

Asymptotic regime for improperness tests of complex random vectors

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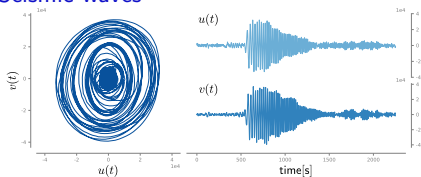


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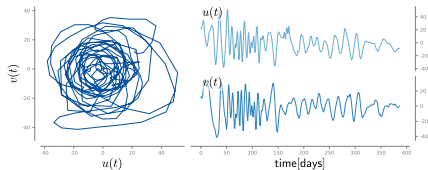


Complex valued signals

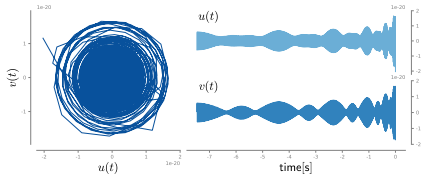
Seismic waves



Ocean currents

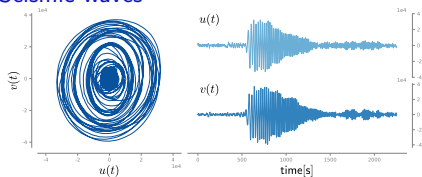


Gravitational waves

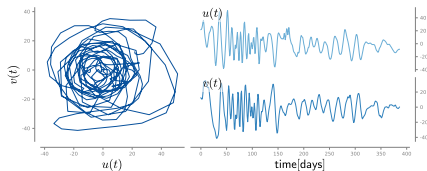


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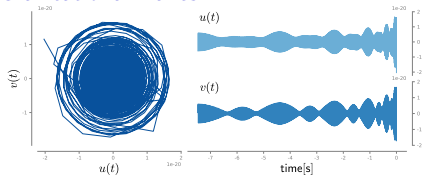
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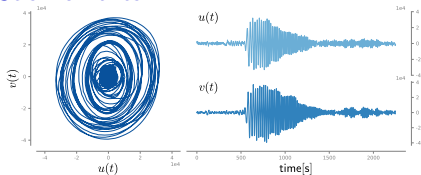


Properness/Circularity

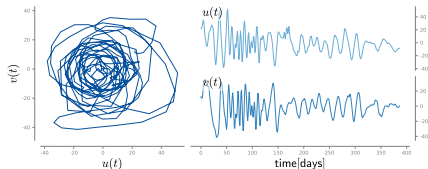
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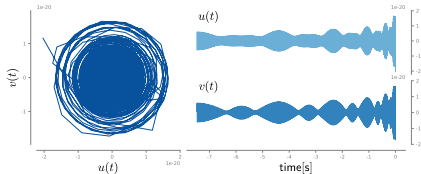
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Improperness testing

- GRLT:
Olila et al. [2004],
Schreier et al. [2006],
- Asymptotics:
Delmas et al. [2011],
- Frequency domain:
Walden et al. [2017].

Assumptions

- Complex vector $\mathbf{z} \in \mathbb{C}^N \leftrightarrow N$ -samples of \mathbb{C} -valued signal,
- Vectors/Signals are centered, *i.e.* $\mathbb{E}[\mathbf{z}] = 0$,
- Gaussian case,
- Sample size: M (number of independent observed signals),
- $M \geq 2N$ (sample covariance is not rank deficient).

Context & Applications

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Applications[†]

- Symmetry deciphering (noise vs. signal),
- Low-rank improper signal in proper noise,
- Fluorescence imaging in complex media (Phase retrieval).

[†]: see "Statistical Signal Processing of Complex-Valued data. The theory of improper and noncircular signals" by Schreier P. and Scharff, L.L., Cambridge Univ. Press, 2010.

