```
# Host fitness for slow social information dynamics #
      restart:
     with (VectorCalculus):
\triangleright with (LinearAlgebra):
    interface(imaginaryunit = I):
> # Mutant dynamics
\triangleright Nm := SUm + SAm + IUm + IAm :
 > dSUm := (b - q \cdot N) \cdot Nm - \frac{cm \cdot c \cdot SUm}{N} \cdot (beta \cdot (IU + IA) + tau \cdot (SA + IA)) - d \cdot SUm
            + \operatorname{gamma} \cdot IUm + \operatorname{sigma} \cdot SAm :
 > dSAm := \frac{cm \cdot c}{N} \cdot (\tan \cdot SUm \cdot (SA + IA) - \cot \cdot SAm \cdot (IU + IA)) - a \cdot d \cdot SAm + \operatorname{gamma} \cdot IAm
            -\operatorname{sigma} \cdot SAm:
 | > dIUm := \frac{cm \cdot c}{N} \cdot (\text{beta} \cdot SUm \cdot (IU + IA) - \text{tau} \cdot IUm \cdot (SA + IA)) - (d + \text{alpha} + \text{gamma}) \cdot IUm 
            + sigma·IAm:
> dIAm := \frac{cm \cdot c}{N} \cdot (\text{beta} \cdot SAm \cdot (IU + IA) + \text{tau} \cdot IUm \cdot (SA + IA)) - (a \cdot d + \text{alpha} + \text{gamma})
            + sigma) \cdot IAm:
=
> # Calculate the Jacobian
 J := (Jacobian([dSUm, dSAm, dIUm, dIAm], [SUm, SAm, IUm, IAm]));
 J := \left[ \left[ -q N + b - \frac{cm c \left( \beta \left( IU + IA \right) + \tau \left( SA + IA \right) \right)}{N} - d, -q N + b + \sigma, -q N + b \right] \right]
                                                                                                                                          (1)
       + \gamma, -q N + b
       \left[\frac{cm c \tau (SA + IA)}{N}, -\frac{cm c \beta (IU + IA)}{N} - a d - \sigma, 0, \gamma\right],
       \left[\frac{cm\ c\ \beta\ (IU+IA)}{N},\,0,\,-\frac{cm\ c\ \tau\ (SA+IA)}{N}-d-\alpha-\gamma,\,\sigma\right]
       \left[0, \frac{cm \ c \ \beta \ (IU + IA)}{N}, \frac{cm \ c \ \tau \ (SA + IA)}{N}, -a \ d - \alpha - \gamma - \sigma\right]
    # Split the Jacobian into components F and V as follows
     F := \langle \langle b - q \cdot N, 0, 0, 0 \rangle | \langle b - q \cdot N, 0, 0, 0 \rangle | \langle b - q \cdot N, 0, 0, 0, 0 \rangle | \langle b - q \cdot N, 0, 0, 0, 0 \rangle \rangle;
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$$V := F - J;$$

$$V := \left[\left[\frac{cm c \left(\beta \left(IU + IA \right) + \tau \left(SA + IA \right) \right)}{N} + d, -\sigma, -\gamma, 0 \right],$$

$$\left[-\frac{cm c \tau \left(SA + IA \right)}{N}, \frac{cm c \beta \left(IU + IA \right)}{N} + a d + \sigma, 0, -\gamma \right],$$

$$\left[-\frac{cm c \beta \left(IU + IA \right)}{N}, 0, \frac{cm c \tau \left(SA + IA \right)}{N} + d + \alpha + \gamma, -\sigma \right],$$

$$\left[0, -\frac{cm c \beta \left(IU + IA \right)}{N}, -\frac{cm c \tau \left(SA + IA \right)}{N}, a d + \alpha + \gamma + \sigma \right] \right]$$

- # Now calculate the next-generation matrix
- V1 := MatrixInverse(V):
- $NG := simplify(F \cdot VI)$:
- # Fitness is equal to the largest eigenvalue of the NG matrix minus 1
- > w := simplify(NG[1, 1]) 1;

$$w := -\left(\left((ad + \sigma) (d + \alpha + \gamma) (ad + \alpha + \gamma + \sigma) N^{3} + cm c \left((a + 1) (\beta (IU + IA) + \tau (SA + IA)) a d^{2} + \left(2 (\alpha + \gamma + \sigma) a + \frac{\alpha}{2} + \frac{\sigma}{2}\right) (IU + IA) \beta + 2 (\alpha + \gamma + \frac{\sigma}{2}) a + \frac{\alpha}{2} + \frac{\gamma}{2} + \frac{\sigma}{2}) (SA + IA) \tau d + (\alpha^{2} + (\gamma + 2\sigma) \alpha + 2\gamma\sigma + \sigma^{2}) (IU + IA) \beta + \tau (SA + IA) (\alpha + \gamma) (\alpha + \gamma + 2\sigma) N^{2} + cm^{2} (\alpha (IU + IA)^{2} \beta^{2} + 2 (SA + IA) (a + \frac{1}{2}) \tau (IU + IA) \beta + \tau^{2} a (SA + IA)^{2} d + (IU + IA)^{2} (\alpha + \sigma) \beta^{2} + 2 \tau (SA + IA) (IU + IA) (\alpha + \gamma + \sigma) \beta + \tau^{2} (SA + IA)^{2} (\alpha + \gamma) c^{2} N + \beta (\beta (IU + IA) + \tau (SA + IA)) (SA + IA) \tau c^{3} (IU + IA) cm^{3} (qN - b) \right) / (\beta (\beta (IU + IA) + \tau (SA + IA)) (SA + IA) \tau (ad + \alpha) c^{3} (IU + IA) cm^{3})$$

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+ N \left( a \left( \left( IU + IA \right)^2 \beta^2 + \tau \left( SA + IA \right) \left( IU + IA \right) \left( a + 2 \right) \beta + \tau^2 a \left( SA + IA \right)^2 \right) d^2
                                       +\left(\left(IU+IA\right)^{2}\left(a\alpha+\alpha+\sigma\right)\beta^{2}+2\left(SA+IA\right)\left(\left(\alpha+\gamma+\frac{\sigma}{2}\right)a+\alpha+\frac{\sigma}{2}\right)\tau\left(IU\right)
                                       +IA)\beta + \tau^{2}a(SA + IA)^{2}(\alpha + \gamma)d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma))d + \beta((IU + IA)(\alpha + \sigma)\beta + \tau(SA + IA)(\alpha + \sigma)\beta + \tau(SA
                                       +\gamma + 2\sigma) \alpha (IU + IA) c^2 cm^2 + N^2 \left(2\left(\frac{(IU + IA)(a+1)\beta}{2} + \tau a(SA)\right)\right)
                                       +IA) a d^3 + ((\alpha a^2 + (2\alpha + 2\gamma + 2\sigma) a + \alpha + \sigma) (IU + IA) \beta + (SA)
