

Lecture Notes I

- Simple Linear Regression -

June 25, 2016

1 Basic Structure of Simple Linear Regression Model

1.1 The description of the Population

Definition 1. The conditional expectation function $E(Y|X)$ is given by

$$E(Y|X) = \int_{-\infty}^{\infty} yp(y|x)dy \quad (1)$$

Theorem 1. We can describe the relationship between the dependent variable Y and the independent variable X as

$$Y = E(Y|X) + \epsilon \quad (2)$$

where

(1) ϵ is mean- independent ¹ of X , i.e., $E(\epsilon|X) = 0$

(2) ϵ is uncorrelated with any function of X

Proof. For (1),

$$E(\epsilon|X) = E(Y - E(Y|X)|X) = E(Y|X) - E(E(Y|X)|X) = E(Y|X) - E(Y|X) = 0 \quad (4)$$

For (2),

$$Cov(h(X), \epsilon) = E(h(X)\epsilon) = E(E(h(X)\epsilon|X)) = E(h(X)E(\epsilon|X)) = 0 \quad (5)$$

□

¹ A random variable Y is said to be mean independent of X if and only if

$$E(Y|X) = E(Y) \quad (3)$$

Theorem 2. Let $m(X)$ be any function of X . Then CEF is the best predictor of Y given X

$$E(Y|X) = \operatorname{argmin}_{m(X)} E(Y - m(X))^2 \quad (6)$$

Proof.

$$(Y - m(X))^2 = [(Y - E(Y|X)) + (E(Y|X) - m(X))]^2 \quad (7)$$

$$= (Y - E(Y|X))^2 + 2(Y - E(Y|X))(E(Y|X) - m(X)) + (E(Y|X) - m(X))^2$$

Since $E[2(Y - E(Y|X))(E(Y|X) - m(X))] = 0$ by Theorem 1, $E(Y - m(X))^2$ is minimized when $m(X) = E(Y|X)$ \square

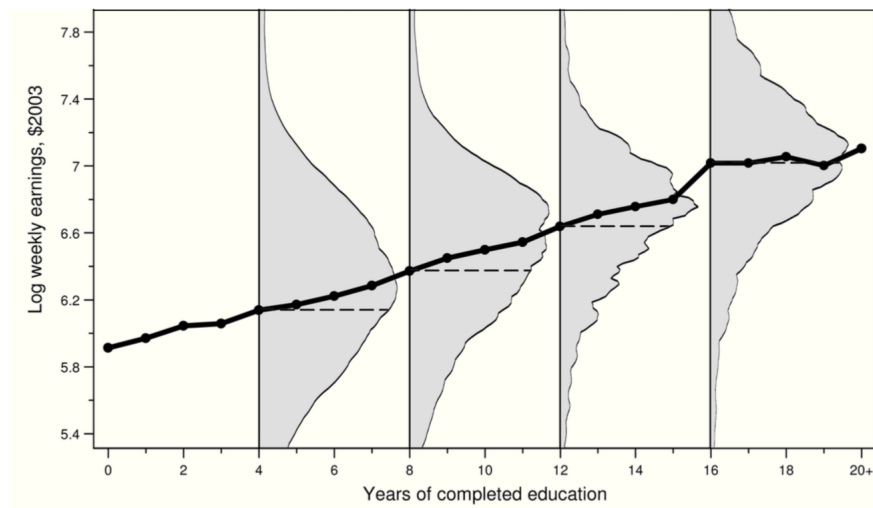


Figure 1: Conditional Expectation (Function)

1.2 Gauss-Markov Assumptions

$$A.1 \quad y = \beta_0 + \beta_1 x + \epsilon \quad (8)$$

$$A.2 \quad \sum_{i=1}^n (x_i - \bar{x})^2 \neq 0 \quad (9)$$

$$A.3 \quad E(\epsilon|x) = 0 \quad (10)$$

$$A.4 \quad Var(\epsilon|x) = \sigma^2, \quad Cov(\epsilon_i, \epsilon_j) = 0 \quad \forall i, j \quad (11)$$

A.1 and A.3 together imply that the *CEF* is linear, i.e., $E(Y|X) = \beta_0 + \beta_1 X$

