

Experiment 2

Blink an LED in the Arduino hardware using Matlab Simulink

Objective:

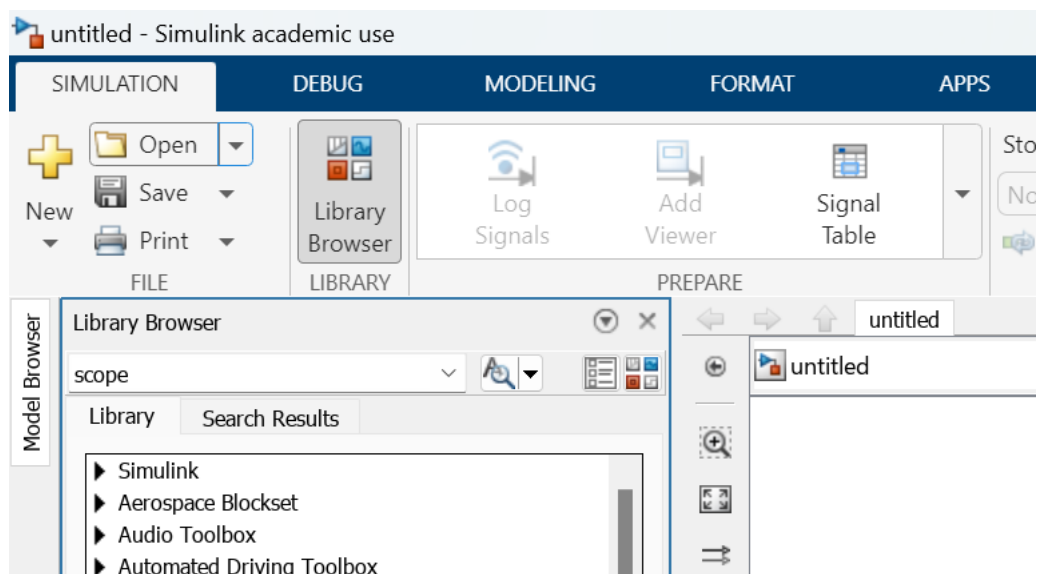
To build and simulate a model for blinking an LED using Matlab Simulink interfaced with Arduino hardware.

Setup Required:

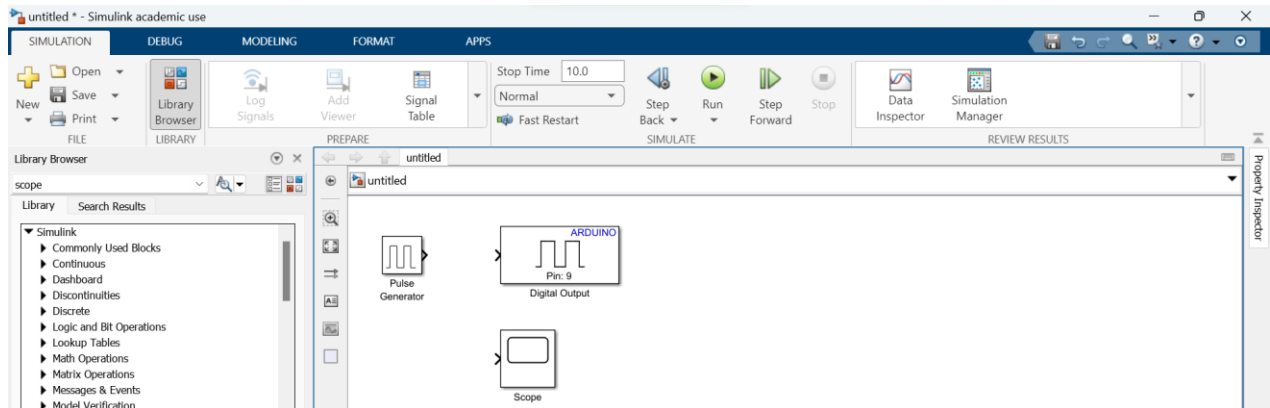
- Matlab software
- Arduino Uno with USB cable – 1 No.
- Breadboard – 1 No.
- Resistor – 220 ohm – 1No.
- LED – 1 No.
- Jumper wires – few Nos.

