

Introduction to Robotics

Manipulation and Programming

Unit 3: Sensors and Vision

SENSOR DEVELOPMENT KIT XARM (DRY LAB)

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Disclaimer

- •In the following dry lab, the instructor does not promote any product. The example development kit is chosen completely based on the convenience of promoting robot education.
- •Student are not required to purchase any thing. Nor will any part of the hardware components be required to complete any part of the course assignments.
- •These dry lab are designed for demonstration purpose only.





Objective

- Introduce a sensor development kit and assemble it.
- •Give student a sense of what will be needed when a robot system is going to be developed. (Only an example)





XArm and its Secondary Development Kit (SDK)

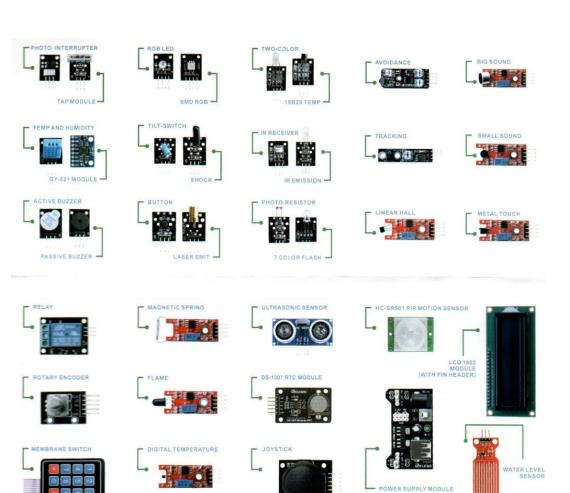
Overview of SDK

SECTION 1

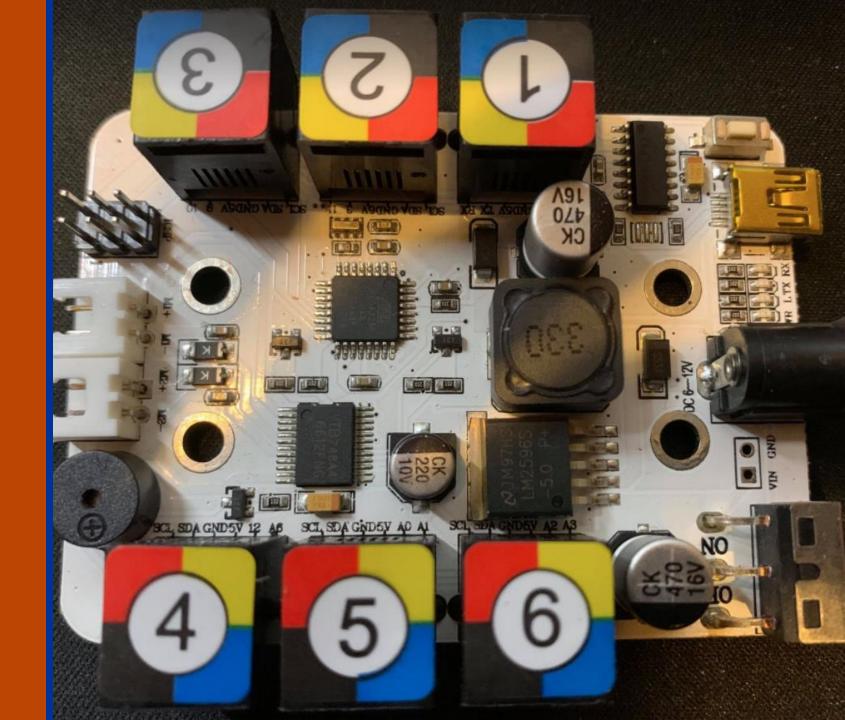
Scratch/Arduino secondary development kit (Extra purchase)

Controller	1pcs	Touch button module	1pcs	Dot matric board	1pcs	Digital tube module	1pc:
Infrared sensor	1pcs	Infrared receiver	1pcs	Infrared remote controller	1pcs	Ultrasonic sensor	1pc
Sound sensor	1pcs	RGBindicator module	1pcs	Rotary knob sensor	1pcs	Serial port switching module	1pc
Servo switching module	1pcs	Micro servo	1pcs	L-shaped bracket	2pcs	Connection wire	6рс