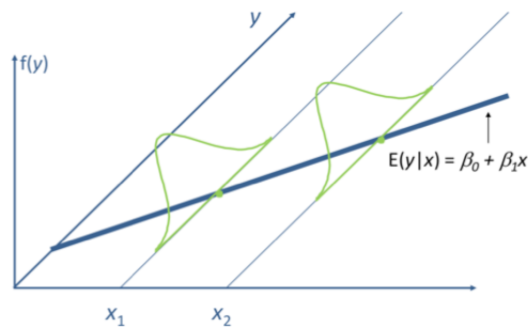


Figure 2: Gauss-Markov Assumptions

1.3 Sample

$$y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} \quad x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad (12)$$

1.4 Scatter Plot

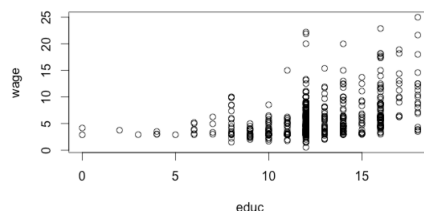


Figure 3: Scatter Plot

2 Point Estimation : Ordinary Least Square Method

2.1 Basic Idea

Definition 2. *Residual vector*

Let's assume that $\hat{\beta}$ is an estimator of β .

Then residual vector e is defined to be

$$e = y - \hat{y} = y - X\hat{\beta} \quad (13)$$

where

$$y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} \quad X = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix} \quad \hat{\beta} = \begin{pmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{pmatrix} \quad (14)$$

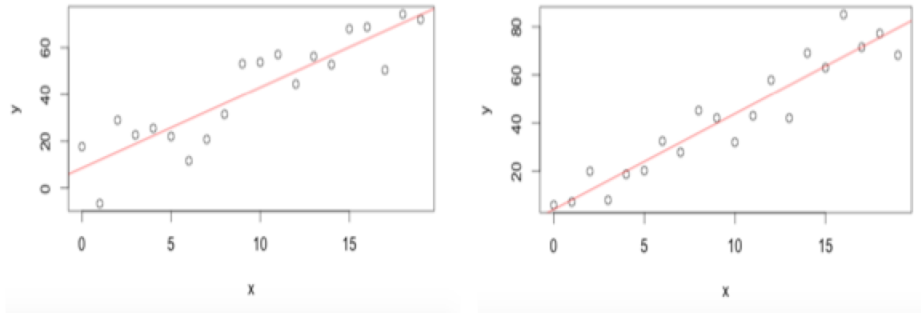


Figure 4: Ordinary Least Square Method

Definition 3. *Ordinary Least Square Estimator*

Ordinary Least Square Estimator $\hat{\beta}$ is the function from (y, X) to R^2 that minimize the sum of squares of residuals.

$$\hat{\beta} = \operatorname{argmin} \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i)^2 \quad (15)$$

2.2 The Derivation of OLS Estimator $\hat{\beta}_{OLS}$

$$\min \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i)^2 \quad (16)$$

F.O.C

$$\frac{\partial}{\partial \hat{\beta}_0} \sum_{i=1}^n e_i^2 = -2 \sum_{i=1}^n (y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i) = -2 \sum e_i = 0 \quad (17)$$

$$\frac{\partial}{\partial \hat{\beta}_1} \sum_{i=1}^n e_i^2 = -2 \sum_{i=1}^n x_i (y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i) = -2 \sum x_i e_i = 0 \quad (18)$$

By rearranging,

$$\bar{y} = \hat{\beta}_0 + \hat{\beta}_1 \bar{x} \quad (19)$$

$$\sum_{i=1}^n x_i y_i = \hat{\beta}_0 \sum_{i=1}^n x_i + \hat{\beta}_1 \sum_{i=1}^n x_i^2 \quad (20)$$

These equations are called the *Normal Equations*

From the Normal equations, OLS Estimator $\hat{\beta}_{OLS}$ can be deduced as follows

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2} = \frac{\sum_{i=1}^n (x_i - \bar{x})y_i}{\sum_{i=1}^n (x_i - \bar{x})^2} \quad (21)$$

$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x} \quad (22)$$

2.3 The Derivation of OLS Estimator $\hat{\beta}_{OLS}$ in matrix form

$$\min e'e = (y - X\hat{\beta})'(y - X\hat{\beta}) \quad (23)$$

$$\frac{\partial}{\partial \hat{\beta}} e'e = -2X'y + 2X'X\hat{\beta} = 0 \quad (24)$$

