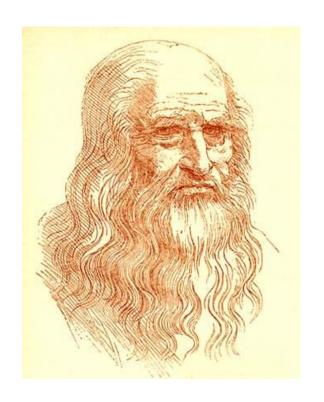
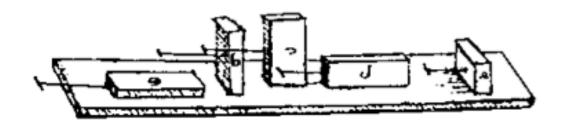
Brittle deformation and Faulting

Goal: To understand relationships between brittle failure, stresses, and fault orientation.



Question Da Vinci asked: Given that all objects shown below are of equal mass and identical shape, in which case the frictional force is greater?



Leonardo Da Vinci (1452-1519) showed that the friction force is independent of the geometrical area of contact.

- Amontons' first law: The frictional force is independent of the geometrical contact area.
- Amontons' second law: The friction force, F_S, is proportional to the normal force, F_N:

$$F_S = \mu F_N$$

$$\sigma_{s} = \mu \sigma_{n}$$



μ: static coefficient of friction

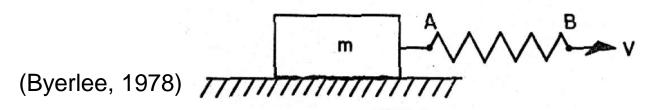
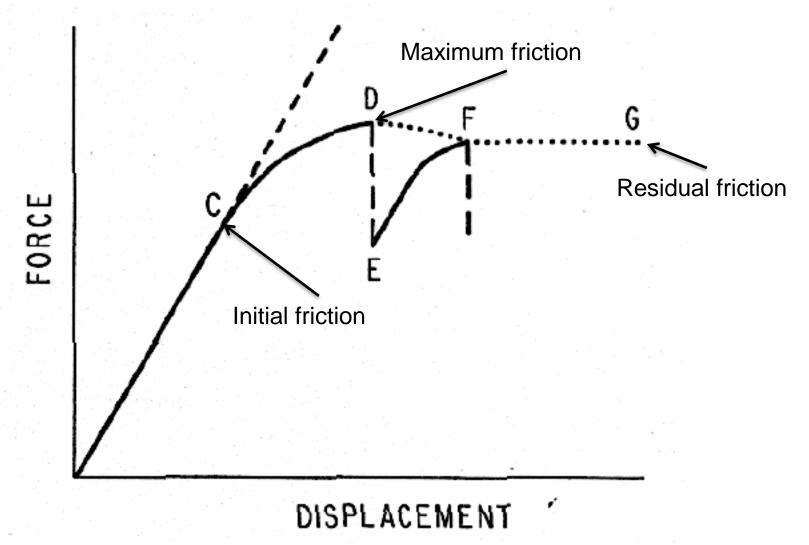
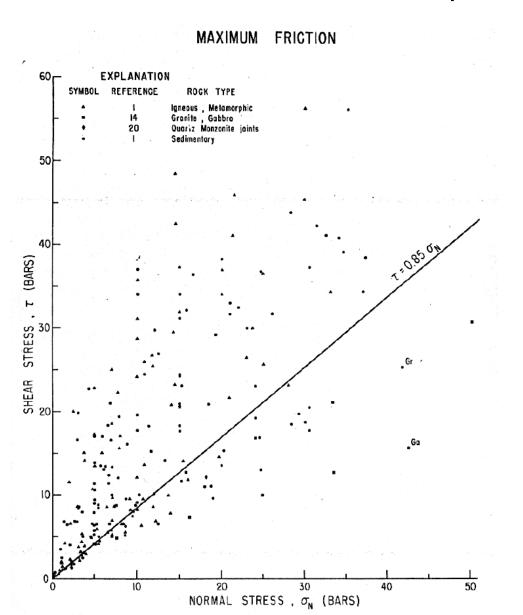


