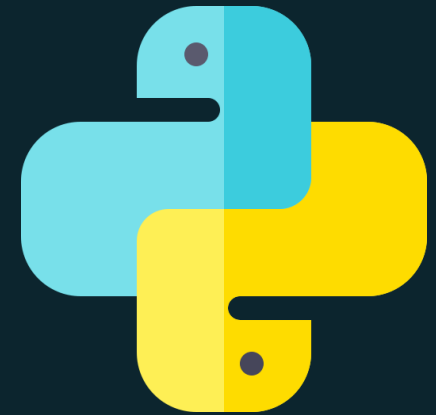


Brief Python

Python Course for Programmers



Learn Python Language for Data Science

CHAPTER 9: DATA VISUALIZATION WITH PYLAB

DR. ERIC CHOU

IEEE SENIOR MEMBER



Objectives

- Data Sets
- Using API (Geopy)
- Data Analysis
- Web Crawler
- Google Architecture



Data Set

LECTURE 1



Agriculture



Climate



Consumer



Ecosystems



Education



Energy



Finance



Health



Local
Government



Manufacturing



Maritime



Ocean



Public Safety

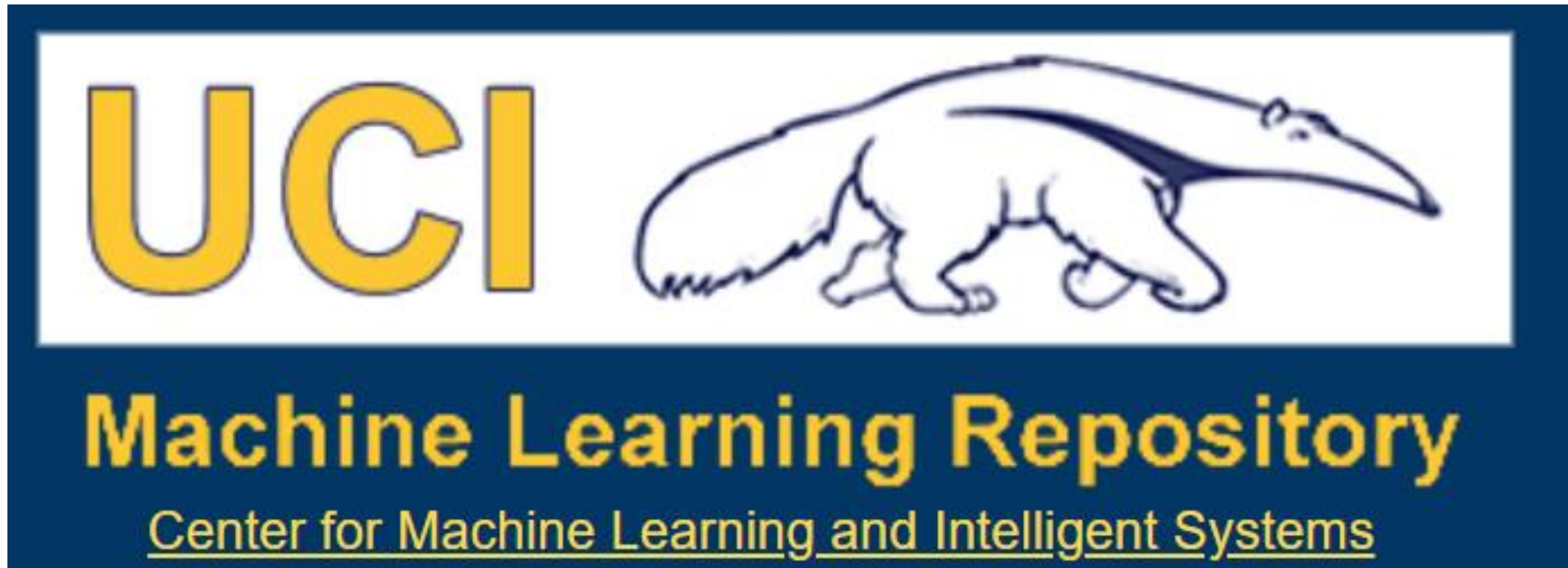


Science &
Research

Data.gov



UC Irvine Machine Learning Repository





Buckingham Palace

LECTURE 2



Numpy cos/sin

Home Data

Home <-0.4198, -0.6724, 0.6096>

```
from geopy import distance
# Data Model
# 38781 Tyson Lane, Fremont, CA 94536
tyson_home = (37.562001, -121.9768045)
tlat = np.deg2rad(tyson_home[0])
tlong = np.deg2rad(tyson_home[1])

xt = np.cos(tlat) * np.cos(tlong)
yt = np.cos(tlat) * np.sin(tlong)
zt = np.sin(tlat)

print("Home <%7.4f, %7.4f, %7.4f>" % (xt, yt, zt))
```



Numpy cos/sin

Buckingham Data

Palace< 0.6225, -0.0016, 0.7826>

```
# Westminster, London SW1A 1AA, UK
buckingham_palace = (51.5013673, -0.1440787) # (lat, long) of my home
blat = np.deg2rad(buckingham_palace[0])
blong = np.deg2rad(buckingham_palace[1])

xb = np.cos(blat) * np.cos(blong)
yb = np.cos(blat) * np.sin(blong)
zb = np.sin(blat)
print("Palace<%7.4f, %7.4f, %7.4f>" % (xb, yb, zb))
```

Python Code (Linear Algebra Calculation for Distance)

```
v = np.array([xt, yt, zt])
w = np.array([xb, yb, zb])
zero = np.array([0, 0, 0])
print("v=", v)
print("w=", w)
vw = np.inner(v, w)
print("v . w=", vw)
v_abs = np.linalg.norm(v-zero)
w_abs = np.linalg.norm(w-zero)
print("|v|=", v_abs)      # both are 1
print("|w|=", w_abs)
print("(vw)/(v_abs*w_abs)=%8.4f" % ((vw)/(v_abs*w_abs)))
print()
theta = np.arccos((vw)/(v_abs*w_abs))
print("theta(deg)=%8.4f\u00B0" % np.rad2deg(theta))
print("theta(rad)=%8.4f (rad)" % theta)
print()
print("Distance(Home, Buckingham Palace)=%10.4f Km" % (6371*theta))
print("Distance(Home, Buckingham Palace)=%10.4f miles" % (6371*theta*0.621371))
```

v= [-0.4197917 -0.67241274 0.60961958]
w= [0.62249399 -0.00156536 0.78262301]
v . w= 0.2168370628092262
|v|= 1.0
|w|= 1.0
(vw)/(v_abs*w_abs)= 0.2168
theta(deg)= 77.4767°
theta(rad)= 1.3522 (rad)
Distance(Home, Buckingham Palace)= 8615.0131 Km
Distance(Home, Buckingham Palace)= 5353.1193 miles



Distance Calculation by Geopy

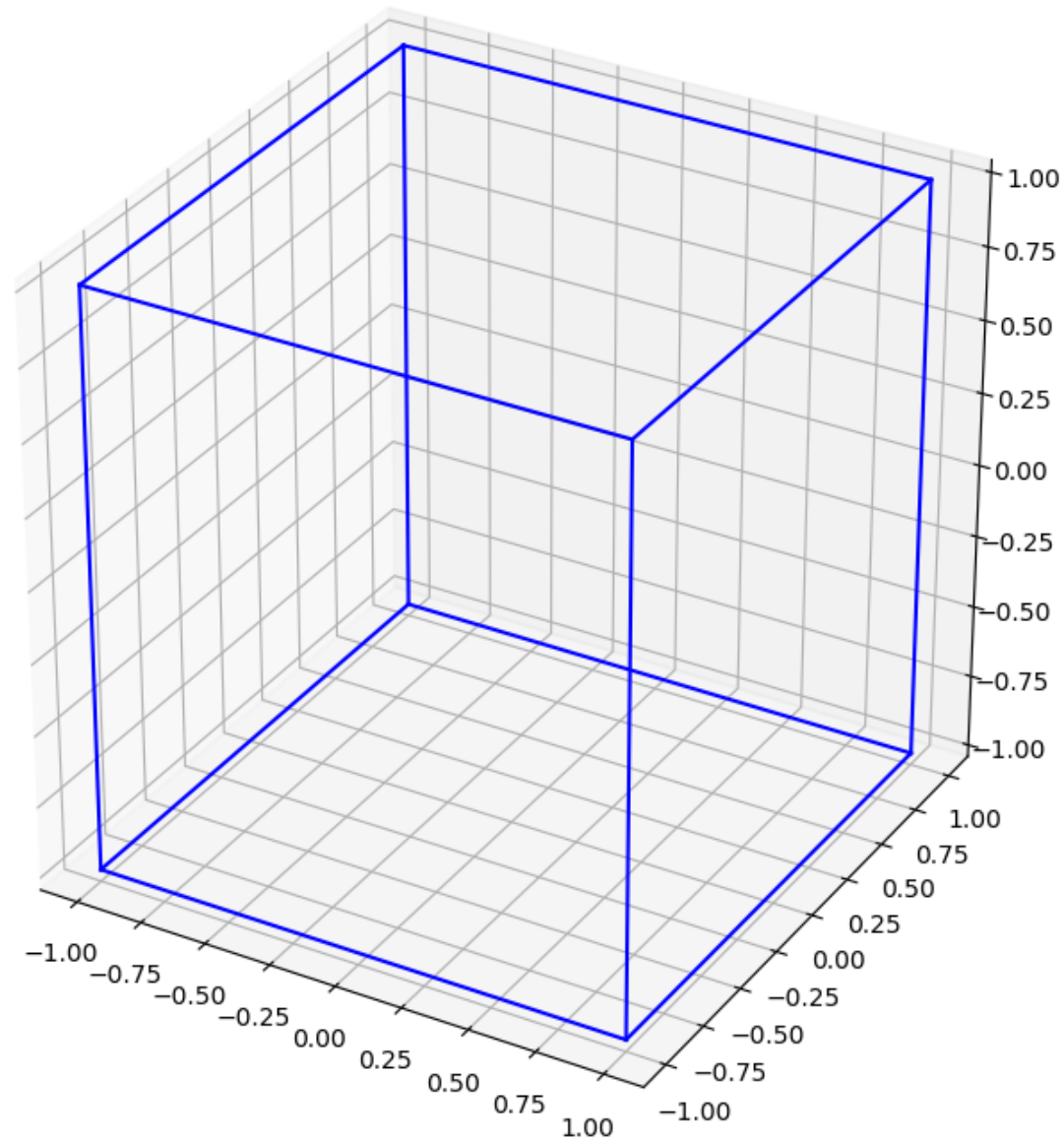
```
# distance calculation by geopy
dis_miles = distance.distance(tyson_home, buckingham_palace).miles
dis_km    = distance.distance(tyson_home, buckingham_palace).km
print("Distance(Home, Buckingham Palace)=%10.4f Km (geopy)" % dis_km)
print("Distance(Home, Buckingham Palace)=%10.4f miles (geopy)" % dis_miles)
```

```
Distance(Home, Buckingham Palace)= 8637.2216 Km (geopy)
Distance(Home, Buckingham Palace)= 5366.9207 miles (geopy)
```

```
from mpl_toolkits.mplot3d import Axes3D
import matplotlib.pyplot as plt
import numpy as np
from itertools import product, combinations

fig = plt.figure("Earth", figsize=(12, 9))
ax = fig.gca(projection='3d')
ax.set_aspect("equal")

# draw cube
r = [-1, 1]
for s, e in combinations(np.array(list(product(r, r, r))), 2):
    if np.sum(np.abs(s-e)) == r[1]-r[0]:
        ax.plot3D(*zip(s, e), color="b")
plt.show()
```

