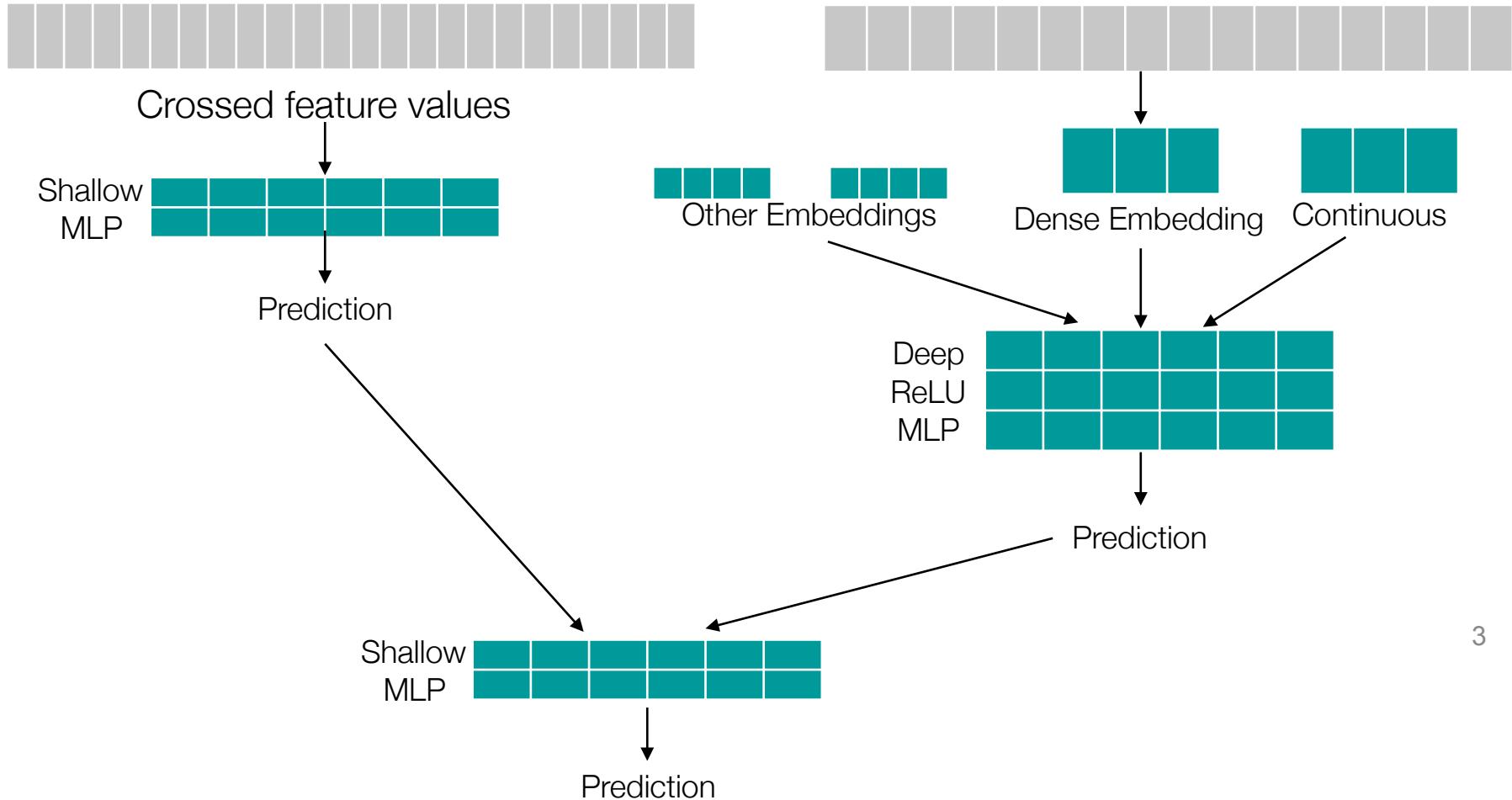

Lecture Notes for Machine Learning in Python

Professor Eric Larson
Basic Convolutional Neural Networks

Logistics and Agenda

- Logistics
 - Wide/Deep due this week
- Agenda
 - Basic CNN architectures and Demo

Last Time:



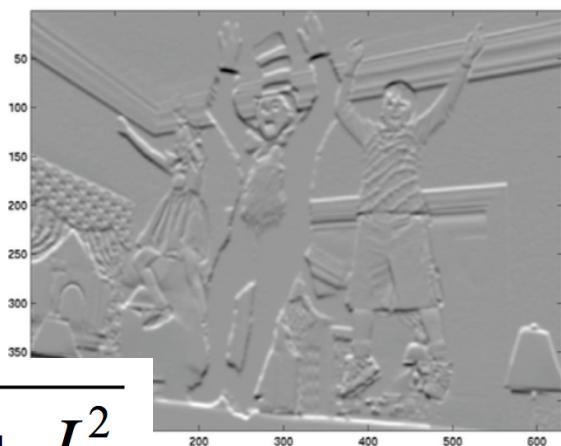
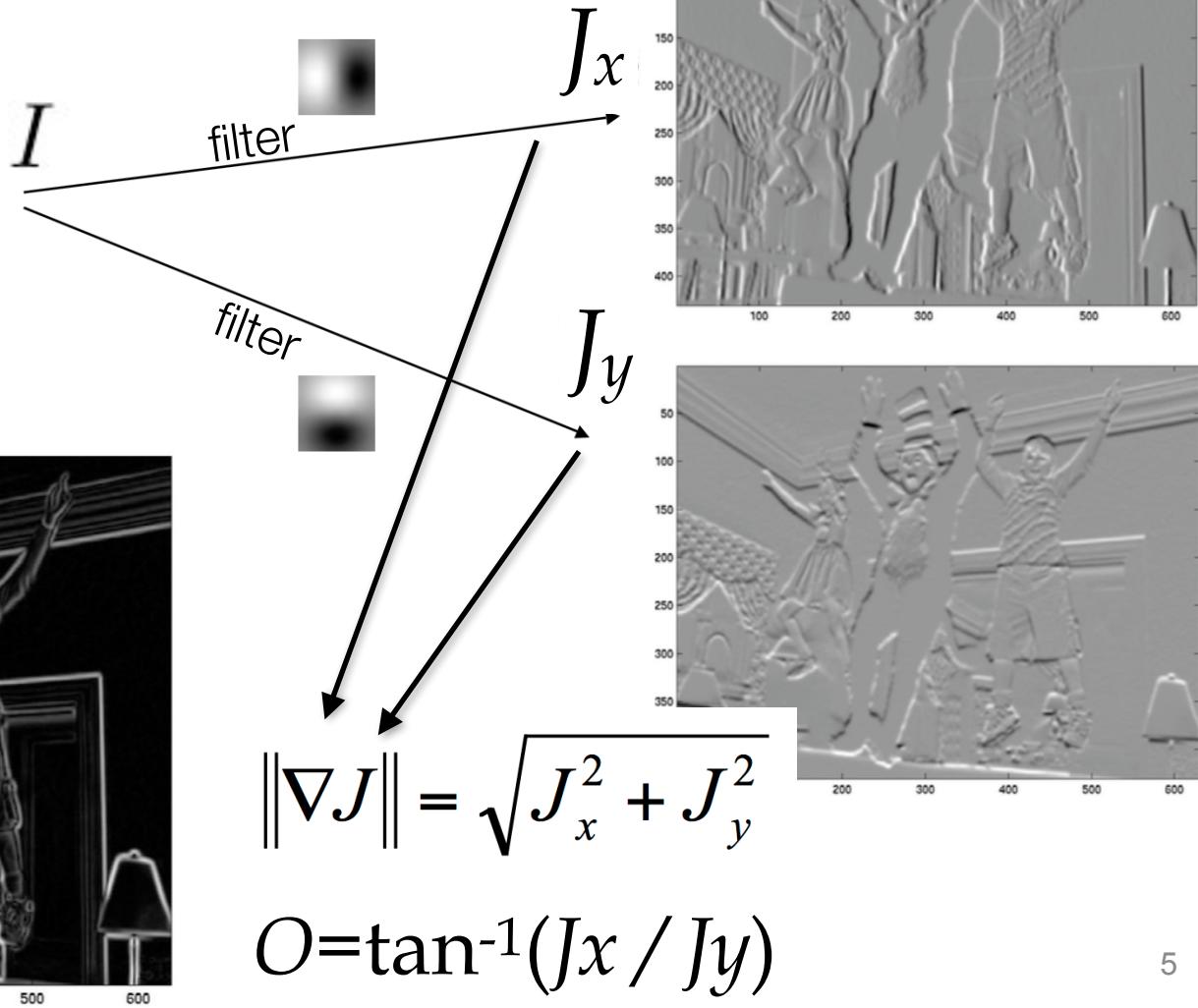
Convolutional Neural Networks



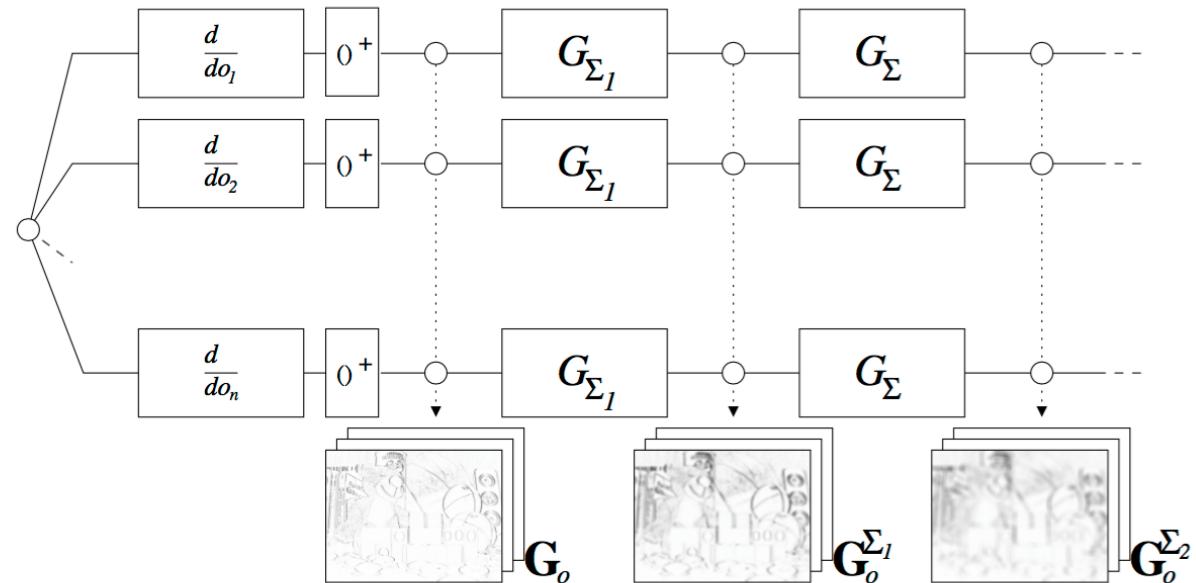
IN CS, IT CAN BE HARD TO EXPLAIN
THE DIFFERENCE BETWEEN THE EASY
AND THE VIRTUALLY IMPOSSIBLE.

What we did before

- the gradient (2D derivative)



What we did before



take normalized histogram at point u, v

$$\tilde{\mathbf{h}}_{\Sigma}(u, v) = \left\| [\mathbf{G}_1^{\Sigma}(u, v), \dots, \mathbf{G}_H^{\Sigma}(u, v)]^{\top} \right\|$$

$$\begin{aligned} \mathcal{D}(u_0, v_0) = \\ \left[\begin{aligned} & \tilde{\mathbf{h}}_{\Sigma_1}^{\top}(u_0, v_0), \\ & \tilde{\mathbf{h}}_{\Sigma_1}^{\top}(\mathbf{l}_1(u_0, v_0, R_1)), \dots, \tilde{\mathbf{h}}_{\Sigma_1}^{\top}(\mathbf{l}_T(u_0, v_0, R_1)), \\ & \tilde{\mathbf{h}}_{\Sigma_2}^{\top}(\mathbf{l}_1(u_0, v_0, R_2)), \dots, \tilde{\mathbf{h}}_{\Sigma_2}^{\top}(\mathbf{l}_T(u_0, v_0, R_2)), \end{aligned} \right] \end{aligned}$$

Tola et al. "Daisy: An efficient dense descriptor applied to wide-baseline stereo." Pattern Analysis and Machine Intelligence, IEEE Transactions

CNN Overview

- First layer(s):
 - convolution with different filters
 - nonlinearity
 - pooling
 - Each pooling layer can make the input image “smaller”
 - allows for more summative explanations
 - less dependence on exact pixels
- Final layers are densely connected
 - typically multi-layer perceptrons

