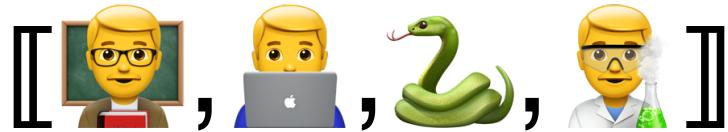


Lecture Notes for **Machine Learning in Python**

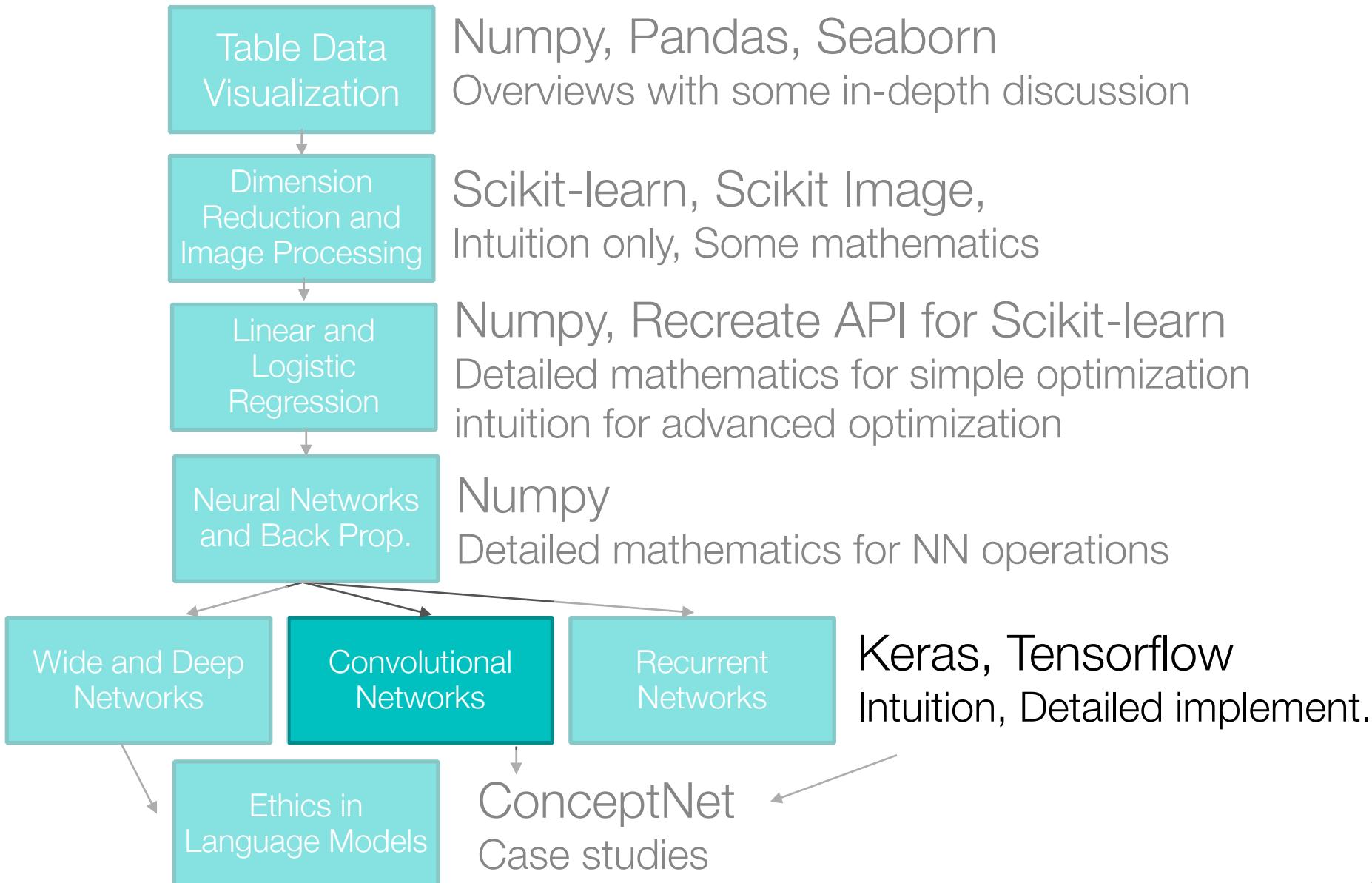


Professor Eric Larson
Convolutional Networks

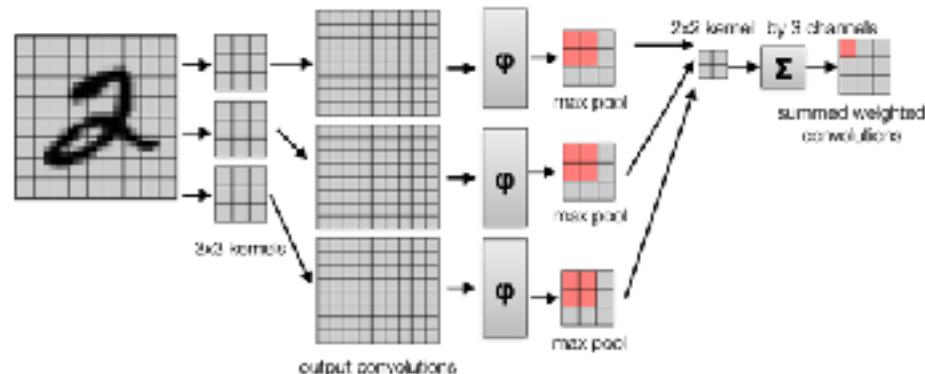
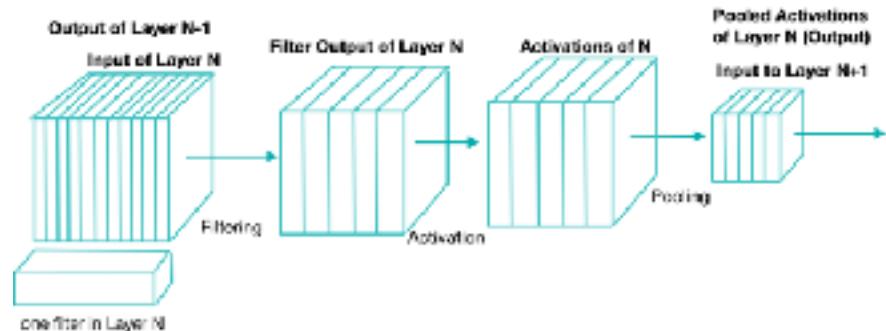
Class logistics and Agenda

- Logistics:
 - Next week, Thanksgiving break (lecture)
 - Lab due dates
- Agenda:
 - CNN Review
 - CNN Demo
 - CNN Town Hall
- Next Time:
 - More Advanced CNNs