By rearranging,

$$\hat{\beta}_{OLS} = (X'X)^{-1}X'y \quad (25)$$

2.4 Geometric Interpretation of OLS Estimator $\hat{\beta}_{OLS}$

To find the OLS estimator is equal to find the projection of y on X

$$\hat{\beta} = \operatorname{argmin} \|e\|^2 = \operatorname{argmin} \|e\| \quad (26)$$

where $\|e\|$ is the norm of residual vector e

$$X'e = X'(y - X'\hat{\beta}) = 0 \quad (27)$$

By rearranging ,

$$X'X\hat{\beta} = X'y \quad (28)$$

$$\hat{\beta} = (X'X)^{-1}X'y \quad (29)$$

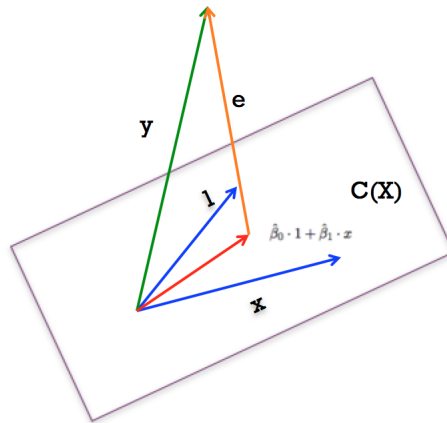


Figure 5: Projection of y on $C(X)$

2.5 The OLS Estimator as Sample Analog Estimator(or *MOM* Estimator)

In the population

$$E(\epsilon) = E(y - X\beta) = 0 \quad (30)$$

$$E(x\epsilon) = E[x(y - X\beta)] = 0 \quad (31)$$

The sample counterpart of the above equations are

$$\frac{1}{n}\sum e_i = \frac{1}{n}\sum (y_i - (X\hat{\beta})_i) = 0 \quad (32)$$

$$\frac{1}{n}\sum x_i e_i = \frac{1}{n}\sum x_i (y_i - (X\hat{\beta})_i) = 0 \quad (33)$$

or in matrix form

$$X'e = X'(y - X\hat{\beta}) = 0 \quad (34)$$

Thus, *OLS* estimator is a kind of sample analogue estimator (or *MOM* estimator)

3 The Properties of OLS Estimators, $\hat{\beta}_{OLS}$

3.1 Unbiasedness

Theorem 3. Under the Assumptions A.1 through A.3,

$$E(\hat{\beta}) = \beta \quad (35)$$

Proof.

$$\hat{\beta}_1 = \frac{\sum (x_i - \bar{x})y_i}{\sum (x_i - \bar{x})^2} = \frac{\sum (x_i - \bar{x})(\beta_0 + \beta_1 x_i + \epsilon_i)}{\sum (x_i - \bar{x})^2} = \beta_1 + \frac{\sum (x_i - \bar{x})\epsilon_i}{\sum (x_i - \bar{x})^2} \quad (36)$$

$$E(\hat{\beta}_1) = \beta_1 + \sum \frac{(x_i - \bar{x})}{\sum (x_i - \bar{x})^2} E(\epsilon_i) = \beta_1 \quad (37)$$

$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x} = (\beta_0 + \beta_1 \bar{x} + \bar{\epsilon}) - \hat{\beta}_1 \bar{x} = \beta_0 + (\beta_1 - \hat{\beta}_1) \bar{x} + \bar{\epsilon} \quad (38)$$

$$E(\hat{\beta}_0) = \beta_0 + (\beta_1 - E(\hat{\beta}_1)) \bar{x} + E(\bar{\epsilon}) = \beta_0 \quad (39)$$

□

3.2 Variances of the *OLS* Estimator

Theorem 4. Under the Assumption A.1 through A.4,

$$Var(\hat{\beta}_1) = \frac{\sigma^2}{\sum (x_i - \bar{x})^2} \quad (40)$$

Proof.