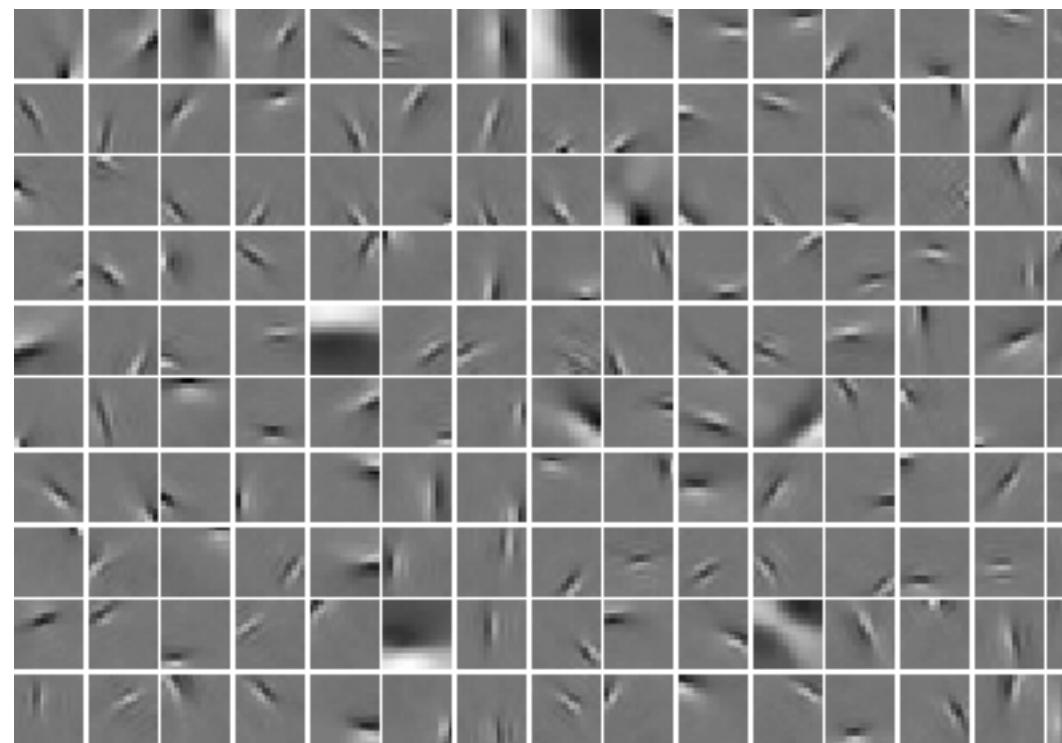
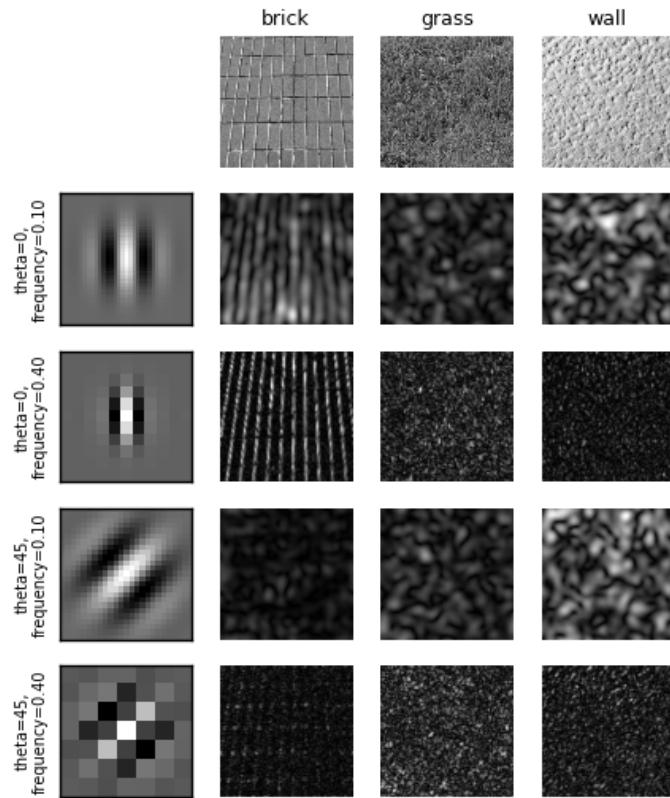
CNN Overview: Self Test

- First layer(s):
 - convolution with different filters
 - nonlinearity
 - pooling
 - Each pooling layer *can* make the input image “smaller”
 - allows for more summative explanations
 - less dependence on exact pixels
- Final layers are densely connected
 - typically multi-layer perceptrons
- Where are unstable gradients **most** problematic?
 - (A) During Convolution Layer(s) updates
 - (B) During Fully Connected Layer(s) updates
 - (C) Both A and B
 - (D) They are not a problem

CNN Filtering

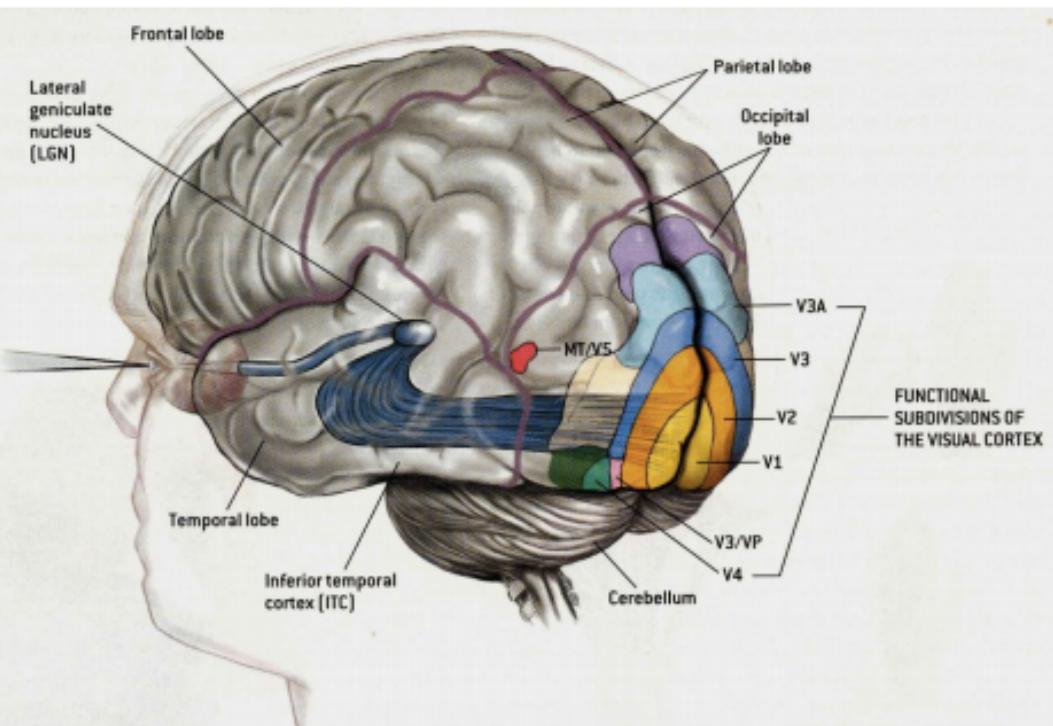
- Why perform lots of filtering?
 - recall gabor filtering?

Image responses for Gabor filter kernels



CNN Filtering

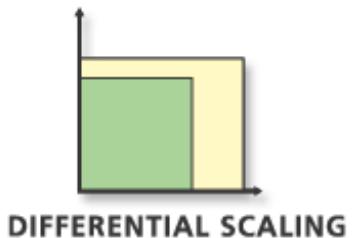
- Why perform lots of filtering?
 - recall gabor filtering?



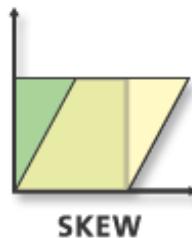
V1	Motion
V2	Stereo
V3	Color
V3a	Texture segregation
V3b	Segmentation, grouping
V4	Recognition
V7	Face recognition
MT	Attention
MST	Working memory/mental imagery

CNN Pooling

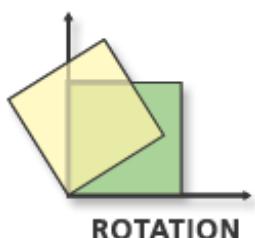
- Why perform pooling?
- Why max pooling?
 - reduce translation effects
 - param reduction