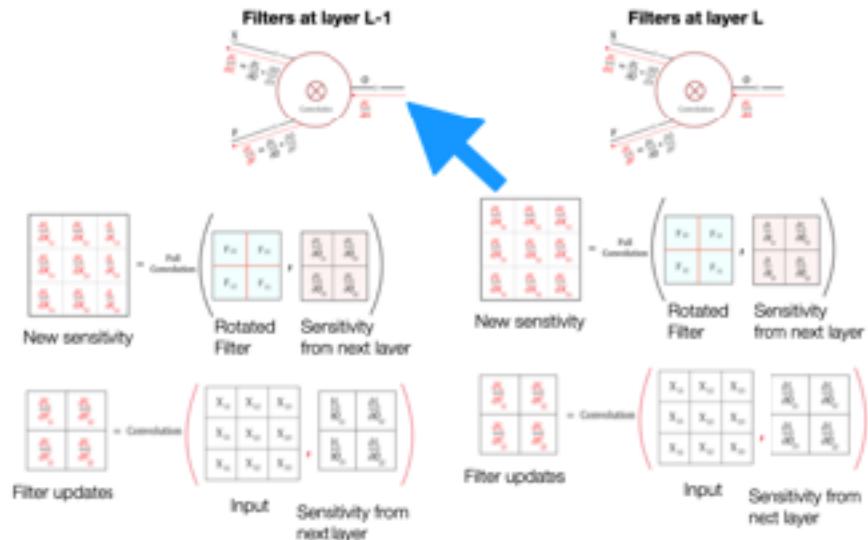
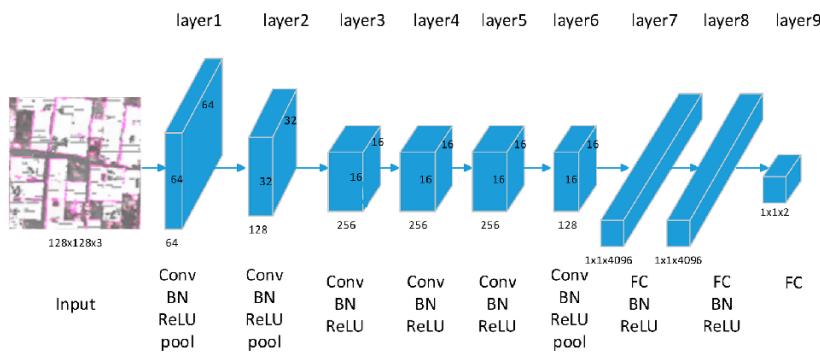
Class Overview, by topic



Last Time:



