

Div: $\nabla \cdot \vec{v} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$

Curl: $\nabla \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u & v & w \end{vmatrix} = \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \hat{i} - \left(\frac{\partial w}{\partial x} - \frac{\partial u}{\partial z} \right) \hat{j} + \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) \hat{k}$

vorticity: $\xi = 2\omega = \nabla \times \vec{v}$

streamline: $d\vec{s} \times \vec{v} = 0$ (tangent to velocity)

$u dy - v dx = 0$
 $u dz - w dx = 0$
 $v dx - u dy = 0 \rightarrow \frac{dy}{dx} = \frac{v}{u}$

stream: $\psi(x,y) = \psi(r,\theta) \rightarrow u = \frac{\partial \psi}{\partial y} \quad v = -\frac{\partial \psi}{\partial x} \quad v_r = \frac{1}{r} \frac{\partial \psi}{\partial \theta} \quad v_\theta = -\frac{\partial \psi}{\partial r}$

vel. potential: $\vec{v} = \nabla \phi \rightarrow \phi(x,y) \rightarrow u = \frac{\partial \phi}{\partial x} \quad v = \frac{\partial \phi}{\partial y} \quad v_r = \frac{\partial \phi}{\partial r} \quad v_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta}$

incompressible: $\nabla \cdot \vec{v} = 0 \rightarrow \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 = \frac{1}{r} \frac{\partial(rv_r)}{\partial r} + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta}$

irrotational: $\nabla \times \vec{v} = 0 \rightarrow \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = 0 = \frac{1}{r} \left[\frac{\partial(rv_\theta)}{\partial r} - \frac{\partial v_r}{\partial \theta} \right]$

Laplace: $\nabla \cdot \vec{v} = 0$

$\nabla \cdot (\nabla \phi) = 0$

$\nabla^2 \phi = 0$

$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$

$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$
 $\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0$

$\nabla f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k} = \frac{\partial f}{\partial r} \hat{e}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{e}_\theta + \frac{\partial f}{\partial z} \hat{e}_z$

$C_L = \frac{L}{\rho_\infty S} \quad C_D = \frac{D}{\rho_\infty S} \quad C_M = \frac{M}{\rho_\infty S c} \quad q_\infty = \frac{1}{2} \rho v_\infty^2$
 unit span
 $S = c(1)$

$C_L = \frac{L}{\rho_\infty c} \quad C_D = \frac{D}{\rho_\infty c} \quad C_M = \frac{M}{\rho_\infty c^2} \quad C_P = \frac{P - P_\infty}{\rho_\infty} \quad C_f = \frac{\tau}{\rho_\infty}$

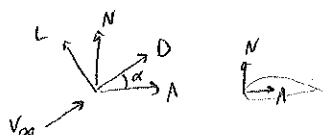
$C_n = \frac{1}{c} \left[\int_0^c (C_{p,l} - C_{p,u}) dx + \int_0^c (C_{f,u} \frac{dy_u}{dx} + C_{f,l} \frac{dy_l}{dx}) dx \right]$

$C_a = \frac{1}{c} \left[\int_0^c (C_{f,u} + C_{f,l}) dx + \int_0^c (C_{p,u} \frac{dy_u}{dx} - C_{p,l} \frac{dy_l}{dx}) dx \right]$

$C_{m,LE} = \frac{1}{c^2} \left[\int_0^c (C_{p,u} - C_{p,l}) x dx - \int_0^c (C_{f,u} \frac{dy_u}{dx} + C_{f,l} \frac{dy_l}{dx}) x dx + \int_0^c (C_{f,u} + C_{f,l} \frac{dy_u}{dx}) y_u dx + \int_0^c (C_{f,l} - C_{p,l} \frac{dy_l}{dx}) y_l dx \right]$

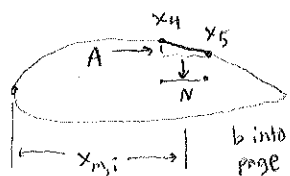
$C_L = C_n \cos \alpha - C_a \sin \alpha$

