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> #####
> # Host fitness for approximation to fast social information dynamics #
> #####
>
> restart :
> with( VectorCalculus ) :
> with( LinearAlgebra ) :
> interface(imaginaryunit = _I) :
>
> # First calculate information awareness in mutant when rare (Ams)
> A := 1 -  $\frac{\sigma}{\tau \cdot c \cdot c}$  :
> dSAms :=  $\frac{cm \cdot c}{N} \cdot (\tau \cdot SUM \cdot A \cdot N) - \sigma \cdot SAms$  :
> dIAms :=  $\frac{cm \cdot c}{N} \cdot (\tau \cdot IUms \cdot A \cdot N) - \sigma \cdot IAms$  :
> dAms :=  $\frac{1}{Nm} \cdot \left( \frac{cm \cdot c}{N} \cdot (\tau \cdot (1 - Ams) \cdot Nm \cdot A \cdot N) - \sigma \cdot Ams \cdot Nm \right)$  :
> Ams := solve(dAms, Ams);

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$$Ams := \frac{cm (\tau c^2 - \sigma)}{c^2 cm \tau + \sigma c - cm \sigma} \quad (1)$$

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>
> # Now calculate resident equilibrium
> dS := (b - q \cdot (S + I)) \cdot (S + I) -  $\frac{\beta \cdot c \cdot c \cdot S \cdot I}{(S + I)}$  - d \cdot (1 - (1 - a) \cdot A) \cdot S + gamma \cdot I :
> dI :=  $\frac{\beta \cdot c \cdot c \cdot S \cdot I}{(S + I)}$  - (d \cdot (1 - (1 - a) \cdot A) + alpha + gamma) \cdot I :
> dN := (b - q \cdot N) \cdot N - d \cdot (1 - (1 - a) \cdot A) \cdot N - alpha \cdot I :
> sol := solve([dS, dI], [S, I]) :
> eql := simplify(sol[2]) :
> Ns := simplify(subs(eql, S + I));

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$$Ns := \frac{-\tau \beta (a d + \alpha - b) c^4 + (\alpha (a d + \alpha + \gamma) \tau + \sigma d \beta (-1 + a)) c^2 - \sigma d \alpha (-1 + a)}{\beta c^4 \tau q} \quad (2)$$

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> # Mutant dynamics
> dSm := (b - q \cdot N) \cdot (Sm + Im) -  $\frac{\beta \cdot cm \cdot c \cdot Sm \cdot I}{N}$  - d \cdot (1 - (1 - a) \cdot Ams) \cdot Sm + gamma
    \cdot Im :
> dIm :=  $\frac{\beta \cdot cm \cdot c \cdot Sm \cdot I}{N}$  - (d \cdot (1 - (1 - a) \cdot Ams) + alpha + gamma) \cdot Im :
>

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> # Calculate the Jacobian
> $J := (\text{Jacobian}([dSm, dIm], [Sm, Im]));$

$$J := \begin{bmatrix} -qN + b - \frac{\beta cm c I}{N} - d \left(1 - \frac{(1-a) cm (c^2 \tau - \sigma)}{c^2 cm \tau + c \sigma - cm \sigma} \right), -qN + b + \gamma \\ \frac{\beta cm c I}{N}, -d \left(1 - \frac{(1-a) cm (c^2 \tau - \sigma)}{c^2 cm \tau + c \sigma - cm \sigma} \right) - \alpha - \gamma \end{bmatrix} \quad (3)$$

> # Split the Jacobian into components F and V as follows
> $F := \langle \langle b - q \cdot N, 0 \rangle | \langle b - q \cdot N, 0 \rangle \rangle;$

$$F := \begin{bmatrix} -qN + b & -qN + b \\ 0 & 0 \end{bmatrix} \quad (4)$$

> $V := F - J;$

$$V := \begin{bmatrix} \frac{\beta cm c I}{N} + d \left(1 - \frac{(1-a) cm (c^2 \tau - \sigma)}{c^2 cm \tau + c \sigma - cm \sigma} \right), -\gamma \\ -\frac{\beta cm c I}{N}, d \left(1 - \frac{(1-a) cm (c^2 \tau - \sigma)}{c^2 cm \tau + c \sigma - cm \sigma} \right) + \alpha + \gamma \end{bmatrix} \quad (5)$$

> # Now calculate the next-generation matrix
> $VI := \text{MatrixInverse}(V);$
> $NG := \text{simplify}(F \cdot VI);$
> # Fitness is equal to the largest eigenvalue of the NG matrix minus 1
> $w := \text{simplify}(NG[1, 1]) - 1;$

$$w := -((c^2 \tau - \sigma) cm + c \sigma) (qN - b) (-I\beta c (-c^2 \tau + \sigma) cm^2 + ((I\beta \sigma + N\tau (ad + \alpha + \gamma)) c^2 - \sigma N (ad + \alpha + \gamma) cm + \sigma N c (\alpha + \gamma + d))) / (I\beta c (-c^2 \tau + \sigma)^2 (ad + \alpha) cm^3 - 2 \left(\left(\left(\frac{a}{2} + \frac{1}{2} \right) d + \alpha \right) I\beta \sigma + \frac{Na d \tau (ad + \alpha + \gamma)}{2} \right) c^2 - \frac{\sigma Na d (ad + \alpha + \gamma)}{2} (-c^2 \tau + \sigma) cm^2 + c ((I\beta (\alpha + d) \sigma + d N \tau (2ad + (a + 1) (\alpha + \gamma))) c^2 - d N \sigma (2ad + (a + 1) (\alpha + \gamma))) \sigma cm + \sigma^2 N c^2 d (\alpha + \gamma + d)) - 1 \quad (6)$$

