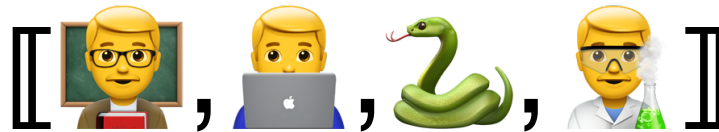


Lecture Notes for **Machine Learning in Python**



Professor Eric Larson
Convolutional Networks

Class logistics and Agenda

- Logistics:
 - Next week, Thanksgiving break (lecture)
 - Lab due dates
- Agenda:
 - CNN Review
 - CNN Demo
 - CNN Town Hall
- Next Time:
 - More Advanced CNNs

Class Overview, by topic

Table Data
Visualization

Numpy, Pandas, Seaborn
Overviews with some in-depth discussion

Dimension
Reduction and
Image Processing

Scikit-learn, Scikit Image,
Intuition only, Some mathematics

Linear and
Logistic
Regression

Numpy, Recreate API for Scikit-learn
Detailed mathematics for simple optimization
intuition for advanced optimization

Neural Networks
and Back Prop.

Numpy
Detailed mathematics for NN operations

Wide and Deep
Networks

Convolutional
Networks

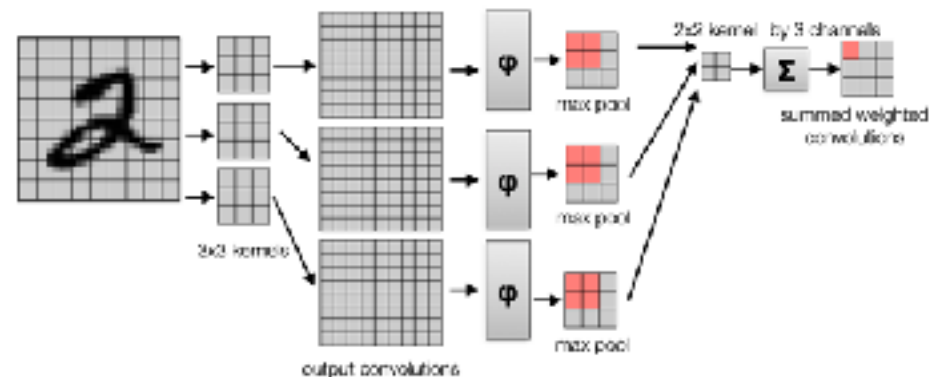
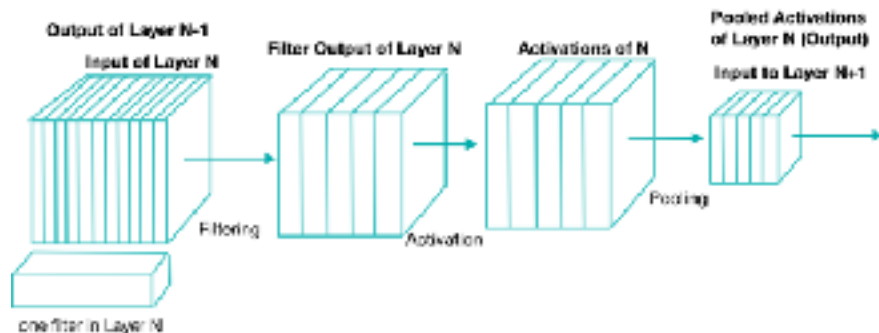
Recurrent
Networks

Keras, Tensorflow
Intuition, Detailed implement.