Procedure:

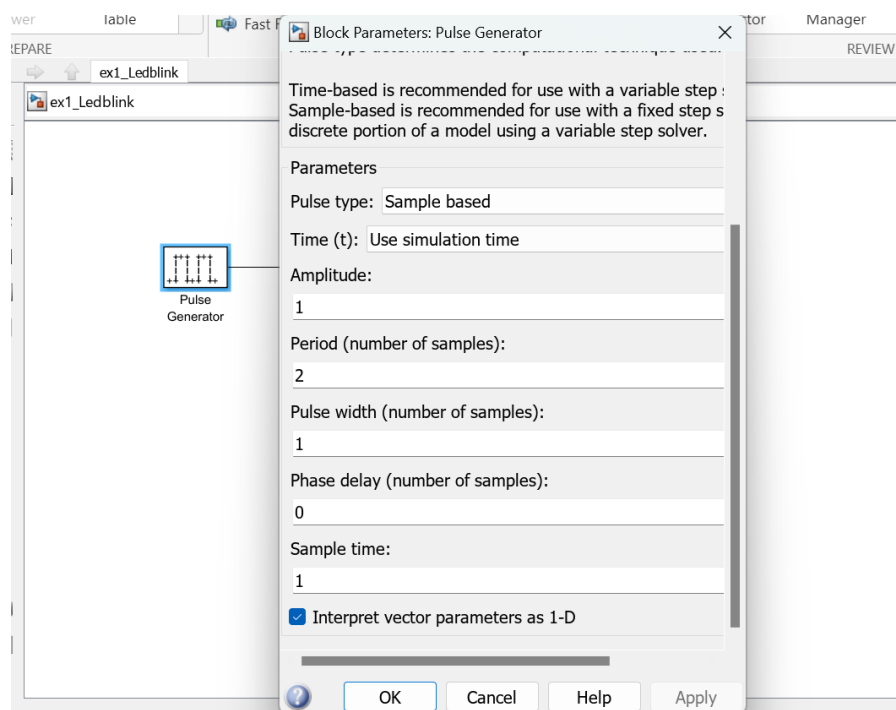
Go to Matlab -> Simulink -> open Blank Model, as shown below. Open the Simulink library browser.



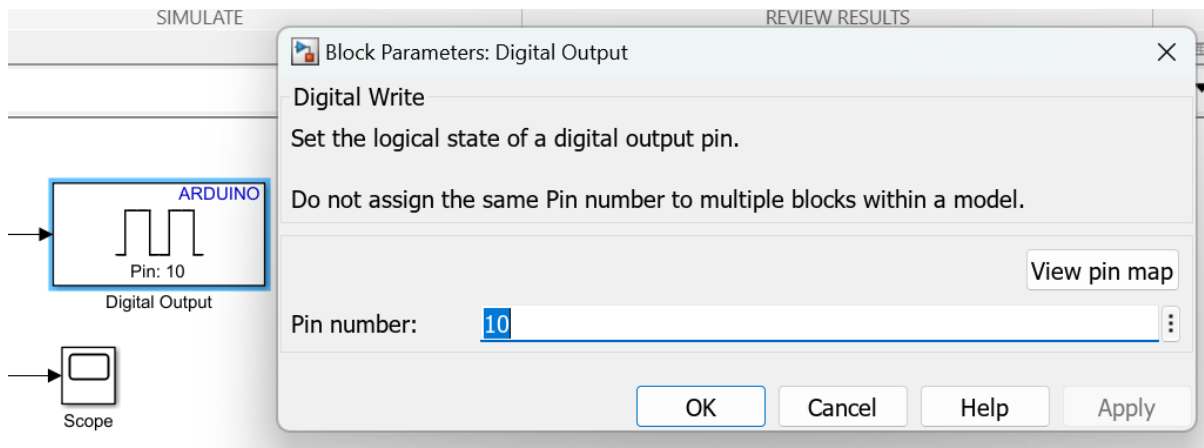
From the library browser go to sources ->drag and drop pulse generator block in the blank model, Simulink support package for Arduino ->common ->digital output block, drag and drop into the blank model and from the Simulink ->sink->scope block, drag and drop into the model.