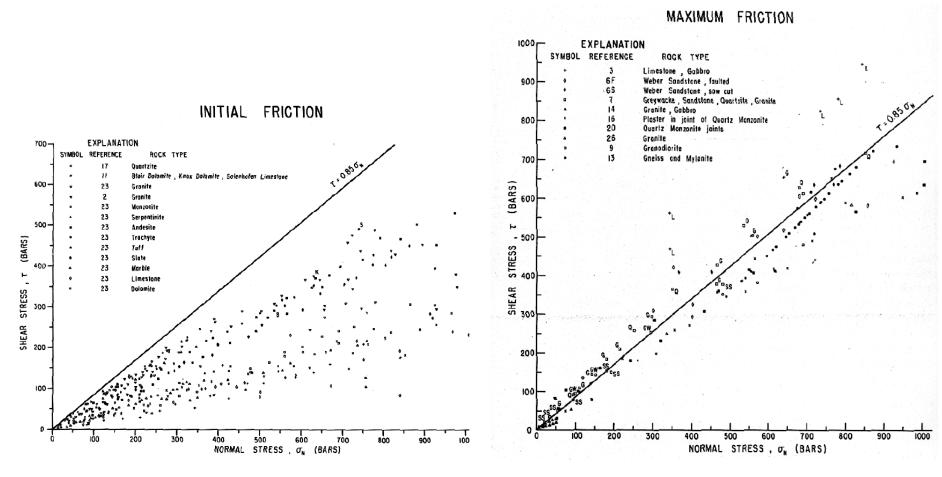
Figure 1
Schematic diagram of a typical friction experiment. For explanation see text.



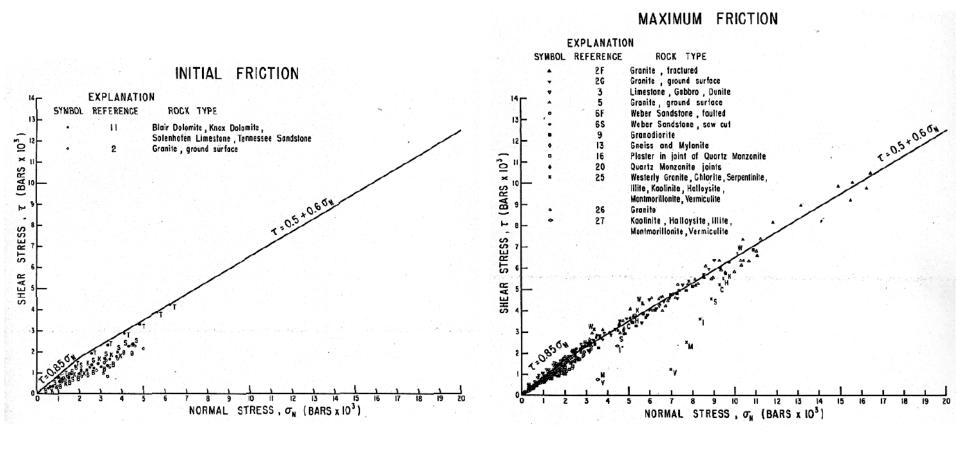
< Maximum friction for normal stress up to 50 bar >



< Initial and maximum friction for normal stress up to 1 kbar >

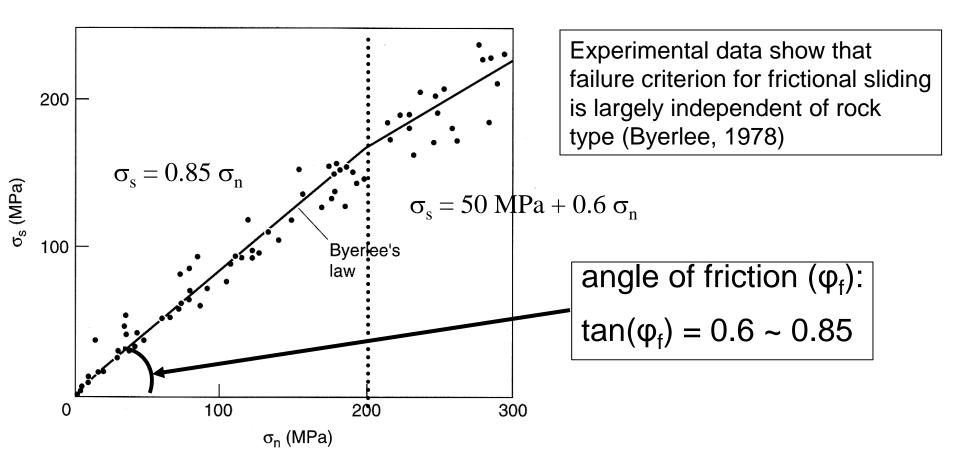


< Initial and maximum friction for normal stress up to 20 kbar >



Frictional sliding criterion for most ROCKS is simple

Because of friction, certain critical shear stress is required before sliding initiates on preexisting fracture



But, besides friction we have to think about how to break a surface.