Improprieness testing

Canonical Correlation distribution

Generalized Likelihood Ratio Test

Roy's test

Spiked model/Phase transition

Simulations

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Representation of $\mathbf{z} \in \mathbb{C}^N$

Real representation

N -dimensional complex-valued Gaussian vector $\mathbf{z} = \mathbf{u} + \mathbf{i}\mathbf{v} \in \mathbb{C}^N$ with $\mathbf{u}, \mathbf{v} \in \mathbb{R}^N$ and $\mathbf{i}^2 = -1$ can be represented as:

$$\mathbf{x} = [\mathbf{u}^T, \mathbf{v}^T]^T \in \mathbb{R}^{2N}$$

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Statistics

Second-order statistics of \mathbf{z} consists of the *real covariance matrix* $\mathbf{C} \in \mathbb{R}^{2N \times 2N}$ of \mathbf{x} given by:

$$\mathbf{C} = \mathbb{E}[\mathbf{x}\mathbf{x}^T] = \begin{pmatrix} \mathbf{C}_{\mathbf{u}\mathbf{u}}, & \mathbf{C}_{\mathbf{u}\mathbf{v}} \\ \mathbf{C}_{\mathbf{v}\mathbf{u}}, & \mathbf{C}_{\mathbf{v}\mathbf{v}} \end{pmatrix}$$

with $\mathbf{C}_{\mathbf{ab}} = \mathbb{E}[\mathbf{a}\mathbf{b}^T] \in \mathbb{R}^{N \times N}$ for $\mathbf{a}, \mathbf{b} \in \mathbb{R}^N$.

Properness/Improperness

Definition

The complex vector $\mathbf{z} \in \mathbb{C}^N$ is called *proper*[†] iff:

$$\mathbf{C}_{\mathbf{u}\mathbf{u}} = \mathbf{C}_{\mathbf{v}\mathbf{v}} \quad \text{and} \quad \mathbf{C}_{\mathbf{u}\mathbf{v}}^T = -\mathbf{C}_{\mathbf{u}\mathbf{v}} \quad (1)$$

or *improper* otherwise.

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Testing problem

$$\begin{cases} H_0 : \mathbf{z} \text{ is proper if condition (1) holds} \\ H_1 : \mathbf{z} \text{ is improper otherwise} \end{cases}$$

Invariant Parameters I

Definition

Let \mathcal{G} be the set of non-singular matrices $\mathbf{G} \in \mathbb{R}^{2N \times 2N}$ s.t.

$$\mathbf{G} = \begin{pmatrix} \mathbf{G}_1 & -\mathbf{G}_2 \\ \mathbf{G}_2 & \mathbf{G}_1 \end{pmatrix}, \quad \text{where} \quad \mathbf{G}_1, \mathbf{G}_2 \in \mathbb{R}^{N \times N}$$

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Properties

- Null hypothesis H_0 is equivalent to $\mathbf{C} \in \mathcal{T} = \mathcal{S} \cap \mathcal{G}$.
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 \Rightarrow Parameters to be tested should be the same for \mathbf{C} and $\mathbf{G}\mathbf{C}\mathbf{G}^T$ for any
 $\mathbf{G} \in \mathcal{G}$

Invariant Parameters II

Definition

Consider the real symmetric $2N \times 2N$ matrix:

$$\Gamma(\mathbf{C}) = \dot{\mathbf{C}}^{-\frac{1}{2}} \ddot{\mathbf{C}} \dot{\mathbf{C}}^{-\frac{1}{2}}.$$

with $\mathbf{C} = \dot{\mathbf{C}} + \ddot{\mathbf{C}}$ and

$$\begin{aligned}\dot{\mathbf{C}} &= \frac{1}{2} \begin{pmatrix} \mathbf{C}_{uu} + \mathbf{C}_{vv} & \mathbf{C}_{uv} - \mathbf{C}_{vu} \\ \mathbf{C}_{vu} - \mathbf{C}_{uv} & \mathbf{C}_{uu} + \mathbf{C}_{vv} \end{pmatrix} \in \mathcal{G}, \\ \ddot{\mathbf{C}} &= \frac{1}{2} \begin{pmatrix} \mathbf{C}_{uu} - \mathbf{C}_{vv} & \mathbf{C}_{uv} + \mathbf{C}_{vu} \\ \mathbf{C}_{uv} + \mathbf{C}_{vu} & \mathbf{C}_{vv} - \mathbf{C}_{uu} \end{pmatrix}.\end{aligned}$$

