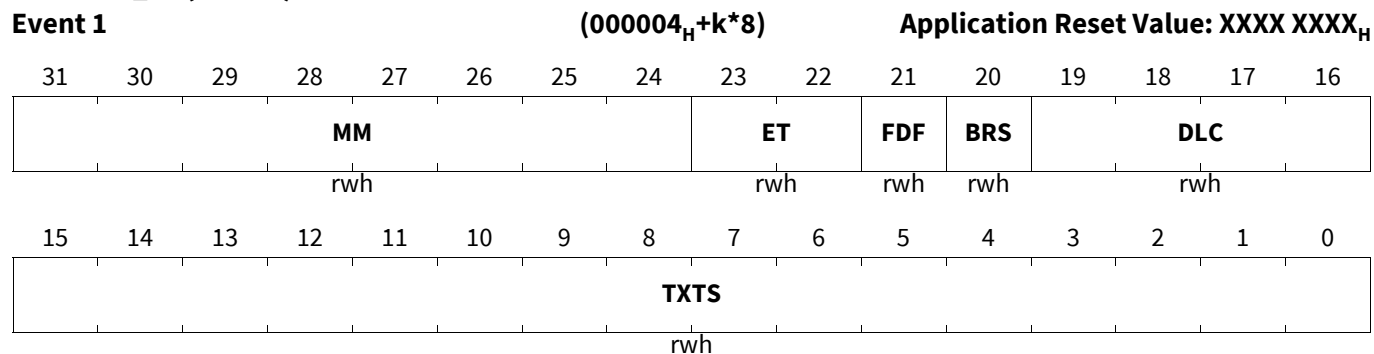
Field	Bits	Type	Description
ID	28:0	rwh	Identifier Standard or extended identifier depending on bit XTD. A standard identifier is stored into ID[28:18].
RTR	29	rwh	Remote Transmission Request 0 _B Data frame transmitted 1 _B Remote frame transmitted
XTD	30	rwh	Extended Identifier 0 _B 11-bit standard identifier 1 _B 29-bit extended identifier
ESI	31	rwh	Error State Indicator 0 _B Transmitting node is error active 1 _B Transmitting node is error passive

Event 1

See Message layout.

CAN Interface (MCMCAN)

TxEventk_E1 (k=0-31)



Field	Bits	Type	Description
TXTS	15:0	rwh	Tx Timestamp Timestamp Counter value captured on start of frame transmission. Resolution depending on configuration of the Timestamp Counter Prescaler TSCC.TCP.
DLC	19:16	rwh	Data Length Code 0 _H CAN + CAN FD: received frame has 0 data bytes ... 8 _H CAN + CAN FD: received frame has 8 data bytes 9 _H CAN FD: received frame has 12 (9*4-24) data bytes CAN: received frame has 8 data bytes ... C _H CAN FD: received frame has 24 (12*4-24) data bytes CAN: received frame has 8 data bytes D _H CAN FD: received frame has 32 (13*16-176) data bytes CAN: received frame has 8 data bytes ... F _H CAN FD: received frame has 64 (15*16-176) data bytes CAN: received frame has 8 data bytes
BRS	20	rwh	Bit Rate Switch 0 _B Frame transmitted without bit rate switching 1 _B Frame transmitted with bit rate switching
FDF	21	rwh	FD Format 0 _B Standard frame format 1 _B CAN FD frame format (new DLC-coding and CRC)
ET	23:22	rwh	Event Type 00 _B Reserved 01 _B Tx event 10 _B Transmission in spite of cancellation (always set for transmissions in DAR mode) 11 _B Reserved
MM	31:24	rwh	Message Marker Copied from Tx Buffer into Tx Event FIFO element for identification of Tx message status.