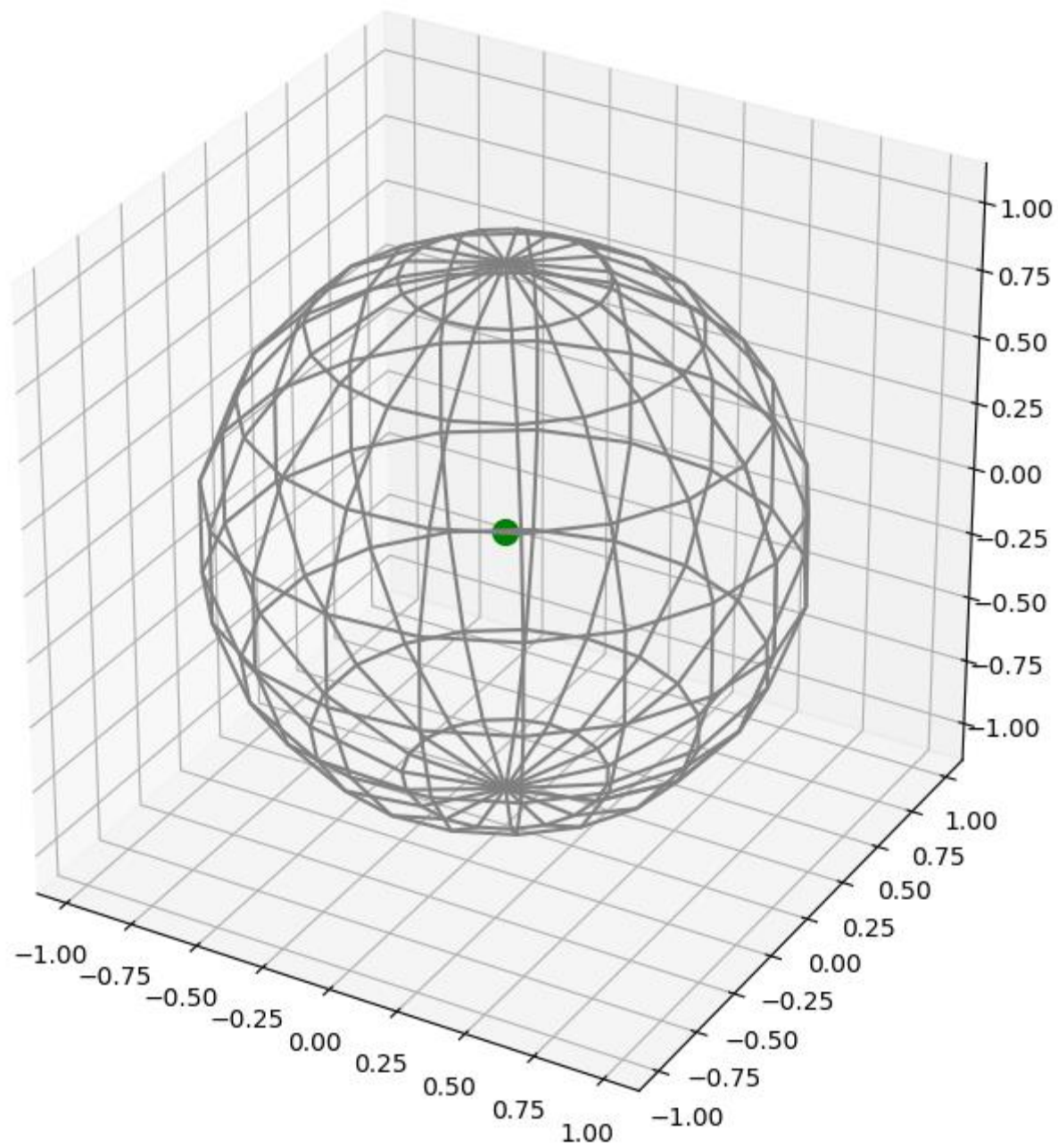


```
from mpl_toolkits.mplot3d import Axes3D
import matplotlib.pyplot as plt
import numpy as np
from itertools import product, combinations

fig = plt.figure("Earth", figsize=(12, 9))
ax = fig.gca(projection='3d')
ax.set_aspect("equal")

# draw sphere
u, v = np.mgrid[0:2*np.pi:20j, 0:np.pi:10j]
x = np.cos(u)*np.sin(v)
y = np.sin(u)*np.sin(v)
z = np.cos(v)
ax.plot_wireframe(x, y, z, color="gray")

# draw a point
ax.scatter([0], [0], [0], color="g", s=100)
plt.show()
```



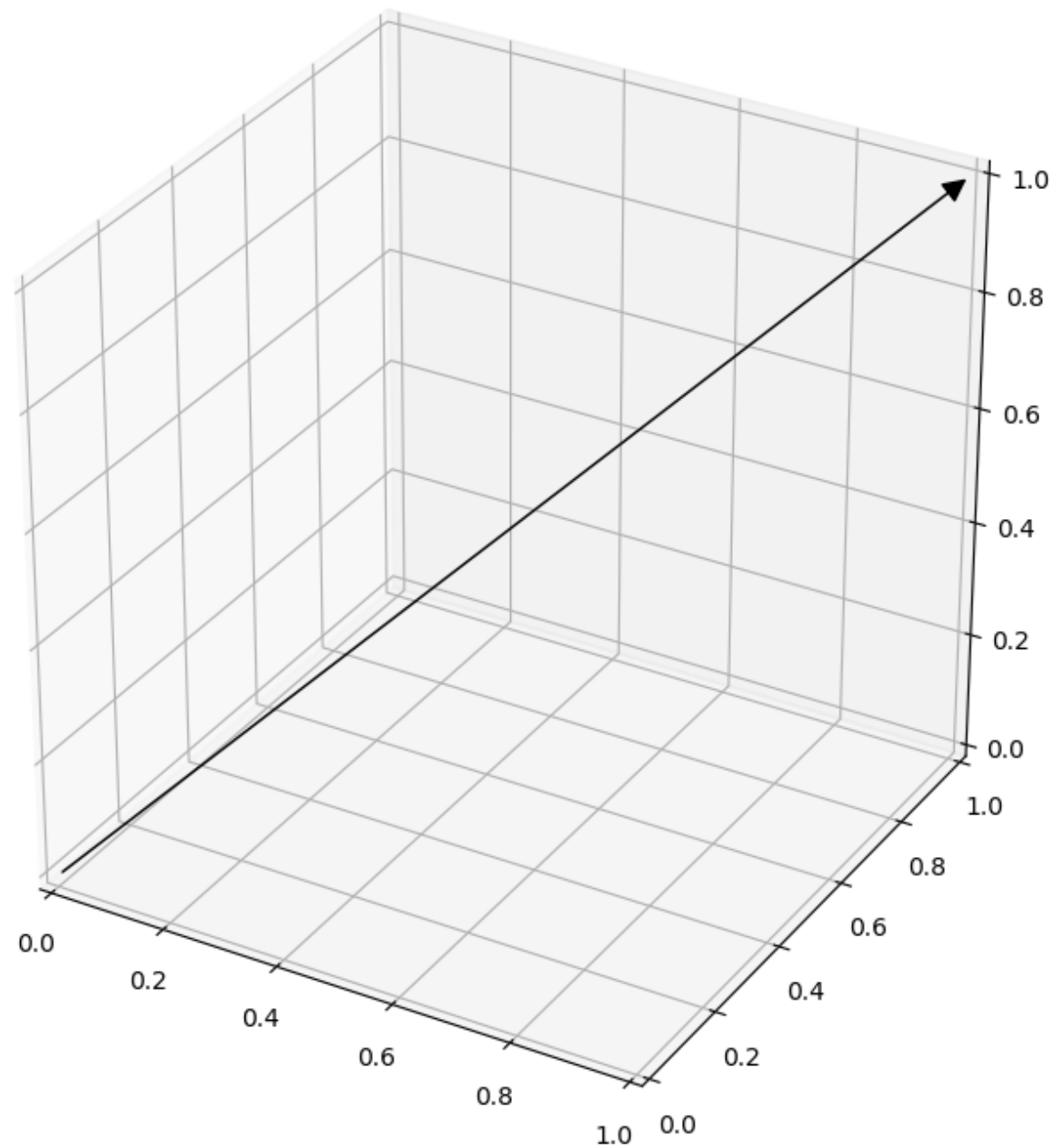

```
from mpl_toolkits.mplot3d import Axes3D
import matplotlib.pyplot as plt
import numpy as np
from itertools import product, combinations

fig = plt.figure("Earth", figsize=(12, 9))
ax = fig.gca(projection='3d')
ax.set_aspect("equal")

# draw a vector
from matplotlib.patches import FancyArrowPatch
from mpl_toolkits.mplot3d import proj3d

class Arrow3D(FancyArrowPatch):
    def __init__(self, xs, ys, zs, *args, **kwargs):
        FancyArrowPatch.__init__(self, (0, 0), (0, 0), *args, **kwargs)
        self._verts3d = xs, ys, zs
    def draw(self, renderer):
        xs3d, ys3d, zs3d = self._verts3d
        xs, ys, zs = proj3d.proj_transform(xs3d, ys3d, zs3d, renderer.M)
        self.set_positions((xs[0], ys[0]), (xs[1], ys[1]))
        FancyArrowPatch.draw(self, renderer)

a = Arrow3D([0, 1], [0, 1], [0, 1], mutation_scale=20,
            lw=1, arrowstyle="->", color="k")
ax.add_artist(a)
plt.show()
```



```
from mpl_toolkits.mplot3d import Axes3D
import matplotlib.pyplot as plt
import numpy as np
from itertools import product, combinations

fig = plt.figure("Earth", figsize=(12, 9))
ax = fig.gca(projection='3d')
ax.set_aspect("equal")

# draw cube
r = [-1, 1]
for s, e in combinations(np.array(list(product(r, r, r))), 2):
    if np.sum(np.abs(s-e)) == r[1]-r[0]:
        ax.plot3D(*zip(s, e), color="b")

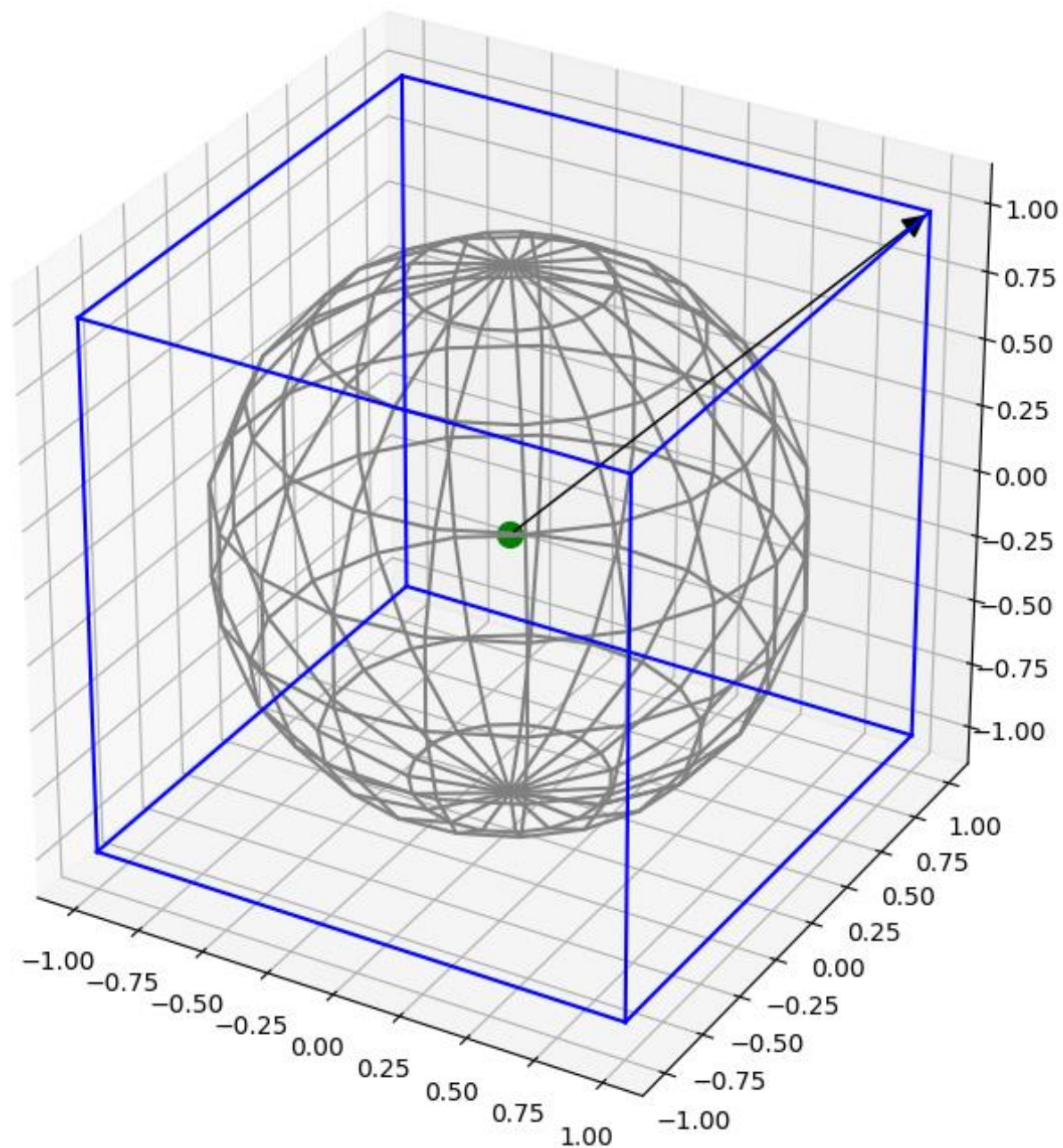
# draw sphere
u, v = np.mgrid[0:2*np.pi:20j, 0:np.pi:10j]
x = np.cos(u)*np.sin(v)
y = np.sin(u)*np.sin(v)
z = np.cos(v)
ax.plot_wireframe(x, y, z, color="gray")

# draw a point
ax.scatter([0], [0], [0], color="g", s=100)
```

```
# draw a vector
from matplotlib.patches import FancyArrowPatch
from mpl_toolkits.mplot3d import proj3d

class Arrow3D(FancyArrowPatch):
    def __init__(self, xs, ys, zs, *args, **kwargs):
        FancyArrowPatch.__init__(self, (0, 0), (0, 0), *args, **kwargs)
        self._verts3d = xs, ys, zs
    def draw(self, renderer):
        xs3d, ys3d, zs3d = self._verts3d
        xs, ys, zs = proj3d.proj_transform(xs3d, ys3d, zs3d, renderer.M)
        self.set_positions((xs[0], ys[0]), (xs[1], ys[1]))
        FancyArrowPatch.draw(self, renderer)

a = Arrow3D([0, 1], [0, 1], [0, 1], mutation_scale=20,
            lw=1, arrowstyle="-|>", color="k")
ax.add_artist(a)
plt.show()
```