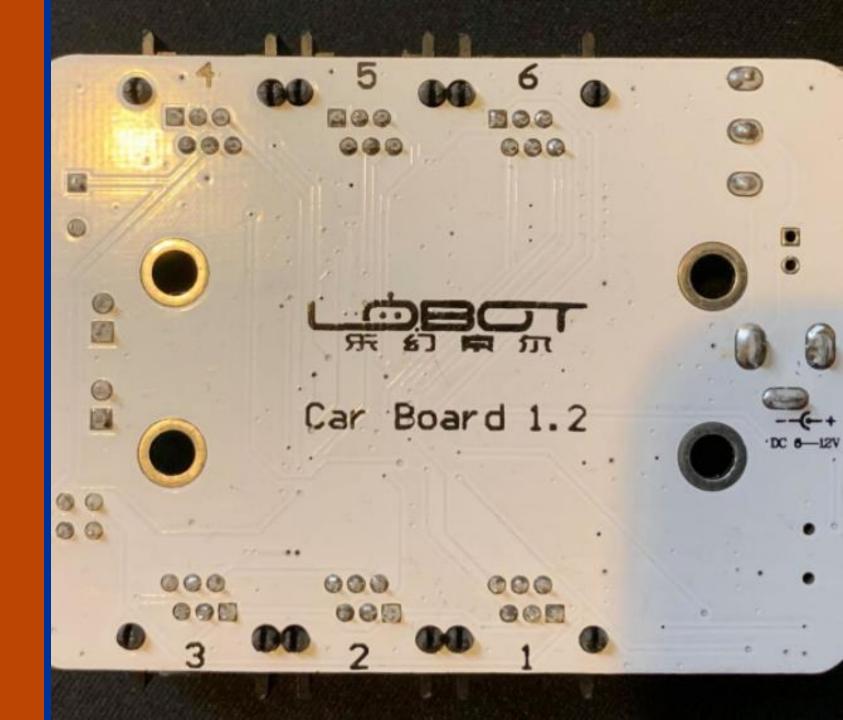




Controller
Connect to
Arduino
Processor and
XArm

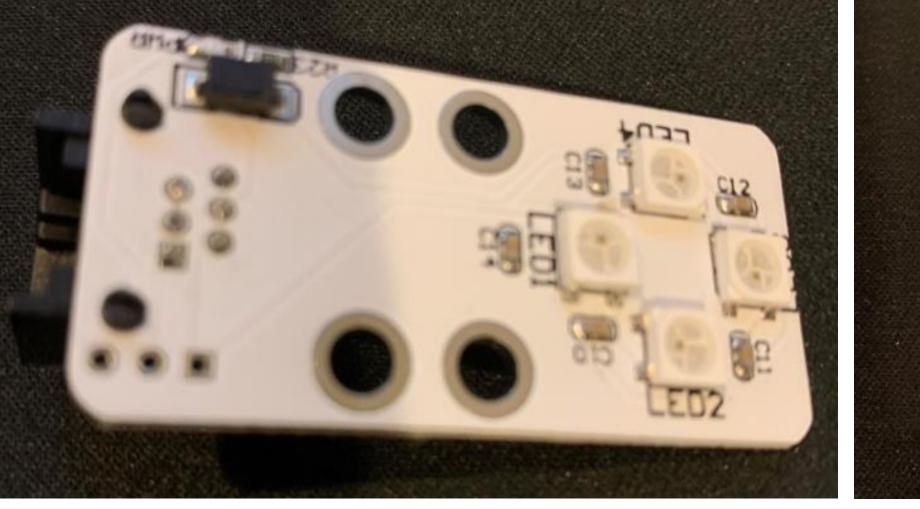


Backview of Controller Board





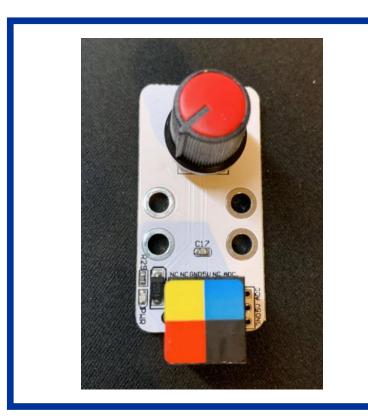
Electrical Sensors

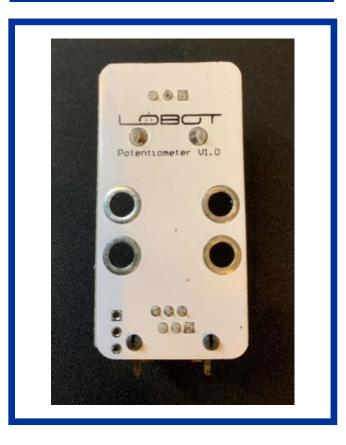




RGB LED Module

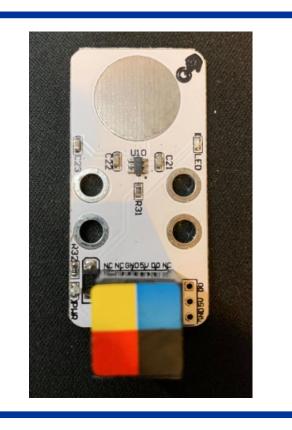
Potentiometer Module