Invariant Parameters III

Lemma (Invariant parameters (Andersson 1975))

Any matrix $\mathbf{C} \in \mathcal{S}$ can be written as:

$$\mathbf{C} = \mathbf{G} \begin{pmatrix} \mathbf{I}_N + \mathbf{D}_\lambda & 0 \\ 0 & \mathbf{I}_N - \mathbf{D}_\lambda \end{pmatrix} \mathbf{G}^T,$$

where

- $\mathbf{G} \in \mathcal{G}$,
- $\mathbf{D}_\lambda = \text{diag}(\lambda_1, \dots, \lambda_N)$,
- λ_n : non-negative eigenvalues of $\mathbf{\Gamma}(\mathbf{C})$.
- $\lambda_n \in [0, 1]$ and ordering: $1 \geq \lambda_1 \geq \dots \geq \lambda_N \geq 0$.

Back to the improperness test

Invariant parametrization

- Invariant parameterization of \mathbf{C} for the group action of \mathcal{G} depends only on the N (non-negative) eigenvalues $1 \geq \lambda_1 \geq \dots \geq \lambda_N \geq 0$ of $\mathbf{\Gamma}(\mathbf{C})$.
- Eigenvalues λ_n are termed *maximal invariant parameters* or **population canonical correlation coefficients**.
- Under the null hypothesis H_0 : \ddot{C} reduces to the zero matrix.

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Test reformulation

The **invariant** properness testing problem is thus:

$$\begin{cases} H_0 : \mathbf{z} \text{ is } \textit{proper} \text{ if } \lambda_1 = 0 \\ H_1 : \mathbf{z} \text{ is } \textit{improper} \text{ otherwise} \end{cases} \quad (2)$$

Dataset

Consider we are given a sample of size $M \geq 2N$, denoted $\{\mathbf{x}_m\}_{m=1}^M$ where $\mathbf{x}_m = [\mathbf{u}_m^T, \mathbf{v}_m^T]^T$ are $2N$ -dimensional i.i.d. Gaussian real vectors with zero mean and covariance matrix \mathbf{C} .

Invariant statistics

Dataset

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Sample canonical correlation coefficients

The **sample covariance matrix** $\mathbf{S} \in \mathbb{R}^{2N \times 2N}$ is:

$$\mathbf{S} = \frac{1}{M} \sum_{m=1}^M \mathbf{x}_m \mathbf{x}_m^T = \begin{pmatrix} \mathbf{S}_{\mathbf{u}\mathbf{u}}, & \mathbf{S}_{\mathbf{u}\mathbf{v}} \\ \mathbf{S}_{\mathbf{v}\mathbf{u}}, & \mathbf{S}_{\mathbf{v}\mathbf{v}} \end{pmatrix} = \dot{\mathbf{S}} + \ddot{\mathbf{S}}$$

\Rightarrow Invariant statistics depend on the N non-negative eigenvalues of $\Gamma(\mathbf{S})$, denoted l_n

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Sample canonical correlation coefficients $r_n = l_n^2$

Improperness testing

Canonical Correlation distribution

Generalized Likelihood Ratio Test

Roy's test

Spiked model/Phase transition

Simulations

Canonical correlation distribution I

Limiting marginal empirical distribution under H_0

As $M, N \rightarrow \infty$ with the ratio $M/N \rightarrow \gamma \in [2, +\infty)$ being finite, the marginal empirical distribution of the (unsorted) r_n converges, under H_0 , to the probability measure with density:

$$f(r) = \frac{1}{2\pi(1-r)} \sqrt{4(\gamma-1)\frac{1-r}{r} - (\gamma-2)^2}$$

on its support $r \in (0, c)$, with $c = \frac{4(\gamma-1)}{\gamma^2} \in (0, 1]$.

PS: Joint distribution of vector (r_1, \dots, r_N) known (eigenvalues of matrix-variate beta) but no closed-form.