                                        +IA) \tau a ((\alpha + \gamma) a + 2 \alpha + 2 \gamma + 2 \sigma)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2 + (\gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2) + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2) + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2) + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2) + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2) + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2) + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + \gamma + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2 \sigma) a + \alpha^2)) d^2 + ((\alpha (\alpha + 2
                                        (IU + IA)\beta + (SA + IA)(\alpha + \gamma)\tau((\alpha + \gamma + \sigma)a + \sigma)d
                                        +\beta\alpha\sigma(IU+IA)(\alpha+\gamma+\sigma) ccm+N^3d(ad+\sigma)(d+\alpha+\gamma)(ad+\alpha+\gamma)
                                       +\sigma))-1
                               # Calculate the fitness gradient (output hidden for brevity)
                                dw := simplify(subs(cm = c, diff(w, cm))):
                               # Calculate evolutionary stability (output hidden for brevity)
                               E := simplify(subs(cm = c, diff(w, cm, cm))):
                               \# Special case - 1) R0 I < 1
| > dw1 := simplify(subs(\{SA = 0, IA = 0, N = SU + IU\}, dw));
dw1 := -\frac{(SU + IU)\beta\alpha IU(d + \alpha + \gamma)(-q IU - q SU + b)c}{((d^2 + (\beta c^2 + \alpha + \gamma)d + c^2\beta\alpha)IU + d SU(d + \alpha + \gamma))^2}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   (5)
                             # Intuitively if R0 D>1 and alpha>0, this is always negative (since b > q \cdot N)
                              # Special case - 2) R0 D < 1
                       dw1 := simplify(subs(\{IU = 0, IA = 0, N = SU + SA\}, dw));
                                                                                      dw1 := -\frac{c \left(-q SA - q SU + b\right) \left(a d + \sigma\right) \tau \left(a - 1\right) SA \left(SU + SA\right)}{d \left(\left(c^2 \tau + d\right) a + \sigma\right) SA + SU \left(a d + \sigma\right)\right)^2}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   (6)
                               # Intuitively if R0 I > 1 and a < 1, this is always positive (since b > q \cdot N)
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# Host fitness for approximation to fast social information dynamics #
              restart :
 with (VectorCalculus)with (LinearAlgebra):
          with (VectorCalculus):
interface(imaginaryunit = I):

| The imaginary interface interface imaginary interface interface imaginary interface inte
   A := 1 - \frac{\text{sigma}}{\text{tau} \cdot c \cdot c}
 \Rightarrow dSAm := \frac{cm \cdot c}{N} \cdot (\tan \cdot SUm \cdot A \cdot N) - \text{sigma} \cdot SAm :
 \rightarrow dIAm := \frac{cm \cdot c}{N} \cdot (\tan \cdot IUm \cdot A \cdot N) - \text{sigma} \cdot IAm :
   > dAm := \frac{1}{Nm} \cdot \left( \frac{cm \cdot c}{N} \cdot (\tan \cdot (1 - Am) \cdot Nm \cdot A \cdot N) - \operatorname{sigma} \cdot Am \cdot Nm \right) : 
  \rightarrow Ams := solve(dAm, Am);
                                                                                                 Ams := \frac{cm (\tau c^2 - \sigma)}{c^2 cm \tau + \sigma c - cm \sigma}
                                                                                                                                                                                                                                                                                                          (1)
> | Now calculate resident equilibrium
   > dS := (b - q \cdot (S + I)) \cdot (S + I) - \frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S + I)} - d \cdot (1 - (1 - a) \cdot A) \cdot S + \text{gamma} \cdot I:
  > dI := \frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S+I)} - (d \cdot (1-(1-a) \cdot A) + \text{alpha} + \text{gamma}) \cdot I:
 \triangleright dN := (b - q \cdot N) \cdot N - d \cdot (1 - (1 - a) \cdot A) \cdot N - \text{alpha} \cdot I:
  \gt{sol} := solve([dS, dI], [S, I]):
\triangleright eql := simplify(sol[2]):
  \triangleright Ns := simplify(subs(eql, S + I));
                                                                                                                                                                                                                                                                                                          (2)
                 \frac{-\tau \beta (a d + \alpha - b) c^{4} + (\alpha (a d + \alpha + \gamma) \tau + \sigma d \beta (-1 + a)) c^{2} - \sigma d \alpha (-1 + a)}{\beta c^{4} \tau q}
> # Mutant dynamics
  > dSm := (b - q \cdot N) \cdot (Sm + Im) - \frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N} - d \cdot (1 - (1 - a) \cdot Ams) \cdot Sm + \text{gamma}
> dIm := \frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N} - (d \cdot (1 - (1 - a) \cdot Ams) + \text{alpha} + \text{gamma}) \cdot \text{Im}:
```