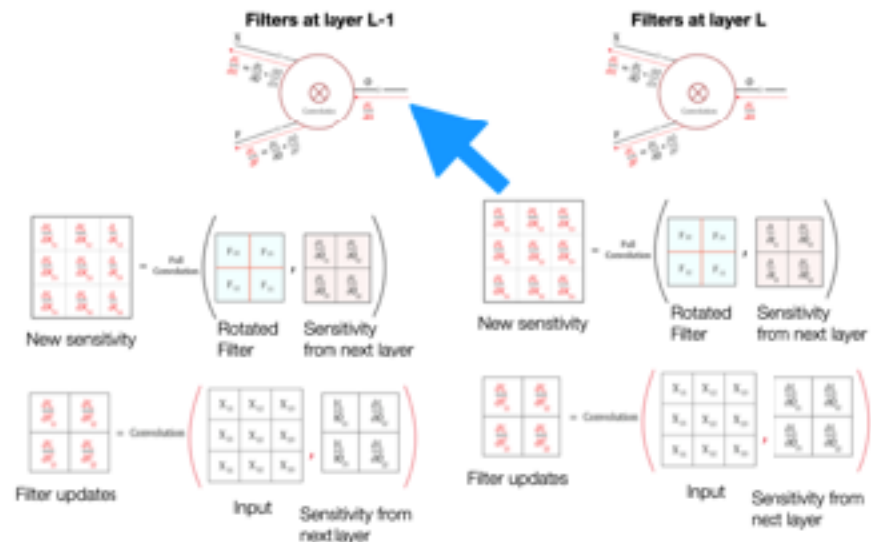
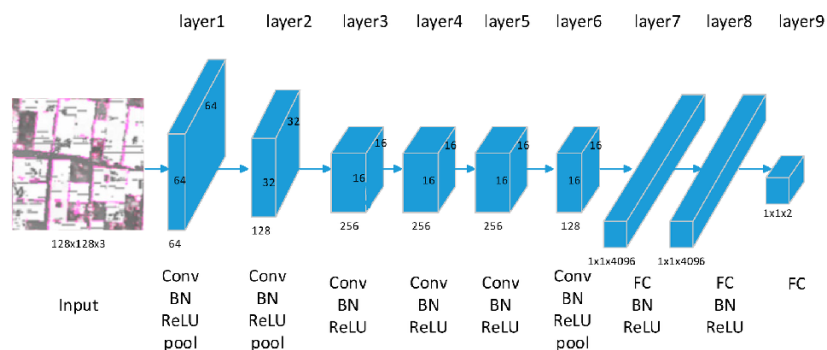
Ethics in
Language Models

ConceptNet
Case studies

Last Time:



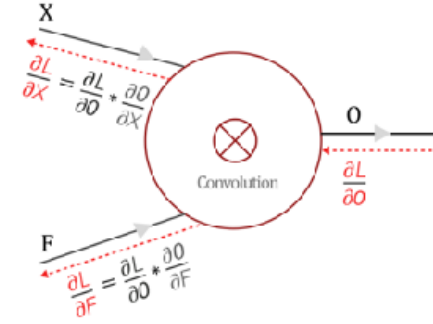
Structure of Each Tensor: Channels x Rows x Columns



CNN Back Propagation

Sensitivity to layer in back propagation

$$V^{(N)} = \frac{\partial O^{(N)}}{\partial X^{(N)}} \cdot \frac{\partial L^{(N)}}{\partial O^{(N)}} \cdot V_{pool}^{(N+1)} = \frac{\partial J_{obj}}{\partial X^{(N)}}$$