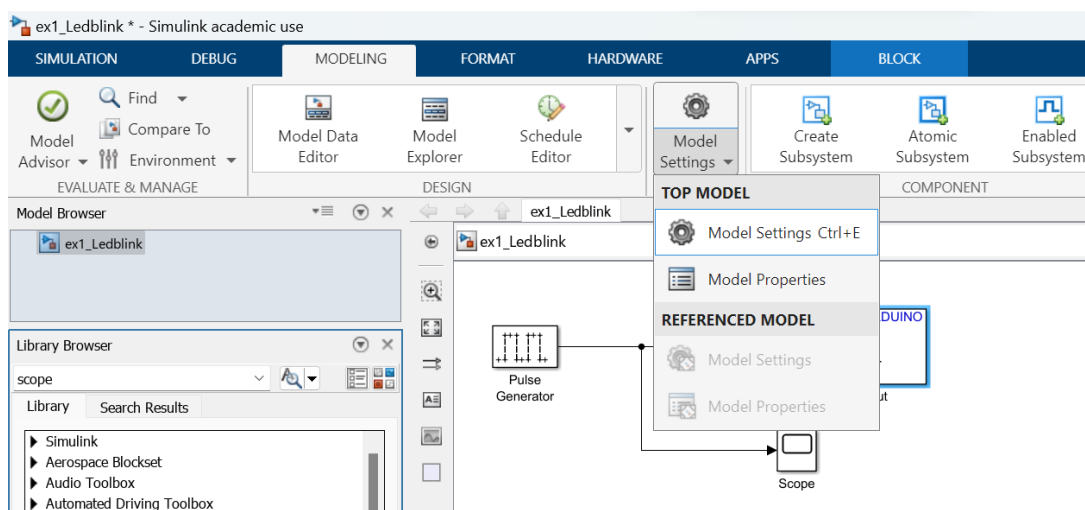
Connect the blocks as shown below and double click the pulse generator to change the parameters as follows.



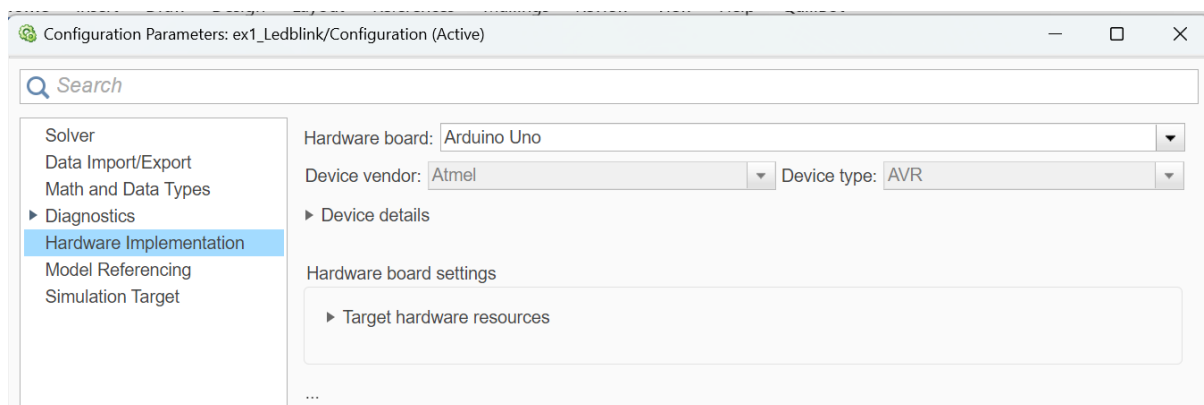
Double click the digital output block and set the pin to which pin you will connect the LED in the Arduino UNO. So here the pin is set to 10 as we use LED in 10th pin in the Arduino.



Save the model as ex1 _ ledblink and go Modelling tab -> model setting ->



Configure the parameters for the hardware. Select the hardware as Arduino Uno in the hardware board as shown below.



Under hardware board settings, specify the COM port number, at this time the hardware i.e. Arduino uno must be connected with the laptop using a usb cable. Check the port number in the command window using the following command.

```
>> a = arduino
```

Arduino Uno detected.

This device is ready for use with MATLAB Support Package for Arduino Hardware

This device is ready for use with Simulink Support Package for Arduino Hardware

```
>> a=arduino
```

Updating server code on board Uno (COM4). This may take a few minutes.

a =

arduino with properties:

Port: 'COM4'

Board: 'Uno'

