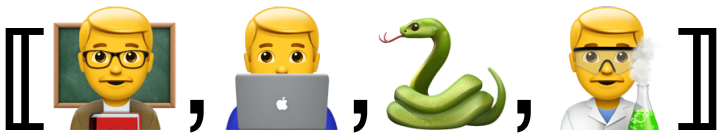
Lecture Notes for

Machine Learning in Python



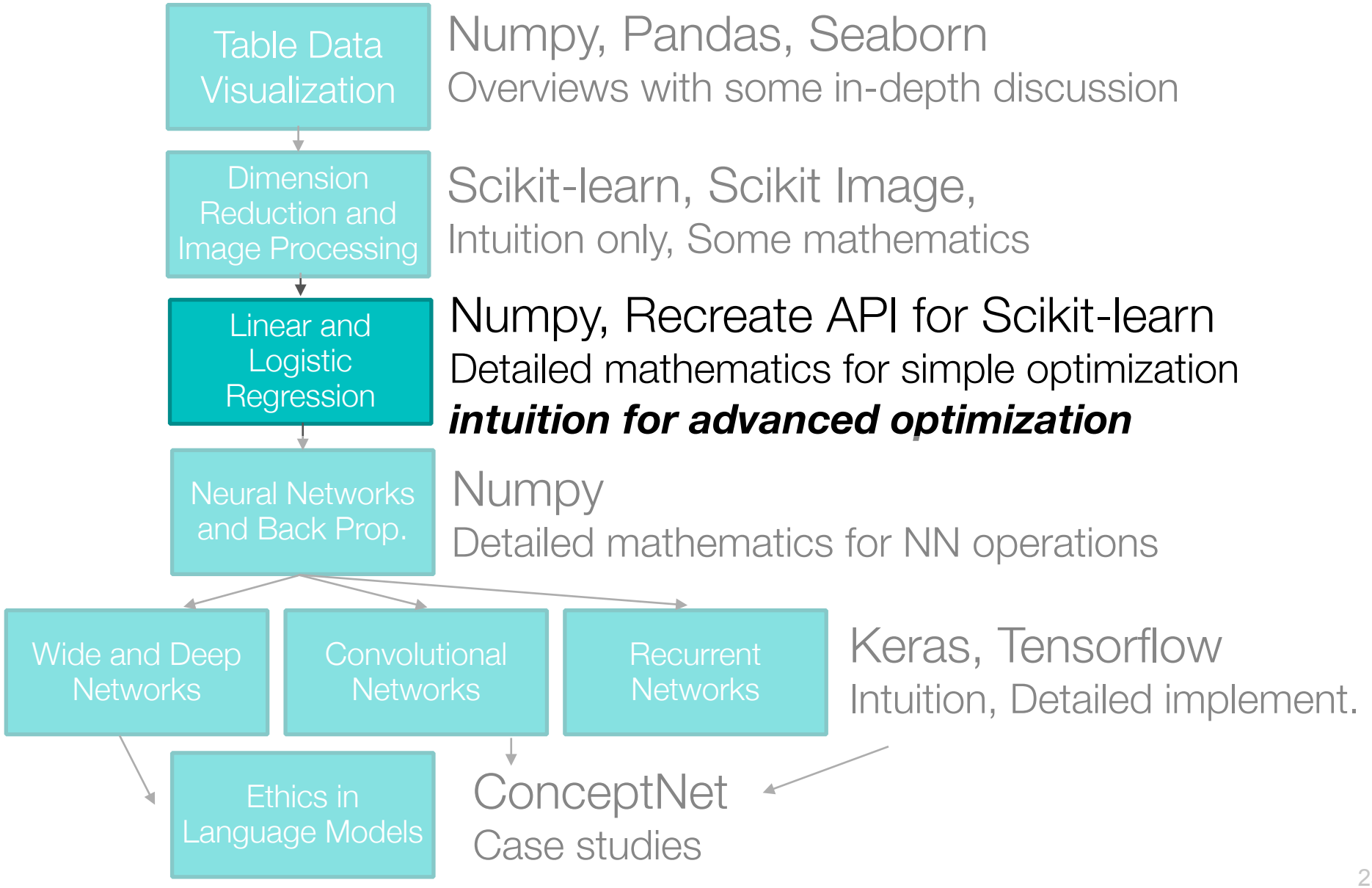
Professor Eric Larson

Optimization Techniques for Logistic Regression Continued

Class Logistics and Agenda

- Agenda
  - Numerical Optimization Techniques
    - Types of Optimization
    - Programming the Optimization
- **Last Time:**
  - Logistic regression update equations
  - Line Searches
  - Stochastic small batches
  - Hessian-based methods

Class Overview, by topic



Demo Lecture, Continued

$$\mathbf{H}_{j,k}(\mathbf{w}) = \frac{\partial}{\partial w_k}\frac{\partial}{\partial w_j} l(\mathbf{w}) \rightarrow \frac{\partial}{\partial w_j} l(\mathbf{w}) = \sum_i \left(y^{(i)} - g(\mathbf{w}^T \cdot \mathbf{x}^{(i)})\right) x_j^{(i)}$$

$$\mathbf{H}_{j,k}(\mathbf{w}) = \frac{\partial}{\partial w_k} \sum_i \left(y^{(i)} - g(\mathbf{w}^T \cdot \mathbf{x}^{(i)})\right) x_j^{(i)}$$

$$= \sum_i \frac{\partial}{\partial w_k} y^{(i)} x_j^{(i)} - \sum_i \frac{\partial}{\partial w_k} g(\mathbf{w}^T \cdot \mathbf{x}^{(i)}) x_j^{(i)}$$