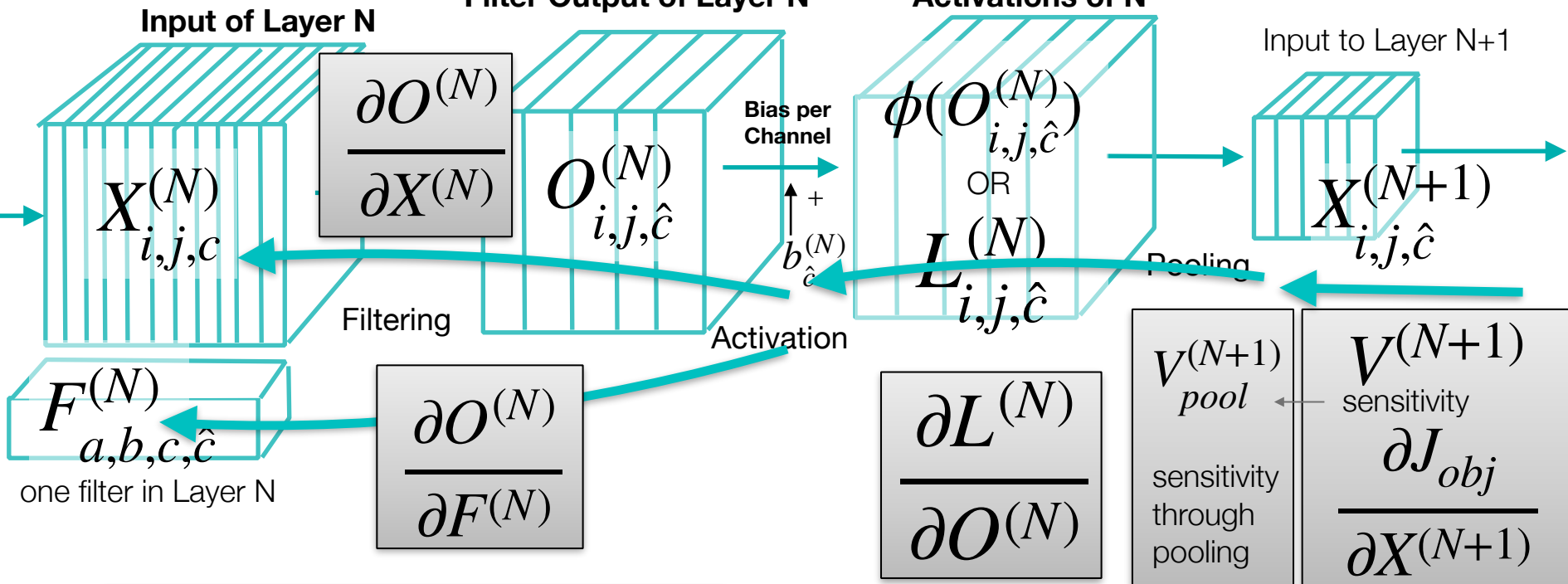
Output of Layer N-1

Filter Output of Layer N

Activations of N

Pooled Activations of Layer N (Output)

Input to Layer N+1



Now we can calc partial derivative

$$\frac{\partial L^{(N)}}{\partial F^{(N)}} = \frac{\partial O^{(N)}}{\partial F^{(N)}} \cdot \frac{\partial L^{(N)}}{\partial O^{(N)}}$$

source:

Just incorporate sensitivity, to get weight update

$$\frac{\partial J_{obj}}{\partial F^{(N)}} = \frac{\partial O^{(N)}}{\partial F^{(N)}} \cdot \frac{\partial L^{(N)}}{\partial O^{(N)}} \cdot V_{pool}^{(N+1)}$$

Self-test

- For each traditional convolutional layer in a CNN, there are two convolutions per filter in the layer during back propagation.
 - **False.** There is a single convolution needed during back propagation for each filter.
 - **False.** The first convolutional layer has only one convolution needed, but all others have two per filter.
 - **True.** The filter weights are updated through two convolutions, one for each dimension.
 - **True.** One convolution is needed for pooling, and the other for filter weight updates.

Convolutional Neural Networks
in TensorFlow
with Keras



11. Convolutional Neural Networks.ipynb

Image Data Augmentation

```
cnn = Sequential()  
  
# add in augmentations directly  
cnn.add( RandomFlip("horizontal") ) # flip horizontally  
cnn.add( RandomRotation(0.05) ) # rotate by 5%  
cnn.add( RandomTranslation(height_factor=0.1, width_factor=0.1) )  
cnn.add( RandomBrightness(factor=0.1, value_range=(0.0, 1.0)) ) #  
cnn.add( RandomContrast(0.1) ) # add or decrease contrast
```