Calculate the Jacobian

J := (Jacobian([dSm, dIm], [Sm, Im]));

$$J := \left[\left[-q N + b - \frac{\beta \operatorname{cm} c I}{N} - d \left(1 - \frac{(1-a)\operatorname{cm} \left(c^2 \tau - \sigma \right)}{c^2 \operatorname{cm} \tau + c \sigma - \operatorname{cm} \sigma} \right), -q N + b + \gamma \right],$$

$$\left[\beta \operatorname{cm} c I - \left((1-a)\operatorname{cm} \left(c^2 \tau - \sigma \right) \right) - q N + b + \gamma \right],$$
(3)

$$\left[\frac{\beta \, cm \, c \, I}{N}, \, -d \left(1 - \frac{(1-a) \, cm \, \left(c^2 \, \tau - \sigma\right)}{c^2 \, cm \, \tau + c \, \sigma - cm \, \sigma}\right) - \alpha - \gamma\right]\right]$$

$$F := \begin{bmatrix} -qN+b & -qN+b \\ 0 & 0 \end{bmatrix} \tag{4}$$

V := F - J;

$$V := \left[\left[\frac{\beta \operatorname{cm} c I}{N} + d \left(1 - \frac{(1-a)\operatorname{cm} \left(c^2 \tau - \sigma \right)}{c^2 \operatorname{cm} \tau + c \sigma - \operatorname{cm} \sigma} \right), -\gamma \right],$$

$$\left[-\frac{\beta \operatorname{cm} c I}{N}, d \left(1 - \frac{(1-a)\operatorname{cm} \left(c^2 \tau - \sigma \right)}{c^2 \operatorname{cm} \tau + c \sigma - \operatorname{cm} \sigma} \right) + \alpha + \gamma \right] \right]$$
(5)

- > # Now calculate the next-generation matrix
 - V1 := MatrixInverse(V):
- # Fitness is equal to the largest eigenvalue of the NG matrix minus 1
- > w := simplify(NG[1, 1]) 1;

$$w := -\left(\left(\left(c^{2} \tau - \sigma\right) cm + c \sigma\right) (q N - b) \left(-I \beta c \left(-c^{2} \tau + \sigma\right) cm^{2} + \left((I \beta \sigma + N \tau (a d + \alpha + \gamma)) c^{2} - \sigma N (a d + \alpha + \gamma)\right) cm + \sigma N c (\alpha + \gamma + d)\right)\right) / \left(I \beta c \left(-c^{2} \tau + \sigma\right)^{2} (a d + \alpha) cm^{3} - 2 \left(\left(\left(\frac{a}{2} + \frac{1}{2}\right) d + \alpha\right) I \beta \sigma\right) + \frac{N a d \tau (a d + \alpha + \gamma)}{2} c^{2} - \frac{\sigma N a d (a d + \alpha + \gamma)}{2} \left(-c^{2} \tau + \sigma\right) cm^{2} + c \left((I \beta (\alpha + d) \sigma + d N \tau (2 a d + (a + 1) (\alpha + \gamma))) c^{2} - d N \sigma (2 a d + (a + 1) (\alpha + \gamma)) \sigma cm + \sigma^{2} N c^{2} d (\alpha + \gamma + d)\right) - 1$$