Structure of Each Tensor: Channels x Rows x Columns

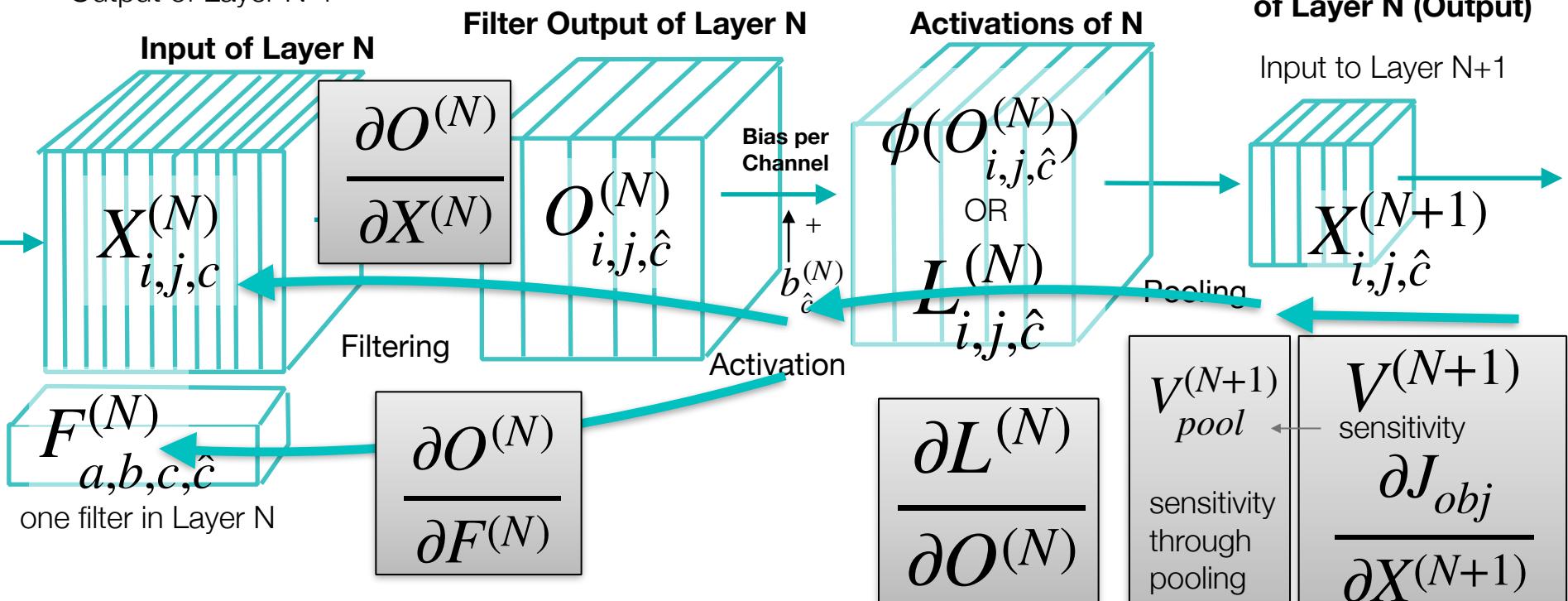


CNNs Back Propagation

Sensitivity to layer in back propagation

$$V^{(N)} = \frac{\partial O^{(N)}}{\partial X^{(N)}} \cdot \frac{\partial L^{(N)}}{\partial O^{(N)}} \cdot V_{pool}^{(N+1)} = \frac{\partial J_{obj}}{\partial X^{(N)}}$$

Output of Layer N-1



Now we can calc partial derivative

$$\frac{\partial L^{(N)}}{\partial F^{(N)}} = \frac{\partial O^{(N)}}{\partial F^{(N)}} \cdot \frac{\partial L^{(N)}}{\partial O^{(N)}}$$

Just incorporate sensitivity, to get weight update

$$\frac{\partial J_{obj}}{\partial F^{(N)}} = \frac{\partial O^{(N)}}{\partial F^{(N)}} \cdot \frac{\partial L^{(N)}}{\partial O^{(N)}} \cdot V^{(N+1)}_{pool}$$

Self-test

- For each traditional convolutional layer in a CNN, there are two convolutions per filter in the layer during back propagation.
 - **False.** There is a single convolution needed during back propagation for each filter.
 - **False.** The first convolutional layer has only one convolution needed, but all others have two per filter.
 - **True.** The filter weights are updated through two convolutions, one for each dimension.
 - **True.** One convolution is needed for pooling, and the other for filter weight updates.

TensorFlow and Basic CNNs

Convolutional Neural Networks
in TensorFlow
with Keras

Demo



11. Convolutional Neural Networks.ipynb

Image Data Augmentation

```
cnn = Sequential()  
  
# add in augmentations directly  
cnn.add( RandomFlip("horizontal") ) # flip horizontally  
cnn.add( RandomRotation(0.05) ) # rotate by 5%  
cnn.add( RandomTranslation(height_factor=0.1, width_factor=0.1) )  
cnn.add( RandomBrightness(factor=0.1, value_range=(0.0, 1.0)) ) #  
cnn.add( RandomContrast(0.1) ) # add or decrease contrast
```



**Image
Augmentation**

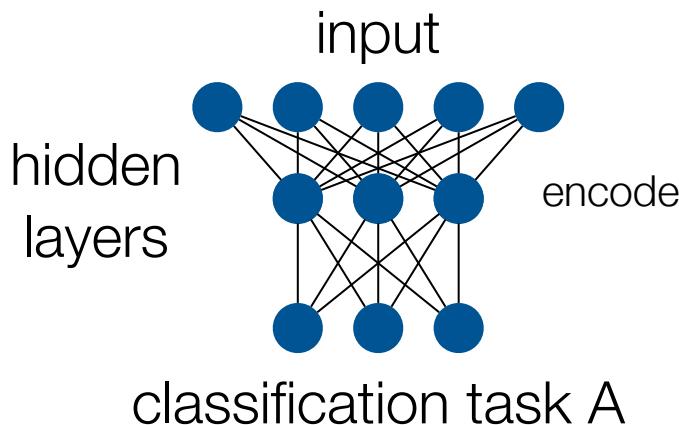
RandomRotation()