AvailablePins: {'D2-D13', 'A0-A5'}

AvailableDigitalPins: {'D2-D13', 'A0-A5'}

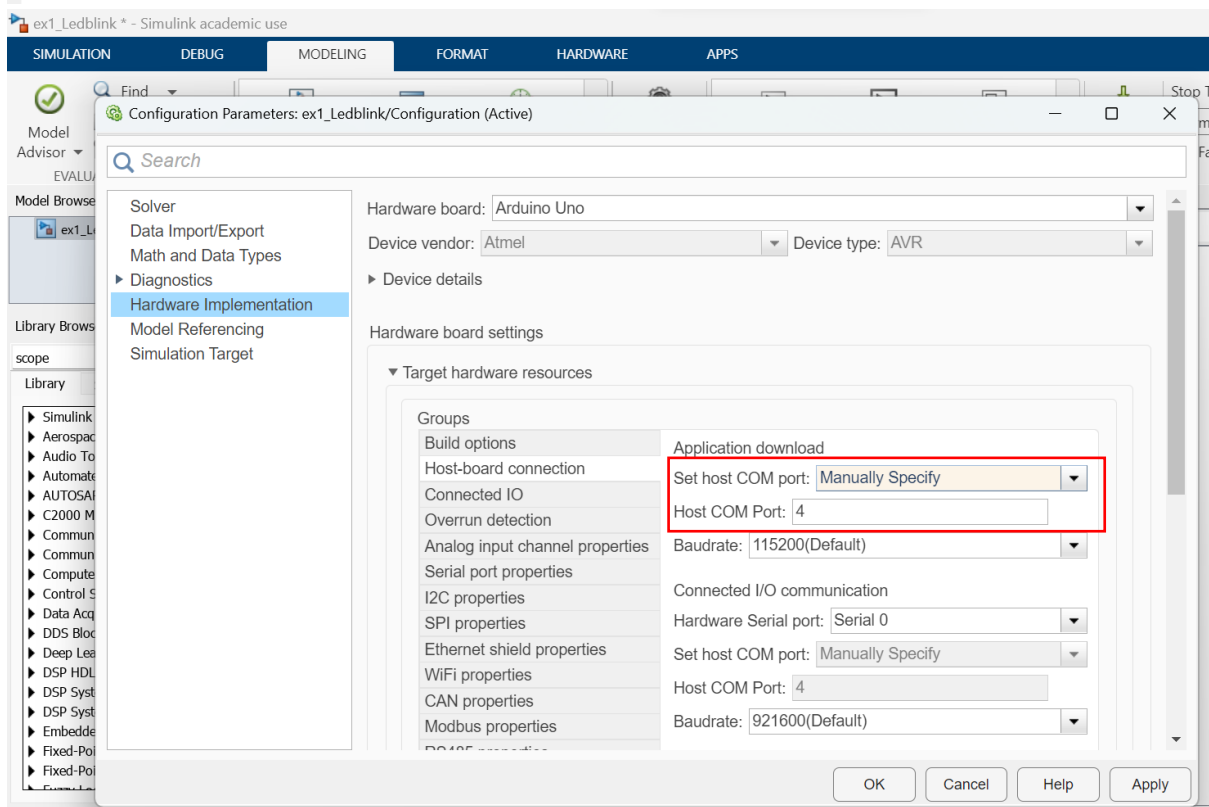
AvailablePWM Pins: {'D3', 'D5-D6', 'D9-D11'}

AvailableAnalogPins: {'A0-A5'}

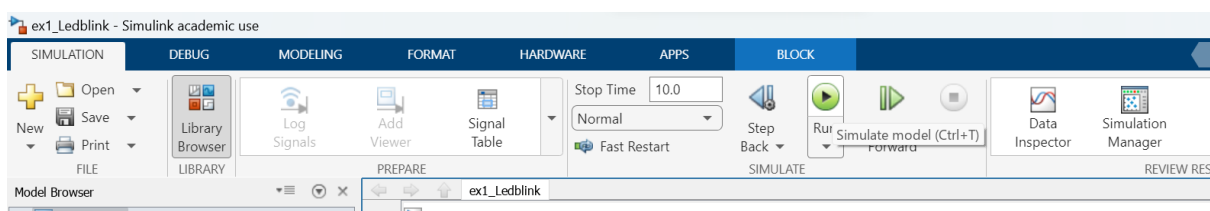
AvailableI2C Bus IDs: [0]