- # Calculate the fitness gradient
- dw0 := simplify(subs(cm = c, diff(w, cm))):
- $\rightarrow dw := simplify(subs(eql, (subs(N = Ns, dw0))));$

$$dw := \left(-\beta \left(\alpha \left(a d + \alpha + \gamma\right) \tau + \sigma d \beta \left(-1 + a\right)\right) \tau^{2} c^{8} + \left(\alpha \left(a d + \alpha + \gamma\right)^{2} \tau^{2}\right)\right)$$
(7)

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+ \, 2 \, d \, \beta \, \alpha \, \sigma \, (\, \neg \, 1 \, + \, a) \, \tau \, + \, d \, \beta^2 \, \sigma^2 \, (\, \neg \, 1 \, + \, a) \, \big) \, \tau \, c^6 \, - \, 3 \, \alpha \, \sigma \, \tau \, (\, \neg \, 1 \, + \, a) \, \, \Big[ \, \big( \, a \, d \, + \, \alpha \, a \, ) \, \big) \, \tau \, c^6 \, - \, 3 \, \alpha \, \sigma \, \tau \, (\, \neg \, 1 \, + \, a) \, \, \big( \, a \, d \, + \, \alpha \, a \, ) \, \big) \, \sigma^2 \, (\, \neg \, 1 \, + \, a) \, \, \Big[ \, (\, a \, d \, + \, \alpha \, ) \, \, (\, \neg \, 1 \, + \, a) \, \, \big( \, a \, d \, + \, \alpha \, ) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 \, + \, a) \, \, \big( \, \neg \, 1 
                                            +\gamma) \tau + \frac{\beta \sigma}{3} dc^4 + 3\alpha \sigma^2 \tau (-1 + a) \left(\frac{\alpha}{3} + \left(a - \frac{2}{3}\right)d + \frac{\gamma}{3}\right)dc^2
                                            -d^{2} \alpha \sigma^{3} (-1+a)^{2} / (\beta c^{7} \tau^{2} (\tau \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \gamma) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \gamma) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \gamma) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \gamma) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \gamma) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \gamma) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha (a d + \alpha) \tau - \sigma d \beta (a d + \alpha) c^{4} + (-\alpha) c
                                       -1 + a) c^2 + \sigma d \alpha (-1 + a))
                                  # Calculate evolutionary stability (output hidden for brevity)
| # Calculate evolutionary
| E0 := simplify(subs(cn))
| E := simplify(subs(eql))
| With (Subs(eql))
| restart :
| with (VectorCalculus) :
| with (LinearAlgebra) :
| interface (imaginaryunit)
| A := 0 :
| Ams := 0 :
                                  E0 := simplify(subs(cm = c, diff(w, cm, cm))):
                             E := simplify(subs(eql, (subs(N = Ns, E0)))):
                             # Special case - 1) R0 I < 1
                            interface(imaginaryunit = I):
       | > dS := (b - q \cdot (S + I)) \cdot (S + I) - \frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S + I)} - d \cdot (1 - (1 - a) \cdot A) \cdot S + \text{gamma} \cdot I : 
       > dI := \frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S+I)} - (d \cdot (1-(1-a) \cdot A) + \text{alpha} + \text{gamma}) \cdot I:
      > dN := (b - q \cdot N) \cdot N - d \cdot (1 - (1 - a) \cdot A) \cdot N - \text{alpha} \cdot I : 
     [ > sol := solve([dS, dI], [S, I]) :
     \triangleright eql := simplify(sol[2]):
         \rightarrow Ns := simplify(subs(eql, S + I));
                                                                                                                                                                   Ns := \frac{\alpha^2 + (-\beta c^2 + d + \gamma) \alpha + c^2 \beta (b - d)}{\beta c^2 a}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   (8)
     > # Mutant dynamics