no dependence on w_k, zero

$$= -\sum_i x_j^{(i)} \frac{\partial}{\partial w_k} g(\mathbf{w}^T \cdot \mathbf{x}^{(i)})$$

already know this as $g(1-g)x_k$

$$\mathbf{H}_{j,k}(\mathbf{w}) = -\sum_{i=1}^{M} \left[g(\mathbf{w}^T\mathbf{x}^{(i)})[1 - g(\mathbf{w}^T\mathbf{x}^{(i)})]\right] \cdot x_k^{(i)} x_j^{(i)}$$

for each j,k pair

Town Hall

$$L_2 = C\sum_j w_j^2$$ `penalty = 'l2'`

$$L_1 = C\sum_j |w_j|$$ `penalty = 'l1'`

$$L_{12} = C_1\sum_j |w_j| + C_2\sum_j w_j^2$$ `penalty = 'elasticnet'`

Warning: The choice of the algorithm depends on the penalty chosen. Supported penalties by solver:

- 'lbfgs' - ['l2', None]
- 'liblinear' - ['l1', 'l2']
- 'newton-cg' - ['l2', None]
- 'newton-cholesky' - ['l2', None]
- 'sag' - ['l2', None]
- 'saga' - ['elasticnet', 'l1', 'l2', None]

Back Up Slides

Last time

$$p(y^{(i)} = 1 \mid x^{(i)}, w) = \frac{1}{1 + \exp(w^T x^{(i)})}$$

$$l(w) = \sum_i \left(y^{(i)} \ln[g(w^T x^{(i)})] + (1 - y^{(i)})(\ln[1 - g(w^T x^{(i)})]) \right)$$