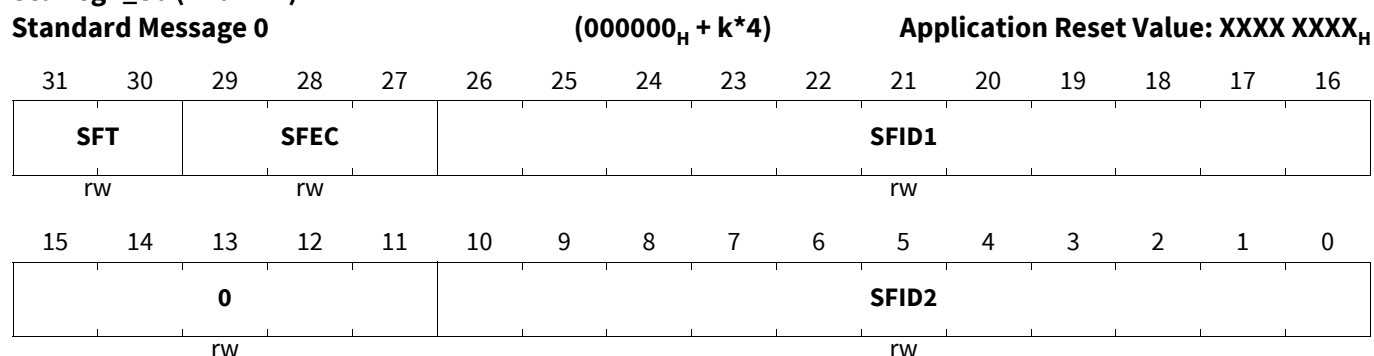
CAN Interface (MCMCAN)

40.4.6.5 Standard Message ID Filter Element

Up to 128 filter elements can be configured for 11-bit standard IDs. When accessing a Standard Message ID Filter element, its address is the Filter List Standard Start Address SIDFCi.FLSSA plus the index of the filter element (0...127).

Standard Message 0

StdMsgk_S0 (k=0-127)



Field	Bits	Type	Description
SFID2	10:0	rw	Standard Filter ID 2 This bit field has a different meaning depending on the configuration of SFEC: 1) SFEC = "001"...110" Second ID of standard ID filter element 2) SFEC = "111" Filter for Rx Buffers or for debug messages SFID2[5:0] defines the offset to the Rx Buffer Start Address RXBC.RBSA for storage of a matching message. SFID2[8:6] is used to control the filter event pins. A one at the respective bit position enables generation of a pulse at the related filter event pin with the duration of one host clock period in case the filter matches. SFID2[10:9] decides whether the received message is stored into an Rx Buffer or treated as message A, B, or C of the debug message sequence. 000 _H Store message into an Rx Buffer ... 1FF _H Store message into an Rx Buffer 200 _H Debug Message A ... 3FF _H Debug Message A 400 _H Debug Message B ... 5FF _H Debug Message B 600 _H Debug Message C ... 7FF _H Debug Message C

CAN Interface (MCMCAN)

Field	Bits	Type	Description
SFID1	26:16	rw	Standard Filter ID 1 First ID of standard ID filter element. When filtering for Rx Buffers or for debug messages this field defines the ID of a standard message to be stored. The received identifiers must match exactly, no masking mechanism is used.
SFEC	29:27	rw	Standard Filter Element Configuration All enabled filter elements are used for acceptance filtering of standard frames. Acceptance filtering stops at the first matching enabled filter element or when the end of the filter list is reached. If SFEC = "100", "101" or "110", a match sets interrupt flag IR.HPM and, if enabled, an interrupt is generated. In this case register HPMS is updated with the status of the priority match. 000 _B Disable filter element 001 _B Store in Rx FIFO 0 if filter matches 010 _B Store in Rx FIFO 1 if filter matches 011 _B Reject ID if filter matches 100 _B Set priority if filter matches 101 _B Set priority and store in FIFO 0 if filter matches 110 _B Set priority and store in FIFO 1 if filter matches 111 _B Store into Rx Buffer or as debug message, configuration of SFT[1:0] ignored
SFT	31:30	rw	Standard Filter Type <i>Note: With SFT = "11" the filter element is disabled and the acceptance filtering continues (same behaviour as with SFEC = "000")</i> 00 _B Range filter from SF1ID to SF2ID (SF2ID ≥ SF1ID) 01 _B Dual ID filter for SF1ID or SF2ID 10 _B Classic filter: SF1ID = filter, SF2ID = mask 11 _B Filter element disabled
0	15:11	rw	Reserved Shall read 0, shall be written with 0.