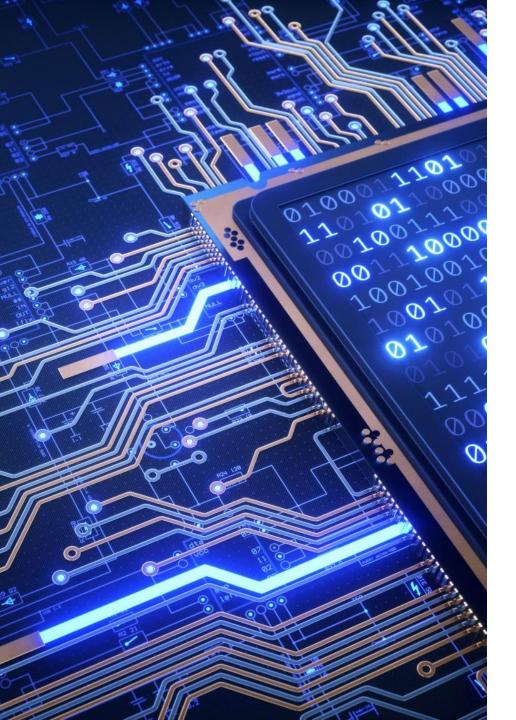




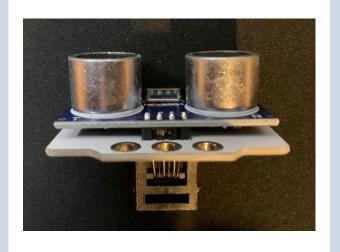
Touch Button Module







Signal Sensors









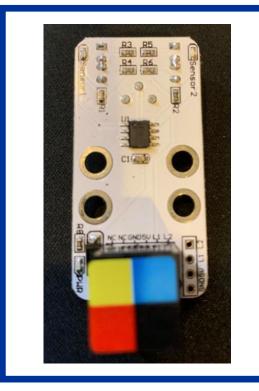
Ultrasonic Sensor Module





Infrared Receiver

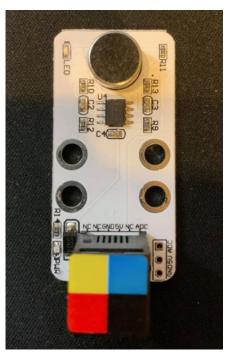




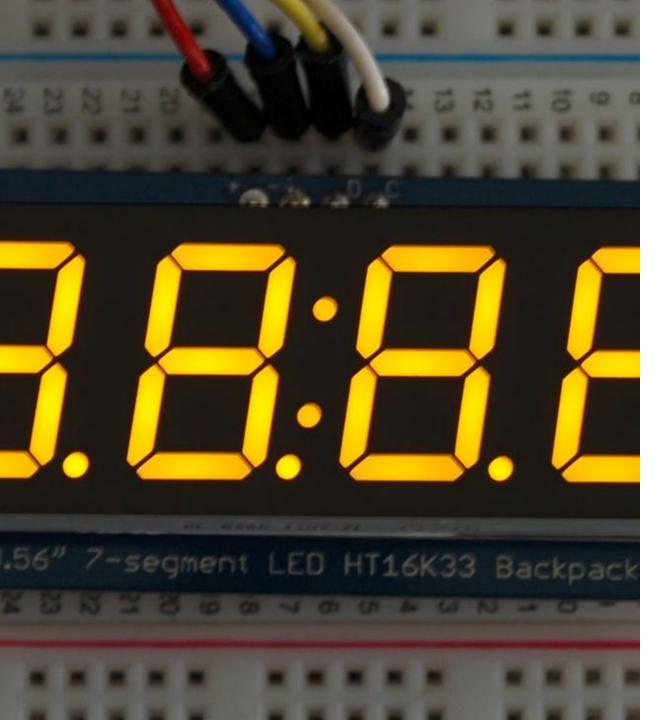
Infrared Sensor (Connector)