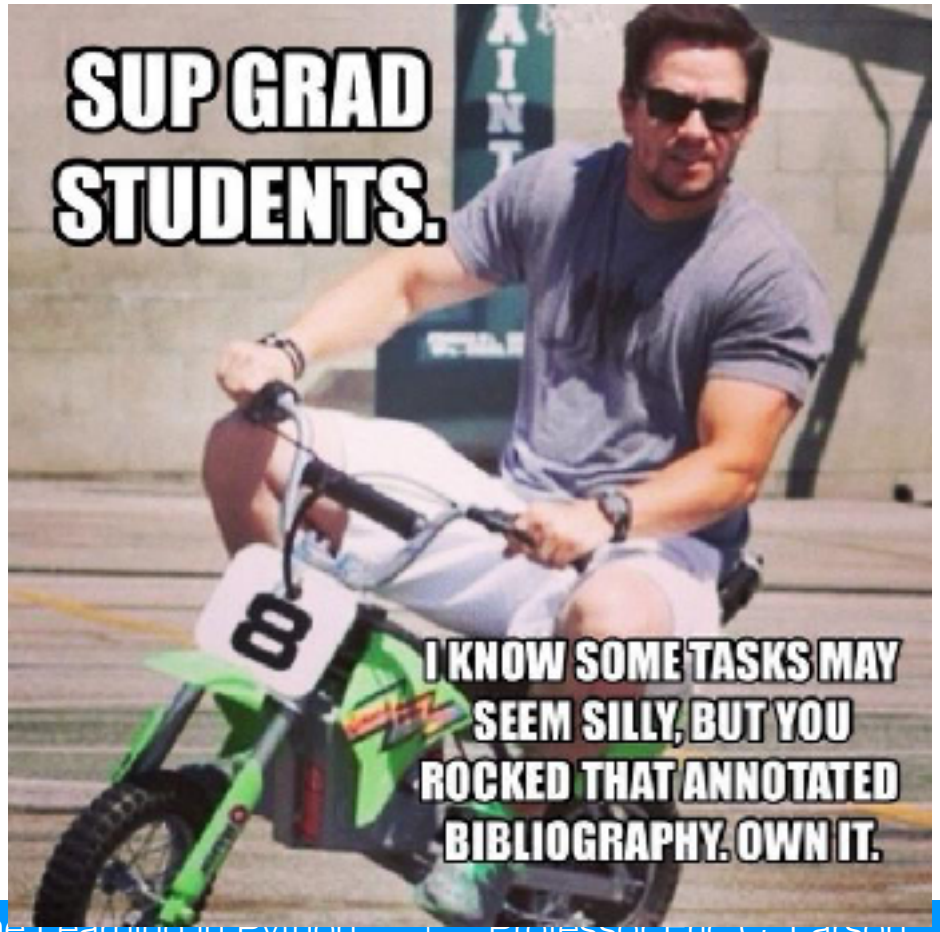
$$\underbrace{w_j}_{\text{new value}} \leftarrow \underbrace{w_j}_{\text{old value}} + \underbrace{\eta \sum_{i=1}^{M} (y^{(i)} - g(x^{(i)}))x_j^{(i)}}_{\text{gradient}}$$

$$w \leftarrow w + \eta \sum_{i=1}^{M} (y^{(i)} - g(x^{(i)}))x^{(i)}$$

$$w \leftarrow w + \eta \left[\underbrace{\nabla l(w)_{old}}_{\text{old gradient}} - C \cdot 2w \right]$$

```
def _get_gradient(self,X,y):
    # programming \sum_i (yi-g(xi))xi
    gradient = np.zeros(self.w_.shape) # set
    for (xi,yi) in zip(X,y):
        # the actual update inside of sum
        gradi = (yi - self.predict_proba(xi,
        # reshape to be column vector and ad
        gradient += gradi.reshape(self.w_.sh

    return gradient/float(len(y))
```