Draw Points

Demo Program: BuckinghamPalace.py

```
# draw a point
ax.scatter([0], [0], [0], color="g", s=100)
ax.scatter([1], [0], [0], color="k", s=20)
ax.scatter([-1], [0], [0], color="k", s=20)
ax.scatter([0], [1], [0], color="k", s=20)
ax.scatter([0], [-1], [0], color="k", s=20)
ax.scatter([0], [0], [1], color="k", s=20)
ax.scatter([0], [0], [-1], color="k", s=20)
ax.scatter([xt], [yt], [zt], color="r", s=100)
ax.scatter([xb], [yb], [zb], color="b", s=100)
ax.set_xlabel('x')
ax.set_ylabel('y')
ax.set_zlabel('z')
```



Draw Vectors

Demo Program: BuckinghamPalace.py

```
a = Arrow3D([0, 1], [0, 0], [0, 0], mutation_scale=20,  
            lw=1, arrowstyle="-", color="k")  
ax.add_artist(a)  
c = Arrow3D([0, -1], [0, 0], [0, 0], mutation_scale=20,  
            lw=1, arrowstyle="-", color="k")  
ax.add_artist(c)  
d = Arrow3D([0, 0], [0, 1], [0, 0], mutation_scale=20,  
            lw=1, arrowstyle="-", color="k")  
ax.add_artist(d)  
e = Arrow3D([0, 0], [0, -1], [0, 0], mutation_scale=20,  
            lw=1, arrowstyle="-", color="k")  
ax.add_artist(e)  
f = Arrow3D([0, 0], [0, 0], [0, -1], mutation_scale=20,  
            lw=1, arrowstyle="-", color="k")  
ax.add_artist(f)
```



Draw Vectors

Demo Program: BuckinghamPalace.py

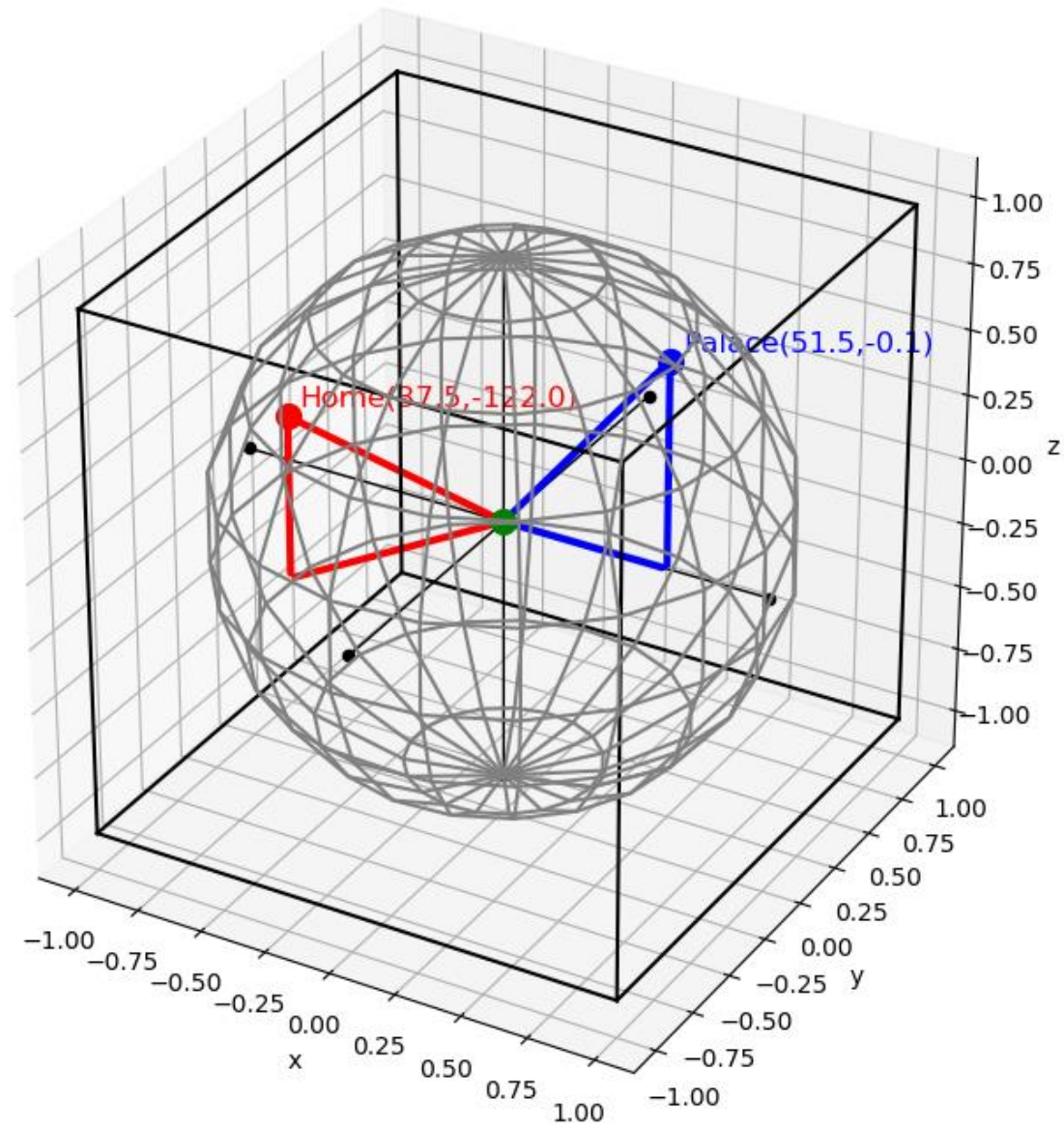
```
g = Arrow3D([0, 0], [0, 0], [0, 1], mutation_scale=20,  
            lw=1, arrowstyle="-", color="k")  
ax.add_artist(g)  
ax.text(xt+0.03,yt+0.03,zt+0.03, '%s' % "Home(37.5,-122.0)", size=12,  
        zorder=1, color='r')  
ht = Arrow3D([0, xt], [0, yt], [0, zt], mutation_scale=20,  
            lw=3, arrowstyle="-", color="r")  
ax.add_artist(ht)  
it = Arrow3D([0, xt], [0, yt], [0, 0], mutation_scale=20,  
            lw=3, arrowstyle="-", color="r")  
ax.add_artist(it)  
jt = Arrow3D([xt, xt], [yt, yt], [zt, 0], mutation_scale=20,  
            lw=3, arrowstyle="-", color="r")  
ax.add_artist(jt)  
ax.text(xb+0.03,yb+0.03,zb+0.03, '%s' % "Palace(51.5,-0.1)", size=12,  
        zorder=1, color='b')
```