Libraries: {'I2C', 'SPI', 'Servo'}

Show all properties

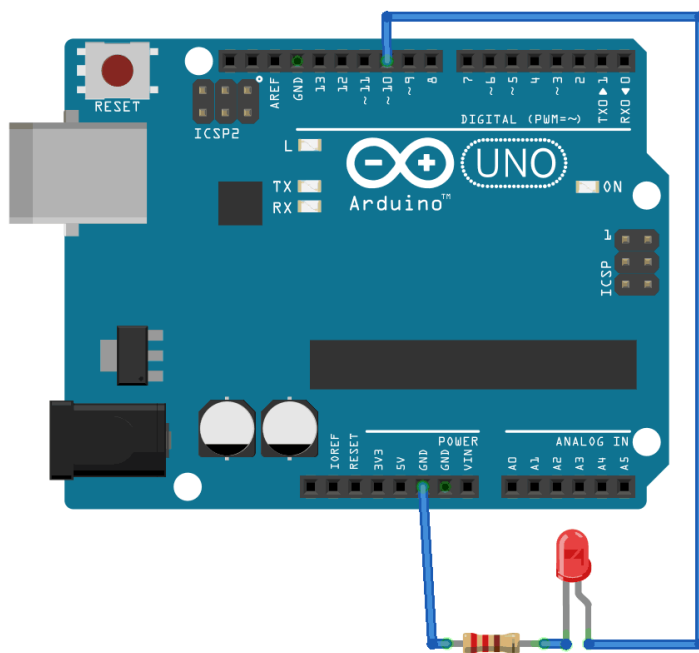


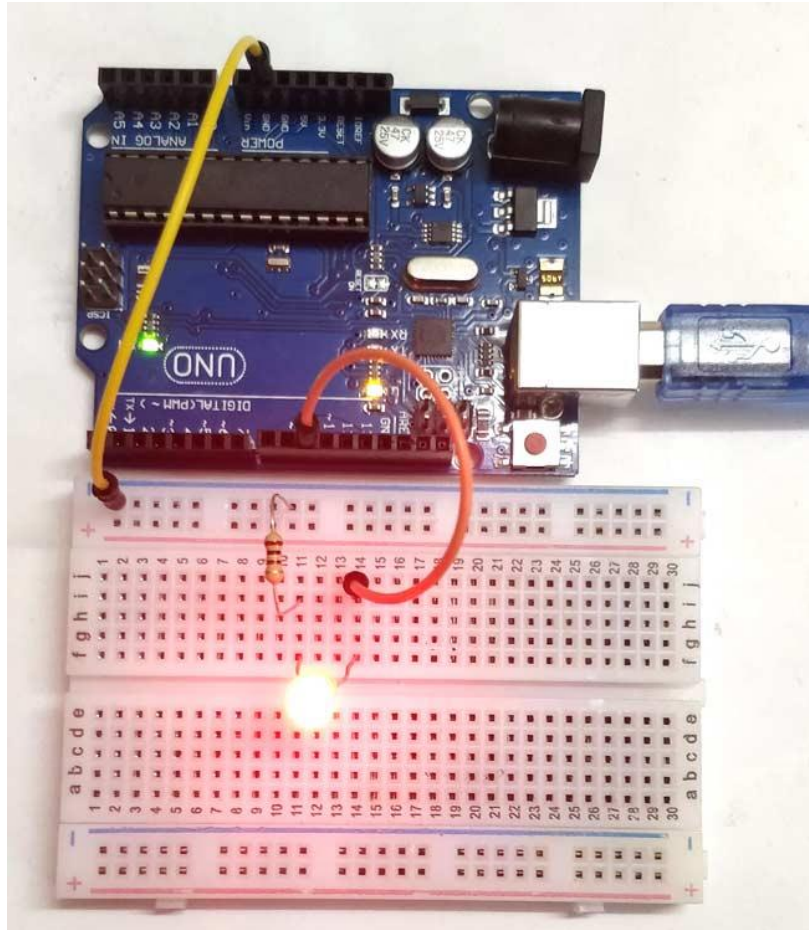
Give apply and OK. Save the model. Go to simulation tab and simulate the model.



The screenshot shows the Simulink academic use interface. The top menu bar includes SIMULATION, DEBUG, MODELING, FORMAT, HARDWARE, and APPS. The Hardware Board is set to Arduino Uno. The Model Browser shows the ex1_Ledblink model. The Deployment menu is open, showing options for Build, Deploy & Start, and Build, Deploy & Start. A tooltip indicates that Build, Deploy & Start (Ctrl+B) generates a stand-alone executable, deploys, and starts the application on hardware.

Schematic Diagram:





Conclusion:

Thus, a Matlab Simulink model was built and simulated to blink a led by interfacing with an Arduino Uno board.