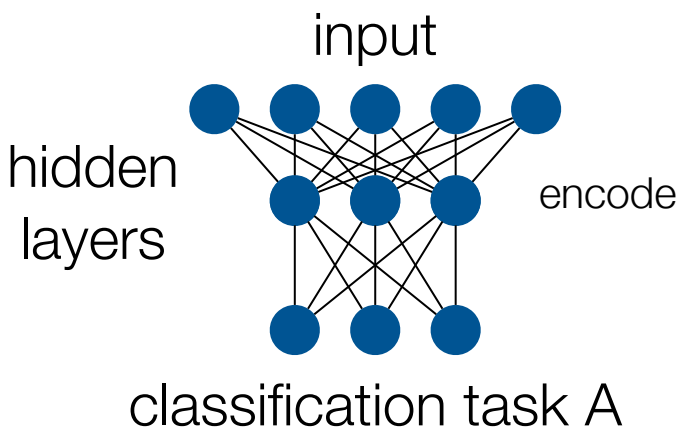
**Image
Augmentation**

RandomRotation()

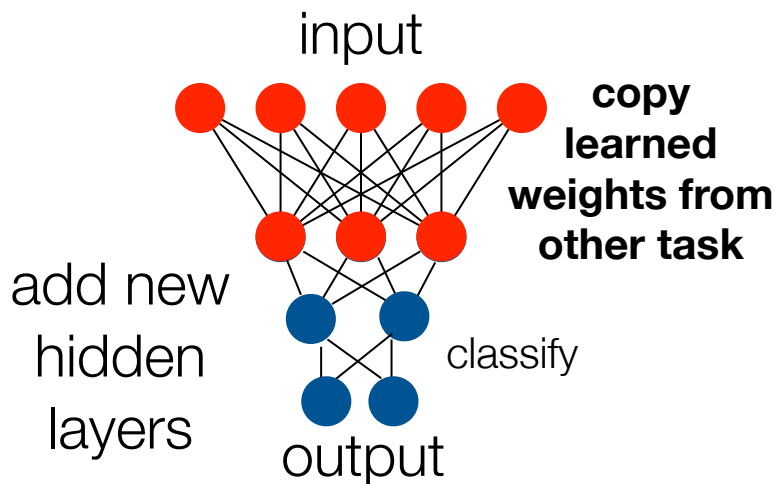
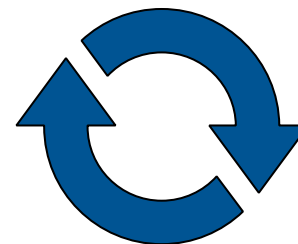


Transfer Learning

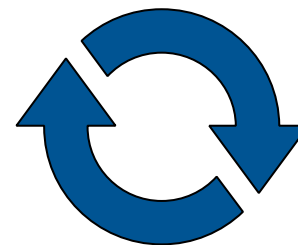
- transfer learning: a basic primer



train with lots of
data (like ImageNet)



train with fewer
labeled data (new task)



Many Pre-trained Models to choose from!

AlexNet

A landmark in computer vision, this 2012 winner of ImageNet has over 50,000 citations.



AlexNet (Places)

The same architecture as the classic AlexNet model, but trained on the Places365 dataset.



Inception v1

Also known as GoogLeNet, this network set the state of the art in ImageNet classification in 2014.



Inception v1 (Places)

The same architecture as the classic Inception v1 model, but trained on the Places365 dataset.



VGG 19

Introduced in 2014, this network is simpler than Inception variants, using only 3x3 convolutions and no branches.



Inception v3

Released in 2015, this iteration of the Inception architecture improved performance and efficiency.