Canonical correlation distribution II

Moments

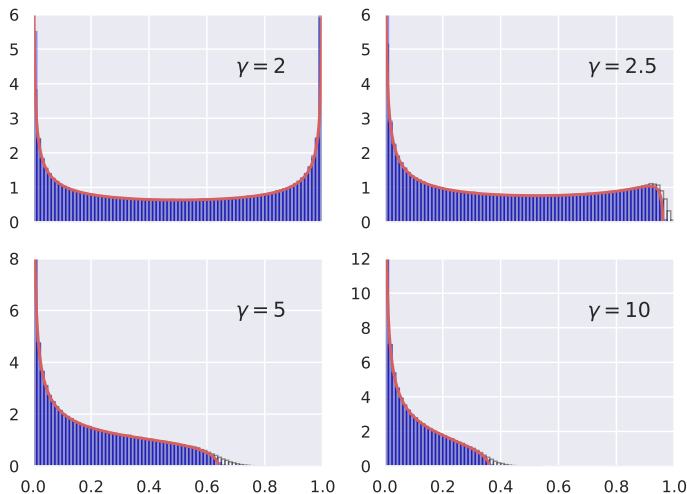
Under H_0 , mean and variance of the limiting distribution of the unsorted r_n are:

- $E[r_n] = 1/\gamma$,
- $\text{var}(r_n) = (\gamma - 1)/\gamma^3$.

Remarks

- When $\gamma \rightarrow +\infty$, $r_n \xrightarrow{a.s.} 0$ (usual behavior in small dimension, i.e. fixed N and $M \rightarrow +\infty$)
- When $\gamma = 2$, $r_n \xrightarrow{d} \mathcal{B}(\frac{1}{2}, \frac{1}{2})$ (arcsine law)

H_0 : Limiting empirical distribution of r_n



Blue: $N = 100$, White: $N = 10$, Red: Limiting distribution $f(r)$.

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Generalized Likelihood Test I

GLRT

Given the sample $\mathbf{X} = \{\mathbf{x}_m\}_{m=1}^M$, the GLRT statistic is defined as:

$$T \propto \frac{\sup_{\mathbf{C} \text{ s.t. } H_0} p(\mathbf{X}; \mathbf{C})}{\sup_{\mathbf{C} \text{ s.t. } H_1} p(\mathbf{X}; \mathbf{C})},$$

where $p(\mathbf{X}; \mathbf{C})$ is the multivariate normal pdf of the sample \mathbf{X} composed of M i.i.d. $2N$ -dimensional real Gaussian vectors with zero mean and covariance matrix \mathbf{C} .

$\hookrightarrow H_0$ is rejected if $T > \eta_\alpha$ $\eta_\alpha : H_0 \text{ law} + PFA$

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GLRT Statistics

$$T = \prod_{n=1}^N (1 - r_n)$$

with r_n the N sample covariance correlation coefficients.

Generalized Likelihood Test II

Theorem

The GLRT statistics T is distributed under H_0 as the following *Wilks lambda distribution*:

$$T \sim \Lambda(N, M - N, N + 1).$$

Moreover this statistics can be expressed under H_0 as:

$$T = \prod_{n=1}^N u_n,$$

where the u_n are independent beta-distributed random variables[†] such that $u_n \sim \mathcal{B}\left(\frac{M-N-n+1}{2}, \frac{N+1}{2}\right)$, for $1 \leq n \leq N$.

[†]: Allows efficient sampling ($O(N)$) from the null hypothesis of T .

Generalized Likelihood Test III

Theorem (Central limit theorem in high dimension)

Let $T' = -\ln T$ where T is the GLRT statistic. Assume that $M, N \rightarrow \infty$ so that the ratio $M/N \rightarrow \gamma \in (2, +\infty)$. Under H_0 , the following asymptotic normal distribution is obtained for T' :

$$\frac{1}{s} (T' - m) \xrightarrow{d} \mathcal{N}(0, 1)$$

where:

- $m = M \left[\ln \frac{\gamma}{\gamma-1} + \frac{\gamma-2}{\gamma} \ln \frac{\gamma-2}{\gamma-1} \right] + \frac{1}{2} \ln \frac{\gamma}{\gamma-2}$,
- $s^2 = 2 \left[\ln \frac{(\gamma-1)^2}{\gamma(\gamma-2)} + \frac{1}{M} \frac{1}{\gamma-2} \right]$.