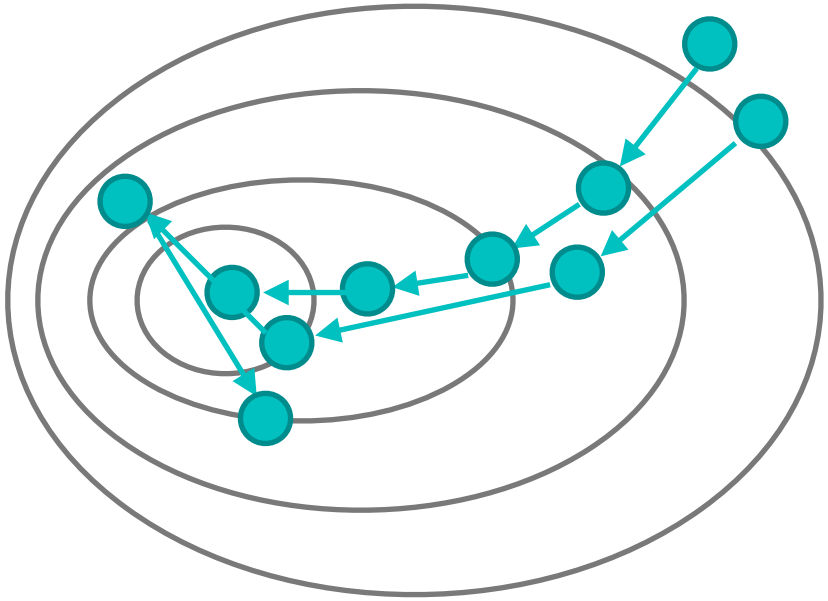

SUP GRAD STUDENTS.
I KNOW SOME TASKS MAY SEEM SILLY, BUT YOU ROCKED THAT ANNOTATED BIBLIOGRAPHY. OWN IT.

Optimization: gradient descent

- What we know thus far:

$$\underbrace{w_j}_{\text{new value}} \leftarrow \underbrace{w_j}_{\text{old value}} + \eta \underbrace{\left[\left(\sum_{i=1}^{M} (y^{(i)} - g(x^{(i)}))x_j^{(i)} \right) - C \cdot 2w_j \right]}_{\nabla l(w)}$$

$$w \leftarrow w + \eta \nabla l(w)$$

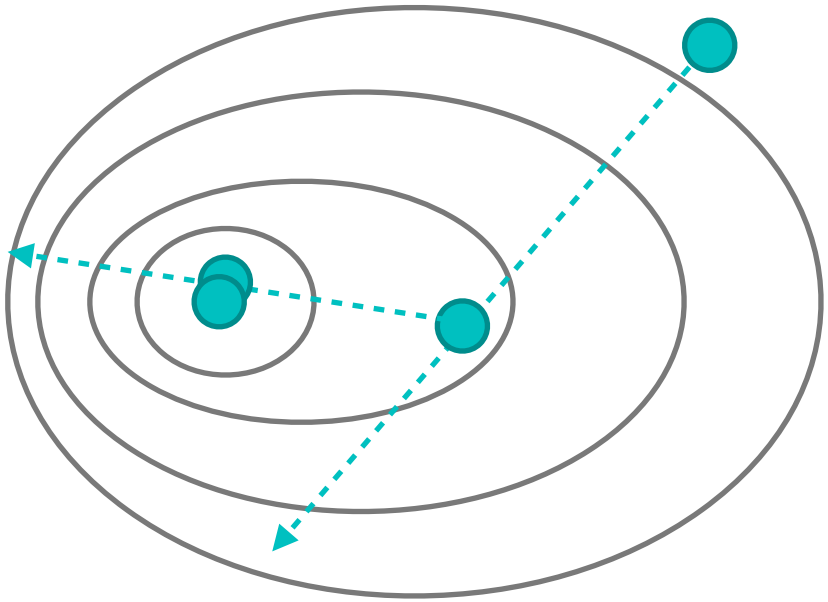


Line Search: a better method

- Line search in direction of gradient:

$$w \leftarrow w + \eta \nabla l(w)$$

$$w \leftarrow w + \underbrace{\eta}_{\text{best step?}} \nabla l(w)$$



Revisiting the Gradient

- How much computation is required (for gradient)?

$$\sum_{i=1}^{M}(y^{(i)} - \hat{y}^{(i)})x^{(i)} - 2C \cdot w$$

M = number of instances
N = number of features

Self Test: How many multiplies per gradient calculation?

