Cornell University

Deparment of Mathematics

Ithaca, NY 14853

⋈ evc34@cornell.edu

in pi.math.cornell.edu/~cartee

Elliot Cartee

Education

- 2014–Present P.h.D., Mathematics, Cornell University, Expected graduation date: May 2020.
 - 2014–2017 M.S., Mathematics, Cornell University.
 - 2011–2014 B.A., Mathematics, Cornell University.

Awards

- 2018-2019 Robert J. Bättig Graduate Prize for Excellent Achievements in Research
- 2011-2014 Pauline and Irving Tanner Dean's Scholar

Research Experience

- 2014–Present Cornell University, Graduate Student, Advisor: Alexander Vladimirsky.
 - Department of Mathematics
 - Fall 2018 **Princeton University**, Visiting Student Research Collaborator.
 - Operations Research and Financial Engineering

Publications

- **E. Cartee and A. Vladimirsky**, *Control-theoretic models of environmental crime*, submitted to SIAM Journal on Applied Mathematics.
- E. Cartee, L. Lai, Q. Song, and A. Vladimirsky, *Time-dependent surveillance-evasion games*, accepted for publication by IEEE CDC 2019.
- **E. Cartee and A. Vladimirsky**, *Anisotropic challenges in pedestrian flow modeling*, Communications in Mathematical Sciences, 16(4), 1067-1093 (2018).
- **L. N. Virgin, R. Plaut, and E. Cartee**, *The effect of gravity on a slender loop structure*, Nonlinear Dynamics, Volume 1 (pp. 185-190). Springer, Cham (2016).
- L. N. Virgin, R. Plaut, and E. Cartee, Adjacent equilibria in highly flexible upright loop on rigid foundation, Experimental Mechanics, 55(6), 1191-1197 (2015).
- **S. Khan, J. Johnson, E. Cartee, and Y. Yao**, *Global regularity of chemotaxis equations with advection*, Involve, a Journal of Mathematics, 9(1), 119-131 (2015).

Presentations

Upcoming Presentations

- October 7th Control-Theoretic Models of Environmental Crime (Poster), 3rd AFOSR Workshop on Computational Control, Monterey, CA.
- Oct. 18-20th Control-Theoretic Models of Environmental Crime, Doctoral Consortium on Computational Sustainability, Carnegie Mellon University.

- October 22nd Modeling Environmental Crime in the Presence of Ground Patrols (Poster), NSF Algorithms for Threat Detection Workshop, George Washington University.
- Dec. 11-13th **Time-dependent Surveillance-Evasion Games**, *IEEE Conference on Decision and Control 2019*, Nice, France.

Past Presentations

- Sept. 2019 **Control-Theoretic Models of Environmental Crime**, *Scientific Computing and Numerical Analysis seminar*, Cornell University.
 - July 2019 **Surveillance-Evasion Mean Field Games**, *International Congress on Industrial and Applied Mathematics*, Valencia, Spain.
- April 2019 **Time-dependent Surveillance-Evasion Games**, *Applied Math Days 2019*, Rensselaer Polytechnic Institute.
- March 2019 **Anisotropic Interactions in Pedestrian Flow Modeling**, New York State Regional Graduate Mathematics Conference, Syracuse University.
- October 2018 **Surveillance-Evasion Mean Field Games**, *NSF Algorithms for Threat Detection Workshop*, American University.
- August 2017 Aniostropic Challenges in Pedestrian Flow Modeling, Mean Field Games Workshop, UCLA (IPAM).
 - April 2015 **Models of Pedestrian Flow**, *Scientific Computing and Numerical Analysis seminar*, Cornell University.

Teaching Experience

Cornell University

- Fall 2019 Head TA, MATH 2940: Linear Algebra for Engineers.
- Spring 2019 **Head TA**, MATH 2930: Differential Equations for Engineers.
- Summer 2018 REU Graduate Student Mentor.
 - Fall 2017 Head TA, MATH 2930: Differential Equations for Engineers.
 - Spring 2017 Instructor, MATH 1110: Calculus I.
 - Fall 2016 **Head TA**, MATH 2930: Differential Equations for Engineers.
 - Spring 2016 TA, MATH 2930: Differential Equations for Engineers.
 - Fall 2015 Grader, MATH 4250: Differential Equations and Numerical Analysis.