

```
import numpy as np
import pandas as pd
import networkx.drawing.nx_pydot as gl
import networkx as nx
import matplotlib.pyplot as plt
from pprint import pprint
##matplotlib inline
```

```
# create state space and initial state probabilities
```

```
states = ['01', '02', '03']
pi = [0.25, 0.4, 0.35]
state_space = pd.Series(pi, index=states, name='states')
print(state_space)
print(state_space.sum())
```

```
01    0.25
02    0.40
03    0.35
Name: states, dtype: float64
1.0
```

+ Code

+ Text

```
# create transition matrix
# equals transition probability matrix of changing states given a state
# matrix is size (M x M) where M is number of states
```

```
q_df = pd.DataFrame(columns=states, index=states)
q_df.loc[states[0]] = [0.4, 0.2, 0.4]
q_df.loc[states[1]] = [0.45, 0.45, 0.1]
q_df.loc[states[2]] = [0.45, 0.25, .3]

print(q_df)
```

```
      01    02    03
01  0.4  0.2  0.4
02  0.45 0.45 0.1
03  0.45 0.25 0.3
```

```
q = q_df.values
print('\n')
print(q, q.shape)
print('\n')
print(q_df.sum(axis=1))
```

```
[[0.4 0.2 0.4]
 [0.45 0.45 0.1]
 [0.45 0.25 0.3]] (3, 3)
```

```
01    1.0
02    1.0
03    1.0
dtype: float64
```

```
from pprint import pprint
```

```
# create a function that maps transition probability dataframe
# to markov edges and weights
```

```
def _get_markov_edges(Q):
    edges = {}
    for col in Q.columns:
        for idx in Q.index:
            edges[(idx,col)] = Q.loc[idx,col]
    return edges
```

```
edges_wts = _get_markov_edges(q_df)
pprint(edges_wts)
```

```
{('01', '01'): 0.4,
 ('01', '02'): 0.2,
 ('01', '03'): 0.4,
 ('02', '01'): 0.45,
 ('02', '02'): 0.45,
 ('02', '03'): 0.1,
 ('03', '01'): 0.45,
 ('03', '02'): 0.25,
 ('03', '03'): 0.3}
```

```
# create graph object
G = nx.MultiDiGraph()
```

```
# nodes correspond to states
G.add_nodes_from(states)
print('Nodes:\n')
print(G.nodes())
print('\n')
```

Nodes:

```
['01', '02', '03']
```

```
# edges represent transition probabilities
for k, v in edges_wts.items():
    tmp_origin, tmp_destination = k[0], k[1]
    G.add_edge(tmp_origin, tmp_destination, weight=v, label=v)
print('Edges:')
pprint(G.edges(data=True))
```

Edges:

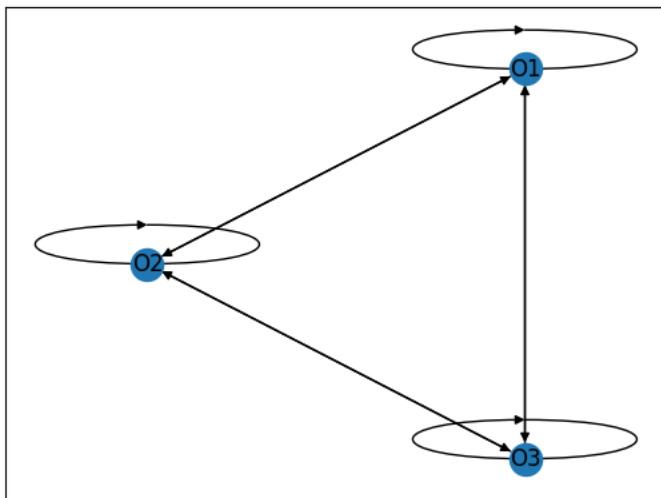
```
OutMultiEdgeDataView([('01', '01', {'weight': 0.4, 'label': 0.4}), ('01', '02', {'weight': 0.2, 'label': 0.2}), ('01', '03', {'weight': 0.2, 'label': 0.2}), ('02', '01', {'weight': 0.2, 'label': 0.2}), ('02', '03', {'weight': 0.2, 'label': 0.2}), ('03', '01', {'weight': 0.2, 'label': 0.2})])
```

```
pos = nx.drawing.nx_pydot.graphviz_layout(G, prog='dot')
nx.draw_networkx(G, pos)
```

<ipython-input-10-4a1a445e3a46>:1: DeprecationWarning: nx.nx_pydot.graphviz_layout depends on the pydot package, which h