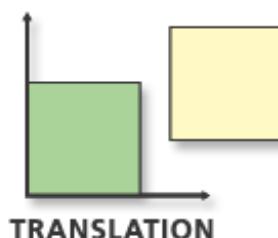
DIFFERENTIAL SCALING



SKEW



ROTATION



TRANSLATION

Filter output			
12	20	30	0
8	12	2	0
34	70	37	4
112	100	25	12

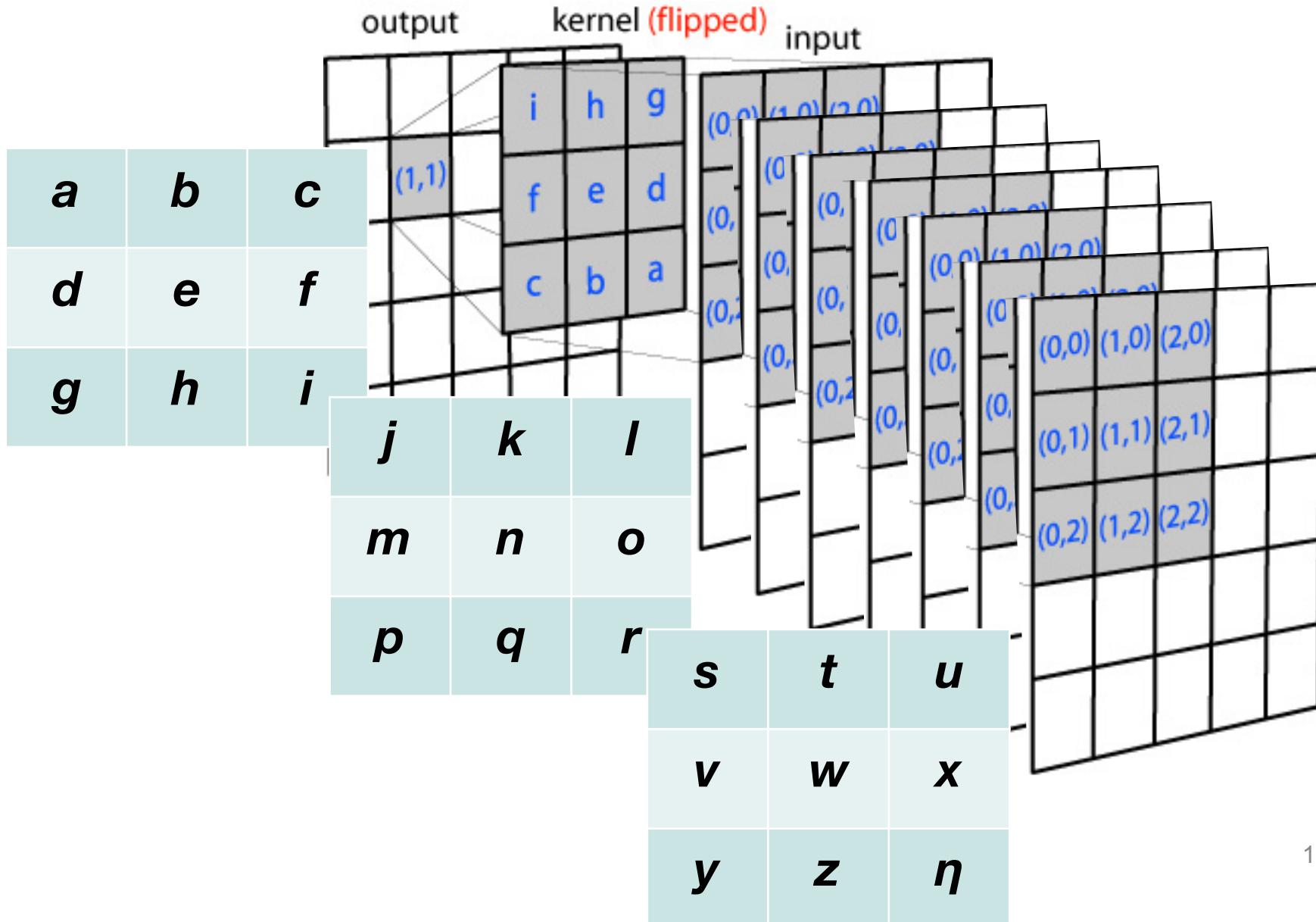
max pooling

20	30
112	37

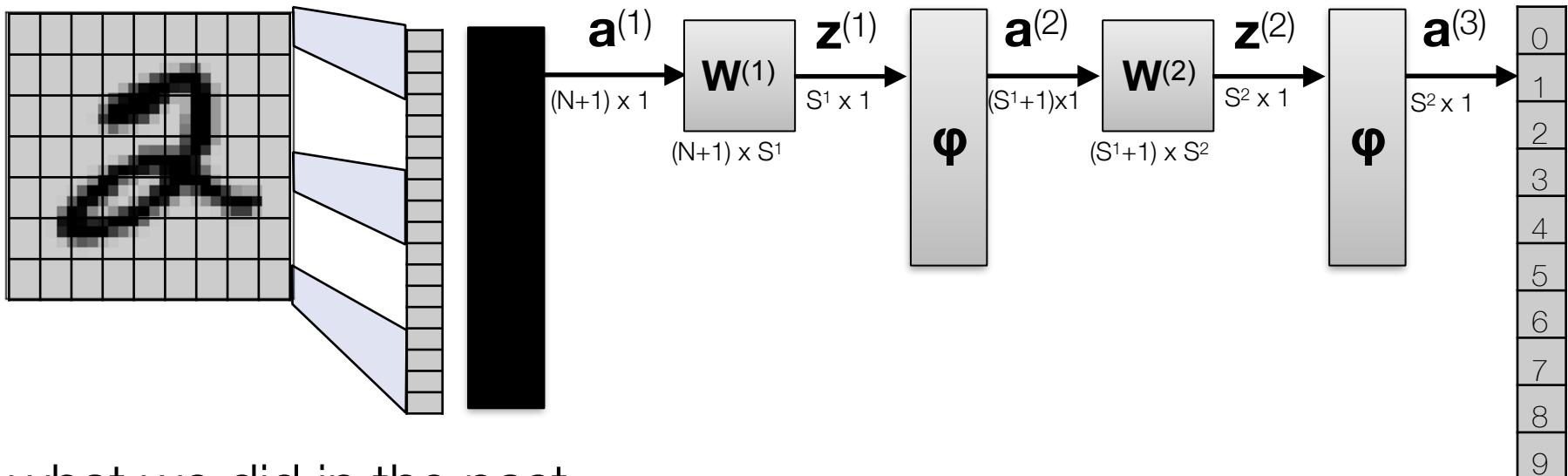
average pooling

13	8
79	20

Convolution in a CNN



From Fully Connected to CNN



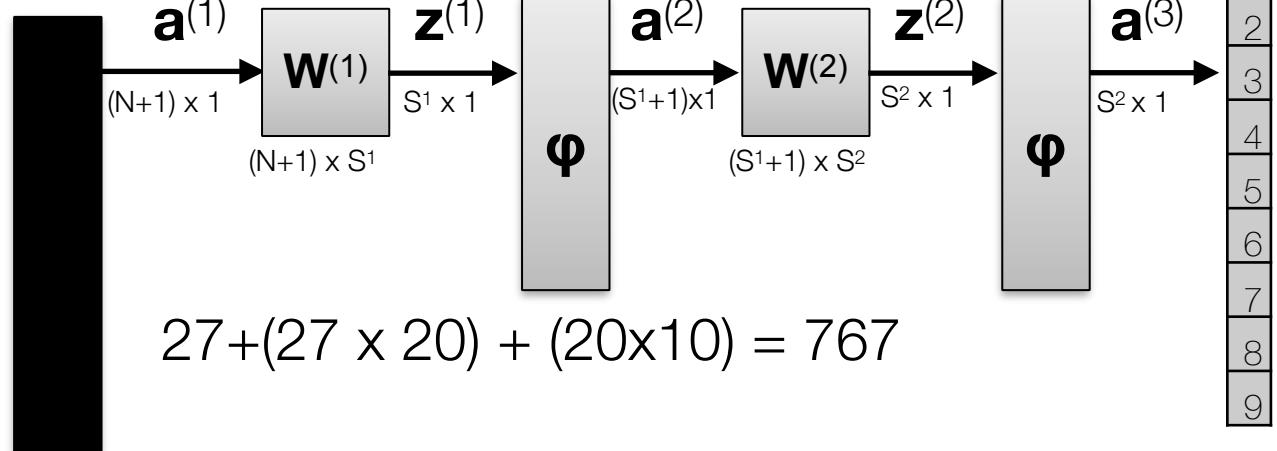
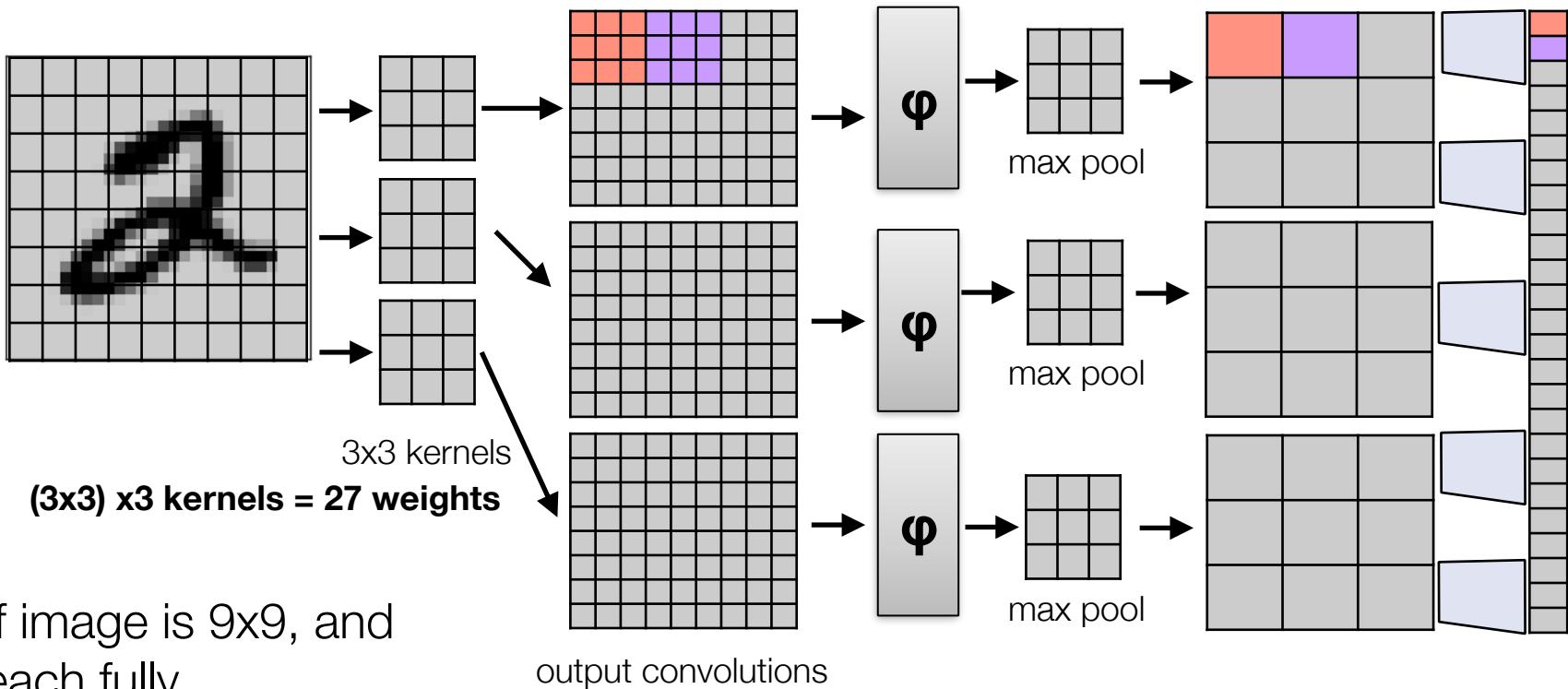
what we did in the past

If image is 9x9, and each fully connected layer is 20 hidden neurons wide, how many parameters are in this NN (ignore bias)?

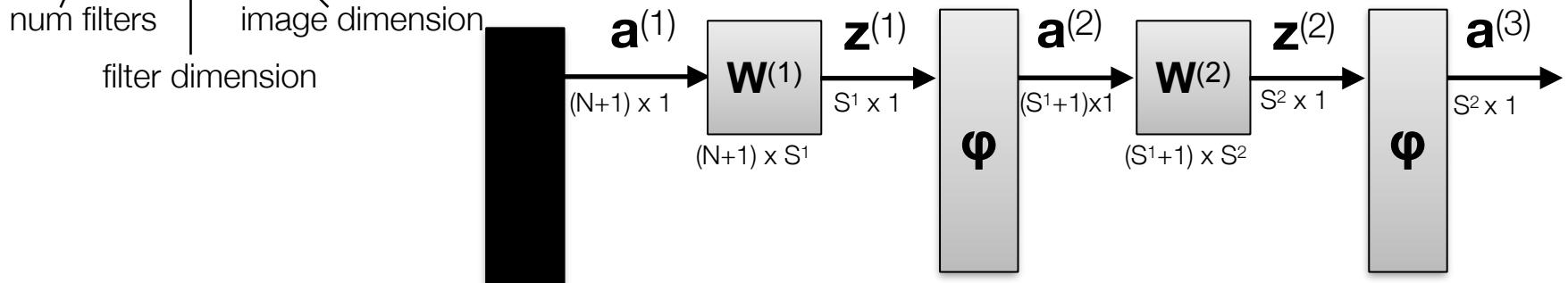
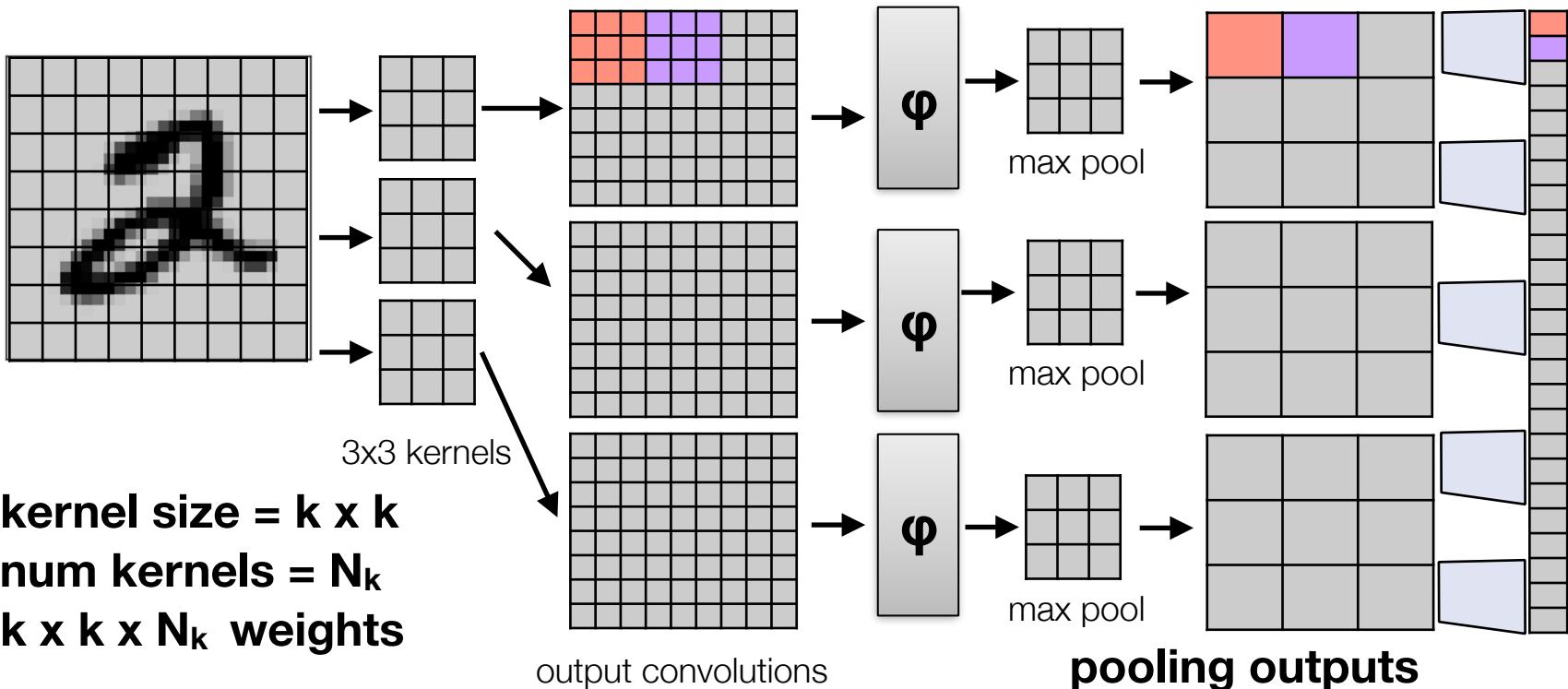
$$(K^2 \times 20) + (20 \times 10) = 200 + 20 K^2$$

for $9 \times 9 = 200 + 20 \times 9^2 = 1,820$ parameters

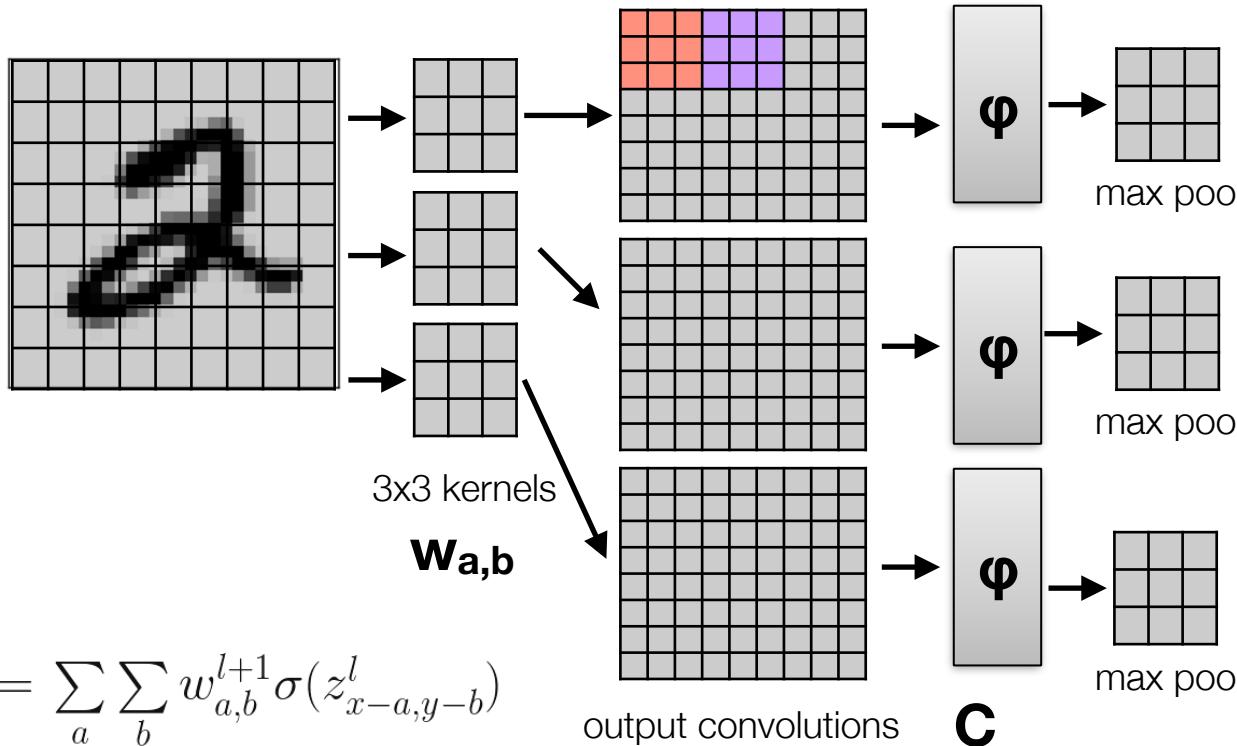
From Fully Connected to CNN



From Fully Connected to CNN



CNN gradient



Derivative of max pool is easy:

for each input x_i

$$f'(x_i) = \begin{cases} 1 & \text{if } x_i \text{ is max} \\ 0 & \text{else} \end{cases}$$