A. M*N+1 multiplications
B. (M+1)*N multiplications
C. 2N multiplications
D. 2N-M multiplications

Stochastic Methods

- How much computation is required (for gradient)?

$$\sum_{i=1}^{M}(y^{(i)} - \hat{y}^{(i)})x^{(i)} - 2C \cdot w$$

Per iteration:

(M+1)*N multiplications

2M add/subtract

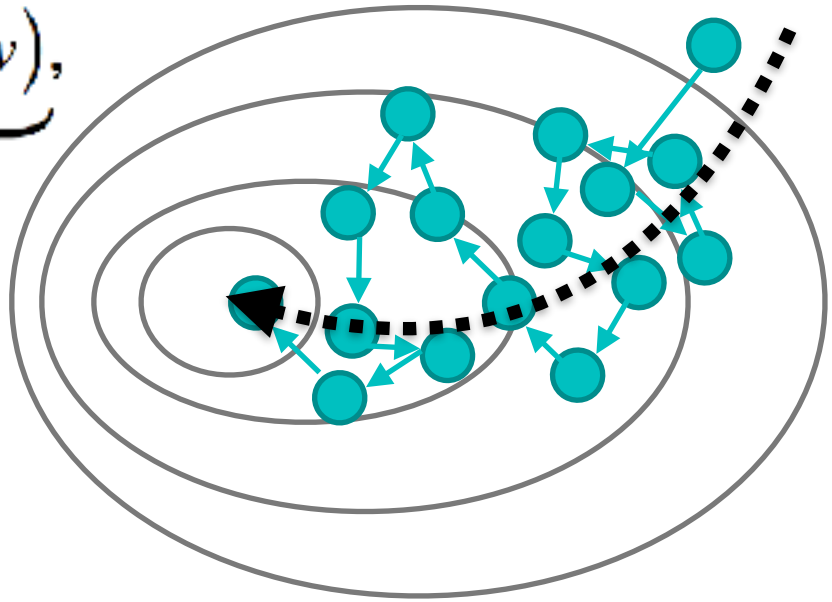
$$w \leftarrow w + \eta\underbrace{\left((y^{(i)} - \hat{y}^{(i)})x^{(i)} - 2C \cdot w\right)}_{\text{approx. gradient}},$$

i chosen at random

Per iteration:

N+1 multiplications

1 add/subtract



06. Optimization.ipynb

Demo

Gradient Descent (with line search)
Stochastic Gradient Descent
Hessian
Quasi-Newton Methods
Multi-processing

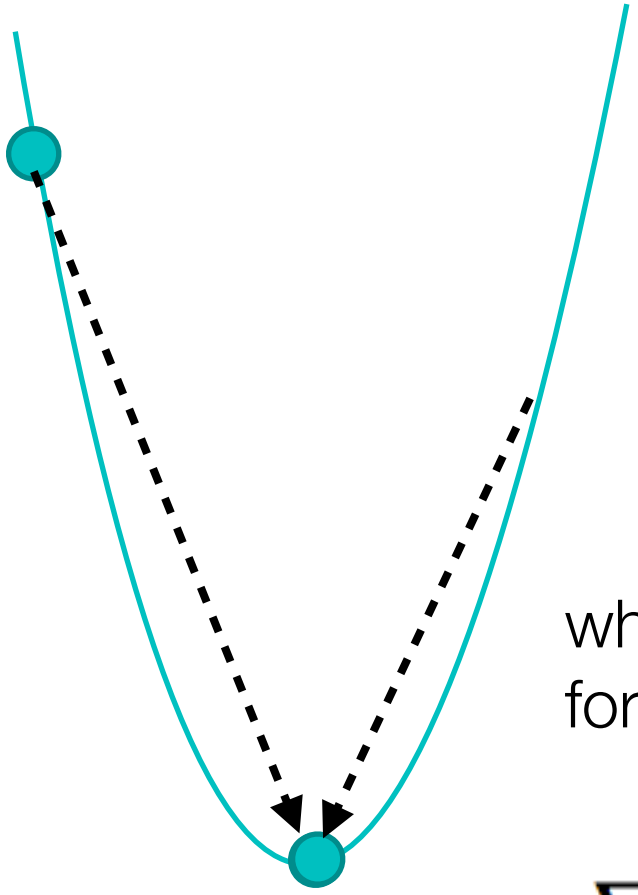
For Next Lecture

- **Next time**: SVMs via in class assignment
- **Next Next time**: Neural Networks