40.4.6.6 Extended Message ID Filter Element

Up to 64 filter elements can be configured for 29-bit extended IDs. When accessing an Extended Message ID Filter element, its address is the Filter List Extended Start Address XIDFCi.FLESA plus two times the index of the filter element (0...63).

Table 385 Message Layout - Extended Message ID Filter Element

3	2	2	1	1	8	7	0
1	4	3	6	5			

CAN Interface (MCMCAN)

Table 385 Message Layout - Extended Message ID Filter Element (cont'd)

F0	EFEC[2:0]	EFID1[28:0]
F1	EFT[1:0] 0	EFID2[28:0]

Filter Element 0

See Message layout.

ExtMsgk_F0 (k=0-63)

Filter Element 0 (000000 _H + k*8)										Application Reset Value: XXXX XXXX _H					
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
EFEC			EFID1												
rw			rw												
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
EFID1															
rw															

Field	Bits	Type	Description
EFID1	28:0	rw	Extended Filter ID 1 First ID of extended ID filter element. When filtering for Rx Buffers or for debug messages this field defines the ID of an extended message to be stored. The received identifiers must match exactly, only XIDAMi masking mechanism is used.
EFEC	31:29	rw	Extended Filter Element Configuration All enabled filter elements are used for acceptance filtering of extended frames. Acceptance filtering stops at the first matching enabled filter element or when the end of the filter list is reached. If EFEC = "100", "101" or "110", a match sets interrupt flag IR.HPM and, if enabled, an interrupt is generated. In this case register HPMS is updated with the status of the priority match. 000 _B Disable filter element 001 _B Store in Rx FIFO 0 if filter matches 010 _B Store in Rx FIFO 1 if filter matches 011 _B Reject ID if filter matches 100 _B Set priority if filter matches 101 _B Set priority and store in FIFO 0 if filter matches 110 _B Set priority and store in FIFO 1 if filter matches 111 _B Store into Rx Buffer or as debug message, configuration of EFT[1:0] ignored

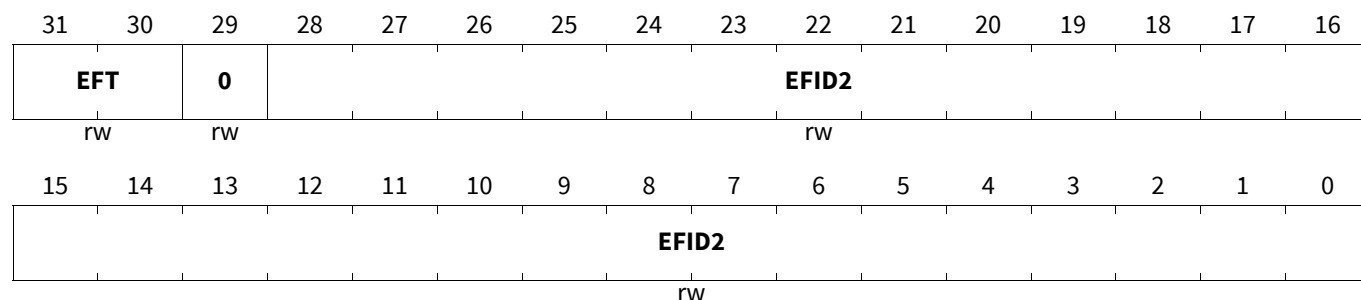
Filter Element 1

See Message layout.