         > dSm := (b - q \cdot N) \cdot (Sm + Im) - \frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N} - d \cdot (1 - (1 - a) \cdot Ams) \cdot Sm + \text{gamma}
     > dIm := \frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N} - (d \cdot (1 - (1 - a) \cdot Ams) + \text{alpha} + \text{gamma}) \cdot \text{Im}:
                             # Calculate the Jacobian
                                   J := (Jacobian(\lceil dSm, dIm \rceil, \lceil Sm, Im \rceil));
```

$$J := \begin{bmatrix} -q N + b - \frac{\beta \operatorname{cm} \operatorname{c} I}{N} - d & -q N + b + \gamma \\ \frac{\beta \operatorname{cm} \operatorname{c} I}{N} & -d - \alpha - \gamma \end{bmatrix}$$

$$(9)$$

- # Split the Jacobian into components F and V as follows
- $F := \langle \langle b q \cdot N, 0 \rangle | \langle b q \cdot N, 0 \rangle \rangle;$

$$F := \begin{bmatrix} -q N + b & -q N + b \\ 0 & 0 \end{bmatrix}$$
 (10)

$$V := \begin{bmatrix} \frac{\beta \ cm \ c \ I}{N} + d & -\gamma \\ -\frac{\beta \ cm \ c \ I}{N} & d + \alpha + \gamma \end{bmatrix}$$
 (11)

- > # Now calculate the next-generation matrix
- $\bigvee V1 := MatrixInverse(V)$:
- \triangleright NG := simplify(F V1):
- # Fitness is equal to the largest eigenvalue of the NG matrix minus 1
- > w := simplify(NG[1, 1]) 1;

$$w := -\frac{\left(\left(d + \alpha + \gamma \right) N + I \beta c cm \right) \left(q N - b \right)}{d \left(d + \alpha + \gamma \right) N + I c cm \beta \left(d + \alpha \right)} - 1$$
(12)

- > # Calculate the fitness gradient
- $\rightarrow dw1 := simplify(subs(cm = c, diff(w, cm)));$

$$dwI := \frac{I\beta c (qN - b) N\alpha (d + \alpha + \gamma)}{\left(d (d + \alpha + \gamma) N + Ic^2 \beta (d + \alpha)\right)^2}$$
(13)

- # Intuitively if $R0_D > 1$ and alpha > 0, this is always negative (since $b > q \cdot N$)
- > # Intuitiv
 >
 >
 > # Special
 > restart: # Special case - 2) R0 D < 1
- > with (VectorCalculus):
 - with(LinearAlgebra):
 - interface(imaginaryunit = I):
- with (Linear Algebra)

 interface (imaginaryu) $A := 1 \frac{\text{sigma}}{\text{tau} \cdot c \cdot c}$:

>
$$Ams := \frac{cm (\tau c^2 - \sigma)}{c^2 cm \tau + \sigma c - cm \sigma}$$
:
> $dS := (b - q \cdot S) \cdot S - d \cdot (1 - (1 - a) \cdot A) \cdot S$:
> $dSm := (b - q \cdot S) \cdot Sm - d \cdot (1 - (1 - a) \cdot Ams) \cdot Sm$:
> $sol := solve(dS, S)$:

>
$$dS := (b - q \cdot S) \cdot S - d \cdot (1 - (1 - a) \cdot A) \cdot S$$

$$dSm := (b - q \cdot S) \cdot Sm - d \cdot (1 - (1 - a) \cdot Ams) \cdot Sm :$$

$$sol := solve(dS, S)$$
:

$$\rightarrow$$
 eql := simplify(sol[2]);

$$eql := \frac{-c^2 (a d - b) \tau + d \sigma (-1 + a)}{c^2 q \tau}$$
 (14)

> # Fitness is straightforward in this case

$$> w := simplify \left(\frac{dSm}{Sm} \right);$$

$$w := \frac{((qS + ad - b) cm - c (qS - b + d)) \sigma - c^{2} cm \tau (qS + ad - b)}{(c - cm) \sigma + c^{2} cm \tau}$$
(15)

> # Calcualte the fitness gradient

$$\rightarrow$$
 $dw1 := simplify(subs(cm = c, subs(S = eql, diff(w, cm))));$

$$dw1 := -\frac{d\sigma(-1+a)(\tau c^2 - \sigma)}{c^5 \tau^2}$$
 (16)

Intuitively if R0 I > 1 & a < 1, then dw > 0 for all c

Trivial: cm does not feature in invasion fitness, so dw=0 for all c

Coevolution: approximation to fast social information dynamics & fast parasite evolution # | with (Linear Algebra) :

with (VectorCalculus):

interface(imaginaryunit = I):

Assume parasite evolves rapidly to maximise R0

 \triangleright beta := kappa·sqrt(alpha) : # This is the transmission-virulence trade-off we are assuming

$$A := 1 - \frac{\text{sigma}}{\text{tau} \cdot c \cdot c}$$

$$A := 1 - \frac{\text{sigma}}{\text{tau} \cdot c \cdot c} :$$