See <https://github.com/networkx/networkx/issues/5723>

```
pos = nx.drawing.nx_pydot.graphviz_layout(G, prog='dot')
```



```
# create edge labels for jupyter plot but is not necessary
edge_labels = {(n1,n2):d['label'] for n1,n2,d in G.edges(data=True)}
nx.draw_networkx_edge_labels(G, pos, edge_labels=edge_labels)
nx.drawing.nx_pydot.write_dot(G, 'markov.dot')
plt.show()
```

```
# create state space and initial state probabilities
```

```
hidden_states = ['S1', 'S2']
pi = [0.5, 0.5]
print('\n')
state_space = pd.Series(pi, index=hidden_states, name='states')
print(state_space)
print('\n')
print(state_space.sum())
```

```
S1    0.5
S2    0.5
Name: states, dtype: float64
```

```
1.0
```

```
# create hidden transition matrix
# a or alpha
# = transition probability matrix of changing states given a state
# matrix is size (M x M) where M is number of states
```

```
a_df = pd.DataFrame(columns=hidden_states, index=hidden_states)
a_df.loc[hidden_states[0]] = [0.7, 0.3]
a_df.loc[hidden_states[1]] = [0.4, 0.6]

print(a_df)
```

```
      S1  S2
S1  0.7  0.3
S2  0.4  0.6
```

```
a = a_df.values
print('\n')
print(a)
print(a.shape)
print('\n')
print(a_df.sum(axis=1))
```

```
[[0.7 0.3]
 [0.4 0.6]]
(2, 2)
```

```
S1    1.0
S2    1.0
dtype: float64
```

```
# create matrix of observation (emission) probabilities
# b or beta = observation probabilities given state
# matrix is size (M x O) where M is number of states
# and O is number of different possible observations
```

```
observable_states = states
```

```
b_df = pd.DataFrame(columns=observable_states, index=hidden_states)
b_df.loc[hidden_states[0]] = [0.2, 0.6, 0.2]
b_df.loc[hidden_states[1]] = [0.4, 0.1, 0.5]

print(b_df)
```

```
      O1  O2  O3
S1  0.2  0.6  0.2
S2  0.4  0.1  0.5
```

```
b = b_df.values
print('\n')
print(b)
print(b.shape)
print('\n')
print(b_df.sum(axis=1))
```

```
[[0.2 0.6 0.2]
 [0.4 0.1 0.5]]
(2, 3)
```

```
S1    1.0
S2    1.0
dtype: float64
```

```
# create graph edges and weights
```

```
hide_edges_wts = _get_markov_edges(a_df)
pprint(hide_edges_wts)
```

```
emit_edges_wts = _get_markov_edges(b_df)
pprint(emit_edges_wts)
```

```
# create graph object
G = nx.MultiDiGraph()
```

```
{('S1', 'S1'): 0.7, ('S1', 'S2'): 0.3, ('S2', 'S1'): 0.4, ('S2', 'S2'): 0.6}
{('S1', '01'): 0.2,
 ('S1', '02'): 0.6,
 ('S1', '03'): 0.2,
 ('S2', '01'): 0.4,
 ('S2', '02'): 0.1,
 ('S2', '03'): 0.5}
```

```
# nodes correspond to states
G.add_nodes_from(hidden_states)
print('Nodes:\n')
print(G.nodes())
print('\n')
```

```
Nodes:

['S1', 'S2']
```

```
# edges represent hidden probabilities
for k, v in hide_edges_wts.items():
    tmp_origin, tmp_destination = k[0], k[1]
    G.add_edge(tmp_origin, tmp_destination, weight=v, label=v)
```

```
# edges represent emission probabilities
for k, v in emit_edges_wts.items():
    tmp_origin, tmp_destination = k[0], k[1]
    G.add_edge(tmp_origin, tmp_destination, weight=v, label=v)
```

```
print('Edges:')
pprint(G.edges(data=True))
```

```
Edges:
OutMultiEdgeDataView([('S1', 'S1', {'weight': 0.7, 'label': 0.7}), ('S1', 'S2', {'weight': 0.3, 'label': 0.3}), ('S1', '01', {'weight': 0.2, 'label': 0.2}), ('S1', '02', {'weight': 0.6, 'label': 0.6}), ('S1', '03', {'weight': 0.2, 'label': 0.2}), ('S2', 'S1', {'weight': 0.4, 'label': 0.4}), ('S2', 'S2', {'weight': 0.6, 'label': 0.6}), ('S2', '01', {'weight': 0.4, 'label': 0.4}), ('S2', '02', {'weight': 0.1, 'label': 0.1}), ('S2', '03', {'weight': 0.5, 'label': 0.5})])
```