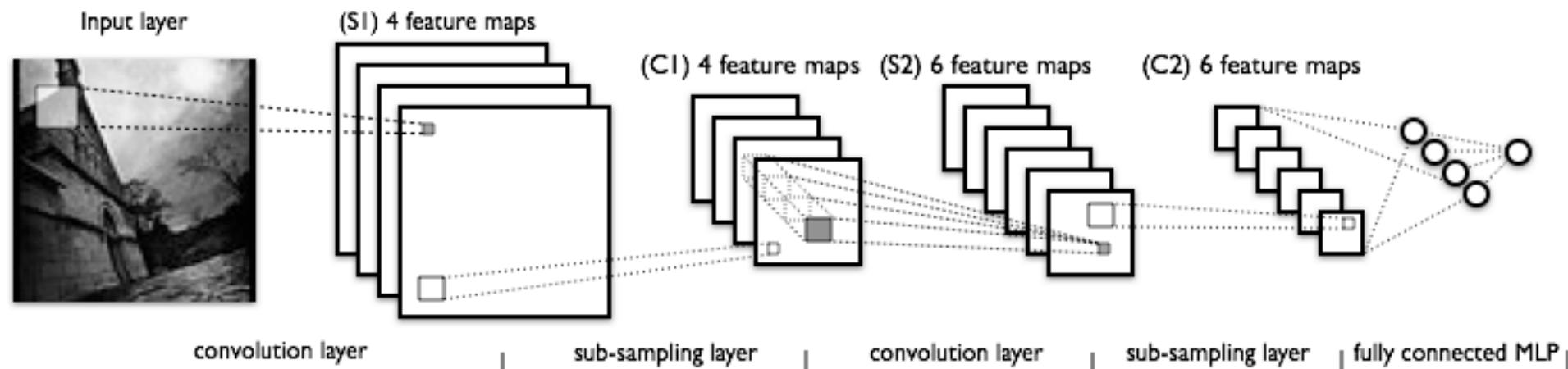
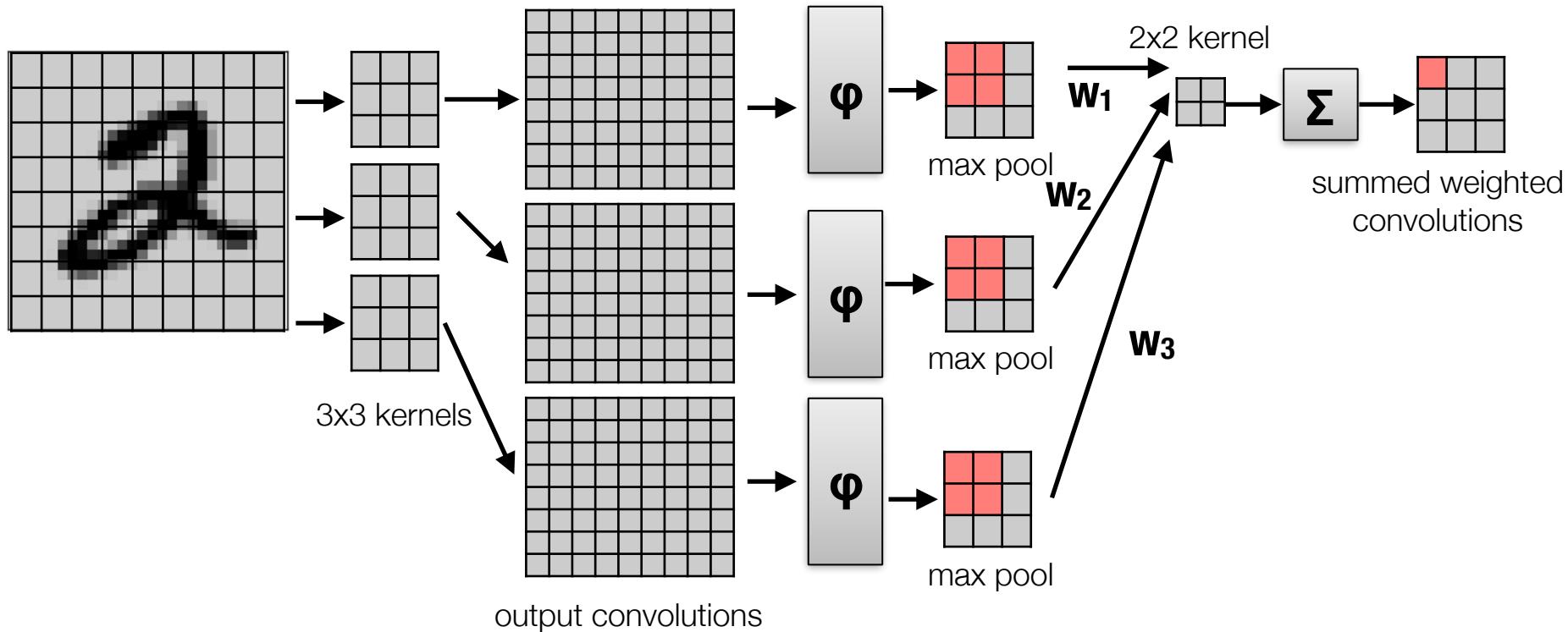
Derivative of convolution is more involved:

$$\frac{\partial C}{\partial w_{a,b}^l} = \sum_x \sum_y \frac{\partial C}{\partial z_{x,y}^l} \frac{\partial z_{x,y}^l}{\partial w_{a,b}^l} = \sum_x \sum_y \delta_{x,y}^l \frac{\partial (\sum_{a'} \sum_{b'} w_{a',b'}^l \sigma(z_{x-a',y-b'}^l) + b_{x,y}^l)}{\partial w_{a,b}^l} =$$
$$\sum_x \sum_y \delta_{x,y}^l \sigma(z_{x-a,y-b}^{l-1}) = \delta_{a,b}^l * \sigma(z_{-a,-b}^{l-1}) = \delta_{a,b}^l * \sigma(ROT180(z_{a,b}^{l-1}))$$

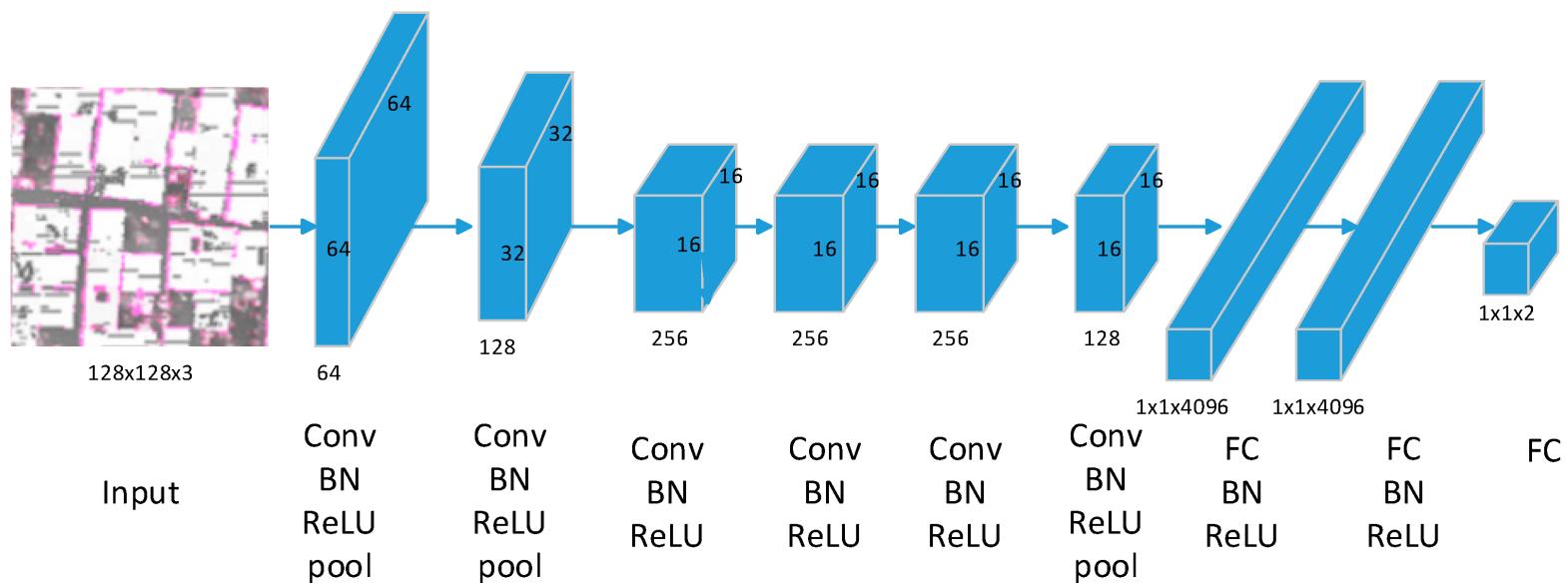
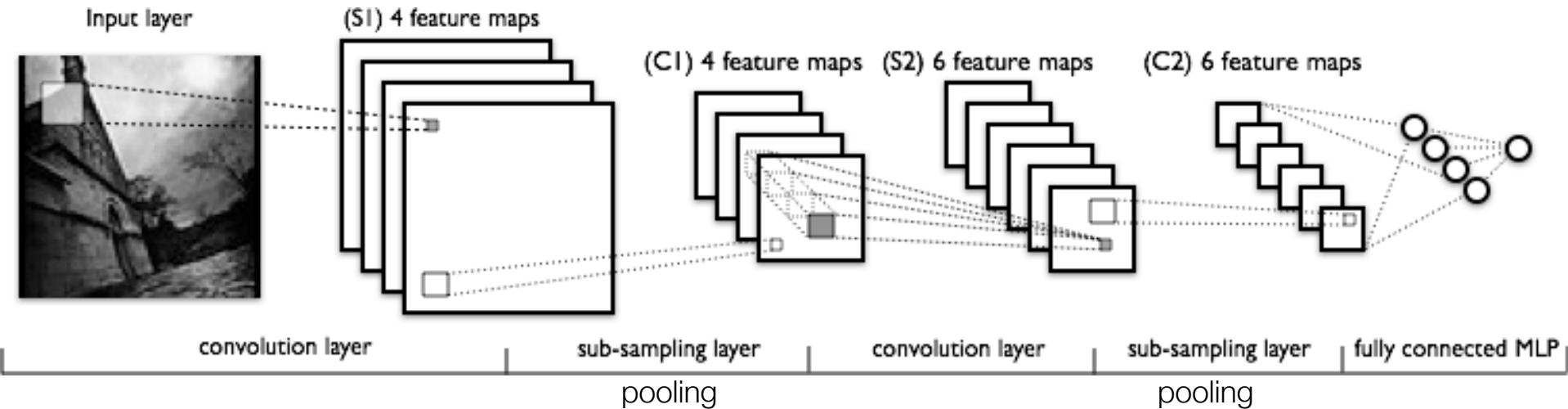
CNN gradient

- But we really want to understand the process!
- These are great guides:
 - [https://grzegorzgwardys.wordpress.com/
2016/04/22/8/](https://grzegorzgwardys.wordpress.com/2016/04/22/8/)
 - [http://andrew.gibiansky.com/blog/machine-
learning/convolutional-neural-networks/](http://andrew.gibiansky.com/blog/machine-learning/convolutional-neural-networks/)

CNN adding more convolutional layers



Some Example CNN Architectures



CNN: What does it all mean?