CAN Interface (MCMCAN)

ExtMsgk_F1 (k=0-63)

Filter Element 1

(000004_H+k*8)Application Reset Value: XXXX XXXX_H

Field	Bits	Type	Description
EFID2	28:0	rw	Extended Filter ID 2 This bit field has a different meaning depending on the configuration of EFEC: 1) EFEC = "001"...110" Second ID of extended ID filter element 2) EFEC = "111" Filter for Rx Buffers or for debug messages EFID2[5:0] defines the offset to the Rx Buffer Start Address RXBC.RBSA for storage of a matching message. EFID2[8:6] is used to control the filter event. A one at the respective bit position enables generation of a pulse at the related filter event pin with the duration of one host clock period in case the filter matches. EFID2[10:9] decides whether the received message is stored into an Rx Buffer or treated as message A, B, or C of the debug message sequence. 00000000 _H Store message into an Rx Buffer ... 000001FF _H Store message into an Rx Buffer 00000200 _H Debug Message A ... 000003FF _H Debug Message A 00000400 _H Debug Message B ... 000005FF _H Debug Message B 00000600 _H Debug Message C ... 000007FF _H Debug Message C
EFT	31:30	rw	Extended Filter Type 00 _B Range filter from EF1ID to EF2ID (EF2ID ≥ EF1ID) 01 _B Dual ID filter for EF1ID or EF2ID 10 _B Classic filter: EF1ID = filter, EF2ID = mask 11 _B Range filter from EF1ID to EF2ID (EF2ID ≥ EF1ID), XIDAM mask not applied
0	29	rw	Reserved Shall read 0, shall be written with 0

CAN Interface (MCMCAN)

40.4.6.7 Trigger Memory Element

Up to 64 trigger memory elements can be configured. When accessing a Trigger Memory element, its address is the Trigger Memory Start Address TTTMC.TMSA plus the index of the trigger memory element (0...63)

Table 386 Message Layout - Trigger Memory Element

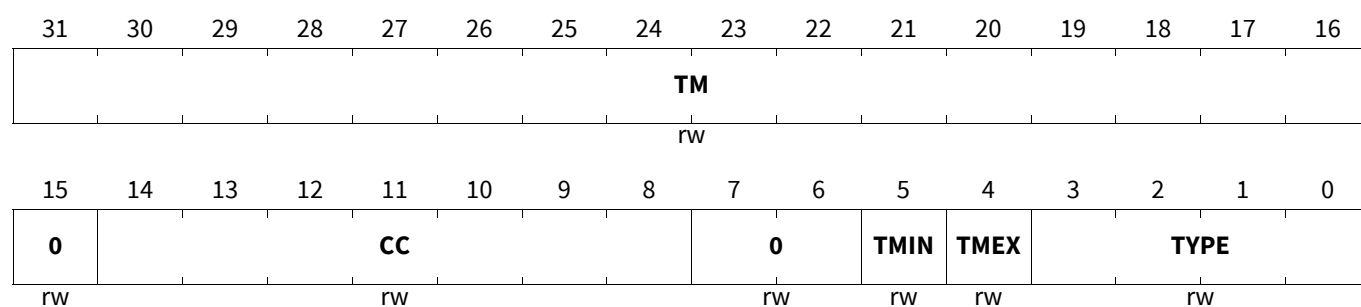
	3 1			1 6	1 5	8	7	0			
T M 0	TM[15:0]				0	CC[6:0]		0	TMIN	TMEX	TYPE[3:0]
T M 1	0	FTYPE	MNR[6:0]		0						MSC [2:0]

Trigger Memory Element 0

See Message layout, see Trigger Memory Element Overview.