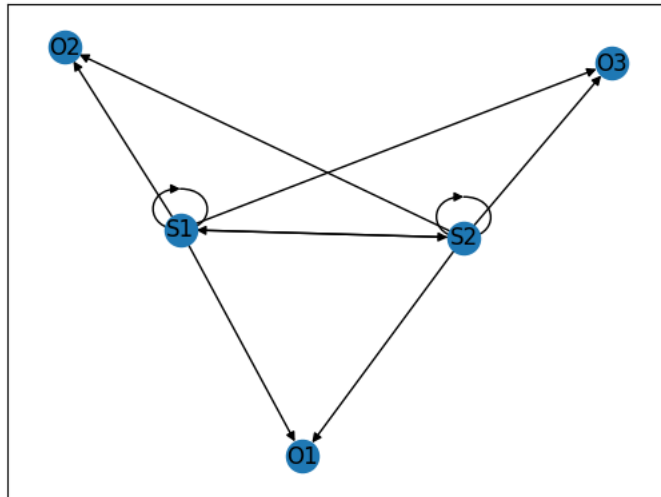
```
pos = nx.drawing.nx_pydot.graphviz_layout(G, prog='neato')
nx.draw_networkx(G, pos)
plt.show()
```

```
# create edge labels
emit_edge_labels = {(n1,n2):d['label'] for n1,n2,d in G.edges(data=True)}
nx.draw_networkx_edge_labels(G, pos, edge_labels=emit_edge_labels)
#plt.show()
nx.drawing.nx_pydot.write_dot(G, 'hidden_markov.dot')
```

<ipython-input-20-e5c76f0145f7>:1: DeprecationWarning: nx.nx_pydot.graphviz_layout depends on the pydot package, which h

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```
pos = nx.drawing.nx_pydot.graphviz_layout(G, prog='neato')
```



```
# observation sequence of dog's behaviors
# observations are encoded numerically
```

```
obs_map = {'01':0, '02':1, '03':2}
obs = np.array([1,1,2,1,0,1,2,1,0,2,2,0,1,0,1])
```

```
inv_obs_map = dict((v,k) for k, v in obs_map.items())
obs_seq = [inv_obs_map[v] for v in list(obs)]
```

```
print( pd.DataFrame(np.column_stack([obs, obs_seq]),
                        columns=['Obs_code', 'Obs_seq']) )
```

	Obs_code	Obs_seq
0	1	02
1	1	02
2	2	03
3	1	02
4	0	01
5	1	02
6	2	03
7	1	02
8	0	01
9	2	03
10	2	03
11	0	01
12	1	02
13	0	01
14	1	02

```
def viterbi(pi,a,b,obs):
```

```
    nStates = np.shape(b)[0]
```

```
    T = np.shape(obs)[0]
```

```
    path = np.zeros(T)
```

```
    delta = np.zeros((nStates,T))
```

```
    phi = np.zeros((nStates,T))
```

```
    delta[:,0] = pi * b[:,obs[0]]
```

```
    phi[:,0] = 0
```

```
path, delta, phi = viterbi(pi, a, b, obs)
```

```
print('\n')
```

```
print('single best state path: ', path)
```

```
print('delta:\n', delta)
```

```
print('phi:\n', phi)
```

```
single best state path: [0. 0. 0. 0. 0. 0. 0. 0. 1. 1. 1. 1. 0. 0. 0.]
```

```
delta:
```

```
[[3.00000000e-01 1.26000000e-01 1.76400000e-02 7.40880000e-03
```

```
1.03723200e-03 4.35637440e-04 6.09892416e-05 2.56154815e-05
```

```
3.58616741e-06 5.02063437e-07 7.37725866e-08 2.21317760e-08
```

```
1.59348787e-08 2.23088302e-09 9.36970868e-10]
```

```
[5.00000000e-02 9.00000000e-03 1.89000000e-02 1.13400000e-03
```

```
8.89056000e-04 5.33433600e-05 6.53456160e-05 3.92073696e-06
```

```
3.07385778e-06 9.22157333e-07 2.76647200e-07 6.63953280e-08
```

```
3.98371968e-09 1.91218545e-09 1.14731127e-10]]
```

```
phi:
```

```
[[0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 1. 1. 1. 0. 0.]
```

```
[0. 0. 0. 1. 0. 1. 0. 1. 0. 1. 1. 1. 1. 0. 1.]]
```

```
state_map = {0:'S1', 1:'S2'}
```

```
state_path = [state_map[v] for v in path]
```

```
result = (pd.DataFrame()
```

```
    .assign(Observation=obs_seq)
```

```
    .assign(Best_Path=state_path))
```

```
print(result)
```

```
Observation Best_Path
```

```
0          02        S1
```

```
1          02        S1
```

```
2          03        S1
```

```
3          02        S1
```

```
4          01        S1
```

```
5          02        S1
```

```
6          03        S1
```

```
7          02        S1
```

```
8          01        S2
```

```
9          03        S2
```

```
10         03        S2
```

```
11         01        S2
```

```
12         02        S1
```

```
13         01        S1
```

```
14         02        S1
```