Deep Visualization Toolbox

yosinski.com/deepvis

#deepvis



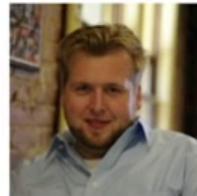
Jason Yosinski



Jeff Clune



Anh Nguyen



Thomas Fuchs



Hod Lipson



Cornell University

UNIVERSITY
OF WYOMING



Jet Propulsion Laboratory
California Institute of Technology

11. Convolutional Neural Networks.ipynb

Demo

TensorFlow and Basic CNNs

Convolutional Neural Networks
in TensorFlow
with Keras



Next Lecture

- More CNN architectures and CNN history

Lecture Notes for Machine Learning in Python

Professor Eric Larson

An Ongoing History of Convolutional Networks

Wanted:

Participants for a Research Study in Biometrics and Privacy



- SMU Researchers are seeking participants for an upcoming research study.
- We will be gathering data about your biometrics as you do a series of everyday tasks on a mobile phone and laptop.
- We ask for about **1.5-2 hours** of your time! For completing the session, you will receive a \$10 Amazon gift card.
- Please contact eesharp@smu.edu



IRB Approved: 02/23/2018
SL
Expires: 02/23/2019
Study ID: H18-020-LARE

Contact

eesharp@smu.edu

eesharp@smu.edu

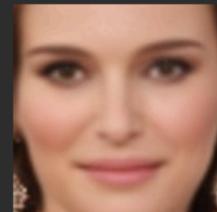
<http://faceface.lyle.smu.edu/>



SMU FaceFace

VOTE RANKING ABOUT

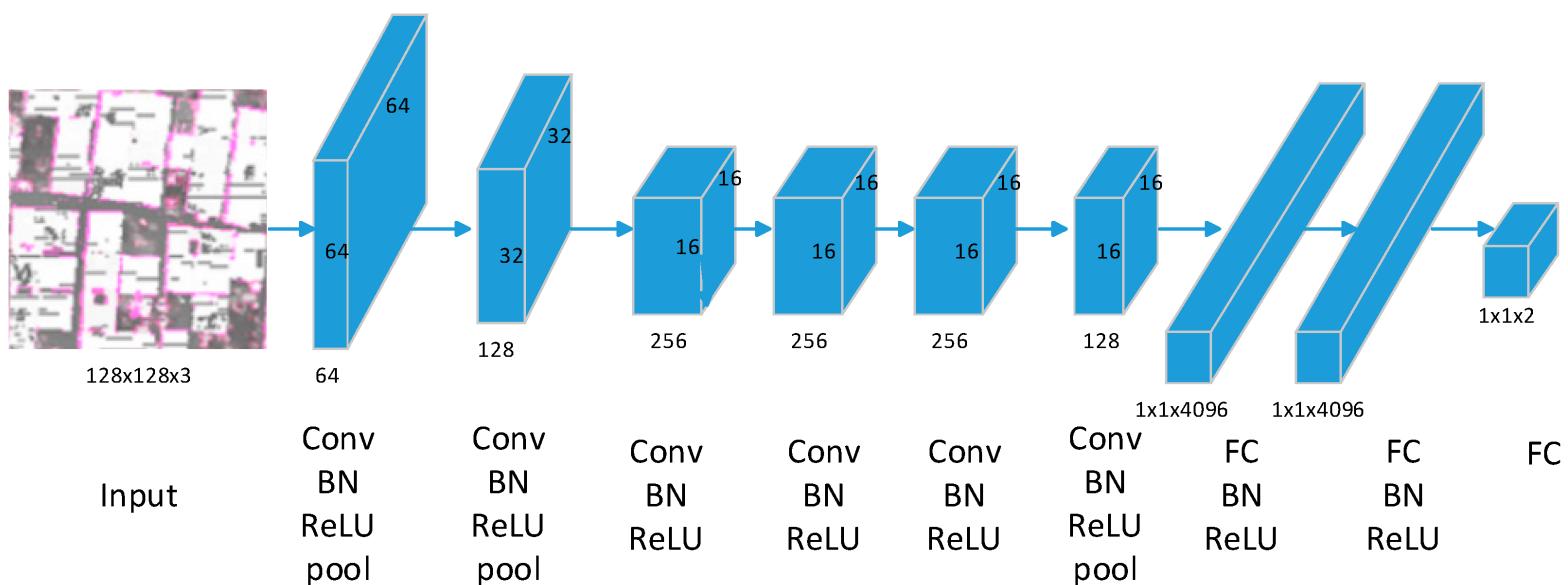
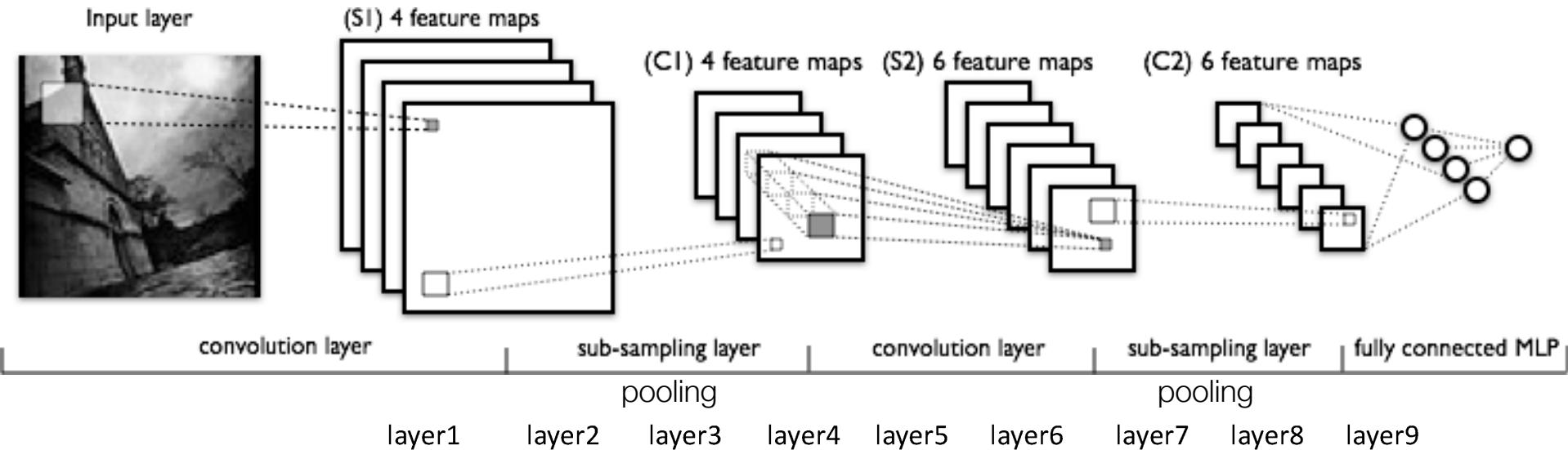
Which of the following two faces looks
MORE FAKE to you?



Class logistics and Agenda

- Wide/Deep Lab due this week
- Agenda:
 - Finish CNN Demo
 - History of CNNs
 - with Modern CNN Architectures
- Next Time:
 - More Advanced CNN Demo

Last Time:

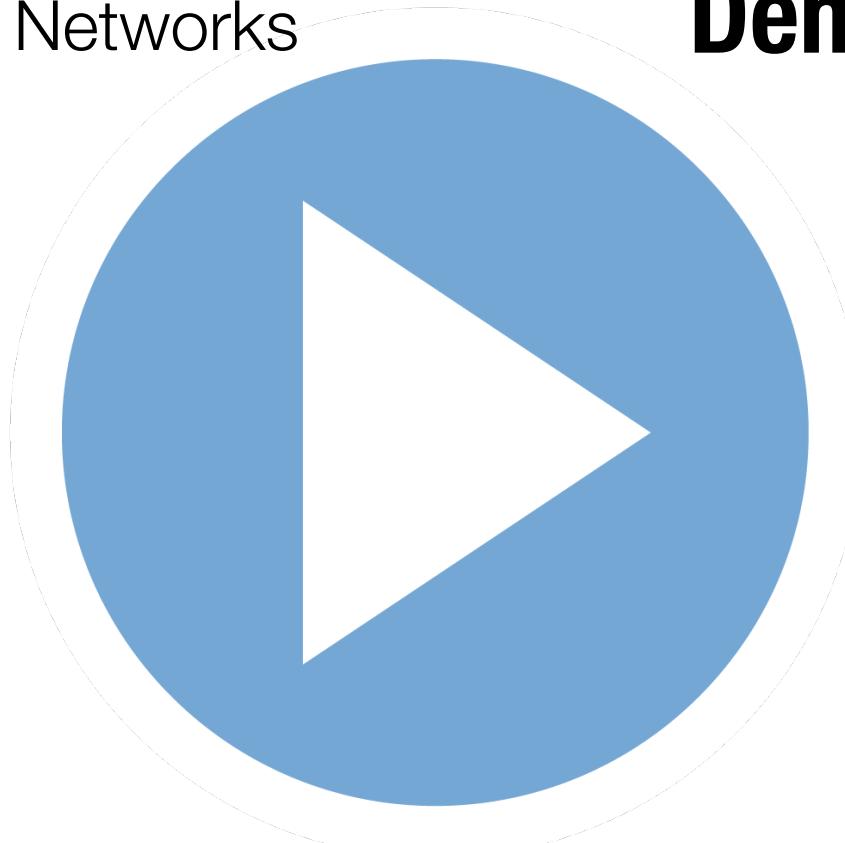


TensorFlow and Basic CNNs

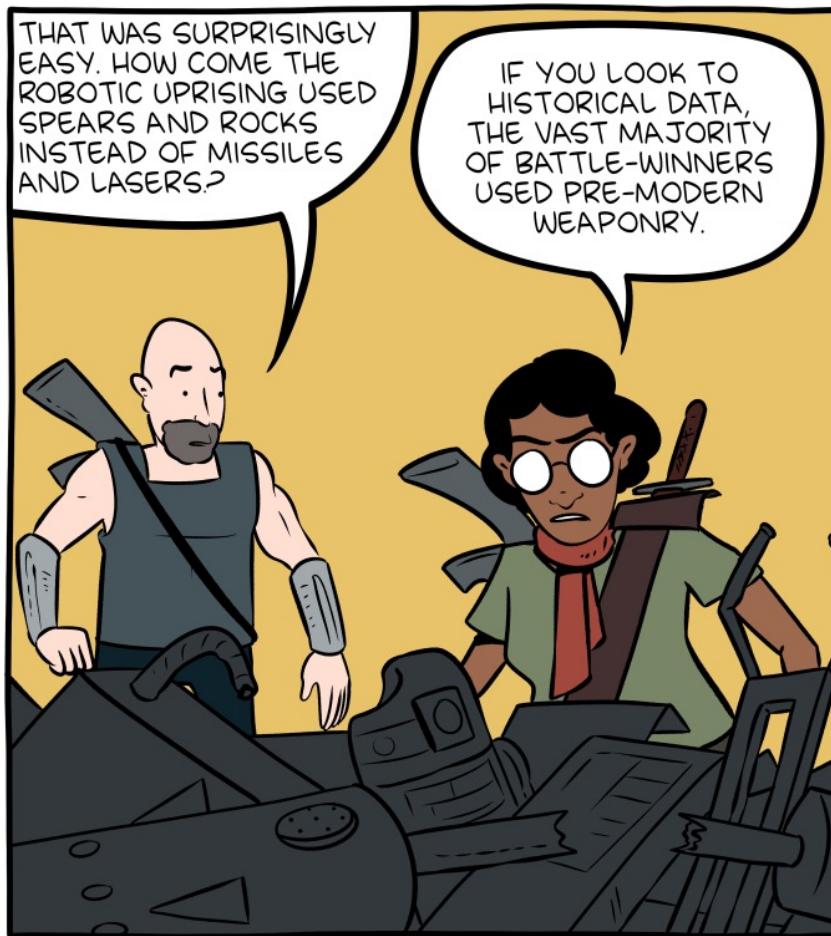
Convolutional Neural Networks
in TensorFlow
with Keras

with Sequential API!

Finish
Demo



History of Convolutional Neural Networks



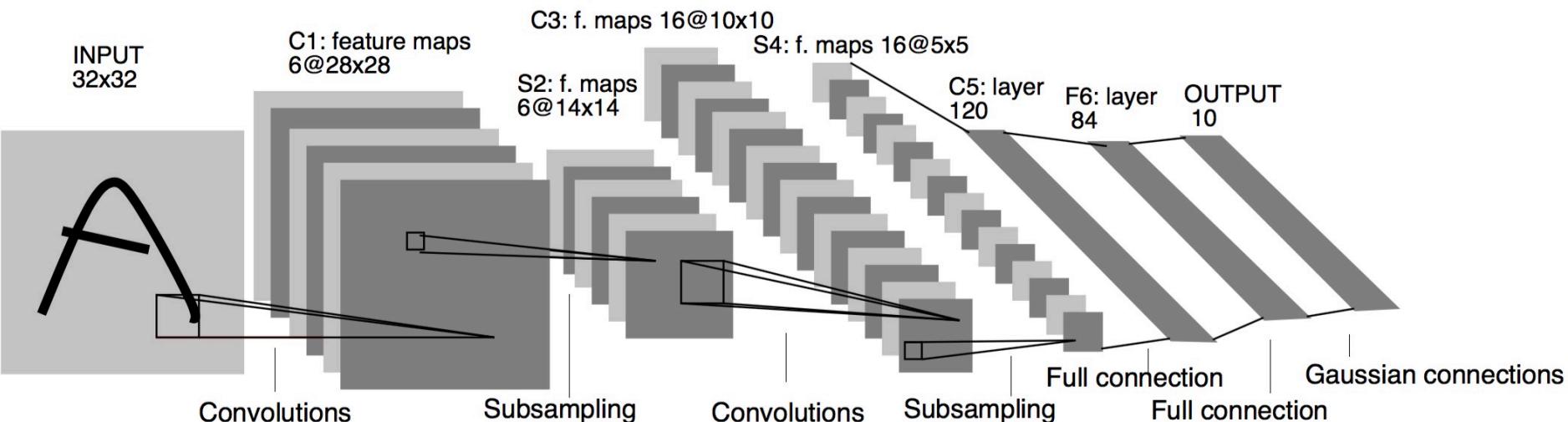
Thanks to machine-learning algorithms,
the robot apocalypse was short-lived.