Fracture Strength

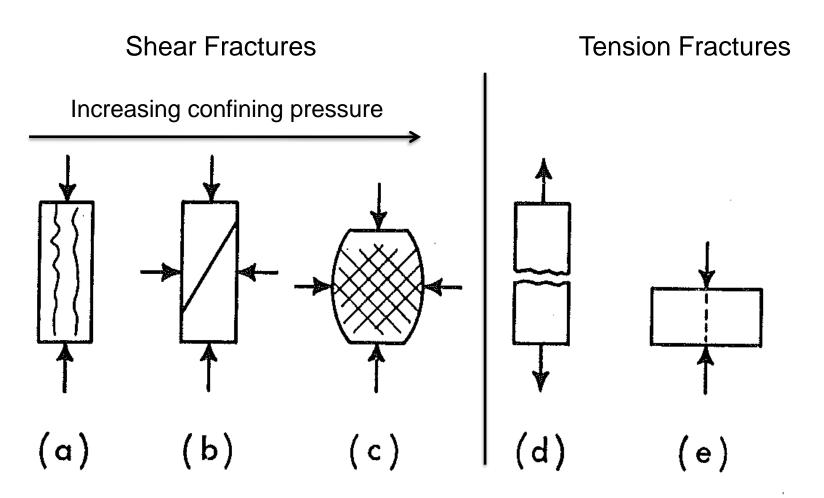
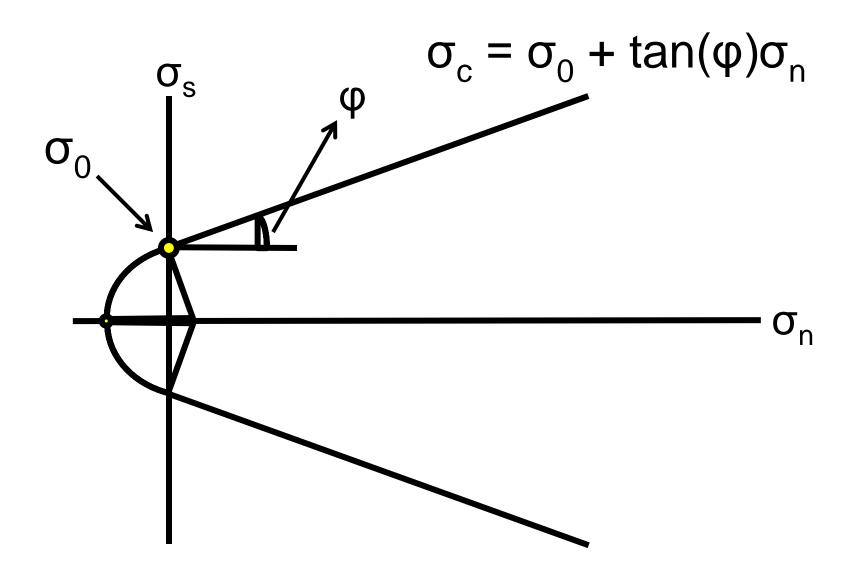


Fig. 4.5.1 (a) Longitudinal splitting in uniaxial compression. (b) Shear fracture. (c) Multiple shear fractures. (d) Extension fracture. (e) Extension fracture produced by line loads.

(Jaeger and Cook, 1976)

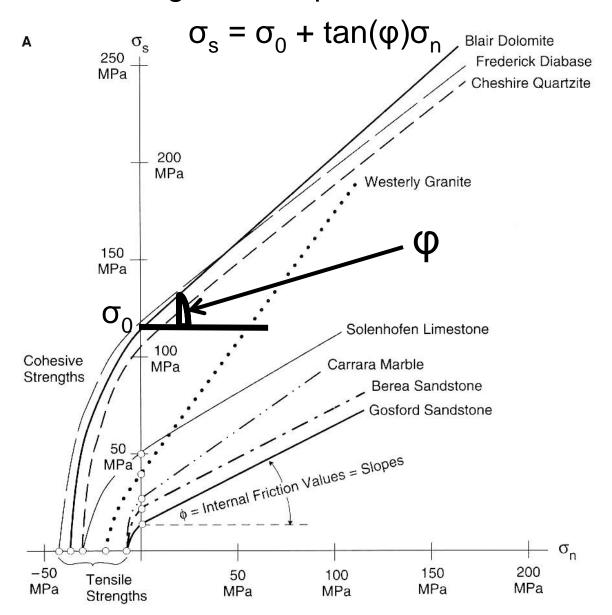
Fracture Strength

Mohr-Coulomb failure criterion



Fracture Strength

< Fracture strength envelopes for different rocks >



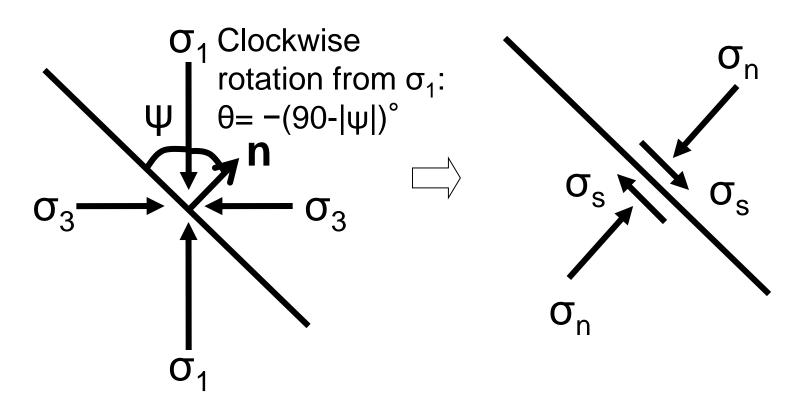
Mohr Circle: A device to relate friction and cohesion to fault *orientation*