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- $s^2 = 2 \left[\ln \frac{(\gamma-1)^2}{\gamma(\gamma-2)} + \frac{1}{M} \frac{1}{\gamma-2} \right]$.

Remark

This CLT theorem provides a **debiased** version of the *low dimensional* Bartlett approximation (N fixed, $M \rightarrow \infty$).

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Roy's test

Principle

This test relies on the statistics of the largest eigenvalue: here, the statistics of the largest squared canonical correlation $r_1 = l_1^2$.

\Rightarrow reject H_0 as soon as $r_1 > \eta_\alpha$

Threshold η_α tuned according to the law of r_1 under H_0 and PFA α .

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Theorem (Limiting null distribution for Roy's test)

As $M, N \rightarrow \infty$ such that the ratio $M/N \rightarrow \gamma \in [2, +\infty)$ is finite, let $W = \log(r_1/(1 - r_1))$ be the logit transform of r_1 . Under H_0 , the asymptotic law of W converges towards a first order Tracy-Widom law denoted as \mathcal{TW}_1 :

$$\frac{W - \mu}{\sigma} \rightarrow \mathcal{TW}_1,$$

with appropriate/tedious parameters $\mu(M, N)$ and $\sigma(M, N)$.

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Spiked correlation model

Phase transition threshold

Recalling that $\gamma = M/N$, assume that $\lambda_1 \geq \dots \geq \lambda_k > 0$, and $\lambda_{k+1} = \dots = \lambda_N = 0$ (fixed k), then for $1 \leq n \leq k$:

$$\begin{aligned} \text{if } \lambda_n^2 \leq \rho_c, \quad & r_n \xrightarrow{\text{a.s.}} c \\ \text{if } \lambda_n^2 > \rho_c, \quad & r_n \xrightarrow{\text{a.s.}} \bar{\rho}_n \end{aligned}$$

- $\rho_c = \frac{1}{\gamma-1}$ is the phase transition threshold,
- $\bar{\rho}_n = \lambda_n^2 \left(\frac{\gamma-1}{\gamma} + \frac{1}{\gamma\lambda_n^2} \right)^2$ is the limiting value,
- c is the right edge of the H_0 bulk.

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Simulation Scenario I: Equi-correlated model

Equal canonical correlation coefficients

Real and imaginary part of z_m are:

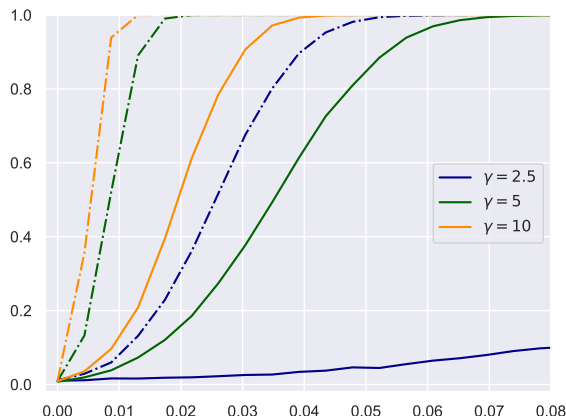
$$\mathbf{u}_m = \mathbf{s}_m + \sqrt{\theta} \mathbf{q}_m,$$

$$\mathbf{v}_m = \mathbf{t}_m + \sqrt{\theta} \mathbf{q}_m,$$

where $\theta > 0$, \mathbf{s}_m , \mathbf{t}_m and \mathbf{q}_m are i.i.d. Gaussian vectors in \mathbb{R}^N , for $1 \leq m \leq M$.

\Rightarrow Population canonical correlations $\lambda_1, \dots, \lambda_N$, are all equal to $\lambda \equiv \frac{\theta}{1+\theta}$.