Types of CNN, 1988-1998



Heads Facebook
AI Team

- **LeNet-1** (1988)
 - ~2600 params, not many layers
- **LeNet-5** (1998)
 - 7 layers, gets excellent MNIST performance
- Major contribution, general structure:
 - conv=>pool=>non-linearity=> ...=>MLP
 - avg
 - tanh or sigmoid



CNN History

- List of major breakthroughs from 1998 through 2010 in convolutional networks:



- 2010



Types of CNN, 2010



Dan
Ciresan

AI Researcher
IDSIA, Switzerland

- **Circesan Net**
- Publishes code for running CNN via GPU
 - Subsequently wins 5 international competitions
 - from stop signs => cancer detection
- Major contribution: NVIDIA parallelized training algorithms

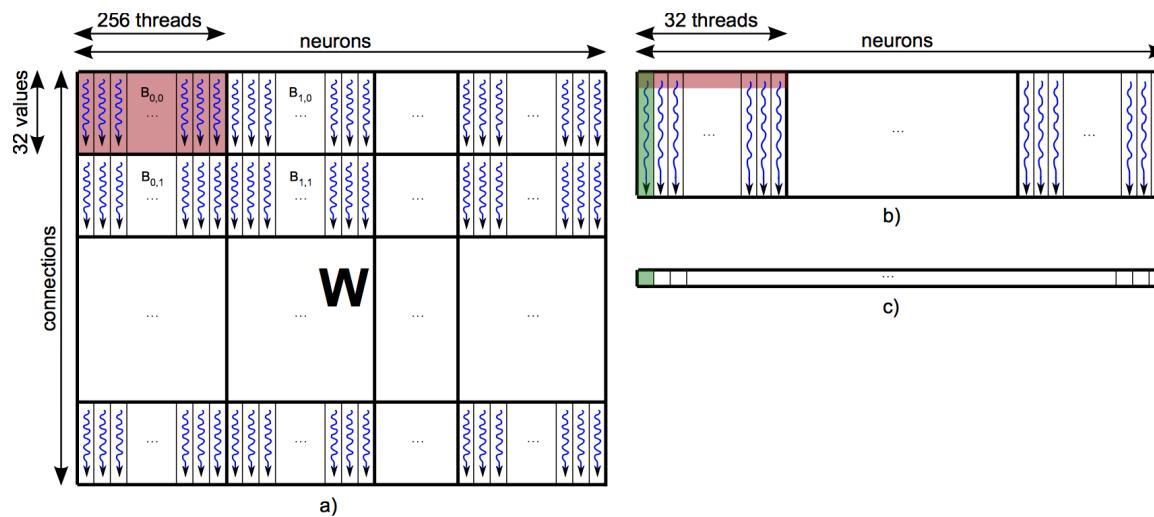
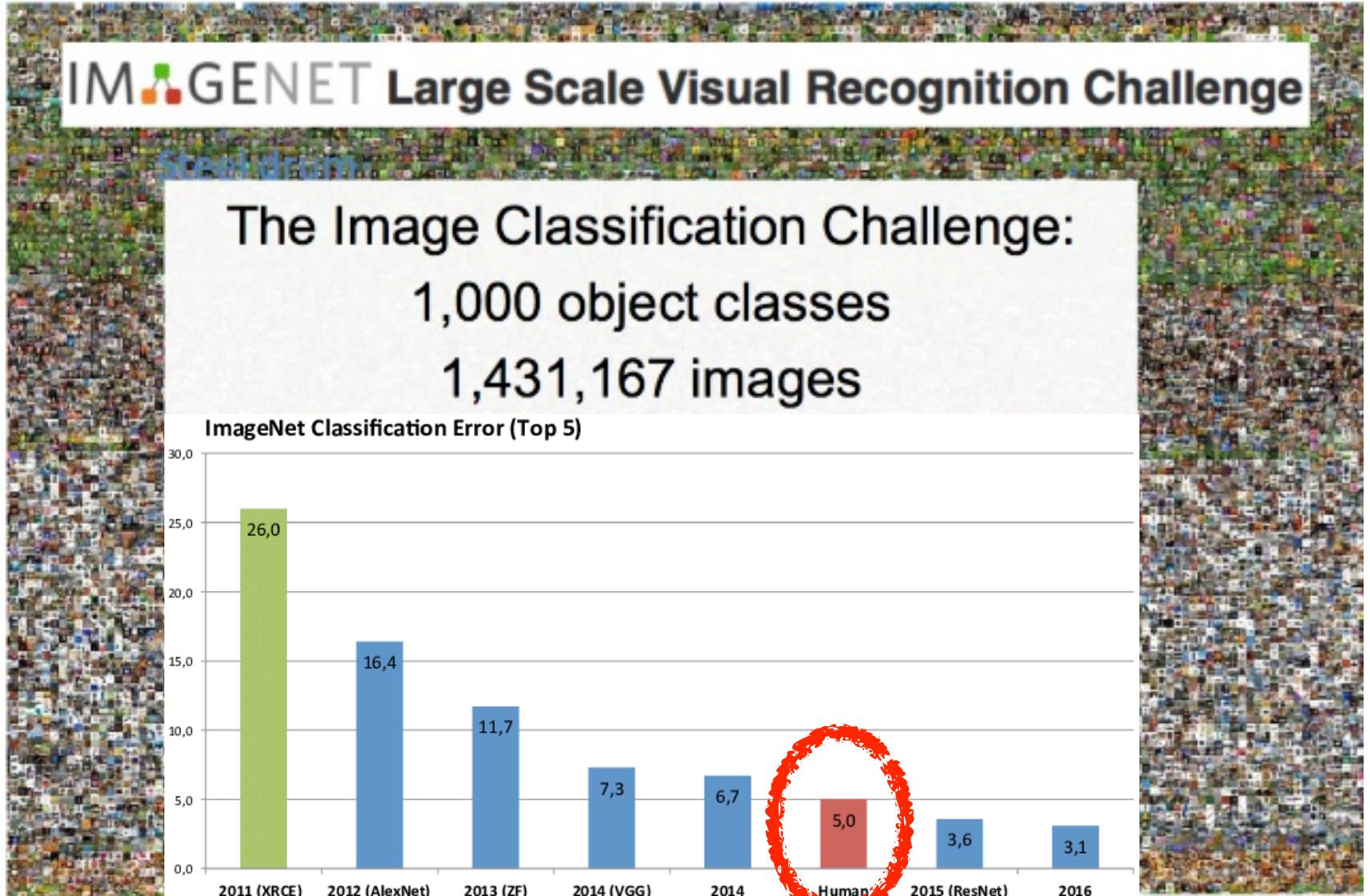


Figure 2: Forward propagation: a) mapping of kernel 1 grid onto the padded weight matrix; b) mapping the kernel 2 grid onto the partial dot products matrix; c) output of forward propagation.

ImageNet Competition (2010-2016)



https://www.researchgate.net/figure/Winner-results-of-the-ImageNet-large-scale-visual-recognition-challenge-LSVRC-of-the_fig7_324476862

<https://www.slideshare.net/nmhkahn/case-study-of-convolutional-neural-network-61556303>

Types of CNN, 2012

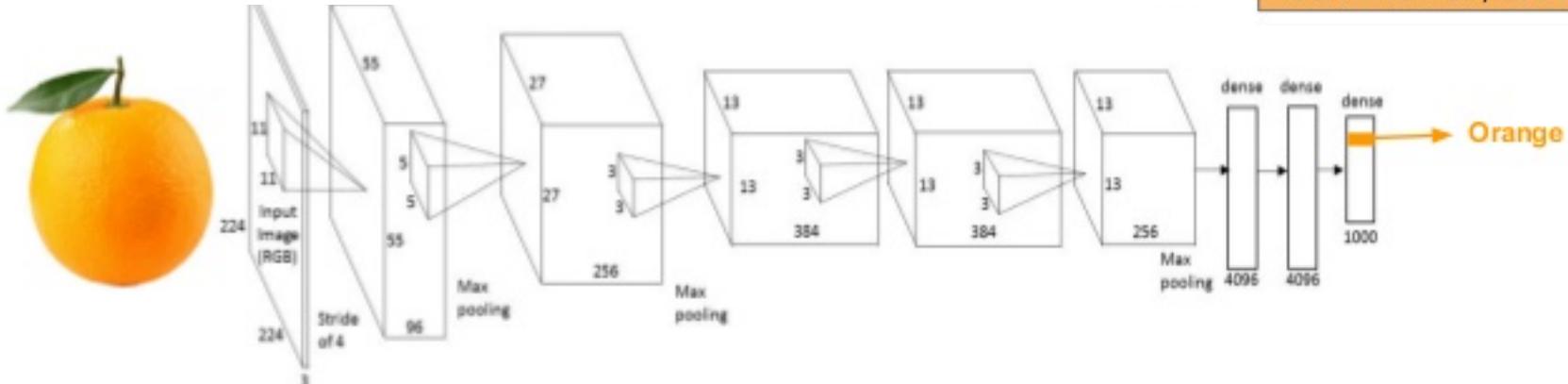
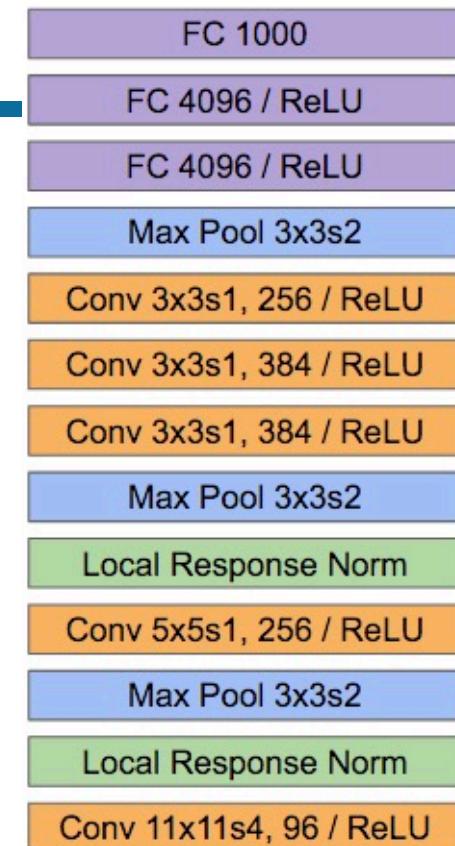
AlexNet



Alex
Krizhevsky

Google

- **AlexNet**, Hinton is mentor
 - wins ImageNet competition
- Major contributions:
 - dropout for regularization
 - systematic use of ReLU
 - data expansion
 - overlapping max pool



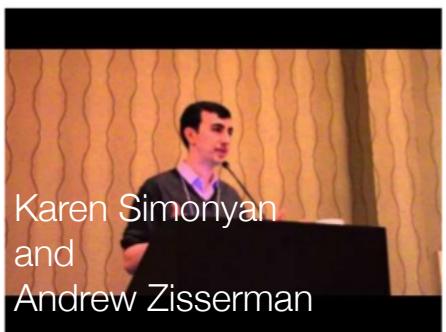
Warning

**DON'T TRY WHAT YOU'RE
ABOUT TO SEE AT HOME**



**WE'RE WHAT YOU CALL
EXPERTS**

Types of CNN, 2013



- Oxford **VGG Net** (Visual Geometry Group)
- Major contributions:
 - small cascaded kernels
 - way more layers (19 versus ~7)
 - “emulates” biology “better”
 - trained on NVIDIA GPUs for 2-3 weeks

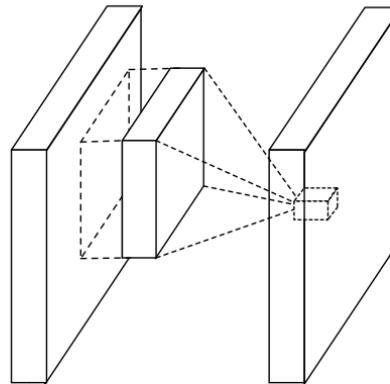
ConvNet Configuration					
A	A-LRN	B	C	D	E
11 weight layers	11 weight layers	13 weight layers	16 weight layers	16 weight layers	19 weight layers
input (224 × 224 RGB image)					
conv3-64	conv3-64 LRN	conv3-64 conv3-64	conv3-64 conv3-64	conv3-64 conv3-64	conv3-64 conv3-64
maxpool					
conv3-128	conv3-128	conv3-128 conv3-128	conv3-128 conv3-128	conv3-128 conv3-128	conv3-128 conv3-128
maxpool					
conv3-256 conv3-256	conv3-256 conv3-256	conv3-256 conv3-256	conv3-256 conv3-256	conv3-256 conv1-256	conv3-256 conv3-256 conv3-256
maxpool					
conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv1-512	conv3-512 conv3-512 conv3-512
maxpool					
conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv1-512	conv3-512 conv3-512 conv3-512
maxpool					
FC-4096					
FC-4096					
FC-1000					
soft-max					

Table 2: Number of parameters (in millions).