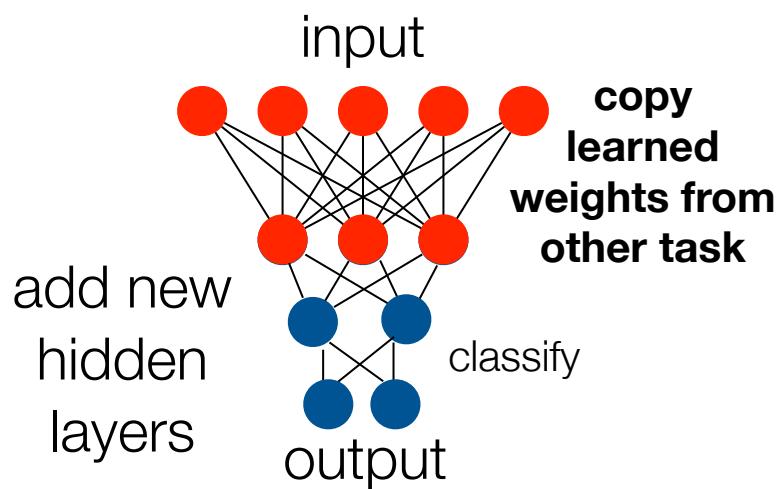
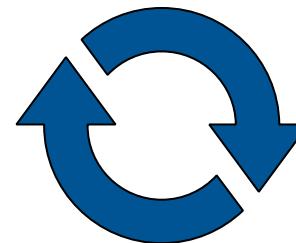
<https://machinelearningmastery.com/how-to-configure-image-data-augmentation-when-training-deep-learning-neural-networks/>

Transfer Learning

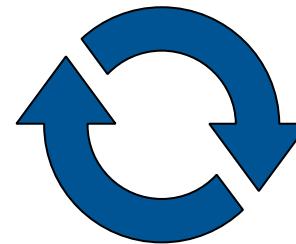
- transfer learning: a basic primer



train with lots of
data (like ImageNet)



train with fewer
labeled data (new task)



Many Pre-trained Models to choose from!

AlexNet

A landmark in computer vision, this 2012 winner of ImageNet has over 50,000 neurons.



29 nodes

AlexNet (Places)

The same architecture as the classic AlexNet model, but trained on the Places365 dataset.



78 nodes

Inception v1

Also known as GoogLeNet, this network set the state of the art in ImageNet classification in 2014.



85 nodes

Inception v1 (Places)

The same architecture as the classic Inception v1 model, but trained on the Places365 dataset.



103 nodes

VGG 19

Introduced in 2014, this network is simpler than Inception variants, using only 3x3 convolutions and no branches.



25 nodes

Inception v3

Released in 2015, this iteration of the Inception architecture improved performance and efficiency.



127 nodes

Inception v4

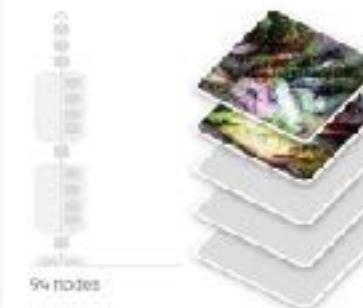
Released in 2016, this is the fourth iteration of the inception architecture, focusing on uniformity.