$$\hat{\beta}_1 - \beta_1 = \frac{\sum (x_i - \bar{x})\epsilon_i}{\sum (x_i - \bar{x})^2} \quad (41)$$

$$Var(\hat{\beta}_1) = E(\hat{\beta}_1 - \beta_1)^2 = E\left(\frac{\sum (x_i - \bar{x})\epsilon_i}{\sum (x_i - \bar{x})^2}\right)^2 = \frac{\sum (x_i - \bar{x})^2 Var(\epsilon_i)}{(\sum (x_i - \bar{x})^2)^2} = \frac{\sigma^2}{\sum (x_i - \bar{x})^2} \quad (42)$$

□

3.3 Gauss-Markov Theorem

Theorem 5. Under the Assumption A.1 through A.4, OLS estimators $\hat{\beta}$ are the Best Linear Unbiased Estimators (BLUEs) of β

Proof. The linear estimator of β_1 must take the form

$$\hat{\beta}_1 = \sum \omega_i y_i \quad (43)$$

For a linear estimator β_1 to be unbiased, the following conditions should be satisfied

$$\sum \omega_i = 0 \quad (44)$$

$$\sum \omega_i x_i = 1 \quad (45)$$

The variance of β_1 is equal to

$$Var(\hat{\beta}_1) = Var(\sum \omega_i y_i) = \sum \omega_i^2 Var(y_i) = \sigma_y^2 \sum \omega_i^2 \quad (46)$$

Now to find the best linear unbiased estimator means to find ω_i, \forall to minimize the variance of β_1 subject to the constraints (44) and (45) That is,

$$\min_{\omega_i} \sum \omega_i^2 \text{ s.t } \sum \omega_i = 0, \sum \omega_i x_i = 1 \quad (47)$$

Setting up the Lagrangian function,

$$L = \sum \omega_i^2 - \mu_1 \sum \omega_i - \mu_2 (\sum \omega_i \tilde{x}_i - 1) \quad (48)$$

where $\tilde{x}_i = x_i - \bar{x}$ The first conditions are as follows

$$\frac{\partial L}{\partial \omega_i} = 2\omega_i - \mu_1 - \mu_2 \tilde{x}_i = 0, \forall i \quad (49)$$

$$\frac{\partial L}{\partial \mu_1} = \sum \omega_i = 0 \quad (50)$$

$$\frac{\partial L}{\partial \mu_2} = \sum \omega_i \tilde{x}_i - 1 = 0 \quad (51)$$

The equation (49) implies

$$\omega_i = \frac{\mu_1}{2} + \frac{\mu_2 \tilde{x}_i}{2} \quad (52)$$

Substituting (52) into (50) yields

$$\mu_1 = 0 \quad (53)$$

thus

$$\omega_i = \frac{\mu_2 \tilde{x}_i}{2} \quad (54)$$

Substituting (54) into (51) yields

$$\mu_2 = \frac{2}{\sum \tilde{x}_i^2} \quad (55)$$

Finally, Substituting (53) and (55) into (52) yields

$$\omega_i = \frac{\tilde{x}_i}{\sum \tilde{x}_i^2} = \frac{x_i - \bar{x}}{\sum (x_i - \bar{x})^2} \quad \forall i \quad (56)$$

,which implies that $\hat{\beta}_{1OLS}$ is BLUE □

4 The Estimator of $\sigma^2, \hat{\sigma}^2$

Theorem 6. *Let's define $\hat{\sigma}^2$ as*

$$\hat{\sigma}^2 = \frac{\sum e_i^2}{n-2} \quad (57)$$

Then, under the Assumption A.1 through A.4,

$$E(\hat{\sigma}^2) = \sigma^2 \quad (58)$$

Proof.

$$\begin{aligned} e_i &= y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i) = (\beta_0 + \beta_1 x_i + \epsilon_i) - (\hat{\beta}_0 + \hat{\beta}_1 x_i) \\ &= (\beta_0 - \hat{\beta}_0) + (\beta_1 - \hat{\beta}_1) x_i + \epsilon_i \end{aligned} \quad (59)$$

From (16),

$$\begin{aligned} \sum e_i &= \sum [(\beta_0 - \hat{\beta}_0) + (\beta_1 - \hat{\beta}_1) x_i + \epsilon_i] \\ &= n(\beta_0 - \hat{\beta}_0) + (\beta_1 - \hat{\beta}_1) \sum x_i + \sum \epsilon_i = 0 \end{aligned} \quad (60)$$

Dividing both sides of (60) by n , then

$$\bar{\epsilon} + (\beta_0 - \hat{\beta}_0) + (\beta_1 - \hat{\beta}_1) \bar{x} = 0 \quad (61)$$