Network	A,A-LRN	B	C	D	E
Number of parameters	133	133	134	138	144

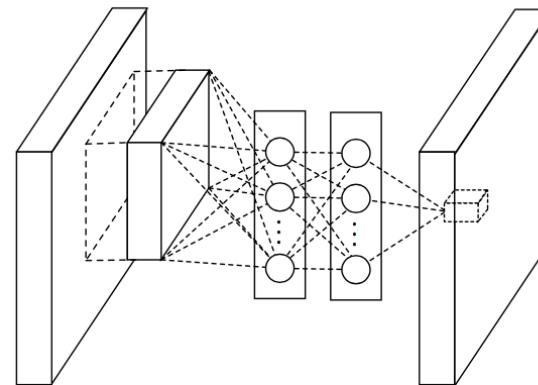
Types of CNN, 2014

- Network in Network **NiN**
 - or MLPConv

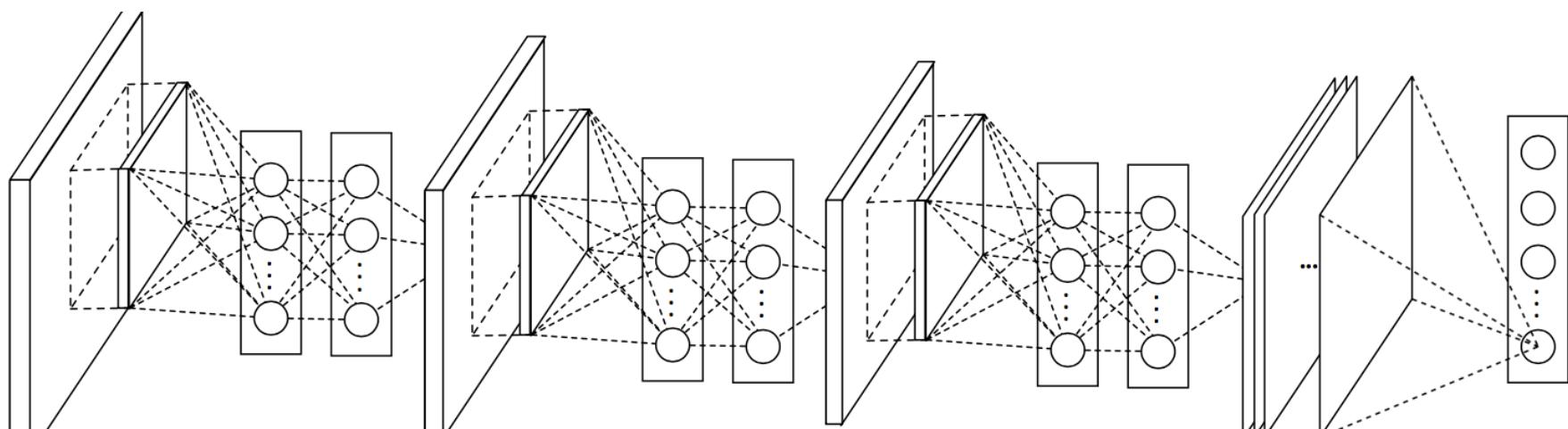


(a) Linear convolution layer

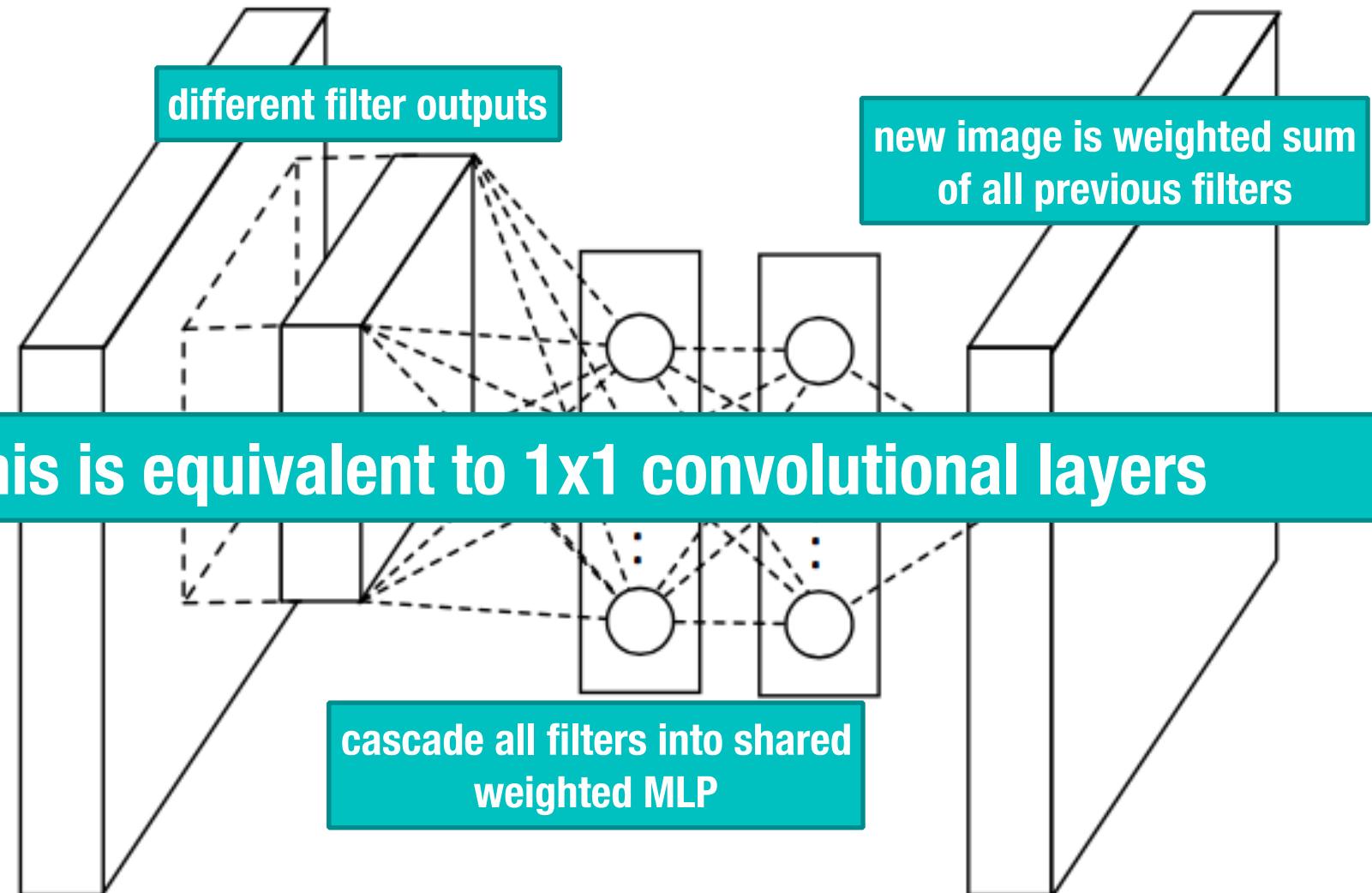
Min Lin^{1,2}, Qiang Chen², Shuicheng Yan²
¹Graduate School for Integrative Sciences and Engineering
²Department of Electronic & Computer Engineering
National University of Singapore, Singapore
`{linmin, chenqiang, eleyans}@nus.edu.sg`



(b) Mlpconv layer



Types of CNN, 2014



Types of CNN, 2014

Research at Google

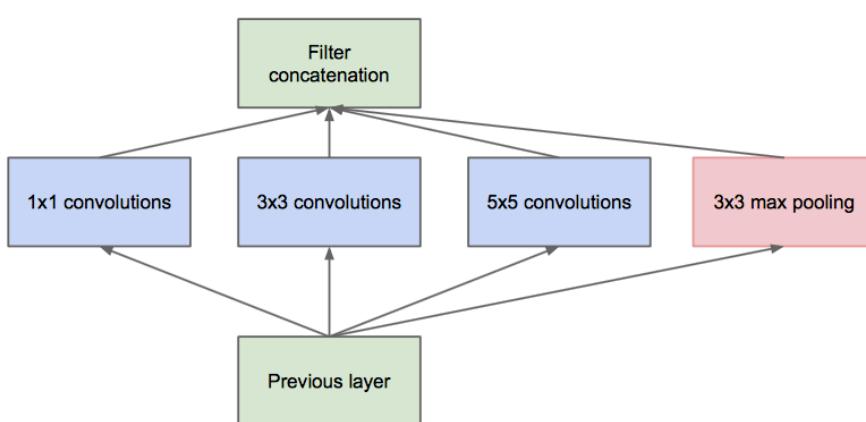
Home Publications People Teams Outreach

Christian Szegedy

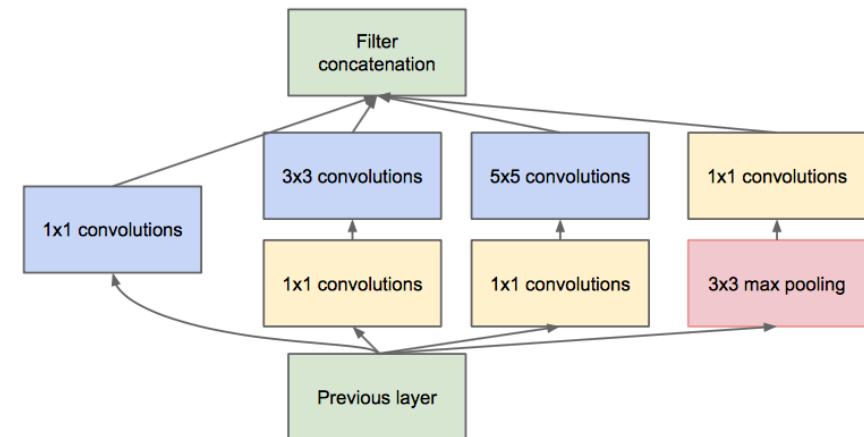


Research Area(s)
Machine Intelligence
Machine Perception

- GoogLeNet
 - or Inception V1
- Major contribution:
 - bottleneck layering
 - parallel NiN



(a) Inception module, naïve version



(b) Inception module with dimension reductions

Figure 2: Inception module

Types of CNN, 2015 February and December

Research at Google

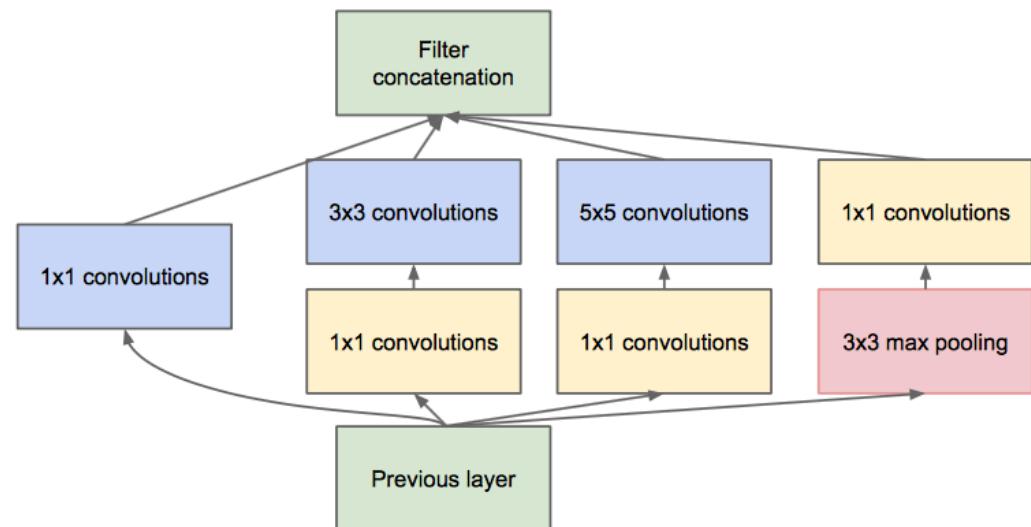
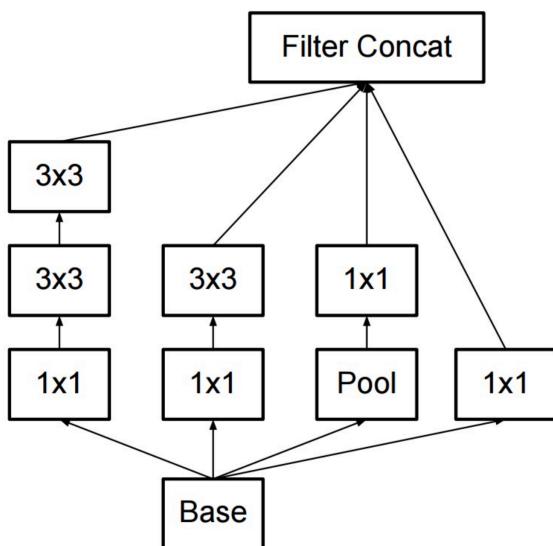
Home Publications People Teams Outreach

Christian Szegedy



Research Area(s)
Machine Intelligence
Machine Perception

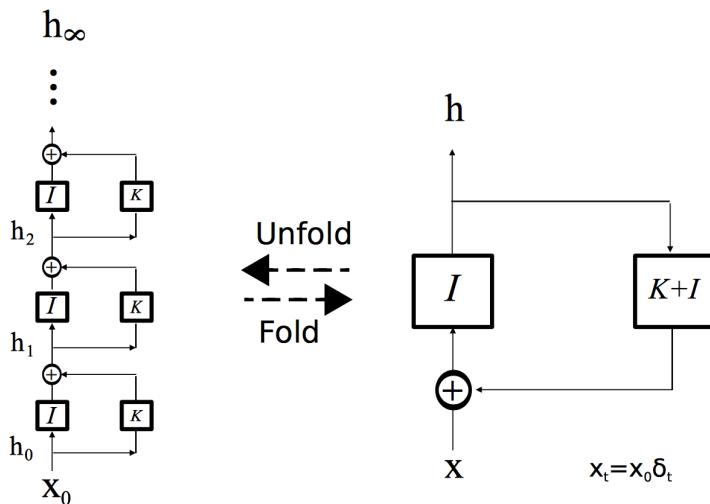
- **Inception V2**, Inception V1 with batch normalization
- **Inception V3**:
 - replace 5×5 with multiple 3×3