A stress review for Mohr Circle

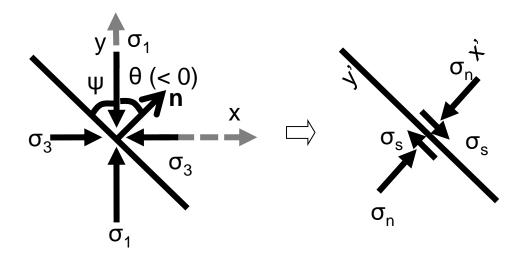
- Stress = Force/Area
- 3 principal values, σ_1 , σ_2 , and σ_3 , corresponding to three principal directions.
- $\sigma_1 \ge \sigma_2 \ge \sigma_3$, and positive when compressional.
- Static stress is when $\sigma_1 = \sigma_2 = \sigma_3$
- <u>Differential stress</u> (σ_d) defined as ($\sigma_1 \sigma_3$)

The stress is resolved into 2 components:

- 1. Shear stress (σ_s) , acting parallel with the plane
- 2. Normal stress (σ_n) , acting perpendicular to the plane



The stress is resolved into 2 components:



In a 2D case (e.g., plane stress), we get the *Mohr Transformation*:

$$\sigma'_{11} = \sigma_{11} \cos^2 \theta + \sigma_{22} \sin^2 \theta + \sigma_{12} \sin 2\theta$$

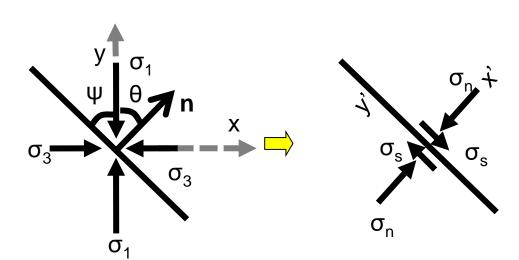
$$\sigma'_{22} = \sigma_{11} \sin^2 \theta + \sigma_{22} \cos^2 \theta - \sigma_{12} \sin 2\theta$$

$$\sigma'_{12} = (\sigma_{22} - \sigma_{11}) \sin \theta \cos \theta + \sigma_{12} \cos 2\theta$$

If we start with principal stresses, $\sigma_{12}=0$, $\sigma_{11}=\sigma_3$ and $\sigma_{22}=\sigma_1$. Also, $\sigma_n=\sigma'_{11}$ and $\sigma_s=\sigma'_{12}$.

- Stress components are related by:
 - $\sigma_s = \frac{1}{2}(\sigma_1 \sigma_3)\sin(2\theta)$
 - $\sigma_n = \frac{1}{2}(\sigma_1 + \sigma_3) \frac{1}{2}(\sigma_1 \sigma_3)\cos(2\theta)$
- From these, we get an equation for a circle:

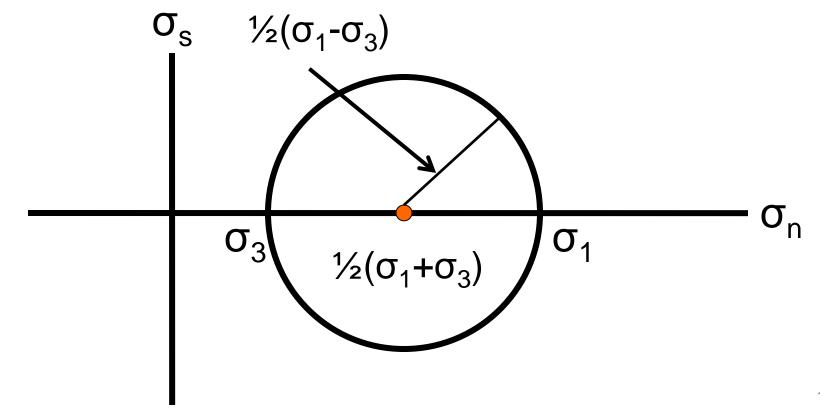
$$[\sigma_n - \frac{1}{2}(\sigma_1 + \sigma_3)]^2 + \sigma_s = \frac{1}{4}(\sigma_1 - \sigma_3)^2$$