From (58) and (60),

$$e_i = (\beta_1 - \hat{\beta}_1)(x_i - \bar{x}) + (\epsilon_i - \bar{\epsilon}) \quad (62)$$

Thus,

$$\begin{aligned} \sum e_i^2 &= \sum (\epsilon_i - \bar{\epsilon})^2 + (\beta_1 - \hat{\beta}_1)^2 \sum (x_i - \bar{x})^2 + 2(\beta_1 - \hat{\beta}_1) \sum (\epsilon_i - \bar{\epsilon})(x_i - \bar{x}) \\ &= \sum (\epsilon_i - \bar{\epsilon})^2 - (\beta_1 - \hat{\beta}_1)^2 \sum (x_i - \bar{x})^2 \end{aligned} \quad (63)$$

And

$$E(\sum e_i^2) = (n-1)\sigma^2 - \sigma^2 = (n-2)\sigma^2 \quad (64)$$

$$\therefore E(\hat{\sigma}^2) = \sigma^2 \quad (65)$$

□

Definition 4. *The standard error of $\hat{\beta}_1$ is defined as*

$$se(\hat{\beta}_1) = \frac{\hat{\sigma}}{\sqrt{\sum (x_i - \bar{x})^2}} \quad (66)$$

5 Goodness-of-Fit

5.1 The decomposition of SST

Definition 5. *Total Sum of Squares(SST), Explained Sum of Squares(SSE) and Residual Sum of Squares(SSR) are defined as*

$$SST \equiv \sum (y_i - \bar{y})^2 \quad (67)$$

$$SSE \equiv \sum (\hat{y}_i - \bar{y})^2 \quad (68)$$

$$SSR \equiv \sum (y_i - \hat{y}_i)^2 \quad (69)$$

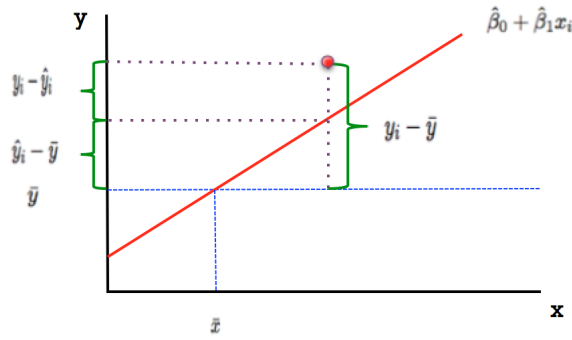


Figure 6: SST,SSE and SSR

Theorem 7. *SST can be decomposed into SSE and SSR , that is,*

$$SST = SSE + SSR \quad (70)$$

Proof.

$$\begin{aligned} \sum (y_i - \bar{y})^2 &= \sum [(y_i - \hat{y}_i) + (\hat{y}_i - \bar{y})]^2 \\ &= \sum (y_i - \hat{y}_i)^2 + \sum (\hat{y}_i - \bar{y})^2 + 2 \sum (y_i - \hat{y}_i)(\hat{y}_i - \bar{y}) \end{aligned} \quad (71)$$

Since

$$\sum (y_i - \hat{y}_i)(\hat{y}_i - \bar{y}) = 0, \quad (72)$$

$$SST = SSE + SSR \quad (73)$$

□

5.2 The coefficient of Determination R^2

Definition 6. The coefficient of determination R^2 is defined as

$$R^2 \equiv \frac{SSE}{SST} = 1 - \frac{SSR}{SST} \quad (74)$$

R^2 is an estimator for the population R-squared given by ²

$$1 - \frac{\sigma_\epsilon^2}{\sigma_y^2} \quad (78)$$

R^2 is an measure of how well the least squares equation

$$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x \quad (79)$$

performs as a predictor of y

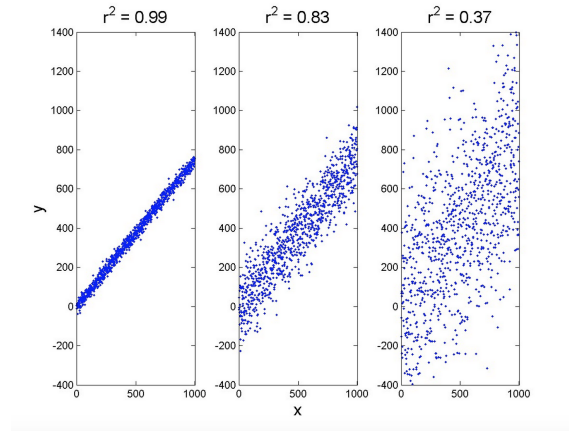


Figure 7: The coefficient of Determination

²The population R-squared can be deduced as follows.
By decomposition of variance,