Draw Vectors

Demo Program: BuckinghamPalace.py

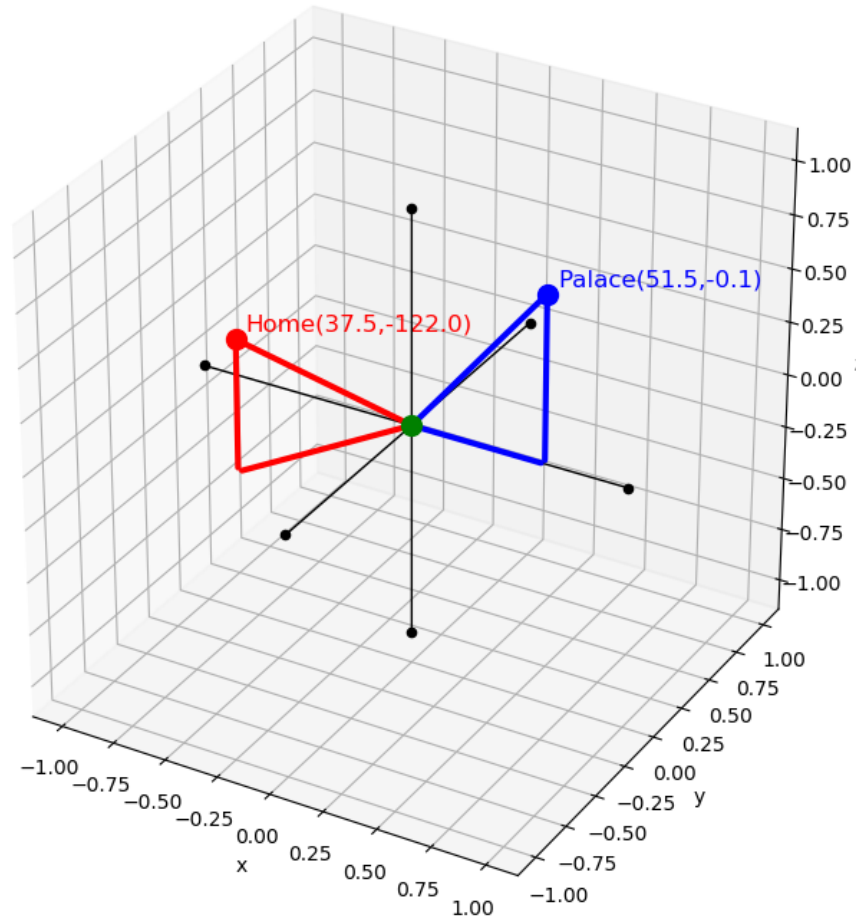
```
hb = Arrow3D([0, xb], [0, yb], [0, zb], mutation_scale=20,  
             lw=3, arrowstyle="-", color="b")  
ax.add_artist(hb)  
ib = Arrow3D([0, xb], [0, yb], [0, 0], mutation_scale=20,  
            lw=3, arrowstyle="-", color="b")  
ax.add_artist(ib)  
jb = Arrow3D([xb, xb], [yb, yb], [zb, 0], mutation_scale=20,  
            lw=3, arrowstyle="-", color="b")  
ax.add_artist(jb)
```

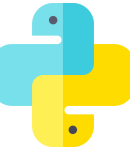




Buckingham Palace

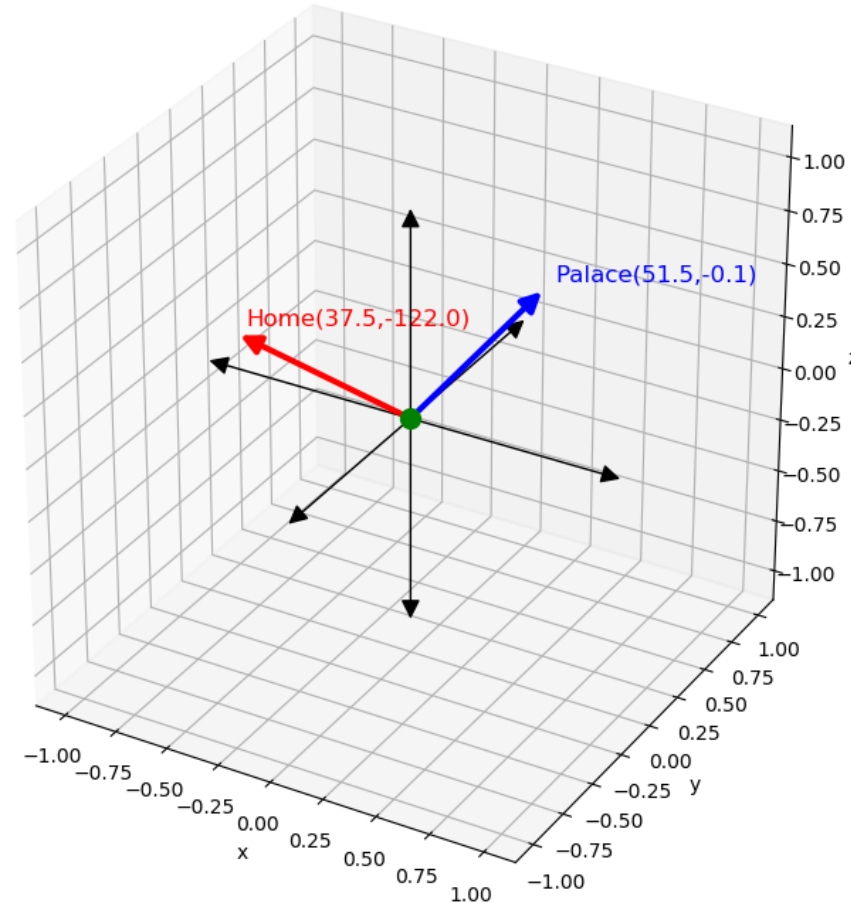
Demo Program: BuckinghamPalaceNoCubeNoBall.py





Buckingham Palace

Demo Program: BuckinghamPalaceVector.py





Storm Tracker

LECTURE 3



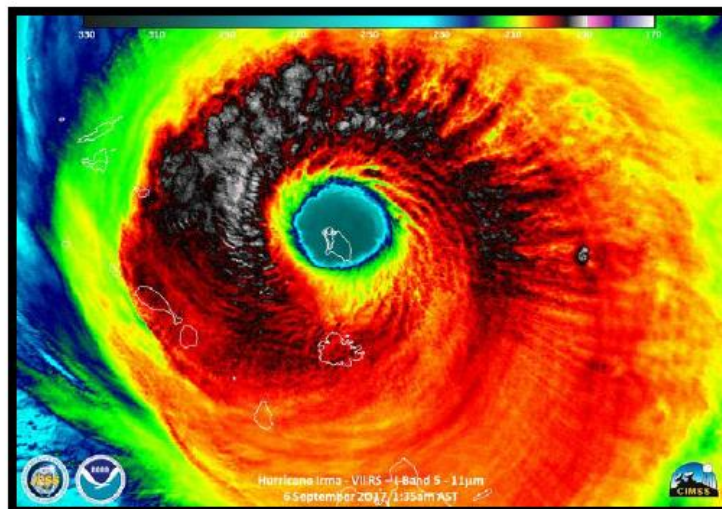
NATIONAL HURRICANE CENTER TROPICAL CYCLONE REPORT

HURRICANE IRMA

(AL112017)

30 August–12 September 2017

John P. Cangialosi, Andrew S. Latta, and Robbie Berg
National Hurricane Center
30 June 2018¹



<https://coast.noaa.gov/hurricanes/#map=4/32/-80>



MATCHING STORMS

1

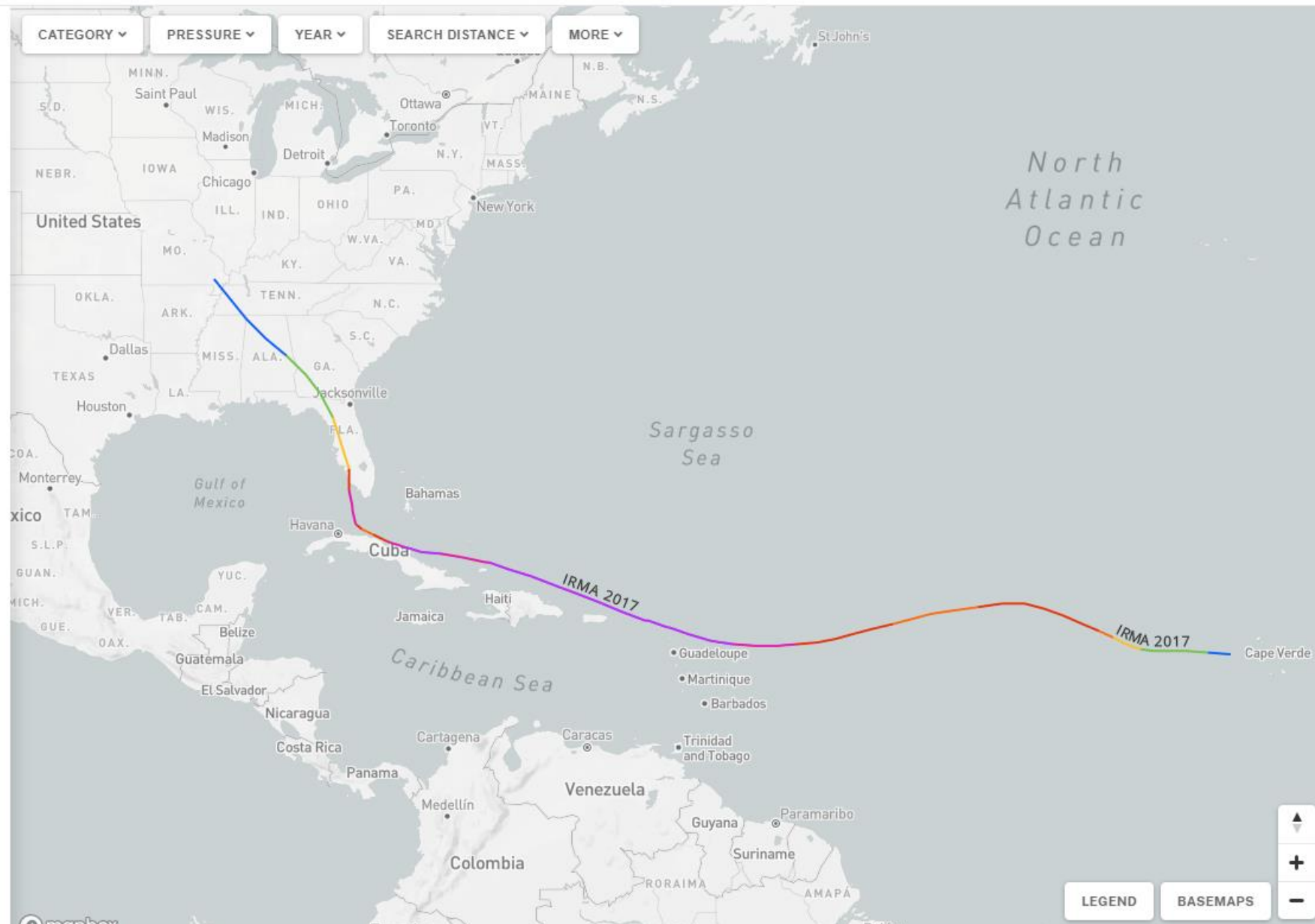
SORTED BY

Year (Newest)