$$R0 := \frac{\text{beta} \cdot c^2}{(d \cdot (1 - (1 - a) \cdot A) + \text{alpha} + \text{gamma})} :$$

$$Fitness gradient for the parasite$$

> $R0 \ 1 := simplify(diff(R0, alpha));$

$$R0_I := \frac{\left(c^2 \left(a d - \alpha + \gamma\right) \tau - d \sigma \left(-1 + a\right)\right) \kappa c^4 \tau}{2 \sqrt{\alpha} \left(c^2 \left(a d + \alpha + \gamma\right) \tau - d \sigma \left(-1 + a\right)\right)^2}$$
 (1)

> # Optimal virulence

 \rightarrow alpha_ss := simplify(solve(R0_1, alpha));

$$alpha_ss := \frac{c^2 (a d + \gamma) \tau - d \sigma (-1 + a)}{c^2 \tau}$$
 (2)

Optimal transmission

 \rightarrow beta ss := subs(alpha = alpha ss, beta);

$$beta_ss := \kappa \sqrt{\frac{c^2 (a d + \gamma) \tau - d \sigma (-1 + a)}{c^2 \tau}}$$
(3)

Host evolution

First calculate information awareness in mutant when rare (Ams)

$$\rightarrow dSAm := \frac{cm \cdot c}{N} \cdot (tau \cdot SUm \cdot A \cdot N) - sigma \cdot SAm :$$

>
$$dIAm := \frac{cm \cdot c}{N} \cdot (\tan \cdot IUm \cdot A \cdot N) - \operatorname{sigma} \cdot IAm$$
:

$$dAm := \frac{1}{Nm} \cdot \left(\frac{cm \cdot c}{N} \cdot (\tan \cdot (1 - Am) \cdot Nm \cdot A \cdot N) - \operatorname{sigma} \cdot Am \cdot Nm \right) :$$

 \rightarrow Ams := solve(dAm, Am);

$$Ams := \frac{cm \left(\tau c^2 - \sigma\right)}{c^2 cm \tau + \sigma c - cm \sigma} \tag{4}$$

> | | Now calculate resident equilibrium

>
$$dS := (b - q \cdot (S + I)) \cdot (S + I) - \frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S + I)} - d \cdot (1 - (1 - a) \cdot A) \cdot S + \text{gamma} \cdot I$$
:

>
$$dI := \frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S+I)} - (d \cdot (1-(1-a) \cdot A) + \text{alpha} + \text{gamma}) \cdot I$$
:

$$dN := (b - q \cdot N) \cdot N - d \cdot (1 - (1 - a) \cdot A) \cdot N - \text{alpha} \cdot I :$$

$$sol := solve([dS, dI], [S, I]) :$$

$$eql := simplify(sol[2]) :$$

$$\rightarrow$$
 sol := solve([dS, dI], [S, I])

$$\rightarrow eql := simplify(sol[2])$$

$$\triangleright$$
 Ns := simplify(subs(eql, S + I));

$$Ns := \frac{1}{\kappa c^4 \tau q} \left(\alpha^{3/2} c^2 \tau + (c^2 (a d + \gamma) \tau - d \sigma (-1 + a)) \sqrt{\alpha} + \kappa c^2 (-\tau (a d + \alpha) - b) c^2 + d \sigma (-1 + a) \right)$$
(5)

>
$$dSm := (b - q \cdot N) \cdot (Sm + Im) - \frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N} - d \cdot (1 - (1 - a) \cdot Ams) \cdot Sm + \text{gamma}$$

·Im:

>
$$dIm := \frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N} - (d \cdot (1 - (1 - a) \cdot Ams) + \text{alpha} + \text{gamma}) \cdot \text{Im} :$$
> # Calculate the Jacobian

Calculate the Jacobian

 $\rightarrow J := (Jacobian([dSm, dIm], [Sm, Im]));$

$$J := \left[\left[-q \, N + b - \frac{\kappa \sqrt{\alpha} \, cm \, c \, I}{N} - d \left(1 - \frac{(1-a) \, cm \, (\tau \, c^2 - \sigma)}{c^2 \, cm \, \tau + c \, \sigma - cm \, \sigma} \right), -q \, N + b + \gamma \right],$$

$$\left[\frac{\kappa \sqrt{\alpha} \, cm \, c \, I}{N}, -d \left(1 - \frac{(1-a) \, cm \, (\tau \, c^2 - \sigma)}{c^2 \, cm \, \tau + c \, \sigma - cm \, \sigma} \right) - \alpha - \gamma \right] \right]$$

$$(6)$$

> # Split the Jacobian into components F and V as follows

>
$$F := \langle \langle b - q \cdot N, 0 \rangle | \langle b - q \cdot N, 0 \rangle \rangle;$$

$$F := \begin{bmatrix} -qN+b & -qN+b \\ 0 & 0 \end{bmatrix} \tag{7}$$

$$V := \left[\left[\frac{\kappa \sqrt{\alpha} \, cm \, c \, I}{N} + d \left(1 - \frac{(1-a) \, cm \, (\tau \, c^2 - \sigma)}{c^2 \, cm \, \tau + c \, \sigma - cm \, \sigma} \right), \, -\gamma \right], \tag{8}$$

