Introduction to Robotics

Manipulation and Programming

Unit 2: Kinematics

PYTHON LAB PROJECT: SIMPLIFIED (2 DOF) SERIAL MANIPULATOR

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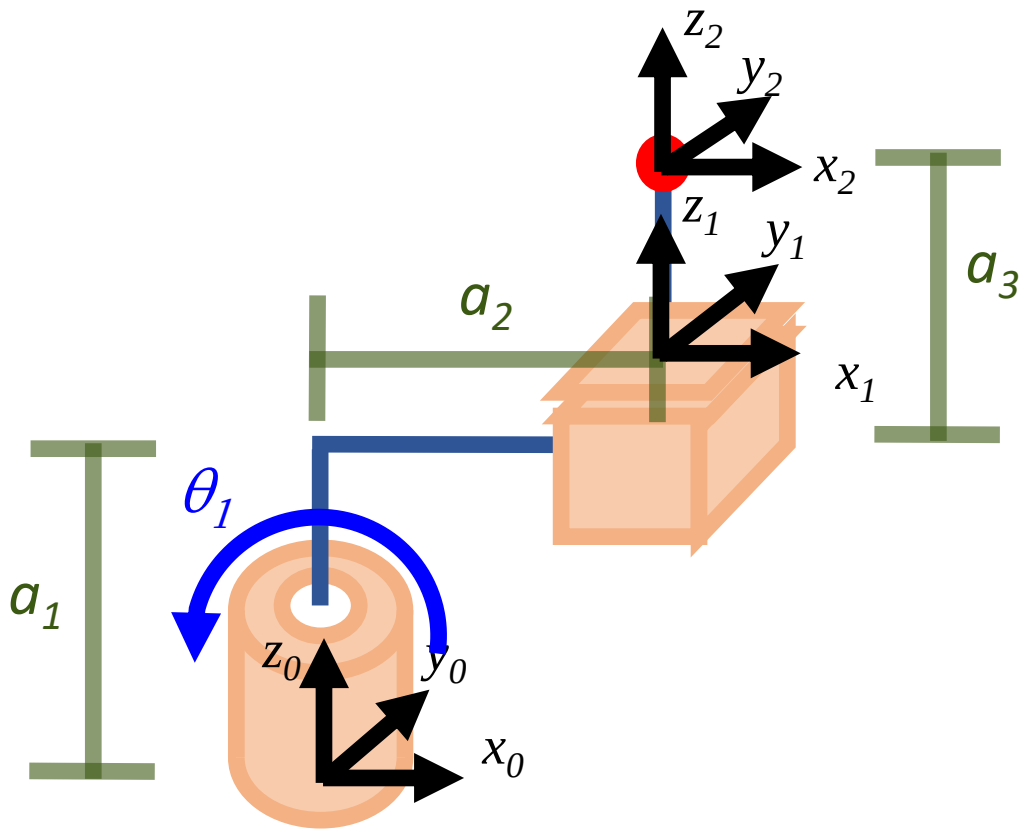
2 DOF Serial Manipulator



Problem:

1) Create the Denavit-Hartenberg Parameter Table. Draw it on a paper and taking picture or use any spreadsheet or word program.
2) Write a Python program to calculate the W0_n for the coordinate of end-effector frame original point w.

submit .py or .zip file