TrigMsgk_TM0 (k=0-63)

Trigger Memory Element 0

(000000_H + k*8)Application Reset Value: XXXX XXXX_H

CAN Interface (MCMCAN)

Field	Bits	Type	Description
TYPE	3:0	rw	Trigger Type <i>Note: No ASC implemented. If and only if implemented: For ASC operation (ASC = "10", "11") only trigger types Rx_Trigger and Time_Base_Trigger should be used.</i> 0 _H Tx_Ref_Trigger - valid when not in Gap 1 _H Tx_Ref_Trigger_Gap - valid when in Gap 2 _H Tx_Trigger_Single - starts a single transmission in an exclusive time window 3 _H Tx_Trigger_Continuous - starts continuous transmission in an exclusive time window 4 _H Tx_Trigger_Arbitration - starts a transmission in an arbitrating time window 5 _H Tx_Trigger_Merged - starts a merged arbitration window 6 _H Watch_Trigger - valid when not in Gap 7 _H Watch_Trigger_Gap - valid when in Gap 8 _H Rx_Trigger - check for reception 9 _H Time_Base_Trigger - only control TMIN, TMEX, and ASC Others , End_of_List - illegal type, causes config error
TMEX	4	rw	Time Mark Event External 0 _B No action 1 _B When the time mark of the trigger memory element becomes active and TTOCN.TTMIE = '1'
TMIN	5	rw	Time Mark Event Internal 0 _B No action 1 _B TTIR.TTMI is set when trigger memory element becomes active

CAN Interface (MCMCAN)

Field	Bits	Type	Description
CC	14:8	rw	Cycle Code Cycle count for which the trigger is valid. Ignored for trigger types Tx_Ref_Trigger, Tx_Ref_Trigger_Gap, Watch_Trigger, Watch_Trigger_Gap, End_of_List. 00 _H valid for all cycles 01 _H valid for all cycles 02 _H valid every second cycle at cycle count mod2 = c 03 _H valid every second cycle at cycle count mod2 = c 04 _H valid every fourth cycle at cycle count mod4 = cc ... 07 _H valid every fourth cycle at cycle count mod4 = cc 08 _H valid every eighth cycle at cycle count mod8 = ccc ... 0F _H valid every eighth cycle at cycle count mod8 = ccc 10 _H valid every sixteenth cycle at cycle count mod16 = cccc ... 1F _H valid every sixteenth cycle at cycle count mod16 = cccc 20 _H valid every thirty-second cycle at cycle count mod32 = ccccc ... 3F _H valid every thirty-second cycle at cycle count mod32 = ccccc 40 _H valid every sixty-fourth cycle at cycle count mod64 = cccccc ... 7F _H valid every sixty-fourth cycle at cycle count mod64 = cccccc
TM	31:16	rw	Time Mark Cycle time for which the trigger becomes active.
0	7:6, 15	rw	Reserved Shall read 0, shall be written with 0.

See Message layout, see Trigger Memory Element Overview.

TrigMsgk_TM1 (k=0-63)

(000004 _H +k*8)								PowerOn Reset Value: XXXX XXXX _H							
31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
0								FTYPE	MMR						
rw								rw	rw						
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0												MSC			
rw												rwh			

CAN Interface (MCMCAN)

Field	Bits	Type	Description
MSC	2:0	rwh	<p>Message Status Count Counts scheduling errors for periodic messages in exclusive time windows. It has no function for arbitrating messages and in event-driven CAN communication (ISO11898-1).</p> <p><i>Note:</i> <i>The trigger memory elements have to be written when the M_CAN is in INIT state. Write access to the trigger memory elements outside INIT state is not allowed. There is an exception for TMIN and TMEX when they are defined as part of a trigger memory element of TYPE Tx_Ref_Trigger. In this case they become active at the time mark modified by the actual Reference Trigger Offset (TTOST.RTO).</i></p> <p>000_B Actual status ... 111_B Actual status</p>
MMR	22:16	rw	<p>Message Number Transmission: Trigger is valid for configured Tx Buffer number. Valid values are 0 to 31. Reception: Trigger is valid for standard / extended message ID filter element number. Valid values are 0 to 63 resp. 0 to 127.</p>
FTYPE	23	rw	<p>Filter Type 0_B 11-bit standard message ID 1_B 29-bit extended message ID</p>
0	15:3, 31:24	rw	<p>Reserved Shall read 0, shall be written with 0.</p>