```
\left[-\frac{\kappa\sqrt{\alpha} \ cm \ c I}{N}, d\left(1-\frac{(1-a) \ cm \left(\tau \ c^2-\sigma\right)}{c^2 \ cm \ \tau+c \ \sigma-cm \ \sigma}\right)+\alpha+\gamma\right]\right]
> # Now calculate the next-generation matrix
           V1 := MatrixInverse(V):
          NG := simplify(F \cdot V1):
           # Fitness is equal to the largest eigenvalue of the NG matrix minus 1
   > w := simplify(NG[1, 1]) - 1;
  w := ((cm \kappa ((\tau c^2 - \sigma) cm + c \sigma) c I \sqrt{\alpha} + N (-(-\tau c^2 + \sigma) (a d + \alpha + \gamma) cm))
                                                                                                                                                                                                                                                                                                                                                              (9)
                   +\sigma c (\alpha + \gamma + d)) ((\tau c^2 - \sigma) cm + c \sigma) (q N - b)) / (-cm \kappa ((\tau c^2 - \sigma) cm + c \sigma))
                   (-\sigma) cm + c\sigma)^2 cI\alpha^{3/2} + (a(-\tau c^2 + \sigma) cm - c\sigma) (cm \kappa ((\tau c^2 - \sigma) cm
                   + c \sigma) c I \sqrt{\alpha} + N \left(-\left(-\tau c^2 + \sigma\right) \left(a d + \alpha + \gamma\right) c m + \sigma c \left(\alpha + \gamma + d\right)\right)\right) d\right) - 1
             # Calculate the fitness gradient
              dw0 := simplify(subs(cm = c, diff(w, cm))):
  \rightarrow dw := simplify(subs(eql, (subs(N = Ns, dw0))));
  dw := \left( \left( -\alpha^{3/2} c^2 \tau + \left( -c^2 (a d + \gamma) \tau + d \sigma (-1 + a) \right) \sqrt{\alpha} + \kappa c^2 (\tau (a d + \alpha) c^2 + \alpha c^2) \right) \right)
                                                                                                                                                                                                                                                                                                                                                          (10)
                   -d\sigma(-1+a)))\left(-\alpha^{3/2}c^{8}\kappa\tau^{3}-(\tau^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{4}-2d\tau\sigma(-1+a)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}+d\sigma^{2}(ad+\gamma)c^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d\sigma^{2}+d
                  (a + a) \tau c^6 - 3 d \tau^2 \sigma (-1 + a) (a d + \alpha + \gamma) c^4 + 3 \sigma^2 d (-1 + a) (a - \frac{2}{3}) d
                   +\frac{\alpha}{3}+\frac{\gamma}{3} \tau c^{2}-d^{2}\sigma^{3}(-1+a)^{2} \alpha \left(\left(\alpha^{3/2}c^{4}\kappa\tau+d\kappa c^{2}(ac^{2}\tau-\sigma)\right)\right)
                 (-1+a) \sqrt{\alpha} -(c^2(ad+\alpha+\gamma)\tau-d\sigma(-1+a))\alpha)^2\kappa c^7\tau^2
              # Calculate evolutionary stability (output hidden for brevity)
               E0 := simplify(subs(cm = c, diff(w, cm, cm))):
               E := simplify(subs(eql, (subs(N = Ns, E0)))):
             # Special case - 1) only information is viable
            eql := simplify(sol[1]);
```

(11)

$$eql := \left[S = \frac{-c^2 (a d - b) \tau + d \sigma (-1 + a)}{c^2 q \tau}, I = 0 \right]$$
 (11)

 \triangleright Ns := simplify(subs(eql, S + I));

$$N_{S} := \frac{-c^{2} (a d - b) \tau + d \sigma (-1 + a)}{c^{2} q \tau}$$
 (12)

- > # Mutant dynamics
- $> w := simplify \left(subs \left(eql, \frac{dSm}{Sm} \right) \right);$ $w := \frac{d\sigma(\tau c^2 - \sigma)(c - cm)(-1 + a)}{\tau c^2(c^2 cm \tau + c \sigma - cm \sigma)}$ (13)
- > # Fitness gradient
- $\rightarrow dw := simplify(subs(cm = c, diff(w, cm)));$

$$dw := -\frac{d\sigma(\tau c^2 - \sigma)(-1 + a)}{\tau^2 c^5}$$
 (14)

- dw := \frac{a \text{of text{c}} \text{of text{c}}}{\text{t}^2 \text{of text{c}}}