HURRICANE
IRMA 2017

Aug 30, 2017 to Sep 13, 2017





Data Set

File: Irma.txt

- Date/Time(UTC),
- Latitude(°N),
- Longitude(°W),
- Pressure(mb),
- WindSpeed (kt),
- Stage


```
from pylab import *
from statistics import mean
f = open("Irma.txt", 'r')
tokens = f.readline().split(',')
for i in range(len(tokens)):
    tokens[i] = tokens[i].strip().lstrip()
    #print(tokens[i])
# assign the title strings
title_dete_time = tokens[0]
title_latitude = tokens[1]
title_longitude = tokens[2]
title_pressure = tokens[3]
title_windspeed = tokens[4]
title_stage = tokens[5]
print("%-14s %-13s %-14s %-12s %-14s %-8s" % (
    title_dete_time,
    title_latitude,
    title_longitude,
    title_pressure,
    title_windspeed,
    title_stage
))
```

```

30 / 0000 16.1 26.9 1008 30 tropical depression
30 / 0600 16.2 28.3 1007 35 tropical storm
30 / 1200 16.3 29.7 1006 45 "
30 / 1800 16.3 30.8 1004 50 "
31 / 0000 16.3 31.7 999 55 "
31 / 0600 16.4 32.5 994 65 hurricane
31 / 1200 16.7 33.4 983 80 "
31 / 1800 17.1 34.2 970 95 "
01 / 0000 17.5 35.1 967 100 "
01 / 0600 17.9 36.1 967 100 "
01 / 1200 18.4 37.3 967 100 "
01 / 1800 18.8 38.5 967 100 "
02 / 0000 19.1 39.7 967 100 "
02 / 0600 19.1 41.1 967 100 "
02 / 1200 18.9 42.6 973 95 "
02 / 1800 18.7 44.1 973 95 "
03 / 0000 18.5 45.5 973 95 "
03 / 0600 18.2 46.7 973 95 "
03 / 1200 17.9 47.9 969 100 "
03 / 1800 17.6 49.2 965 100 "
04 / 0000 17.3 50.4 959 100 "
04 / 0600 17.0 51.5 952 105 "
04 / 1200 16.8 52.6 945 110 "
04 / 1800 16.7 53.9 944 115 "
05 / 0000 16.6 55.1 943 125 "
05 / 0600 16.6 56.4 933 135 "
05 / 1200 16.7 57.8 929 150 "
05 / 1800 16.9 59.2 926 155 "
06 / 0000 17.3 60.6 915 155 "

```

```

06 / 0600 17.7 61.9 914 155 "
06 / 1200 18.1 63.3 915 155 "
06 / 1800 18.6 64.7 916 150 "
07 / 0000 19.2 66.2 916 150 "
07 / 0600 19.7 67.6 920 145 "
07 / 1200 20.2 69.0 921 145 "
07 / 1800 20.7 70.4 922 145 "
08 / 0000 21.1 71.8 919 140 "
08 / 0600 21.5 73.2 925 135 "
08 / 1200 21.8 74.7 927 135 "
08 / 1800 22.0 76.0 925 140 "
09 / 0000 22.1 77.2 924 145 "
09 / 0600 22.4 78.3 930 130 "
09 / 1200 22.7 79.3 941 110 "
09 / 1800 23.1 80.2 938 95 "
10 / 0000 23.4 80.9 932 100 "
10 / 0600 23.7 81.3 930 115 "
10 / 1200 24.5 81.5 931 115 "
10 / 1800 25.6 81.7 936 100 "
11 / 0000 26.8 81.7 942 80 "
11 / 0600 28.2 82.2 961 65 "
11 / 1200 29.6 82.7 970 50 tropical storm
11 / 1800 30.9 83.5 980 45 "
12 / 0000 31.9 84.4 986 35 "
12 / 0600 32.9 85.6 997 25 low
12 / 1200 33.8 86.9 1000 20 "
12 / 1800 34.8 88.1 1003 15 "
13 / 0000 35.6 88.9 1004 15 "
13 / 0600 36.2 89.5 1004 15 "
13 / 1200 36.8 90.1 1005 15 "

```

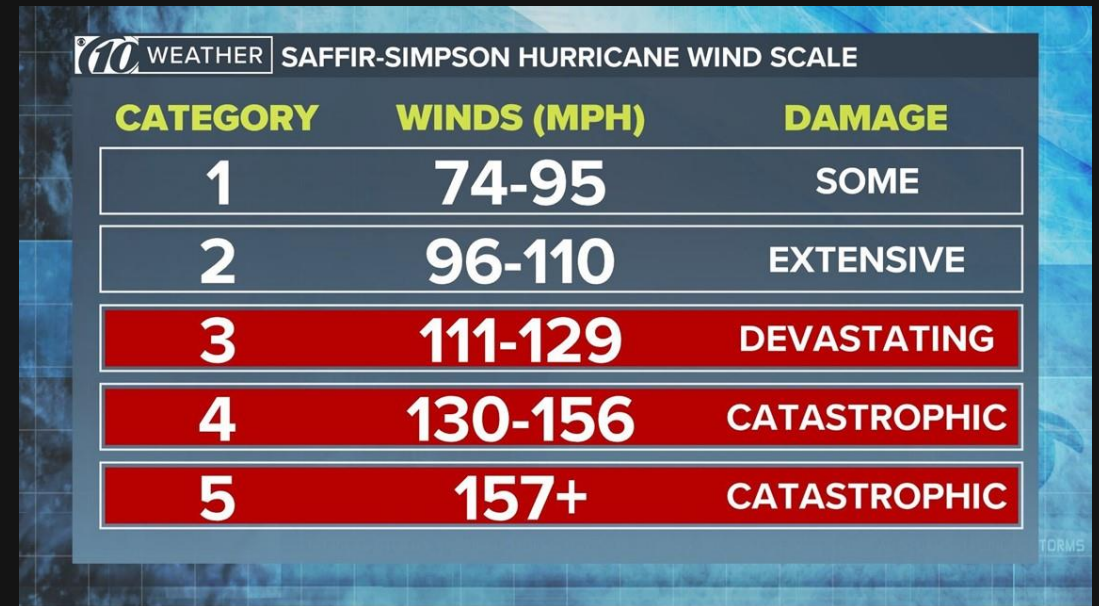
```

irma_path = []
lines = f.readlines()
for line in lines:
    tokens = line.split(' ')
    d = dict()
    for i in range(len(tokens)):
        tokens[i] = tokens[i].strip().lstrip()
        #print(tokens[i], end=" ")
        d['date'] = int(tokens[0])
        d['hour'] = tokens[2]
        d['location'] = (float(tokens[3]), float(tokens[4]))
        d['pressure'] = int(tokens[5])
        d['wind'] = int(tokens[6])
        d['type'] = tokens[7]
        for j in range(8, len(tokens)):
            d['type'] += " "+tokens[j]

    print("      %-14s %-13.2f %-14.2f %-10d %-14d %-s" % (
        str(""+str(d['date'])+"/"+d['hour']),
        d['location'][0],
        d['location'][1],
        d['pressure'],
        d['wind'],
        d['type']
    ))
    irma_path.append(d)

```

```
def category(wind):  
    if (wind>=157): return 5  
    if (wind>=130): return 4  
    if (wind>=111): return 3  
    if (wind>=96): return 2  
    if (wind>=74): return 1  
    return 0
```



The image shows a graphic of the Saffir-Simpson Hurricane Wind Scale. It features a table with five categories, each with a corresponding wind speed range and damage description. The background is a blue and white grid pattern. The table is titled 'SAFFIR-SIMPSON HURRICANE WIND SCALE' and includes a 'WEATHER' logo. The categories are numbered 1 through 5, with wind speeds in MPH and damage descriptions. Categories 3, 4, and 5 are highlighted in red.

CATEGORY	WINDS (MPH)	DAMAGE
1	74-95	SOME
2	96-110	EXTENSIVE
3	111-129	DEVASTATING
4	130-156	CATASTROPHIC
5	157+	CATASTROPHIC

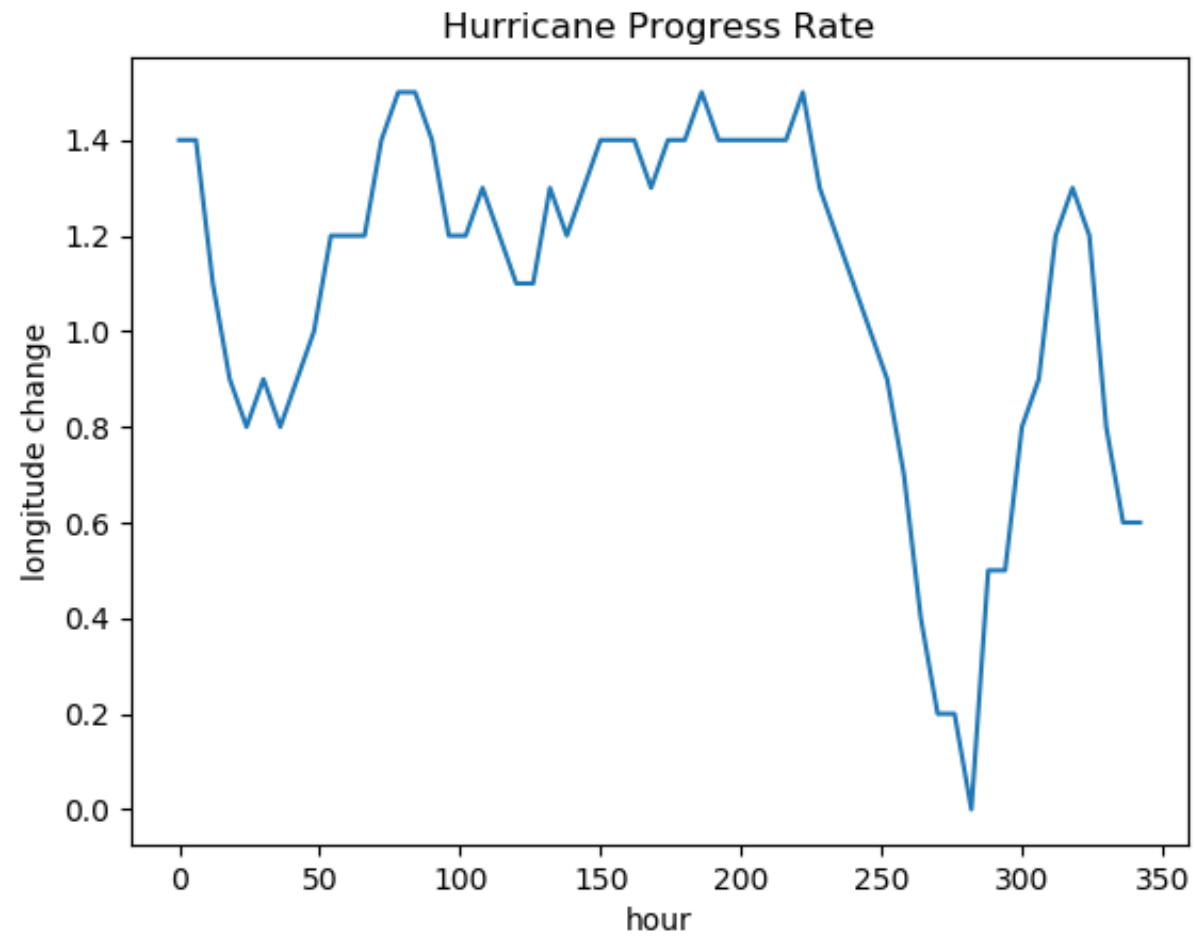
```

g = open("Irma_cat.txt", "w+")
print()
print()
print("Date:Time          Lat.  Long. Cat.", file=g)
# filtering out non-hurricane points.
for d in irma_path:
    if (category(d['wind']*1.15078)==0):
        del d
    elif (int(d['hour'][:2])%6!=0): del d          # take out extra points
    else:
        d['cat'] = category(d['wind']*1.15078)
        if (d['date']>15): print('2017/08', end='', file=g)
        else: print('2017/09', end='', file=g)
        print("/%02d" % d['date'], end=":", file=g)
        print("[%2s:%2s]" % (d['hour'][:2], d['hour'][2:]), end=' ', file=g)
        print("%5.2f" % d['location'][0], end=' ', file=g)
        print("%5.2f" % d['location'][1], end=' ', file=g)
        print(" %d " % d['cat'], file=g)

lat_list = [d['location'][0] for d in irma_path]
lon_list = [d['location'][1] for d in irma_path]

lon = [i*6 for i in range(len(lon_list)-1)]
lon_diff = [(lon_list[i+1]-lon_list[i]) for i in range(len(lon_list)-1)]
avg = mean(lon_diff)