Mohr circle for stress:

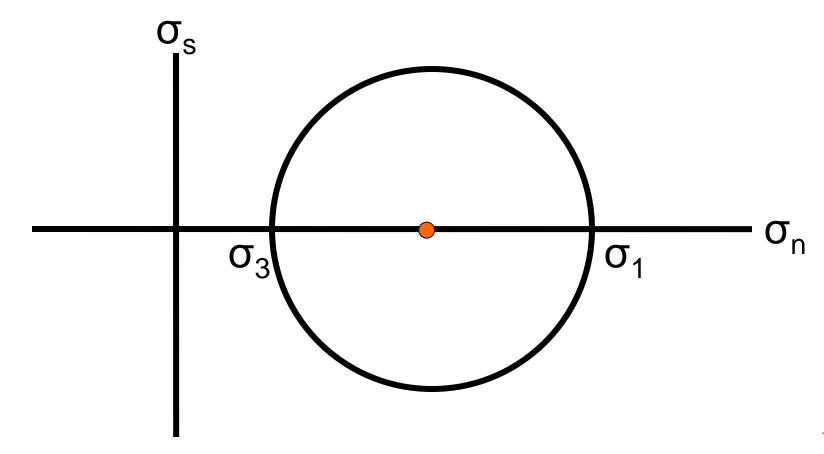
Diameter = $(\sigma_1 - \sigma_3)$, called "differential stress".

Center on the σ_n -axis at point = $\frac{1}{2}(\sigma_1 + \sigma_3)$



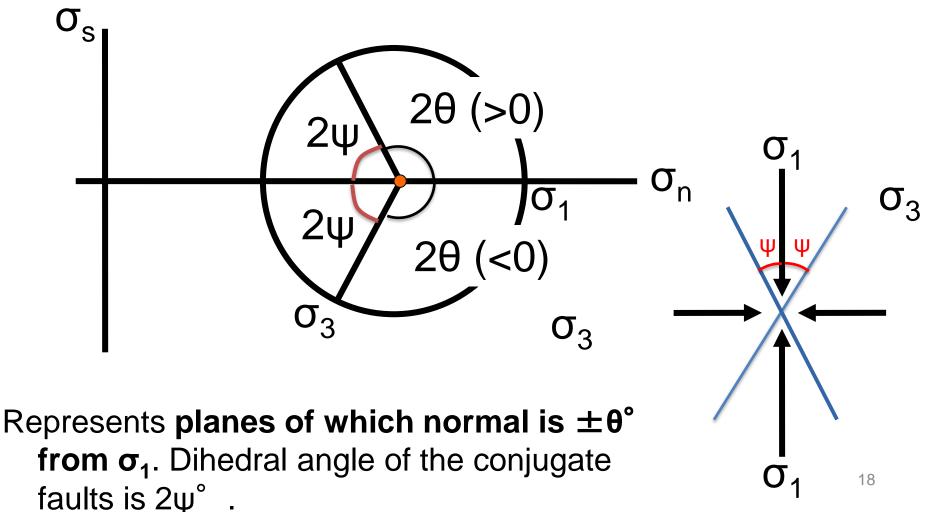
Finding σ_s , and σ_n

Can use a Mohr circle to find σ_s , and σ_n for any plane



Can use a Mohr circle to find σ_s , and σ_n for any plane.

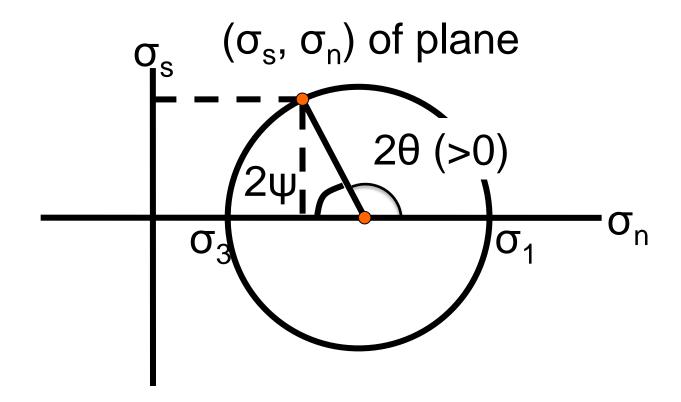
For instance, plot a line from center to edge of circle at angle $2\theta = 180-2\psi^{\circ}$ from σ_1 .



