

# 1 Variable arrangement

The *decision variables* are arranged in the following manner:

$$[u, v, w, \bar{w}, x_0, x, \bar{x}, y_0, y, \bar{y}, z]$$

The lengths of these depends on the the variables  $(i, j, l, r, s, t)$ . Here are the dependencies:

$$u \rightarrow l, r, s, t \quad (1)$$

$$v \rightarrow i, r, s, t \quad (2)$$

$$w, \bar{w} \rightarrow i, r \quad (3)$$

$$x_0 \rightarrow i, j, s, t \quad (4)$$

$$x, \bar{x} \rightarrow i, j, r, s, t \quad (5)$$

$$y_0 \rightarrow i, s, t \quad (6)$$

$$y, \bar{y} \rightarrow i, r, s, t \quad (7)$$

$$z \rightarrow i, r, s, t \quad (8)$$

$$d_0 \rightarrow l, t \quad (9)$$

$$d \rightarrow l, r, t \quad (10)$$

The total length of the coefficient array for the equations is  $(lrst + irst + 2ir + i jst + 2ijrst + ist + 2irst + irst)$ . Assuming the lengths of each as 3, we have  $(81 + 81 + 9 + 9 + 81 + 243 + 243 + 27 + 81 + 81 + 81 + 9 + 27) = 1053$  elements in the coefficient array. Depending on the numbers, this vector can be extremely large.

The decision variables will be arranged in the order of  $(i, j, l, r, s, t)$ . for  $u$  with 2 elements each  $(l, r, s, t)$ , it'll be

$$[u_{1,1}^1(1), u_{1,1}^2(1), u_{2,1}^1(1), u_{2,1}^2(1), u_{1,2}^1(1), u_{1,2}^2(1), u_{2,2}^1(1), u_{2,2}^2(1), \quad (11)$$

$$u_{1,1}^1(2), u_{1,1}^2(2), u_{2,1}^1(2), u_{2,1}^2(2), u_{1,2}^1(2), u_{1,2}^2(2), u_{2,2}^1(2), u_{2,2}^2(2),$$

$$v_{1,1}^1(1), v_{1,1}^2(1), v_{2,1}^1(1), v_{2,1}^2(1), v_{1,2}^1(1), v_{1,2}^2(1), v_{2,2}^1(1), v_{2,2}^2(1), \quad (12)$$

$$v_{1,1}^1(2), v_{1,1}^2(2), v_{2,1}^1(2), v_{2,1}^2(2), v_{1,2}^1(2), v_{1,2}^2(2), v_{2,2}^1(2), v_{2,2}^2(2),$$

$$w_1^1, w_1^2, w_2^1, w_2^2, \bar{w}_1^1, \dots]$$

A matlab function will resolve the position of each decision variable given the values  $(i, j, l, r, s, t)$  in the coefficient vector.

## 2 Example

Considering equation 10 from the original text:

$$y_{0,s}^i(1) = 0$$

The coefficient vector for the first equation  $y_{0,1}^1(1) = 0$  will look like:  $[000000...01000..00000]$  where the single 1 is the  $748^{th}$  position in the coefficient vector. The next iteration of eqn 10 is  $y_{0,1}^2(1) = 0$  which will look like  $[000000...00100..00000]$  while this time, the 1 is in  $749^{th}$  position in the vector (Considering all lengths are 3).

### 3 Summary

What exactly are we finding?

Reserve of the resources and what amount to be placed at which location.

#### 3.1 Locations

We have our first variable  $N$  which is the number of locations. each of these locations are called  $i$ . each  $i$  has a set of nearby location set called  $\varepsilon_i$ . We call each of nearby locations  $j$ .

Right now we know  $i, j, N, \varepsilon$  and we know what they are. in the example,  $N = 8$ . each  $\varepsilon_i$  is also 8. Moving on..

**Possible Conflict:** each  $i$  should be on  $\varepsilon_i$  list as first priority. But, there's the table where C, D has themselves listed lower than others. How is this possible. Also there are no A's

Next thing on list is  $p_{ij}$  which is preference score (ascending) of city  $j$  judging from city  $i$ .  $r_{ij}$  is response time / transfer time of resources from  $j$  to  $i$ .

This means,  $p_{ij}$  will determine the  $\varepsilon_i$ . we will deal with response time  $r_{ij}$  later.

**Concern:** if this  $\varepsilon_i$  is not the same list of cities for every city? If it is, then there is no need to call for additional  $j$ . If not, and it is variable, we need to write a subroutine to generate viable list of  $j$  for each  $i$ .

#### 3.2 Resources

There are few different types. each one of them needs specialist and other general members. In example there are 3 types. Theres a teeny tiny component of setup time for the resources too.

$R$  is the number of resource *types*. in example  $R = 3$ .  $\alpha_r, \beta_r$  are number of specialists and generalists required for each of type- $r$  equipment.  $s_r$  is the setup time for type- $r$  equipment. Obviously this should be independent of number of equipments.