$C_D = C_n \sin \alpha + C_a \cos \alpha$



$Re = \frac{\rho v c}{\mu} \quad M = \frac{v}{a} \quad a = \sqrt{\gamma R T}$

$p = \rho R T \quad p = p_{RT} \quad C_p = f(Re, M_\infty, \alpha, AR)$



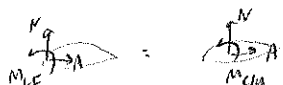
$N_i = b(x_5 - x_4) \left(\frac{\rho_4 + \rho_5}{2} \right)$

$A_i = b(y_5 - y_4) \left(\frac{\rho_4 + \rho_5}{2} \right)$

$M_{LE_i} = N_i \cdot x_{m_i} \quad \text{ignore } A_i \text{ moments}$

$p_8 - p_{24} = -\gamma(h_8 - h_{24}) \quad p + \frac{1}{2} \rho v^2 = \text{constant}$

$M_{LE} = N \left(\frac{c}{4} \right) (-1) + M_{CM} \quad C_{m,x} = C_{m,cm} + C_L \left(\frac{x}{c} - \frac{1}{4} \right)$



$\frac{du}{dt} \approx \frac{u(t+\Delta t) - u(t)}{\Delta t}$

finite-diff

$\frac{d^2 u}{dy^2} = 0$

$\int \frac{d}{dy} \left(\frac{du}{dy} \right) dy = \int dy$

$\frac{du}{dy} = C_1 \rightarrow u = C_1 y + C_2$

$(y=c, u=0) \rightarrow C_2 = 0$

$(y=0, u=v_p) \rightarrow C_1 = \frac{v_p}{d}$

Uniform: $\phi = V_\infty x = V_\infty r \cos \theta$

Circular cylinder: $R = \frac{K}{2\pi V_\infty}$

$\psi = V_\infty y = V_\infty r \sin \theta$

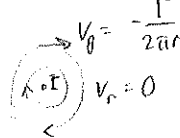
$C_p = 1 - \frac{v^2}{v_\infty^2}$

Source: $\phi = \frac{\Lambda}{2\pi} \ln r \quad \psi = \frac{\Lambda}{2\pi} \theta$

$C_p = 1 - 4 \sin^2 \theta$

Doublet: $\phi = \frac{K}{2\pi r} \cos \theta \quad \psi = \frac{K}{2\pi r} \sin \theta$

Vortex: $\phi = -\frac{\Gamma}{2\pi} \theta \quad \psi = \frac{\Gamma}{2\pi} \ln r$



Lifting cylinder:

$\psi = V_\infty r \sin \theta - \frac{K}{2\pi r} \sin \theta + \frac{\Gamma}{2\pi} \ln r \rightarrow \psi_{stagn} = \frac{\Gamma}{2\pi} \ln R$

$V_\theta = -2V_\infty \sin \theta - \frac{\Gamma}{2\pi R} \rightarrow C_p = 1 - 4 \left[\sin \theta + \frac{\Gamma}{4\pi V_\infty R} \right]^2$

$\rightarrow C_n = \frac{\Gamma}{V_\infty R} \rightarrow \frac{N}{b} = \boxed{N'} = \rho V_\infty \Gamma$

Kutta-Joukowski

$\Gamma = - \oint \vec{v} \cdot d\vec{s} \quad \oint \vec{v} \cdot d\vec{s} = \iint_S (\nabla \times \vec{v}) \cdot d\vec{s} \quad \Gamma = \frac{1}{c} \int_{x=0}^c \gamma(x) dx$

$d\vec{s} = dx \hat{i} + dy \hat{j} = dr \hat{e}_r + r d\theta \hat{e}_\theta$

$C_L = \frac{2\Gamma}{V_\infty c}$

$V_r = V_\infty \cos \theta \left[1 - \frac{R^2}{r^2} \right] \quad V_\theta = -V_\infty \sin \theta \left[1 + \frac{R^2}{r^2} \right] - \frac{\Gamma}{2\pi r}$

$u = V_r \cos \theta - V_\theta \sin \theta \quad v = V_r \sin \theta + V_\theta \cos \theta$

$V_r = u \cos \theta + v \sin \theta \quad V_\theta = -u \sin \theta + v \cos \theta$