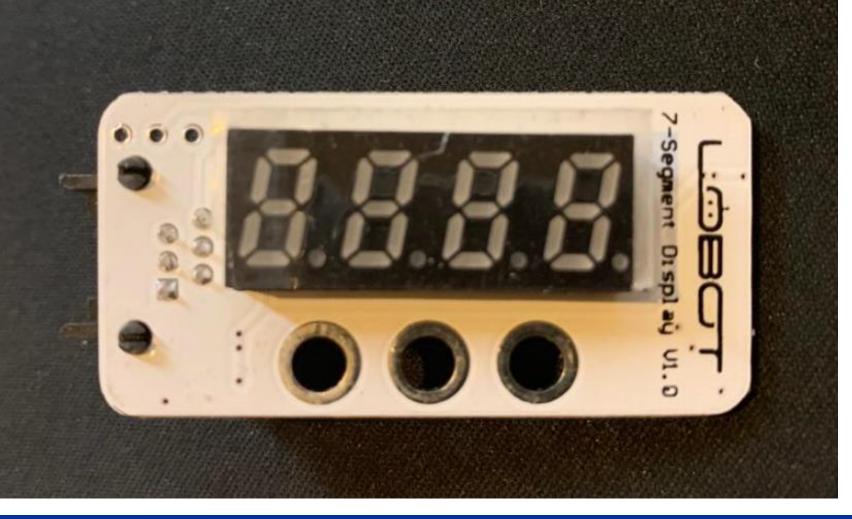


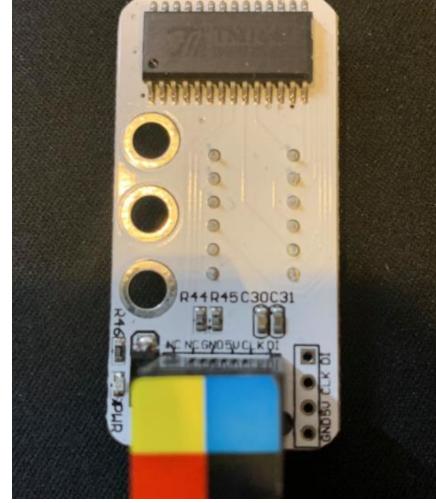


Sound Sensor

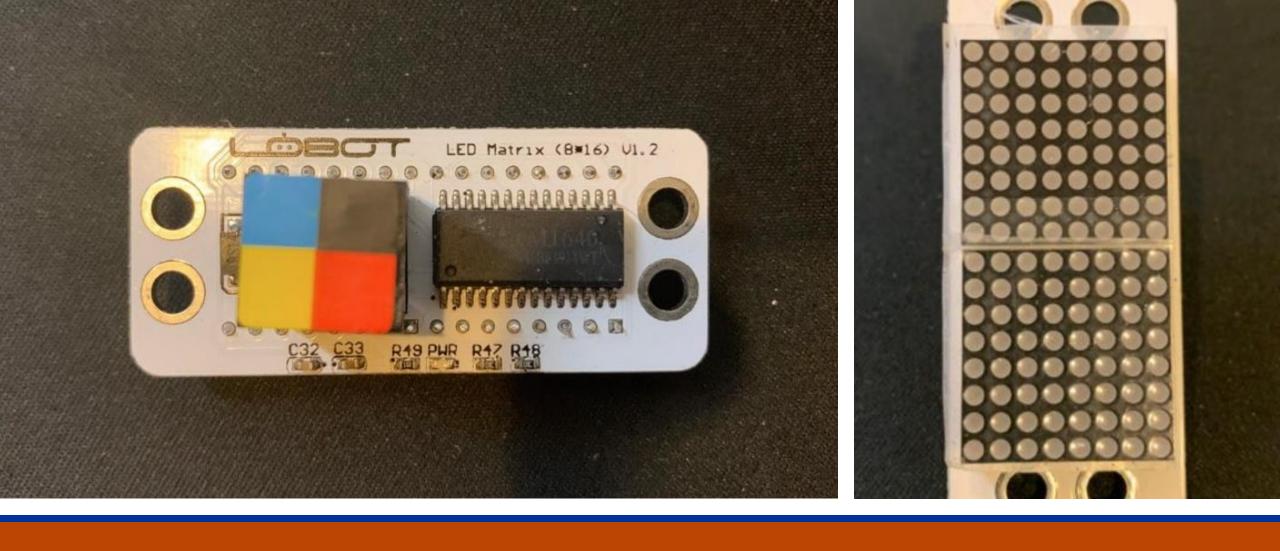


LED Displays





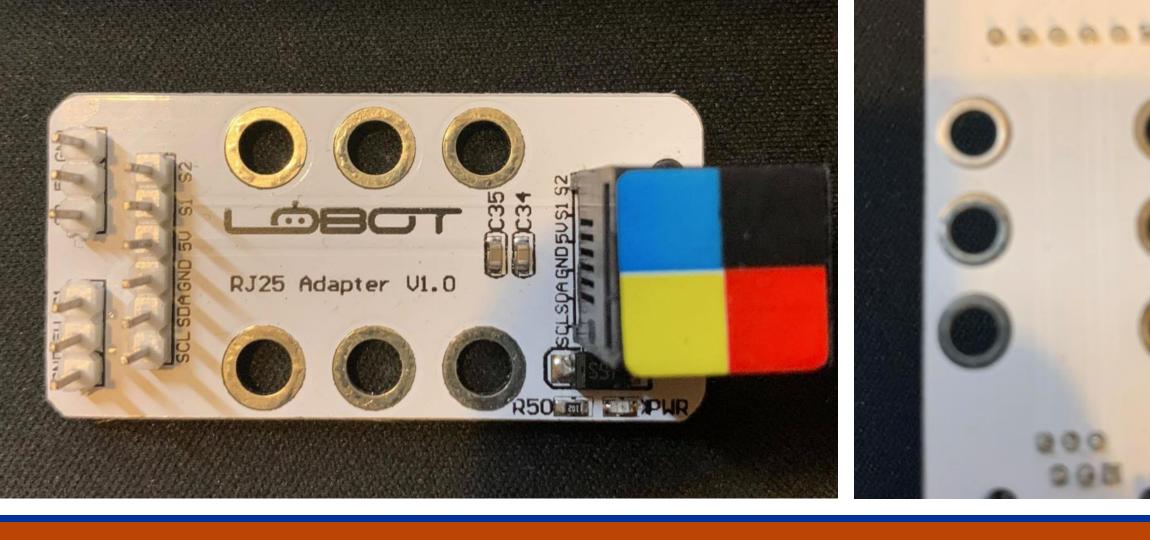
BCD Display
Binary Coded Decimal Display



LED Matrix Display