```



```
figure()
title('Hurricane Progress Rate')
xlabel('hour')
ylabel('longitude change')
plot(lon, lon_diff)
show()
```

```
print("Total Number of Data Points: ", len(lat_list))
# regression (Exponential Regression)
t = linspace(0, 6*(len(lon_list)-1), len(lon_list))
x = 26.9 + avg * (t//6)
print(x)
print(avg)
a = 16.1
b = 1.013
y = a * b ** (x-26.9)

a1 = 0.000165
b1 = 0.0000013
c1 = 16.1
y1 = a1*t**2 + b1*t + c1

a2 = 0.00000142
b2 = -0.00050
c2 = 0.060
d2 = 16.1
y2 = a2*t**3 + b2*t**2 + c2 * t + d2
```

Total Number of Data Points: 59

[26.9	27.98965517	29.07931034	30.16896552	31.25862069	32.34827586
33.43793103	34.52758621	35.61724138	36.70689655	37.79655172	38.8862069
39.97586207	41.06551724	42.15517241	43.24482759	44.33448276	45.42413793
46.5137931	47.60344828	48.69310345	49.78275862	50.87241379	51.96206897
53.05172414	54.14137931	55.23103448	56.32068966	57.41034483	58.5
59.58965517	60.67931034	61.76896552	62.85862069	63.94827586	65.03793103
66.12758621	67.21724138	68.30689655	69.39655172	70.4862069	71.57586207
72.66551724	73.75517241	74.84482759	75.93448276	77.02413793	78.1137931
79.20344828	80.29310345	81.38275862	82.47241379	83.56206897	84.65172414
85.74137931	86.83103448	87.92068966	89.01034483	90.1]
1.089655172413793					


```
print("Date:Time           Lat.   Long. ")
z = 0
for d in irma_path:
    if (d['date'] > 15): print('2017/08', end='')
    else: print('2017/09', end='')
    print("/%02d" % d['date'], end=":")
    print("[%2s:%2s]" % (d['hour'][:2], d['hour'][2:]), end=' ')
    print("%5.2f" % y2[z], end=' ')
    print("%5.2f" % x[z])
    z += 1
```

Date:Time	Lat.	Long.
2017/08/30:[00:00]	16.10	26.90
2017/08/30:[06:00]	16.44	27.99
2017/08/30:[12:00]	16.75	29.08
2017/08/30:[18:00]	17.03	30.17
2017/08/31:[00:00]	17.27	31.26
2017/08/31:[06:00]	17.49	32.35
2017/08/31:[12:00]	17.68	33.44
2017/08/31:[18:00]	17.84	34.53
2017/09/01:[00:00]	17.99	35.62
2017/09/01:[06:00]	18.11	36.71
2017/09/01:[12:00]	18.21	37.80
2017/09/01:[18:00]	18.29	38.89
2017/09/02:[00:00]	18.36	39.98
2017/09/02:[06:00]	18.41	41.07
2017/09/02:[12:00]	18.45	42.16
2017/09/02:[18:00]	18.49	43.24
2017/09/03:[00:00]	18.51	44.33
2017/09/03:[06:00]	18.52	45.42
2017/09/03:[12:00]	18.54	46.51
2017/09/03:[18:00]	18.55	47.60
2017/09/04:[00:00]	18.55	48.69
2017/09/04:[06:00]	18.56	49.78
2017/09/04:[12:00]	18.57	50.87
2017/09/04:[18:00]	18.59	51.96
2017/09/05:[00:00]	18.61	53.05
2017/09/05:[06:00]	18.64	54.14
2017/09/05:[12:00]	18.68	55.23
2017/09/05:[18:00]	18.74	56.32
2017/09/06:[00:00]	18.80	57.41
2017/09/06:[06:00]	18.88	58.50

Date:Time	Lat.	Long.
2017/09/06:[12:00]	18.98	59.59
2017/09/06:[18:00]	19.10	60.68
2017/09/07:[00:00]	19.24	61.77
2017/09/07:[06:00]	19.40	62.86
2017/09/07:[12:00]	19.59	63.95
2017/09/07:[18:00]	19.80	65.04
2017/09/08:[00:00]	20.04	66.13
2017/09/08:[06:00]	20.31	67.22
2017/09/08:[12:00]	20.62	68.31
2017/09/08:[18:00]	20.96	69.40
2017/09/09:[00:00]	21.33	70.49
2017/09/09:[06:00]	21.74	71.58
2017/09/09:[12:00]	22.19	72.67
2017/09/09:[18:00]	22.68	73.76
2017/09/10:[00:00]	23.22	74.84
2017/09/10:[06:00]	23.80	75.93
2017/09/10:[12:00]	24.43	77.02
2017/09/10:[18:00]	25.10	78.11
2017/09/11:[00:00]	25.83	79.20
2017/09/11:[06:00]	26.61	80.29
2017/09/11:[12:00]	27.44	81.38
2017/09/11:[18:00]	28.33	82.47
2017/09/12:[00:00]	29.28	83.56
2017/09/12:[06:00]	30.28	84.65
2017/09/12:[12:00]	31.35	85.74
2017/09/12:[18:00]	32.48	86.83
2017/09/13:[00:00]	33.68	87.92
2017/09/13:[06:00]	34.94	89.01
2017/09/13:[12:00]	36.27	90.10

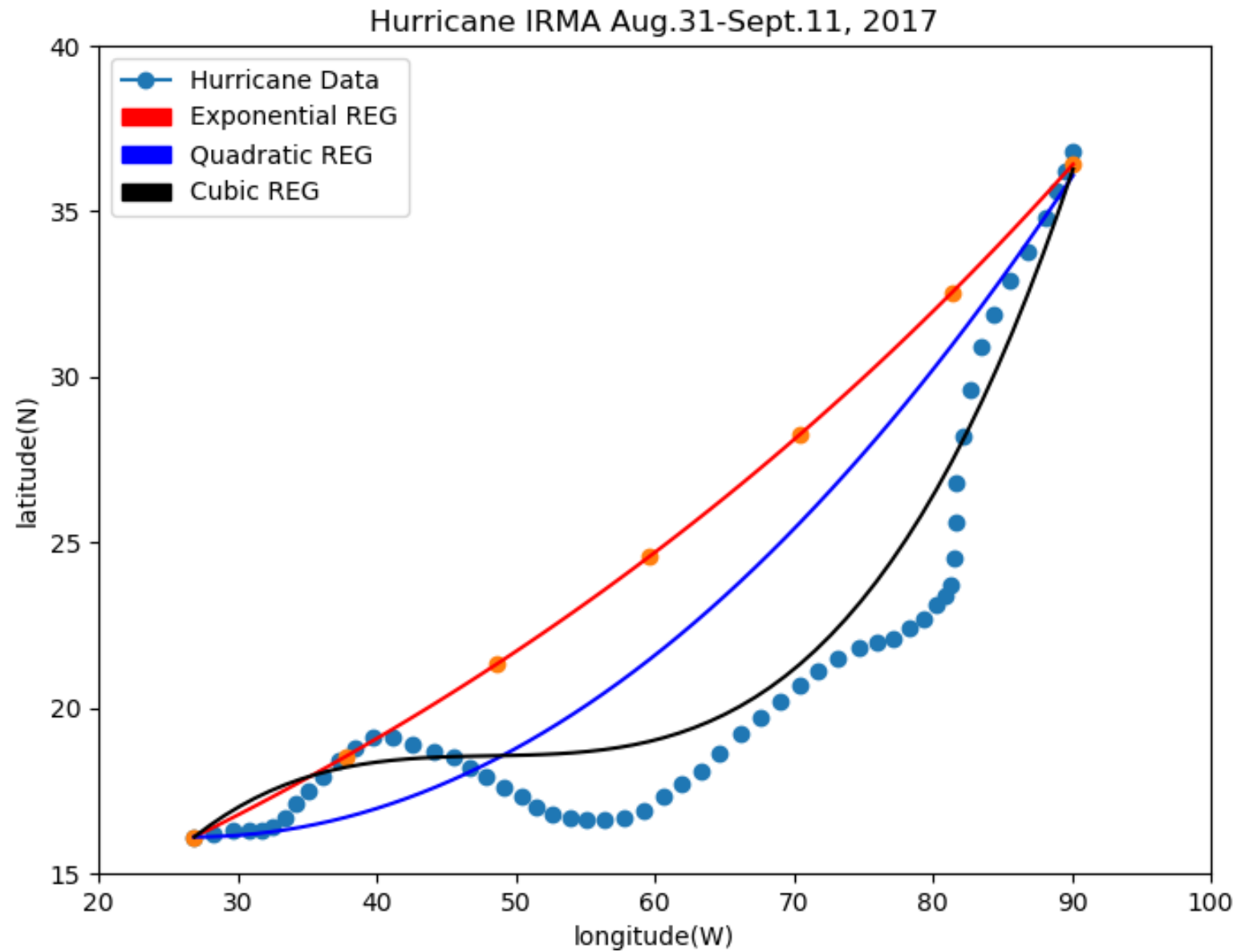
```

import matplotlib.patches as mpatches
figure('Hurricane IRMA Aug.31-Sept.11, 2017', figsize=(8, 6))
xscale('linear')
yscale('linear')
title('Hurricane IRMA Aug.31-Sept.11, 2017')
xlim(20, 100)
ylim(15, 40)
xlabel('longitude(W)')
ylabel('latitude(N)')
scatter(lon_list, lat_list)
plot(x, y, 'r')

scatter([x[0], x[10], x[20], x[30], x[40], x[50], x[58]],
        [y[0], y[10], y[20], y[30], y[40], y[50], y[58]])
plot(x, y1, 'b')
plot(x, y2, 'k')

data_patch = Line2D([], [], marker='o', label='Hurricane Data')
red_patch = mpatches.Patch(color='r', label='Exponential REG')
blue_patch = mpatches.Patch(color='b', label='Quadratic REG')
black_patch = mpatches.Patch(color='k', label='Cubic REG')
legend(handles=[data_patch, red_patch, blue_patch, black_patch], loc=2)
show()