SUP. HAVE YOU HEARD THE LATEST STATS JOKE?
PROBABLY.

Can we do better than the gradient?

- Assume function is quadratic:



function of one variable:

$$w \leftarrow w - \underbrace{[\frac{\partial^2}{\partial w} l(w)]^{-1}}_{\text{inverse 2nd deriv}} \underbrace{\frac{\partial}{\partial w} l(w)}_{\text{derivative}}$$

will solve in one step!

what is the second order derivative for a multivariate function?

$$\nabla^2 l(w) = \mathbf{H}[l(w)]$$

The Hessian

- Assume function is quadratic:

function of one variable:

$$\mathbf{H}[l(w)] = \begin{bmatrix} \frac{\partial^2}{\partial w_1} l(w) & \frac{\partial}{\partial w_1}\frac{\partial}{\partial w_2} l(w) & \dots & \frac{\partial}{\partial w_1}\frac{\partial}{\partial w_N} l(w) \\ \frac{\partial}{\partial w_2}\frac{\partial}{\partial w_1} l(w) & \frac{\partial^2}{\partial w_2} l(w) & \dots & \frac{\partial}{\partial w_2}\frac{\partial}{\partial w_N} l(w) \\ \vdots & & & \\ \frac{\partial}{\partial w_N}\frac{\partial}{\partial w_1} l(w) & \frac{\partial}{\partial w_N}\frac{\partial}{\partial w_2} l(w) & \dots & \frac{\partial^2}{\partial w_N} l(w) \end{bmatrix}$$

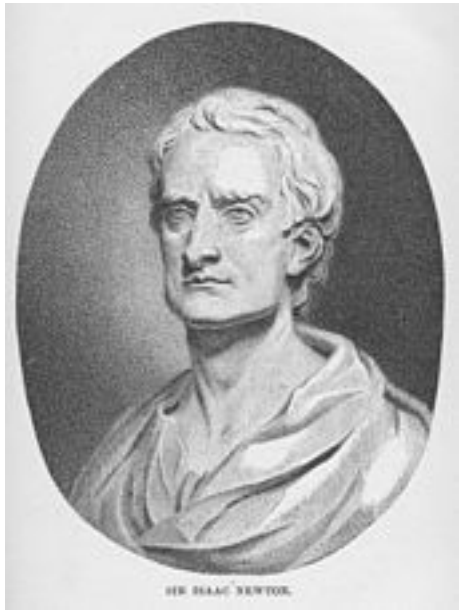
$$\nabla^2 l(w) = \mathbf{H}[l(w)]$$

The Newton Update Method

- Assume function is quadratic (in high dimensions):

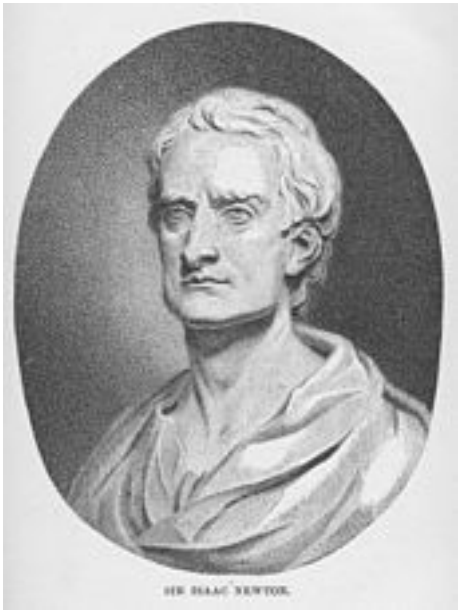
$$w \leftarrow w - \underbrace{[\frac{\partial^2}{\partial w} l(w)]^{-1}}_{\text{inverse 2nd deriv}} \underbrace{\frac{\partial}{\partial w} l(w)}_{\text{derivative}}$$

