VARIATIONAL APPROXIMATION FOR "FINE-MAPPING" MODEL

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First, we define the "fine-mapping" model:

$$p(y \mid \mathbf{X}, \beta, \sigma^2) = N(y \mid \mathbf{X}\beta_1 + \dots + \mathbf{X}\beta_K, \sigma^2 I)$$

$$p(\beta_{jk} \mid \gamma_k = j) = N(0, \sigma^2 \sigma_a^2)$$

$$p(\beta_{jk} \mid \gamma_k \neq j) = \delta_0$$

$$p(\gamma_k = j) = \pi_j.$$

Next, we define the variational approximation:

$$q(\beta, \gamma; \phi) = \prod_{k=1}^{K} q(\beta_k, \gamma_k; \phi_k)$$

where the individual factors are of the form

$$q(\beta_k, \gamma_k; \phi_k) = \prod_{j=1}^p \left\{ \alpha_{jk} N(\beta_{jk} \mid \mu_{jk}, s_{jk}^2) \right\}^{\delta(\gamma_k = j)} \delta_0(\beta_{jk})^{\delta(\gamma_k \neq j)}$$

Under this approximation, the coefficients ("effects") for the kth mixture component are independent of the coefficients for the other mixture components, conditioned on the hyperparameters.

The variational lower bound

$$F(\theta, \phi) \equiv \iint q(\beta, \gamma; \phi) \log \{p(y, \beta, \gamma | \mathbf{X}, \theta) / q(\beta, \gamma; \phi)\} d\beta d\gamma$$

is derived to be

$$F(\theta, \phi) = -\frac{n}{2} \log(2\pi\sigma^{2}) - \frac{\|y - \mathbf{X}r\|^{2}}{2\sigma^{2}} + \frac{1}{2\sigma^{2}} \sum_{k=1}^{K} \|\mathbf{X}r_{k}\|^{2}$$
$$-\frac{1}{2\sigma^{2}} \sum_{k=1}^{K} \sum_{j=1}^{p} (\mathbf{X}^{T}\mathbf{X})_{jj} \alpha_{jk} (\mu_{jk}^{2} + s_{jk}^{2}) + \sum_{k=1}^{K} \sum_{j=1}^{p} \alpha_{jk} \log\left(\frac{\pi_{j}}{\alpha_{jk}}\right)$$
$$+ \sum_{k=1}^{K} \sum_{j=1}^{p} \frac{\alpha_{jk}}{2} \left[1 + \log\left(\frac{s_{jk}^{2}}{\sigma^{2}\sigma_{a}^{2}}\right) - \frac{\mu_{jk}^{2} + s_{jk}^{2}}{\sigma^{2}\sigma_{a}^{2}} \right],$$

in which r_k is a vector with entries $r_{jk} = \alpha_{jk}\mu_{jk}$, and r is a vector with entries $r_j = \sum_{k=1}^K \alpha_{jk}\mu_{jk}$.

The coordinate descent updates for optimizing the variational lower bound can be obtained by taking partial derivatives of the Kullback-Leibler divergence, setting the partial derivatives to zero, and solving for the parameters α_{jk} , μ_{jk} and s_{jk}^2 . This

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yields coordinate updates

$$\begin{split} s_{jk}^2 &= \frac{\sigma^2}{(\mathbf{X}^T \mathbf{X})_{jj} + 1/\sigma_a^2)} \\ \mu_{jk} &= \frac{s_{jk}^2}{\sigma^2} \bigg((\mathbf{X}^T y)_j - (\mathbf{X}^T \mathbf{X})_{jj} \sum_{k' \neq k} \alpha_{jk'} \mu_{jk'} - \sum_{j' \neq j} (\mathbf{X}^T \mathbf{X})_{jj'} \sum_{k' \neq k} \alpha_{j'k'} \mu_{j'k'} \bigg) \\ \alpha_{jk} &= \end{split}$$