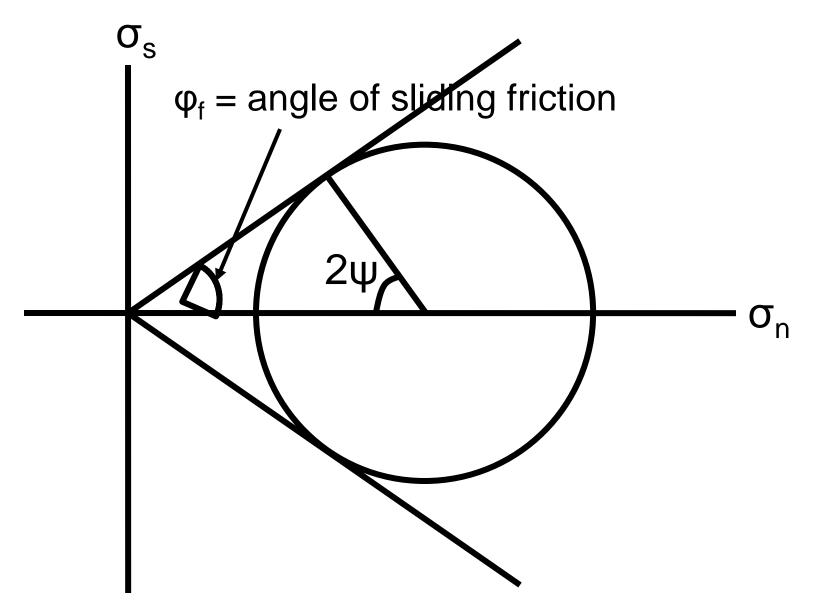
X- and y-coordinates of intersection of line and circle define σ_s and σ_n for the plane

•
$$\sigma_s = \frac{1}{2}(\sigma_1 - \sigma_3)\sin(2\theta)$$

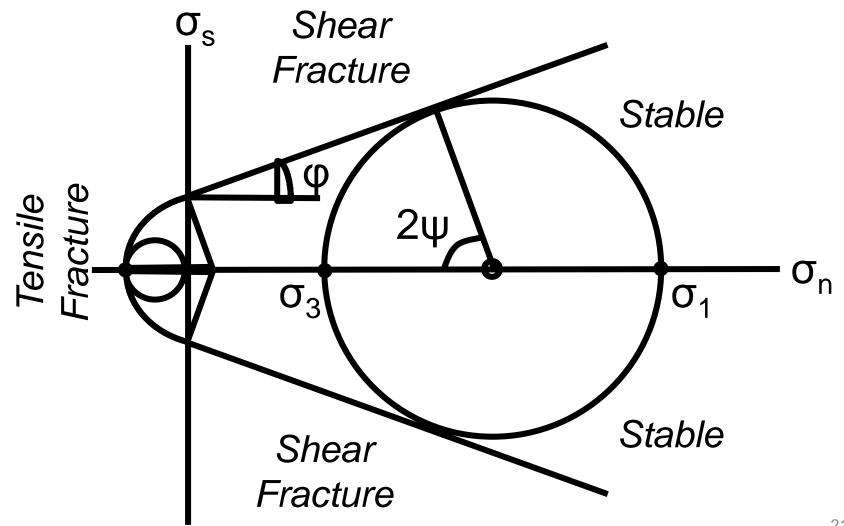
•
$$\sigma_n = \frac{1}{2}(\sigma_1 + \sigma_3) - \frac{1}{2}(\sigma_1 - \sigma_3)\cos(2\theta)$$
,