Types of CNN, 2015 December

Microsoft®
Research

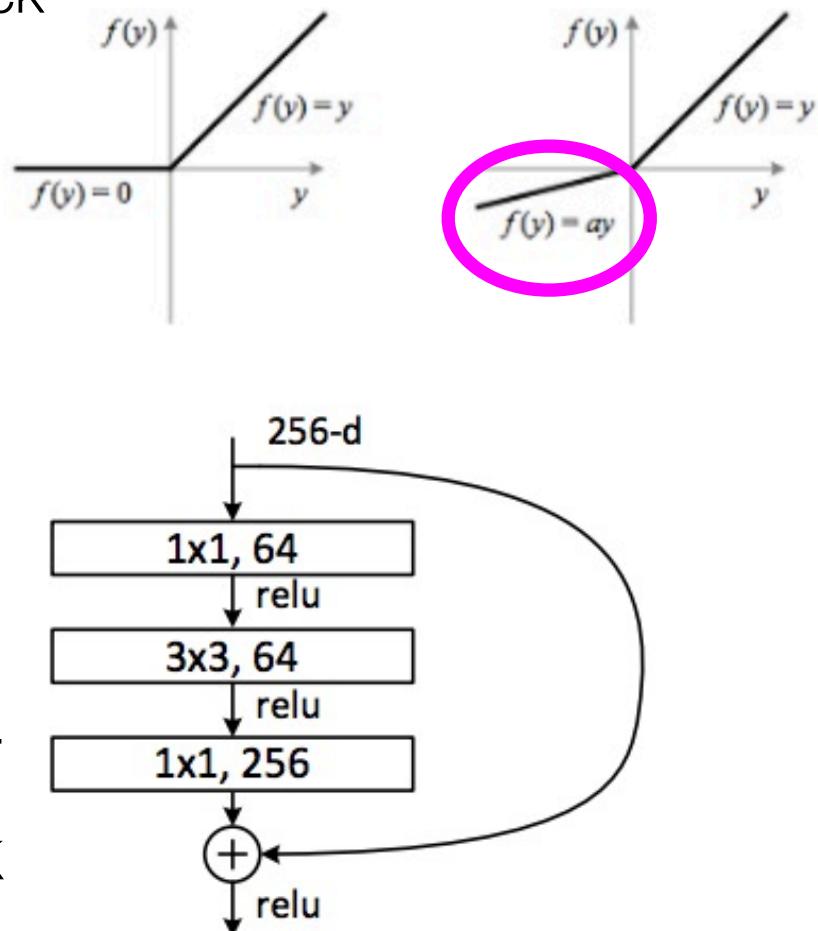
- Major Contributions:
 - ensembles, not strictly sequential
 - bio-plausible with feedback
- ResNet
 - PReLU: adaptive trained slope



(A) ResNet with shared weights

(B) ResNet in recurrent form

- NiN: triple bypass layer
 - similar to bottleneck

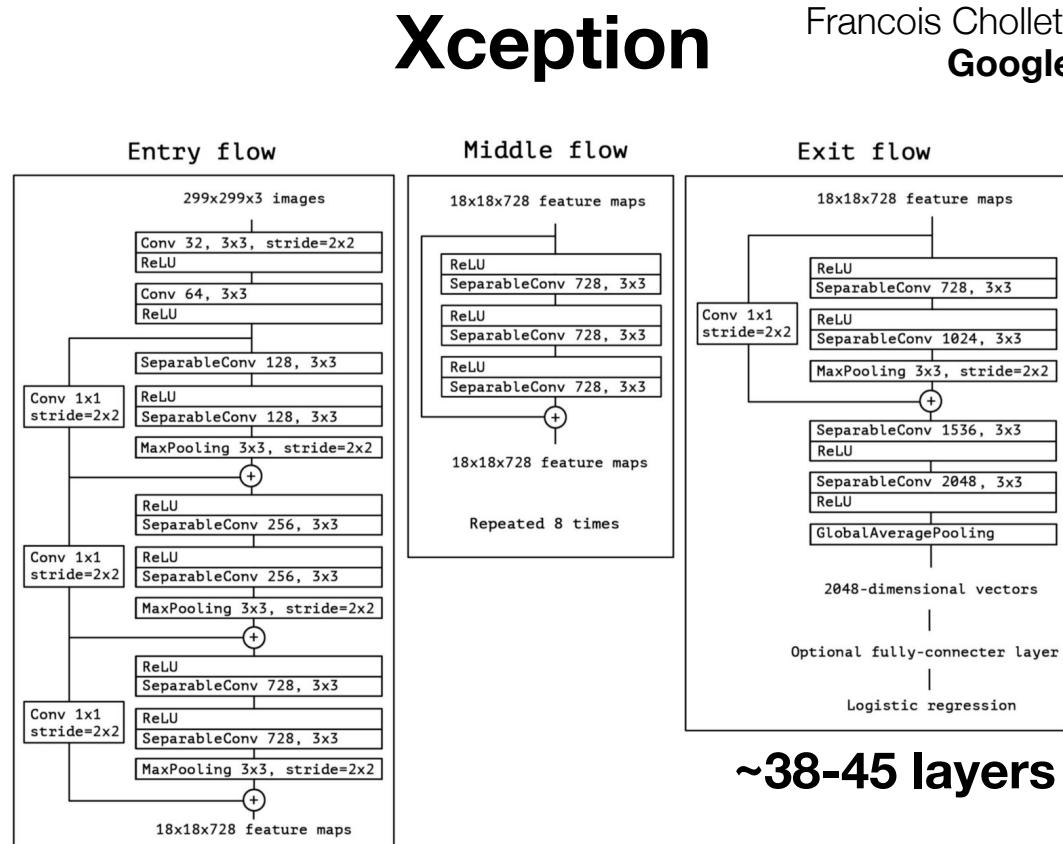
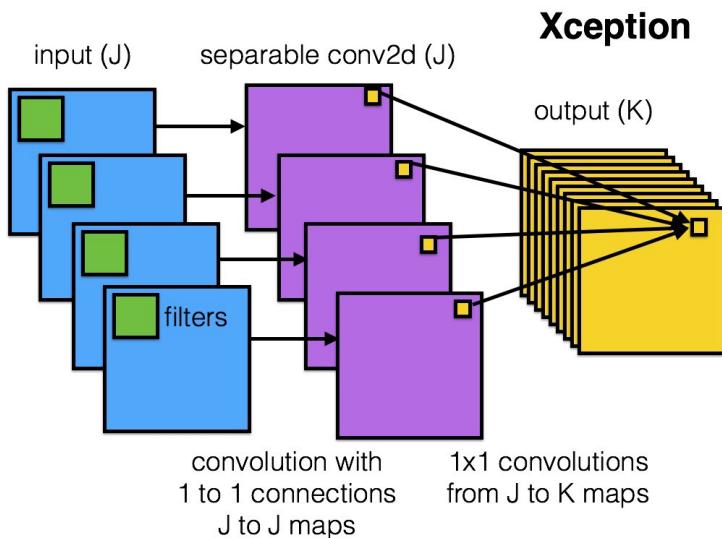


Types of CNN, 2017 April

- Major Contributions:
 - combining branching / residual blocks
 - separable convolutions



Francois Chollet
Google

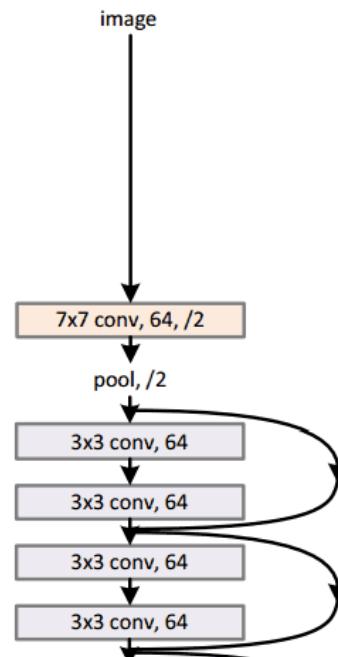
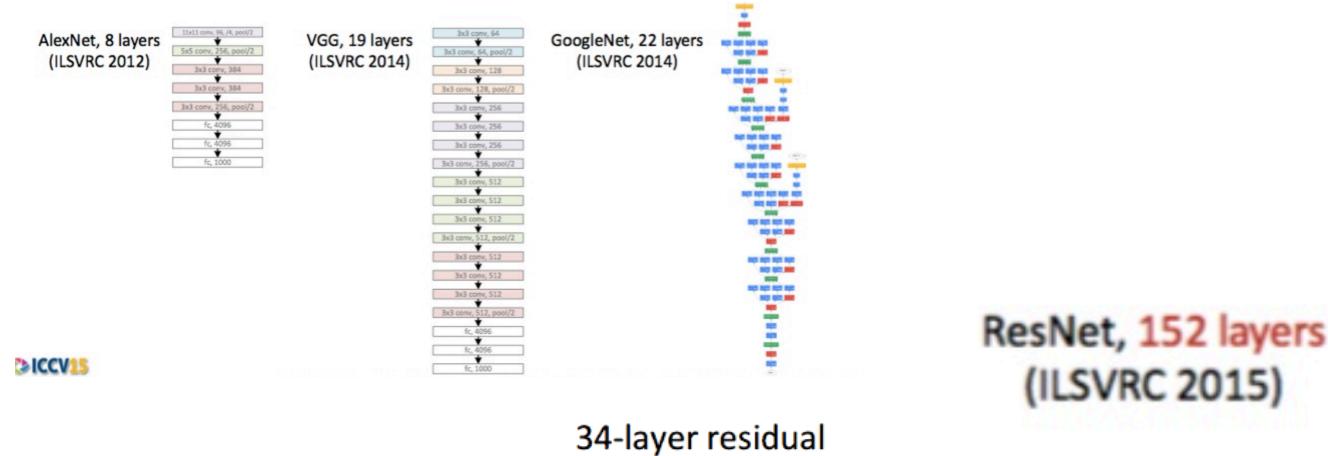


~38-45 layers



How big are these networks?

How big are these networks?



Self Test

- We have seen a lot of different networks.
- The most important concept to understand in using convolutional neural networks is:
 - A. Use proper initialization of layers
 - B. Have plenty of data or use expansion
 - C. Set aside time for training
 - D. Use batch normalization

More Modern CNN Architectures

Even more Convolutional
Neural Networks
...in TensorFlow
...with Keras

Demo



Next Time:

- CNN Lab Discussion (Town Hall)
- Intro to Recurrent Neural Network Architectures
 - RNNs, GRUs, LSTMs
 - Training for characters

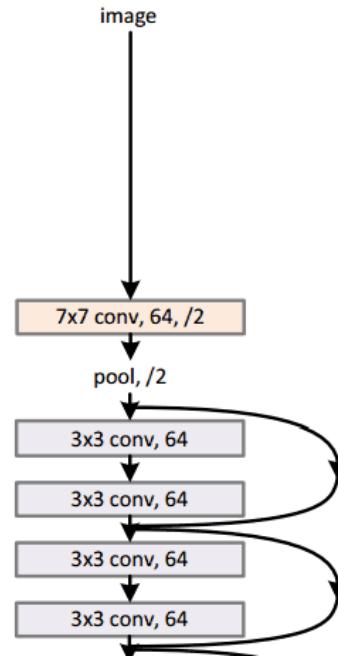
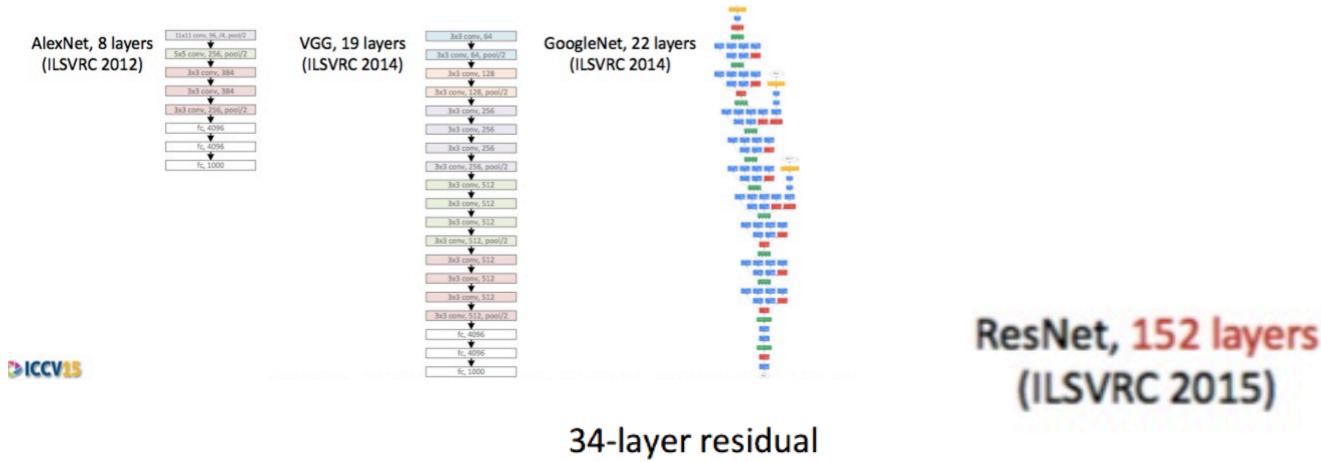
Lecture Notes for Machine Learning in Python

Professor Eric Larson
Demonstration of More Advanced
Convolutional Neural Networks

Class logistics and Agenda

- CNNs due next week
- Agenda:
 - More Advanced CNN Demo
- Next Time:
 - CNN Town Hall
 - Introduction to RNNs

Last Time:



More Modern CNN Architectures

Even more Convolutional
Neural Networks
...in TensorFlow
...with Keras

Demo



Next Time:

- CNN Lab Discussion (Town Hall)
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