Simulation Scenario I: Equi-correlated model



Power of Roy's test [solid line] and GLRT [dashdotted line] vs λ^2 under the **equi-correlated model** ($N=100$, PFA $\alpha = 0.01$).

Simulation Scenario II: Spiked model

Spike correlation model

Real and imaginary parts of z_m have a common contribution of rank one:
Low-rank improper signal corrupted by proper noise, for $1 \leq m \leq M$:

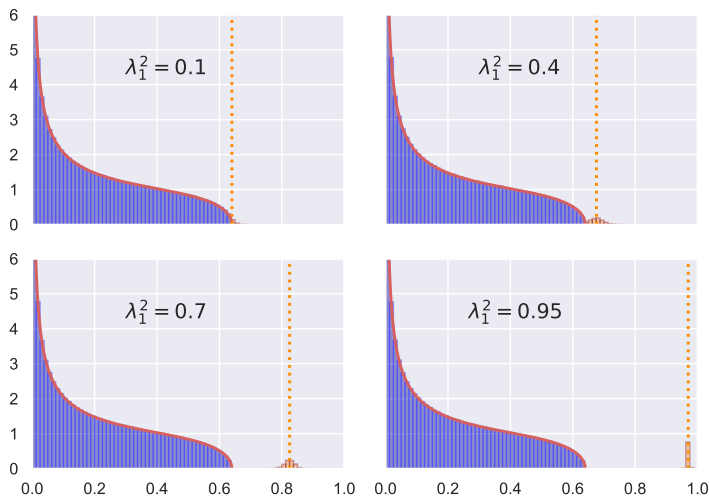
$$\mathbf{u}_m = \mathbf{s}_m + \sqrt{\theta} w_m \boldsymbol{\varphi}$$

$$\mathbf{v}_m = \mathbf{t}_m + \sqrt{\theta} w_m \boldsymbol{\varphi}$$

- $\theta > 0$, $\boldsymbol{\varphi} \in \mathbb{R}^N$ is a normed vector s.t. $\|\boldsymbol{\varphi}\|_2 = 1$,
- w_m are i.i.d. Gaussian centered random variables with unit variance,
- $\mathbf{s}_m, \mathbf{t}_m$ are Gaussian i.i.d. vectors in \mathbb{R}^N ,

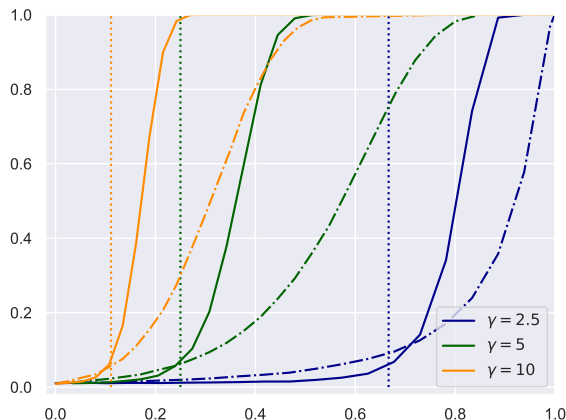
$$\implies \lambda_1 = \frac{\theta}{1+\theta} \text{ (spike)}, \lambda_2 = \dots = \lambda_N = 0.$$

Simulation Scenario II: Spiked model



Histograms of r_n under the spiked Gaussian model for different spike magnitude λ_1 . ($N = 100$, $\gamma = 5$ and $\rho_c = 0.25$.)

Simulation Scenario II: Spiked model



Power of Roy's test [solid line] and GLRT [dashdotted line] vs λ_1^2 under the spiked correlation model (($N=100$, PFA $\alpha = 0.01$)).

Concluding remarks

Results for $M, N \rightarrow \infty$ and finite ratio $M/N \rightarrow \gamma \in [2, +\infty)$

- Statistics/CLT for the GLRT,
- Statistics of the Roy's test,
- Spiked model and phase transition.

Future work

- Quaternion-valued vectors/signals
- Random/Structured approximation