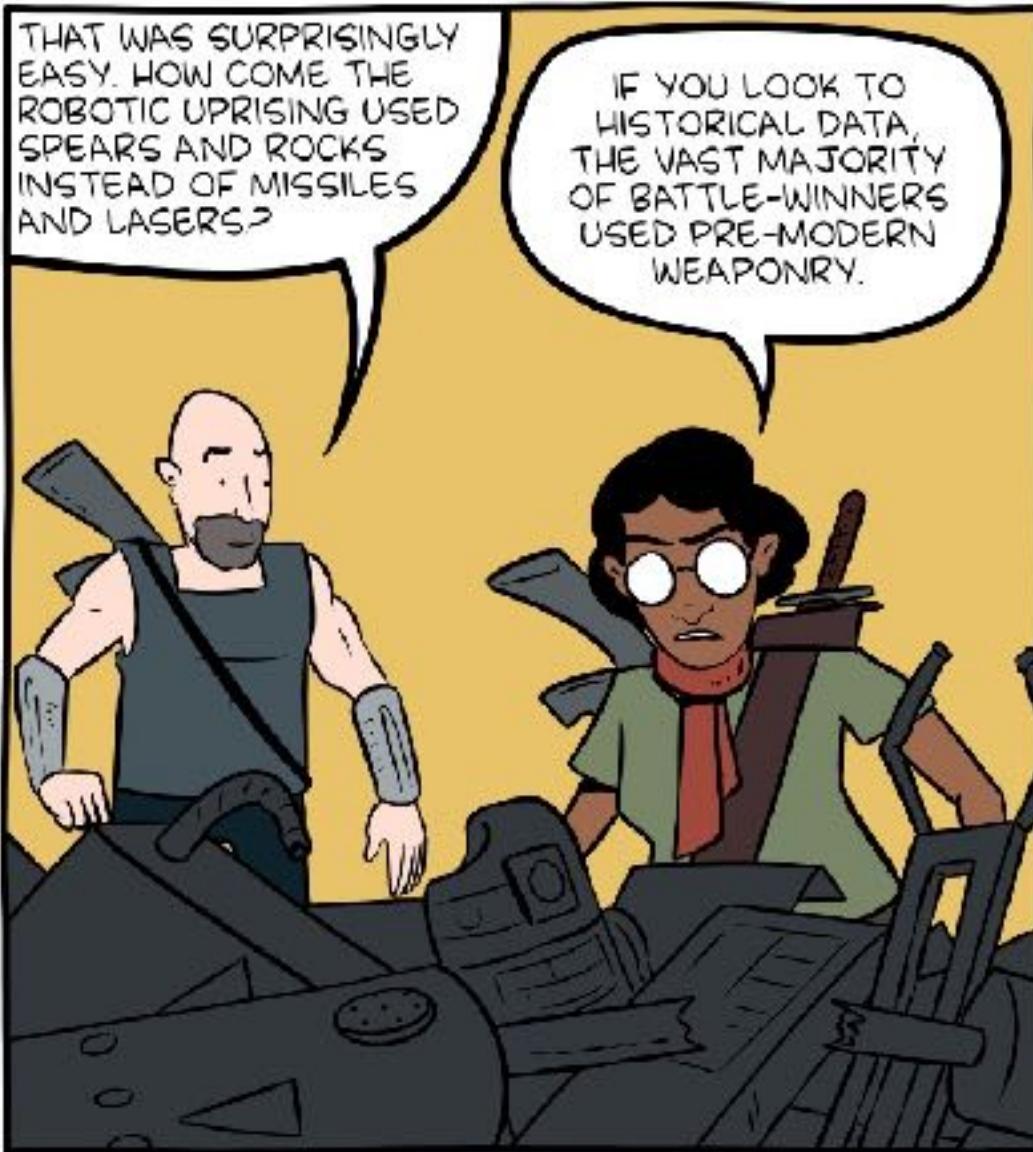
196 nodes

ResNet v2 50

ResNets use skip connections to enable stronger gradients in much deeper networks. This variant has 50 layers.