```



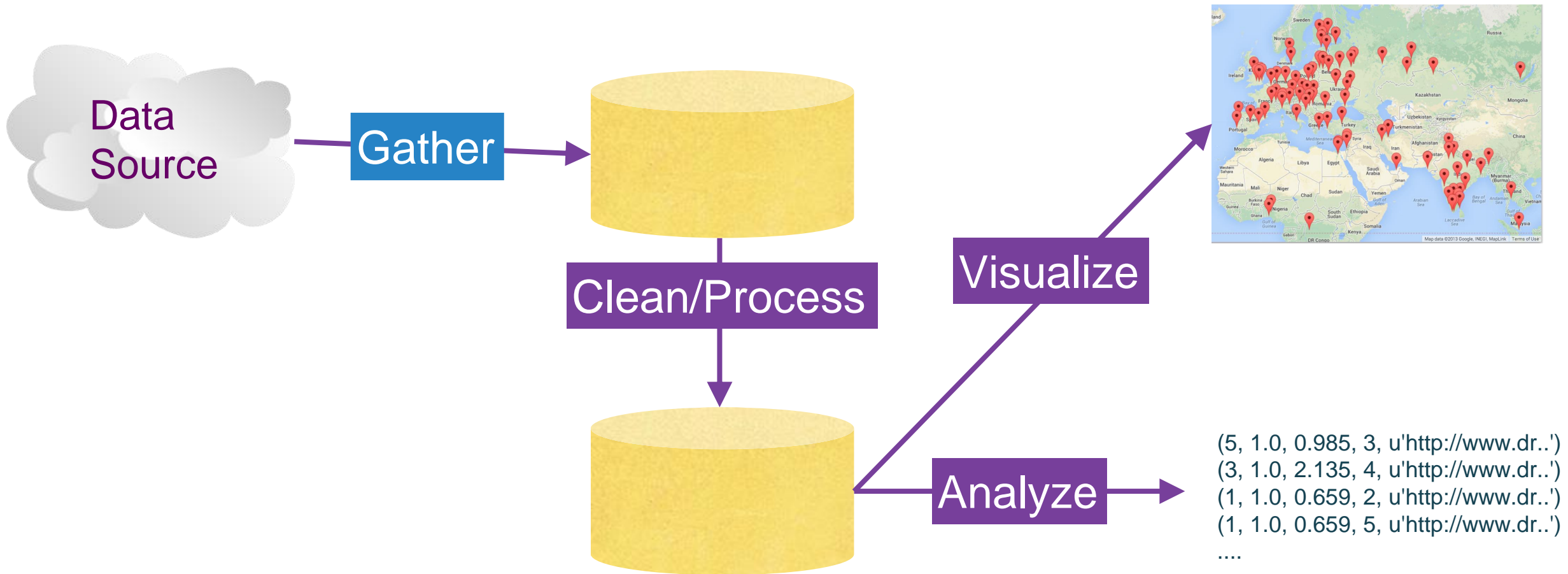


World Universities

LECTURE 4



Multi-Step Data Analysis





Many Data Mining Technologies

<https://hadoop.apache.org/>

<http://spark.apache.org/>

<https://aws.amazon.com/redshift/>

<http://community.pentaho.com/>

....



"Personal Data Mining"

- Our goal is to make you better programmers – not to make you data mining experts

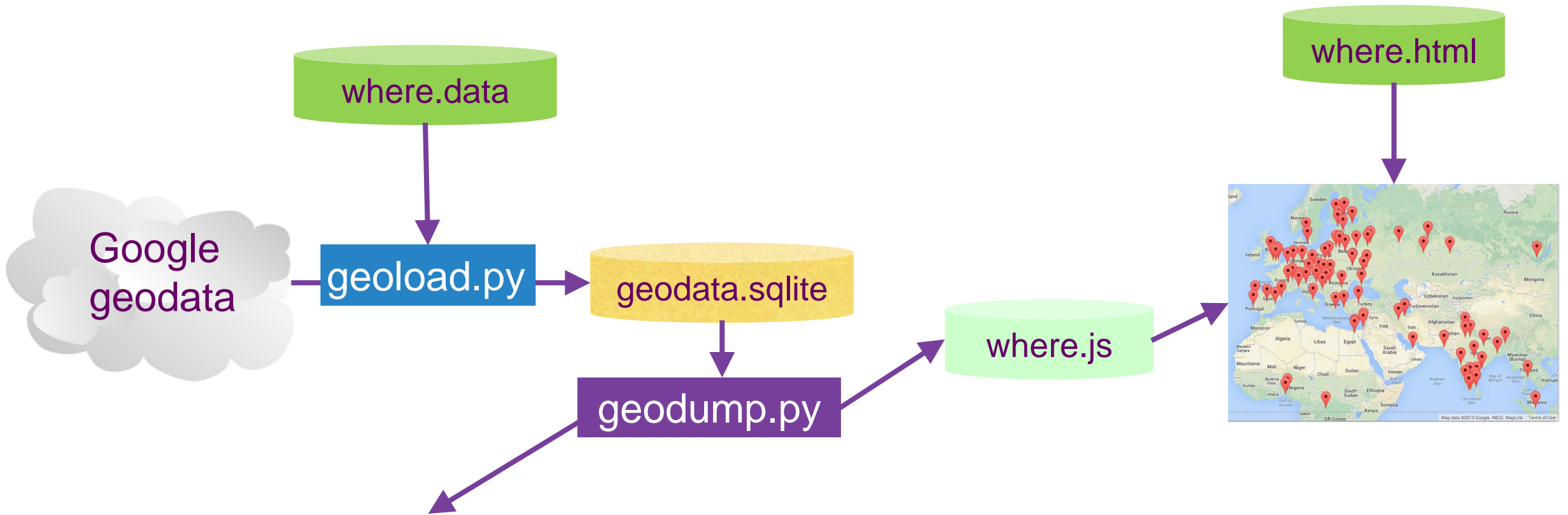


GeoData

- Makes a Google Map from user entered data
- Uses the Google Geodata API
- Caches data in a database to avoid rate limiting and allow restarting
- Visualized in a browser using the Google Maps API



<http://www.py4e.com/code3/geodata.zip>



<http://www.py4e.com/code3/geodata.zip>



Web Crawler

LECTURE 5



Page Rank

- Write a simple web page crawler
- Compute a simple version of Google's Page Rank algorithm
- Visualize the resulting network

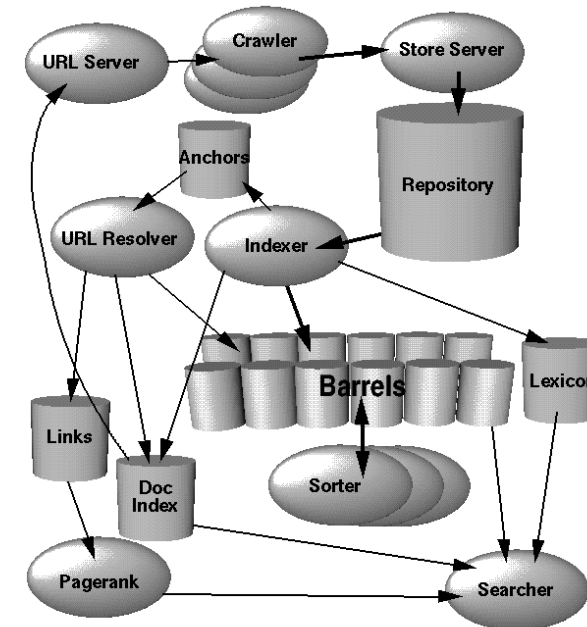


<http://www.py4e.com/code3/pagerank.zip>



Search Engine Architecture

- Web Crawling
- Index Building
- Searching



<http://infolab.stanford.edu/~backrub/google.html>

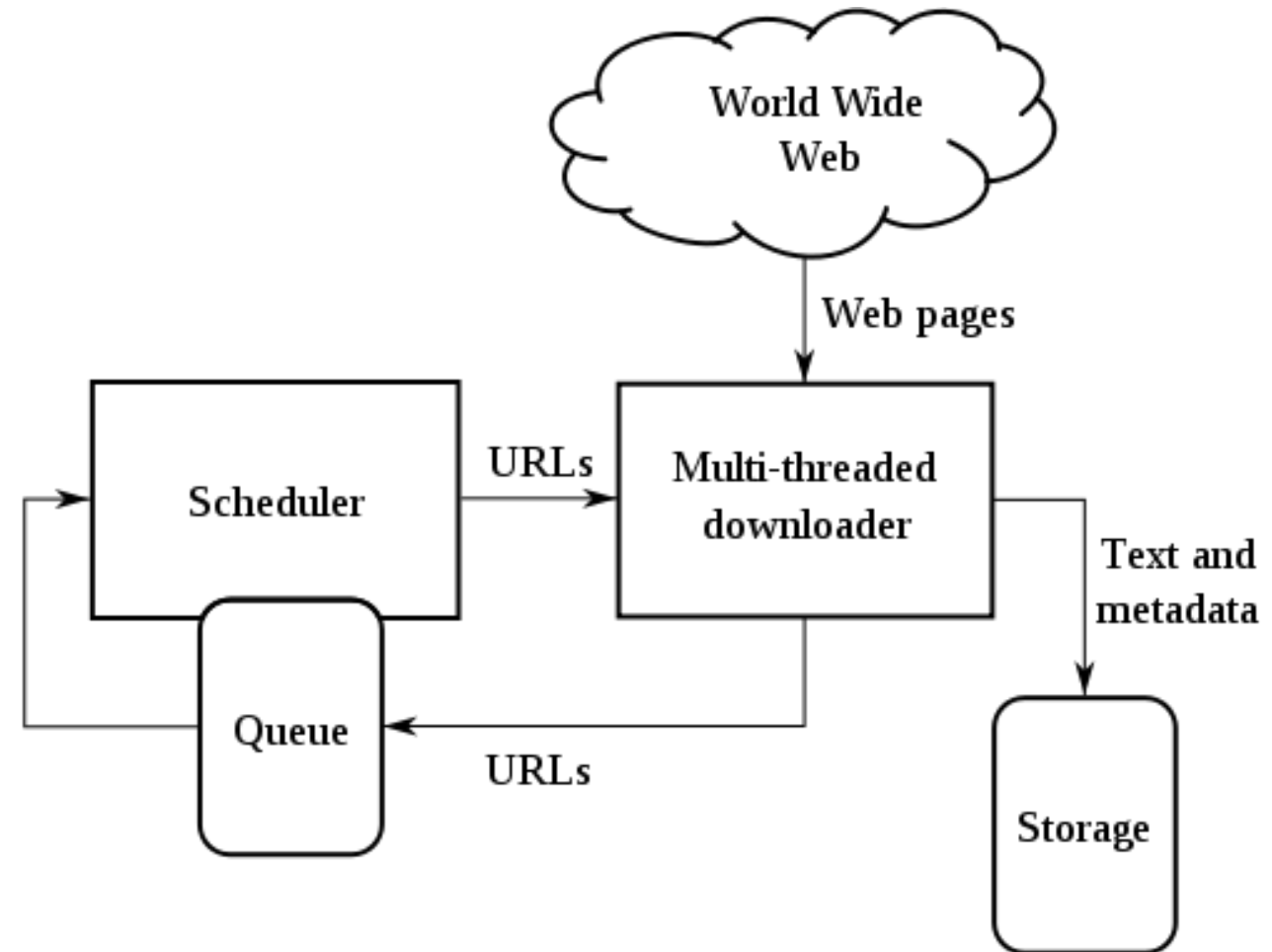


Web Crawler

- A Web crawler is a computer program that browses the World Wide Web in a methodical, automated manner. Web crawlers are mainly used to create a copy of all the visited pages for later processing by a search engine that will index the downloaded pages to provide fast searches.