$$w \leftarrow w + \eta \cdot \underbrace{\mathbf{H}[l(w)]^{-1}}_{\text{inverse Hessian}} \cdot \underbrace{\nabla l(w)}_{\text{gradient}}$$



Js. Newton

I do not know what I may appear to the world, but to myself I seem to have been only like a boy playing on the sea-shore, and diverting myself in now and then finding a smoother pebble or a prettier shell than ordinary, whilst the great ocean of truth lay all undiscovered before me.



Js. Newton

I do not know what I may appear to the world, but to myself I seem to have been only like a boy playing on the sea-shore, and diverting myself in now and then finding a smoother pebble or a prettier shell than ordinary, whilst the great ocean of truth lay all undiscovered before me.

$$\frac{\partial}{\partial w_j} l(w) = \sum_i \left(y^{(i)} - g(x^{(i)})\right) x_j^{(i)}$$

↓ PLUG IN

$$H[k,j] = \frac{\partial}{\partial w_k}\frac{\partial}{\partial w_j} l = \frac{\partial}{\partial w_k}\left(\sum_i \left(y^{(i)} - g(x^{(i)})\right) x_j^{(i)}\right)$$

$$= \sum_i \frac{\partial}{\partial w_k} \overset{0}{y^{(i)}} x_j^{(i)} - \frac{\partial}{\partial w_k} g(x^{(i)}) x_j^{(i)}$$

← LEFT OVER TERM

$$= -\sum_i \frac{\partial}{\partial w_k} g(x^{(i)}) x_j^{(i)}$$

Already know $\frac{\partial}{\partial w_k} g(w^T x^{(i)})$ side calculation

$$= g(x^{(i)})\left(1 - g(x^{(i)})\right) \frac{\partial}{\partial w_k}\left(w^T x^{(i)}\right)$$

$$= g(x^{(i)})\left(1 - g(x^{(i)})\right) x_k^{(i)}$$

← PLUG IN

$$\therefore = -\sum_i g(x^{(i)})\left(1 - g(x^{(i)})\right) x_k^{(i)} x_j^{(i)}$$

↑ THAT'S THE HESSIAN.

$H(k,j) =$ This is a valid equation for the Hessian, but we want to represent it using linear algebra

$$= -\sum_i g(x^{(i)})\left(1 - g(x^{(i)})\right) x_k^{(i)} x_j^{(i)}$$

↑ SIGMOID

The Hessian for Logistic Regression

- The hessian is easy to calculate from the gradient for logistic regression

$$w \leftarrow w + \eta \cdot \underbrace{\mathbf{H}[l(w)]^{-1}}_{\text{inverse Hessian}} \cdot \underbrace{\nabla l(w)}_{\text{gradient}}$$

$$\mathbf{H}_{j,k}[l(w)] = -\sum_{i=1}^{M} g(x^{(i)})(1 - g(x^{(i)})x_k{}^{(i)}x_j{}^{(i)} \qquad \underbrace{\sum_{i=1}^{M}(y^{(i)} - \hat{y}^{(i)})x_j^{(i)}}_{\text{gradient}}$$

$$\mathbf{H}[l(w)] = X^T \cdot \text{diag}[g(x^{(i)})(1 - g(x^{(i)}))] \cdot X \qquad X * y_{diff}$$

$$w \leftarrow w + \eta[X^T \cdot \text{diag}[g(x^{(i)})(1 - g(x^{(i)}))] \cdot X]^{-1} \cdot X * y_{diff}$$