94 nodes

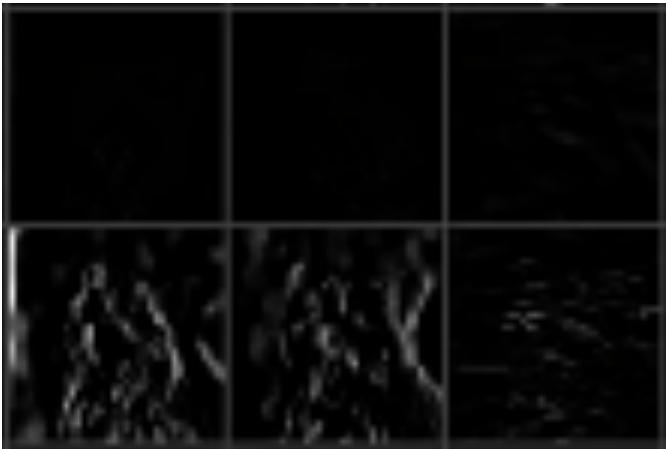
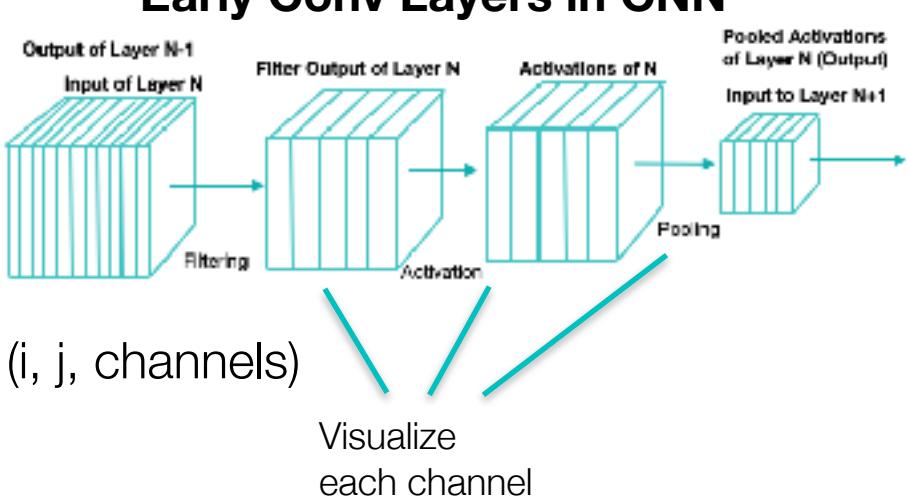


CNN Town Hall

Thanks to
Machine Learning the
robot apocalypse was
short lived!

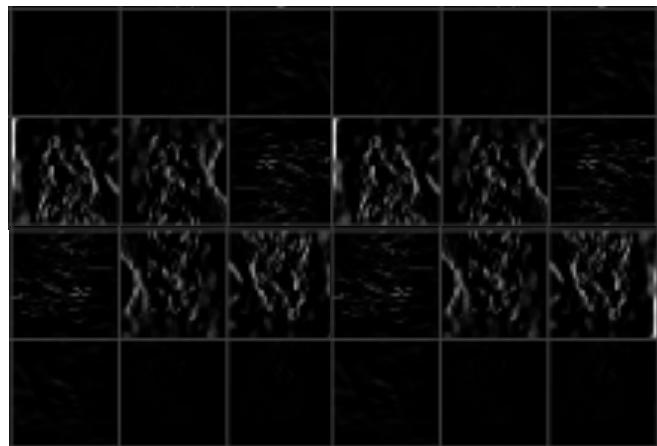
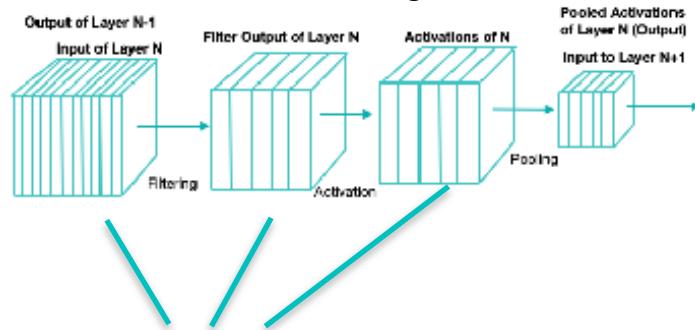
What has a CNN learned?

Early Conv Layers in CNN



Separate channels. Early layers have fewer filters, but larger activations

Later Conv Layers in CNN



Later layers have more filters, but smaller activations

Naming in Video:

- conv1 (output activations of conv)
- p1 (output of pooling)
- n1 (output of normalization)

Deep Visualization Toolbox

yosinski.com/deepvis

#deepvis



Jason Yosinski



Jeff Clune



Anh Nguyen



Thomas Fuchs



Hod Lipson



Cornell University



Jet Propulsion Laboratory
California Institute of Technology

<https://github.com/yosinski/deep-visualization-toolbox>

Next Lecture

- More CNN architectures and CNN history