Envelope of frictional strength



The Coulomb envelope for fracture strength

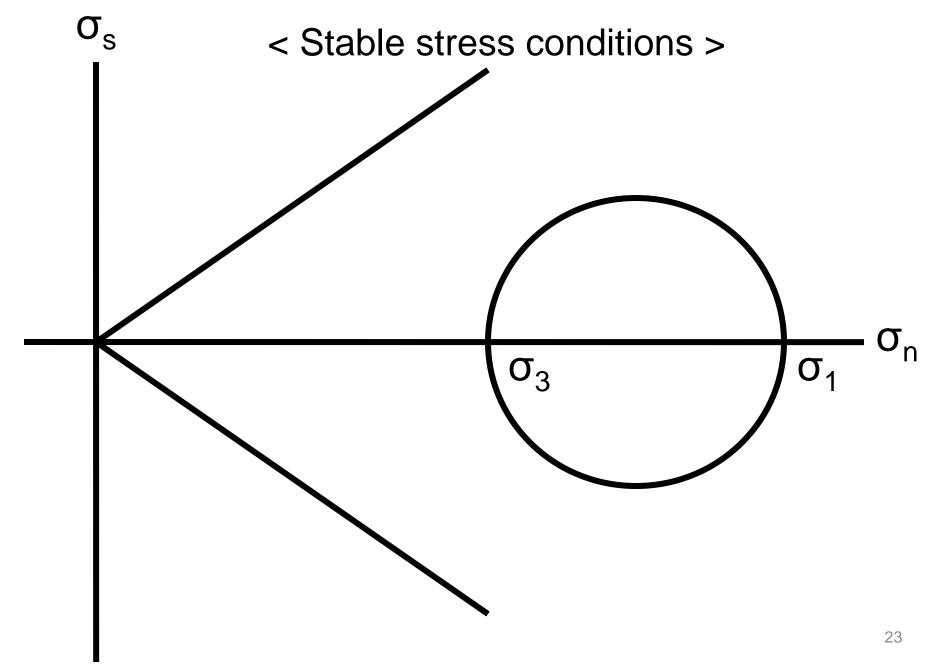


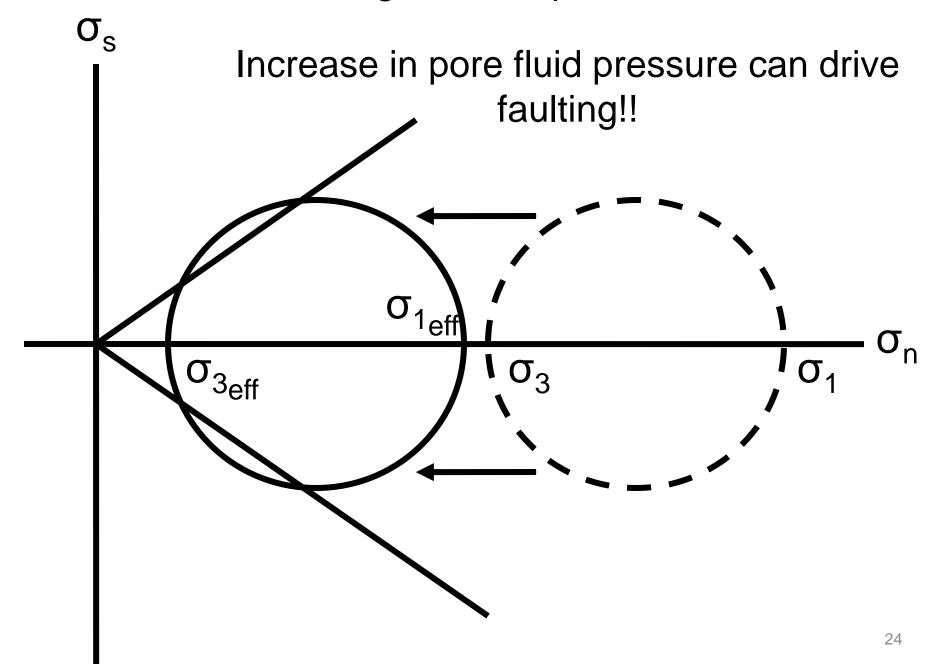
Effect of pore-fluid pressure

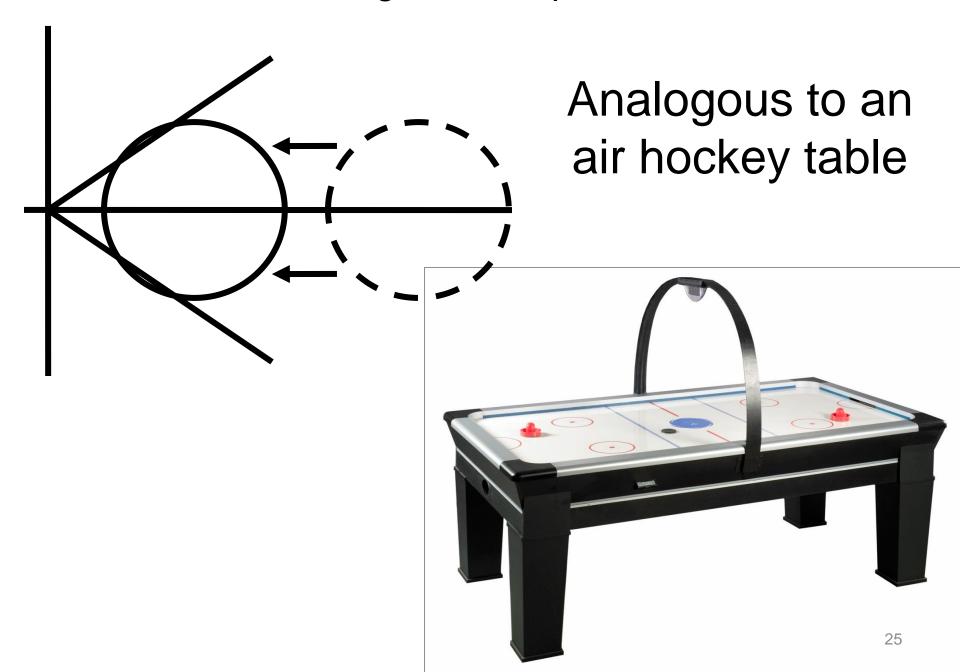
Pore fluid pressure (P_f) effectively lowers the stress in all directions