$$Var(Y) = E_X(Var(Y|X)) + Var_X(E(Y|X)) \quad (75)$$

Dividing both sides of the equation by $Var(Y)$ and rearranging, we get

$$\frac{Var_X(E(Y|X))}{Var(Y)} = 1 - \frac{E_X(Var(Y|X))}{Var(Y)} \quad (76)$$

Since $Var(Y|X) = \sigma_\epsilon^2$,

$$\frac{Var_X(E(Y|X))}{Var(Y)} = 1 - \frac{\sigma_\epsilon^2}{\sigma_y^2} \quad (77)$$

5.3 The relationship between the coefficient of determination R^2 and the sample correlation coefficient ρ_{xy} in the simple regression model

Theorem 8. *In the simple regression model, the coefficient of determination R^2 is equal to the square of sample correlation coefficient between y and x . That is,*

$$R^2 = \rho_{xy}^2 \quad (80)$$

Proof.

$$R^2 = \frac{\sum(\hat{y}_i - \bar{y})^2}{\sum(y_i - \bar{y})^2} \quad (81)$$

Since

$$\hat{y}_i - \bar{y} = (\hat{\beta}_0 + \hat{\beta}_1 x_i) - (\hat{\beta}_0 + \hat{\beta}_1 \bar{x}) = \hat{\beta}_1(x_i - \bar{x}) \quad (82)$$

and

$$\hat{\beta}_1 = \frac{\sum(x_i - \bar{x})(y_i - \bar{y})}{\sum(x_i - \bar{x})^2} \quad (83)$$

we can rewrite R^2 as

$$R^2 = \hat{\beta}_1^2 \frac{\sum(x_i - \bar{x})^2}{\sum(y_i - \bar{y})^2} = \frac{(\sum(x_i - \bar{x})(y_i - \bar{y}))^2}{\sum(x_i - \bar{x})^2 \sum(y_i - \bar{y})^2} \quad (84)$$

Thus

$$R^2 = \rho_{xy}^2 \quad (85)$$

□

6 Regression through the Origin

Suppose

$$y_i = \beta_1 x_i + \epsilon_i \quad (86)$$

In this case, the *OLS* estimator $\hat{\beta}_1^*$ of β_1 is³

$$\hat{\beta}_1^* = \frac{\sum x_i y_i}{\sum x_i^2} \quad (89)$$

³ $\hat{\beta}_1^*$ can be derived by the following procedure

$$\min \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i)^2 \quad (87)$$

$$\frac{d}{d\hat{\beta}_1} (\sum e_i^2) = -2 \sum (y_i - \hat{\beta}_1 x_i) = 0 \quad (88)$$

Unless $\bar{x} = 0$, $\hat{\beta}_1^*$ is different from $\hat{\beta}_1$

$$\hat{\beta}_1^* = \frac{\sum x_i y_i}{\sum x_i^2} \neq \frac{\sum (x_i - \bar{x}) y_i}{\sum (x_i - \bar{x})^2} = \hat{\beta}_1 \quad (90)$$

If $\beta_0 \neq 0$, then $\hat{\beta}_1^*$ is not unbiased.

$$\hat{\beta}_1^* = \frac{\sum x_i (\beta_0 + \beta_1 x_i + \epsilon_i)}{\sum x_i^2} = \frac{\sum x_i}{\sum x_i^2} \beta_0 + \beta_1 + \frac{\sum x_i}{\sum x_i^2} \epsilon_i \quad (91)$$

$$E(\hat{\beta}_1^*) = \frac{\sum x_i}{\sum x_i^2} \beta_0 + \beta_1 + \frac{\sum x_i}{\sum x_i^2} E(\epsilon_i) = \frac{\sum x_i}{\sum x_i^2} \beta_0 + \beta_1 \neq \beta_1 \quad (92)$$