Web Crawler

- Retrieve a page
- Look through the page for links
- Add the links to a list of “to be retrieved” sites
- Repeat...





Web Crawling Policy

- a selection policy that states which pages to download,
- a re-visit policy that states when to check for changes to the pages,
- a politeness policy that states how to avoid overloading Web sites, and
- a parallelization policy that states how to coordinate distributed Web crawlers



robots.txt

- A way for a web site to communicate with web crawlers
- An informal and voluntary standard
- Sometimes folks make a “Spider Trap” to catch “bad” spiders

User-agent: *
Disallow: /cgi-bin/
Disallow: /images/
Disallow: /tmp/
Disallow: /private/

http://en.wikipedia.org/wiki/Robots_Exclusion_Standard

http://en.wikipedia.org/wiki/Spider_trap



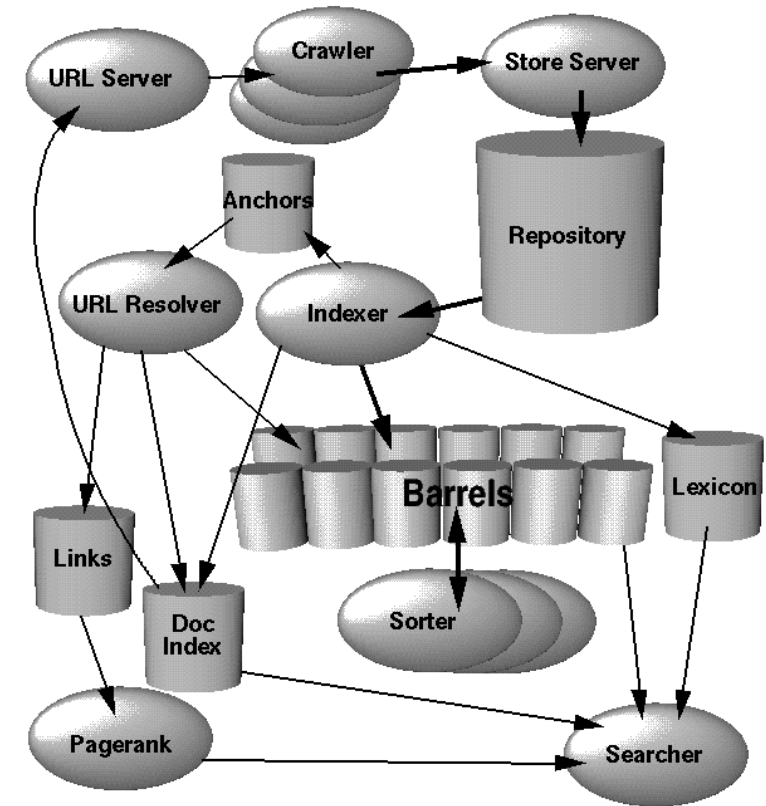
Google Architecture

LECTURE 6



Google Architecture

- Web Crawling
- Index Building
- Searching

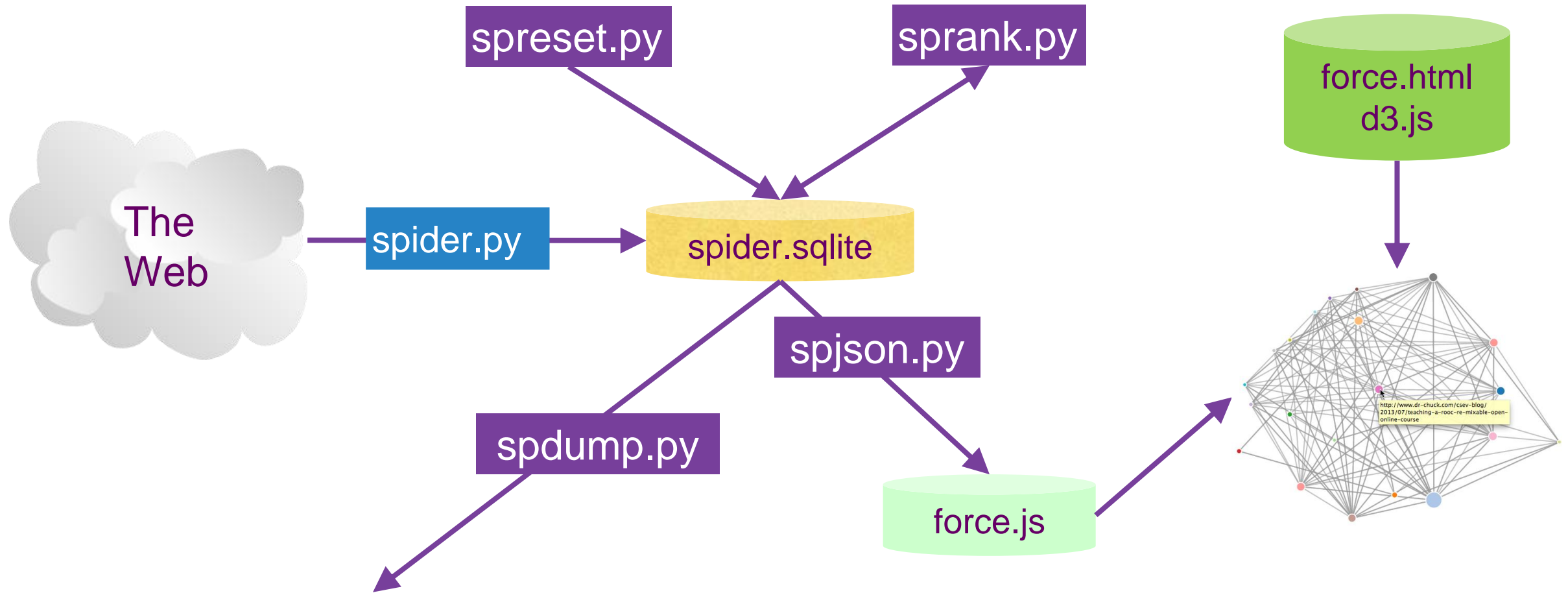


<http://infolab.stanford.edu/~backrub/google.html>



Search Indexing

- Search engine indexing collects, parses, and stores data to facilitate fast and accurate information retrieval. The purpose of storing an index is to optimize speed and performance in finding relevant documents for a search query. Without an index, the search engine would scan every document in the corpus, which would require considerable time and computing power.



(5, None, 1.0, 3, u'http://www.dr-chuck.com/csev-blog')
 (3, None, 1.0, 4, u'http://www.dr-chuck.com/dr-chuck/resume/speaking.htm')
 (1, None, 1.0, 2, u'http://www.dr-chuck.com/csev-blog/')
 (1, None, 1.0, 5, u'http://www.dr-chuck.com/dr-chuck/resume/index.htm')
 4 rows.

<http://www.py4e.com/code3/pagerank.zip>

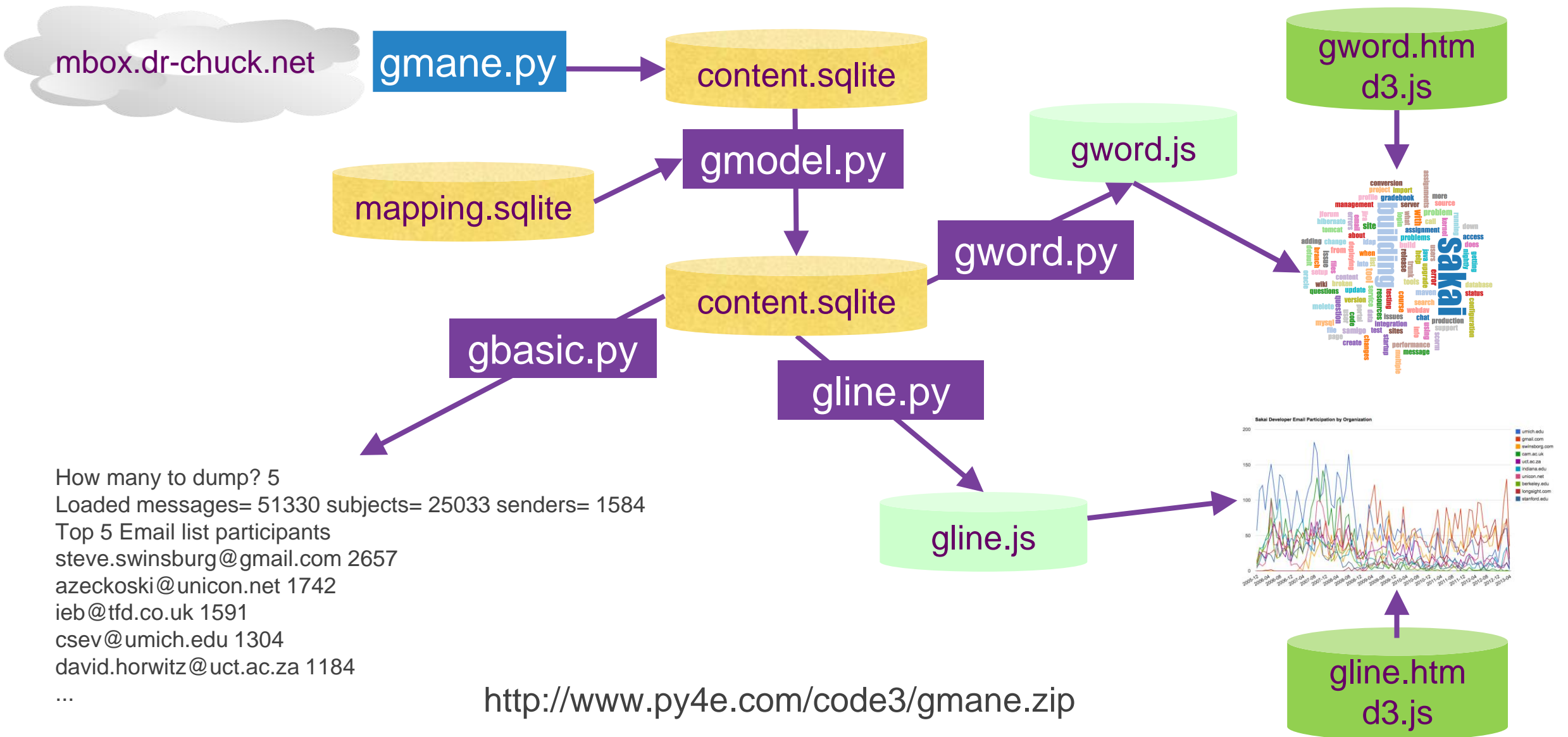


Warning: This Dataset is > 1GB

- Do not just point this application at gmane.org and let it run
- There is no rate limit – these are cool folks

Use this for your testing:

`http://mbox.dr-chuck.net/sakai.devel/4/5`



How many to dump? 5
 Loaded messages= 51330 subjects= 25033 senders= 1584
 Top 5 Email list participants
 steve.swinsburg@gmail.com 2657
 azeckoski@unicon.net 1742
 ieb@tfd.co.uk 1591
 csev@umich.edu 1304
 david.horwitz@uct.ac.za 1184
 ...

<http://www.py4e.com/code3/gmane.zip>