Inception v4

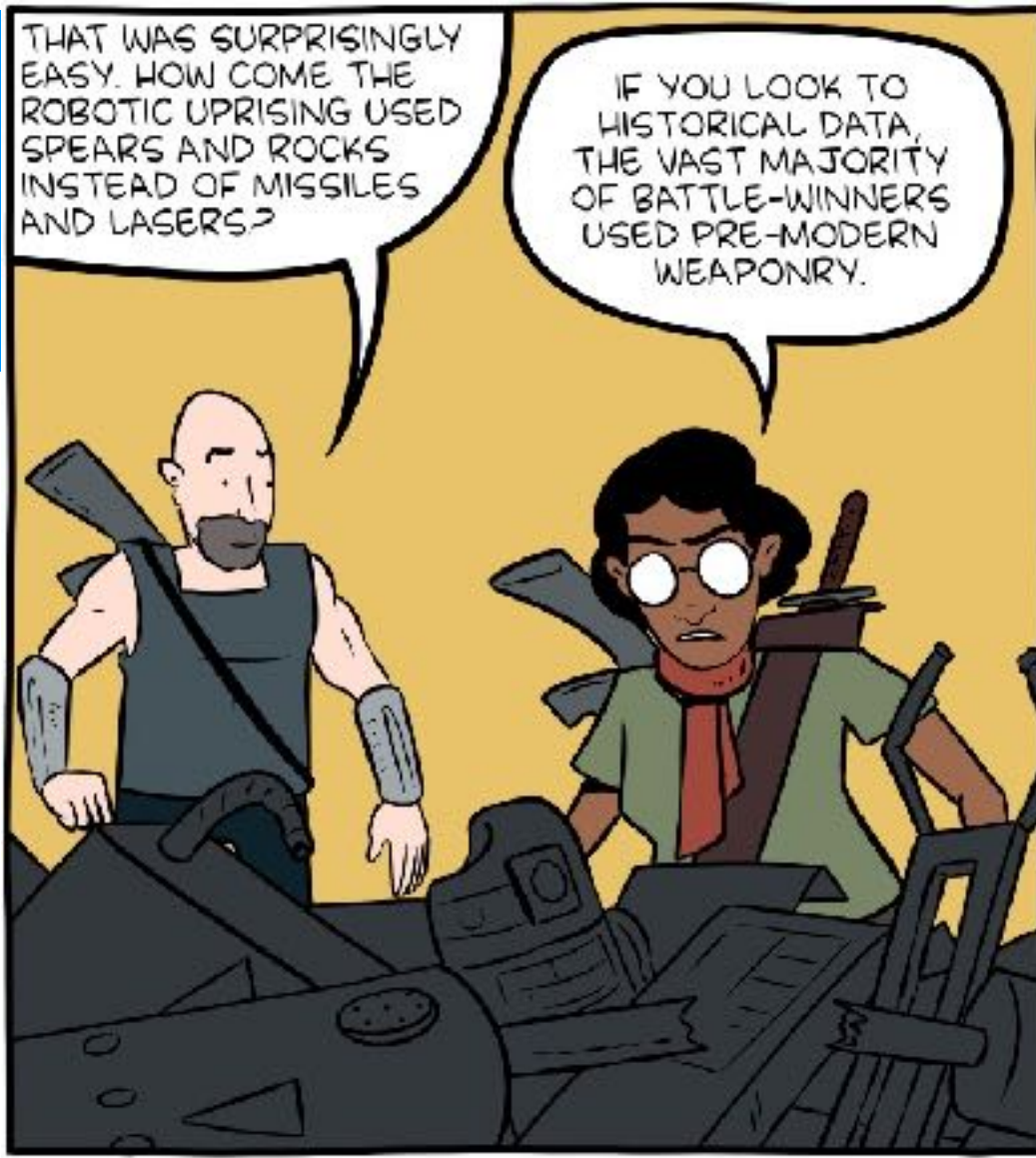
Released in 2016, this is the fourth iteration of the Inception architecture, focusing on uniformity.



ResNet v2 50

ResNets use skip connections to enable stronger gradients in much deeper networks. This variant has 50 layers.