 > # Special case 2) only disease is viable

 > restart:
 | with (Vector Calculus):
 | with (Linear Algebra):
 | interface (imaginary unit = _I):
 | interface (imaginary unit = _I):
 | heta := kanna \text{sqrt (alpha)}: # This is the transmission of the start of the sta
- \triangleright beta := kappa·sqrt(alpha): # This is the transmission-virulence trade-off we are assuming
- $\nearrow A := 0$:

- $\rightarrow R0 \ 1 := simplify(diff(R0, alpha));$

$$R0_I := \frac{\kappa c^2 \left(-\alpha + \gamma + d\right)}{2\sqrt{\alpha} \left(d + \alpha + \gamma\right)^2}$$
 (15)

- > # Optimal virulence
 - $alpha_ss := simplify(solve(R0_1, alpha));$

$$alpha_ss := \gamma + d \tag{16}$$

> # Optimal transmission

>
$$beta_ss := subs(alpha = alpha_ss, beta);$$

$$beta_ss := \kappa \sqrt{\gamma + d}$$
 (17)

Host evolution

| Ams := 0 : | Now calculate resident equilibrium

$$dS := (b - q \cdot (S + I)) \cdot (S + I) - \frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S + I)} - d \cdot (1 - (1 - a) \cdot A) \cdot S + \text{gamma} \cdot I :$$

$$\longrightarrow$$
 $dN := (b - q \cdot N) \cdot N - d \cdot (1 - (1 - a) \cdot A) \cdot N - \text{alpha} \cdot I$:

sol := solve([dS, dI], [S, I]):

[eql := simplify(sol[2]) :

abla Ns := simplify(subs(eql, S + I));

$$Ns := \frac{\alpha^{3/2} + (\gamma + d)\sqrt{\alpha} + (b - d - \alpha)c^2\kappa}{\kappa c^2 q}$$
 (18)

>
$$dSm := (b - q \cdot N) \cdot (Sm + Im) - \frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N} - d \cdot (1 - (1 - a) \cdot Ams) \cdot Sm + \text{gamma}$$

- $\cdot \text{Im}$:

 $\rightarrow J := (Jacobian(\lceil dSm, dIm \rceil, \lceil Sm, Im \rceil));$

$$J := \begin{bmatrix} -q N + b - \frac{\kappa \sqrt{\alpha} cm c I}{N} - d & -q N + b + \gamma \\ \frac{\kappa \sqrt{\alpha} cm c I}{N} & -d - \alpha - \gamma \end{bmatrix}$$
 (19)

> # Split the Jacobian into components F and V as follows

> $F := \langle \langle b - q \cdot N, 0 \rangle | \langle b - q \cdot N, 0 \rangle \rangle;$

$$F := \begin{bmatrix} -q N + b & -q N + b \\ 0 & 0 \end{bmatrix}$$
 (20)

$$V := \begin{bmatrix} \frac{\kappa \sqrt{\alpha} \ cm \ c \ I}{N} + d & -\gamma \\ -\frac{\kappa \sqrt{\alpha} \ cm \ c \ I}{N} & d + \alpha + \gamma \end{bmatrix}$$
 (21)

- > # Now calculate the next-generation matrix

- > V1 := MatrixInverse(V): > $NG := simplify(F \cdot V1)$: > # Fitness is equal to the large # Fitness is equal to the largest eigenvalue of the NG matrix minus 1
- w := simplify(NG[1, 1]) 1;

$$w := -\frac{\left(\kappa\sqrt{\alpha} \, cm \, c \, I + N \left(d + \alpha + \gamma\right)\right) \left(q \, N - b\right)}{I \, \alpha^{3 \mid 2} \, c \, cm \, \kappa + d \left(\kappa\sqrt{\alpha} \, cm \, c \, I + N \left(d + \alpha + \gamma\right)\right)} - 1 \tag{22}$$

- > # Calculate the fitness gradient
- $\rightarrow dw0 := simplify(subs(cm = c, diff(w, cm)))$:
- \rightarrow dw := simplify(subs(eql, (subs(N = Ns, dw0))));

$$dw := (23)$$

$$-\frac{\left(\kappa\sqrt{\alpha}c^{2}-\gamma-\alpha-d\right)\alpha\left(d+\alpha+\gamma\right)\left(-\alpha^{3}|^{2}+\left(-d-\gamma\right)\sqrt{\alpha}+c^{2}\kappa\left(d+\alpha\right)\right)}{\kappa c^{3}\left(\alpha^{3}|^{2}c^{2}\kappa+\sqrt{\alpha}c^{2}d\kappa-\alpha\left(d+\alpha+\gamma\right)\right)^{2}}$$

- \triangleright E0 := simplify(subs(cm = c, diff(w, cm, cm))):
- \vdash E := simplify(subs(eql, (subs(N = Ns, E0))));

$$E := \left(2\left(\kappa\sqrt{\alpha}c^{2} - \gamma - \alpha - d\right)^{2}\alpha\left(d + \alpha + \gamma\right)\left(-\alpha^{3}\right)^{2} + \left(-d - \gamma\right)\sqrt{\alpha} + c^{2}\kappa\left(d + \alpha\right)\right)\left(d + \alpha\right)\right) / \left(\kappa c^{4}\left(\alpha^{3}\right)^{2}c^{2}\kappa + \sqrt{\alpha}c^{2}d\kappa - \alpha\left(d + \alpha + \gamma\right)\right)^{3}\right)$$
(24)