Connectors



RJ 25 Adapter

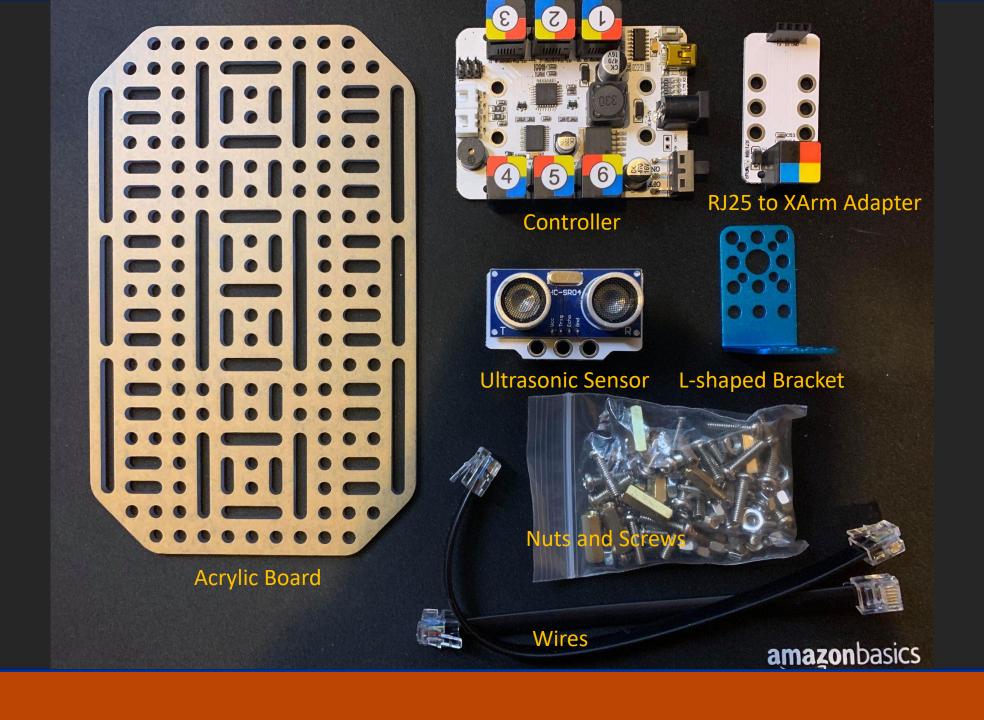
RJ25 to XArm Adapter





Activity 1: Controller and Sensor Assembly

SECTION 2



Action 1: Ultrasonic Sensor

Action 2: Controller Board

Action 3: Ultrasonic Unit to XArm

Action 4: Integration