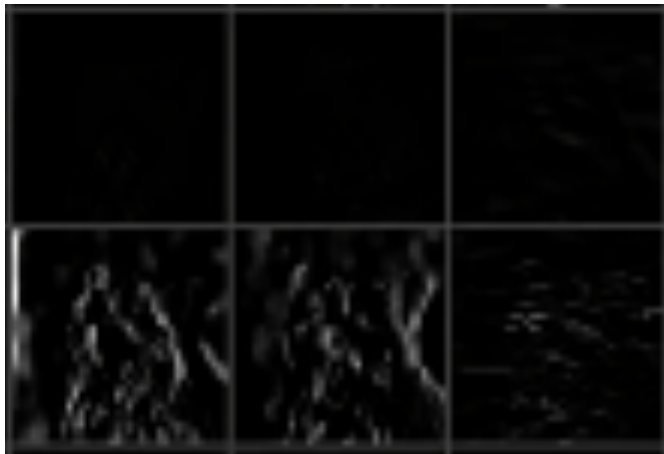
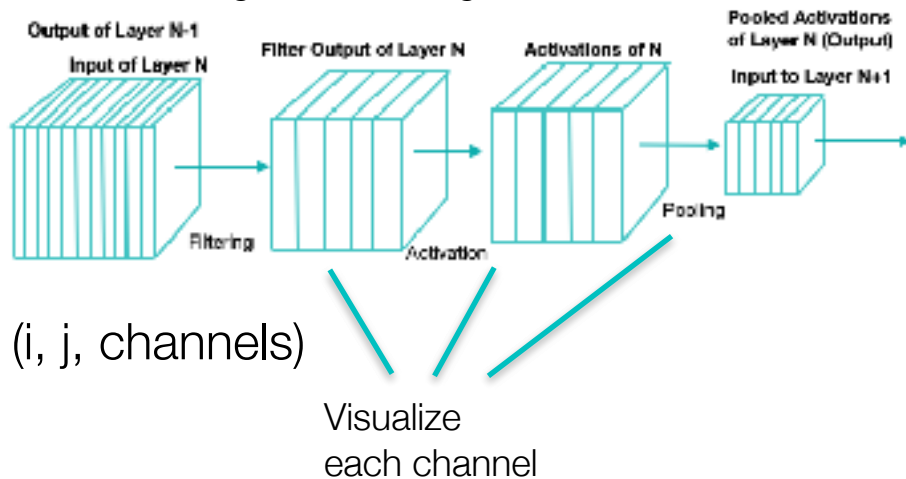


CNN Town Hall

Thanks to
Machine Learning the
robot apocalypse was
short lived!

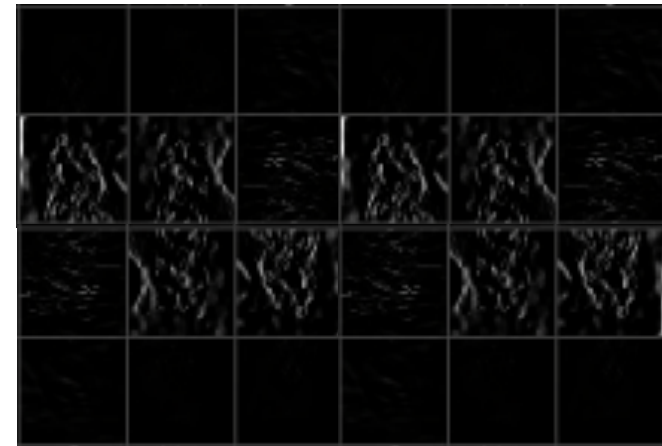
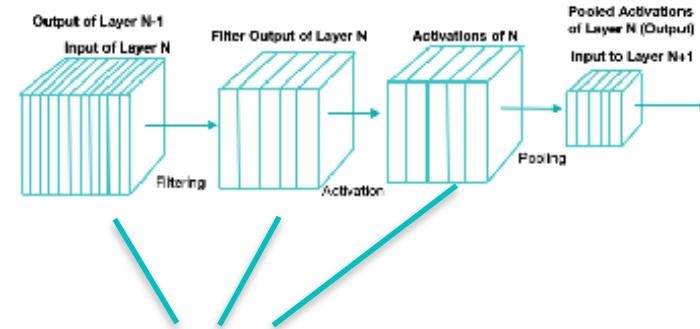
What has a CNN learned?

Early Conv Layers in CNN



Separate channels. Early layers have fewer filters, but larger activations

Later Conv Layers in CNN



Later layers have more filters, but smaller activations

Naming in Video:

conv1 (output activations of conv)

p1 (output of pooling)

n1 (output of normalization)

Deep Visualization Toolbox

yosinski.com/deepvis

#deepvis



Jason Yosinski



Jeff Clune



Anh Nguyen



Thomas Fuchs



Hod Lipson



<https://github.com/yosinski/deep-visualization-toolbox>

Next Lecture

- More CNN architectures and CNN history