The <u>effective stresses</u> ($\sigma_{1_{eff}}$, $\sigma_{2_{eff}}$, and $\sigma_{3_{eff}}$) = principal stresses - P_f

$$\sigma_{1_{eff}} = \sigma_1 - P_f$$
 $\sigma_{2_{eff}} = \sigma_2 - P_f$ $\sigma_{3_{eff}} = \sigma_3 - P_f$







Primary assumptions

- Surface of the earth is not acted on by shear or normal stresses.
 - So 2 of the 3 principal stresses are parallel to the surface.
- 2. Homogenous rocks
- 3. Coulomb behavior

$$\sigma_{xx} = \rho gy + \Delta \sigma_{xx}$$
$$\sigma_{yy} = \rho gy$$

If $\Delta \sigma_{xx}$ is negative (under extension), $\sigma_1 = \sigma_{yy}$ and $\sigma_3 = \sigma_{xx}$.

Then,
$$\sigma_s = \frac{1}{2}(\sigma_{yy} - \sigma_{xx})\sin(2\theta)$$
 and $\sigma_n = \frac{1}{2}(\sigma_{yy} + \sigma_{xx}) - \frac{1}{2}(\sigma_{yy} - \sigma_{xx})\cos(2\theta)$

$$\sigma_n = \rho gy + \frac{\Delta \sigma_{xx}}{2} (1 + \cos 2\theta)$$

$$\sigma_s = -\frac{\Delta \sigma_{xx}}{2} \sin 2\theta$$

Plugging σ_n and σ_s into the Coulomb Failure criterion, $\sigma_s = \sigma_0 + f_s \sigma_n$, where $f_s = tan(\phi)$, we get

$$\pm \frac{\Delta \sigma_{xx}}{2} \sin 2\theta = f_s \left(\rho g y + \frac{\Delta \sigma_{xx}}{2} (1 + \cos 2\theta) \right)$$

$$\pm \frac{\Delta \sigma_{xx}}{2} \sin 2\theta = f_s \left(\rho g y + \frac{\Delta \sigma_{xx}}{2} (1 + \cos 2\theta) \right)$$

In the above equation, upper sign applies to $\Delta\sigma_{xx} > 0$ (i.e., thrust faults) and the lower sign to $\Delta\sigma_{xx} < 0$ (i.e., normal faults). We can also get an expression for $\Delta\sigma_{xx}$ from this equation:

$$\Delta \sigma_{xx} = \frac{2f_s \rho gy}{\pm \sin 2\theta - f_s (1 + \cos 2\theta)}.$$

Now we are interested in the smallest possible $\Delta\sigma_{xx}$ that satisfies the above equation and the corresponding value of f_s because that value will correspond to the strength.

$$\tan 2\theta = \mp \frac{1}{f_s}$$

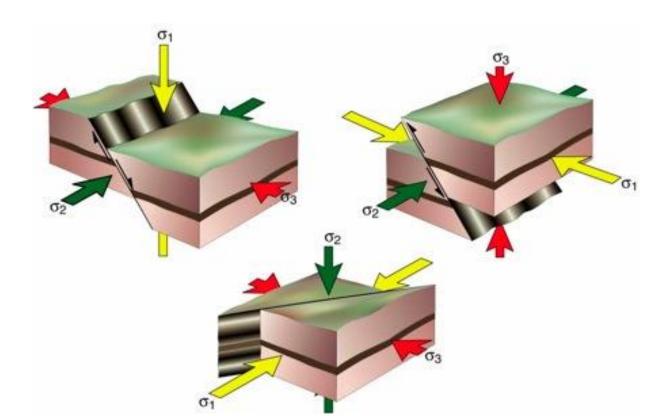
The upper and lower sign corresponds to thrust and normal faults, respectively. This expression simply represents the geometric relation between the failure envelope and the Mohr circle we saw earlier.

The corresponding differential stress becomes

$$\Delta \sigma_{xx} = \frac{\pm 2f_s \rho gy}{(1+f_s)^{1/2} \mp f_s}.$$

Most rocks have an angle of internal friction ≈ 30°

- σ_1 horizontal, σ_3 vertical <u>reverse faults</u>
- σ_1 vertical, σ_3 horizontal <u>normal faults</u>
- σ_1 horizontal, σ_3 horizontal <u>strike-slip faults</u>



- Reverse faults (σ₁ horizontal): should form at ~30°
 dip
- Normal faults (σ₁ vertical): should form at ~60° dip
- Strike-slip faults: should form at ~90° dip and ~60° dihedral angle