> # Calculate the fitness gradient
> $dw0 := \text{simplify}(\text{subs}(cm = c, \text{diff}(w, cm)));$
> $dw := \text{simplify}(\text{subs}(eq1, (\text{subs}(N = Ns, dw0))));$

$$dw := \left(-\beta (\alpha (ad + \alpha + \gamma) \tau + \sigma d \beta (-1 + a)) \tau^2 c^8 + (\alpha (ad + \alpha + \gamma)^2 \tau^2 \right) \quad (7)$$

$$\begin{aligned}
& + 2 d \beta \alpha \sigma (-1 + a) \tau + d \beta^2 \sigma^2 (-1 + a) \tau c^6 - 3 \alpha \sigma \tau (-1 + a) \left((a d + \alpha \right. \\
& + \gamma) \tau + \frac{\beta \sigma}{3} \left. \right) d c^4 + 3 \alpha \sigma^2 \tau (-1 + a) \left(\frac{\alpha}{3} + \left(a - \frac{2}{3} \right) d + \frac{\gamma}{3} \right) d c^2 \\
& - d^2 \alpha \sigma^3 (-1 + a)^2 \left. \right) / \left(\beta c^7 \tau^2 (\tau \beta (a d + \alpha) c^4 + (-\alpha (a d + \alpha + \gamma) \tau - \sigma d \beta (-1 + a)) c^2 + \sigma d \alpha (-1 + a)) \right)
\end{aligned}$$

>

> # Calculate evolutionary stability (output hidden for brevity)

> E0 := simplify(subs(cm = c, diff(w, cm, cm))) :

> E := simplify(simplify(eql, (subs(N = Ns, E0)))) :

>

>

> # Special case - 1) R0_I < 1

>

> restart :

> with(VectorCalculus) :

> with(LinearAlgebra) :

> interface(imaginaryunit = _I) :

>

> A := 0 :

> Ams := 0 :

> dS := (b - q · (S + I)) · (S + I) - $\frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S + I)}$ - d · (1 - (1 - a) · A) · S + gamma · I :

> dI := $\frac{\text{beta} \cdot c \cdot c \cdot S \cdot I}{(S + I)}$ - (d · (1 - (1 - a) · A) + alpha + gamma) · I :

> dN := (b - q · N) · N - d · (1 - (1 - a) · A) · N - alpha · I :

> sol := solve([dS, dI], [S, I]) :

> eql := simplify(sol[2]) :

> Ns := simplify(subs(eql, S + I)) ;

$$N_s := \frac{\alpha^2 + (-\beta c^2 + d + \gamma) \alpha + c^2 \beta (b - d)}{\beta c^2 q}$$

(8)

> # Mutant dynamics

> dSm := (b - q · N) · (Sm + Im) - $\frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N}$ - d · (1 - (1 - a) · Ams) · Sm + gamma · Im :

> dIm := $\frac{\text{beta} \cdot cm \cdot c \cdot Sm \cdot I}{N}$ - (d · (1 - (1 - a) · Ams) + alpha + gamma) · Im :

>

> # Calculate the Jacobian

> J := (Jacobian([dSm, dIm], [Sm, Im])) ;

$$J := \begin{bmatrix} -qN + b - \frac{\beta cm c I}{N} - d & -qN + b + \gamma \\ \frac{\beta cm c I}{N} & -d - \alpha - \gamma \end{bmatrix} \quad (9)$$

> # Split the Jacobian into components F and V as follows

> $F := \langle \langle b - q \cdot N, 0 \rangle | \langle b - q \cdot N, 0 \rangle \rangle;$

$$F := \begin{bmatrix} -qN + b & -qN + b \\ 0 & 0 \end{bmatrix} \quad (10)$$

> $V := F - J;$

$$V := \begin{bmatrix} \frac{\beta cm c I}{N} + d & -\gamma \\ -\frac{\beta cm c I}{N} & d + \alpha + \gamma \end{bmatrix} \quad (11)$$

> # Now calculate the next-generation matrix

> $VI := \text{MatrixInverse}(V) :$

> $NG := \text{simplify}(F \cdot VI) :$

> # Fitness is equal to the largest eigenvalue of the NG matrix minus 1

> $w := \text{simplify}(NG[1, 1]) - 1;$

$$w := -\frac{((d + \alpha + \gamma)N + I\beta cm)(qN - b)}{d(d + \alpha + \gamma)N + Ic cm \beta (d + \alpha)} - 1 \quad (12)$$

> # Calculate the fitness gradient

> $dw1 := \text{simplify}(\text{subs}(cm = c, \text{diff}(w, cm))) ;$

$$dw1 := \frac{I\beta c(qN - b)N\alpha(d + \alpha + \gamma)}{(d(d + \alpha + \gamma)N + Ic^2\beta(d + \alpha))^2} \quad (13)$$

> # Intuitively if $R0_D > 1$ and $\alpha > 0$, this is always negative (since $b > q \cdot N$)

>

>

> # Special case - 2) $R0_D < 1$

>

> restart :

> with(VectorCalculus) :

> with(LinearAlgebra) :

> interface(imaginaryunit = _I) :

>

> $A := 1 - \frac{\text{sigma}}{\text{tau} \cdot c \cdot c} :$

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> Ams :=  $\frac{cm (\tau c^2 - \sigma)}{c^2 cm \tau + \sigma c - cm \sigma}$  :
>
> dS := (b - q·S)·S - d·(1 - (1 - a)·A)·S :
> dSm := (b - q·S)·Sm - d·(1 - (1 - a)·Ams)·Sm :
> sol := solve(dS, S) :
> eql := simplify(sol[2]);

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$$eql := \frac{-c^2 (a d - b) \tau + d \sigma (-1 + a)}{c^2 q \tau} \quad (14)$$

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> # Fitness is straightforward in this case
> w := simplify( $\frac{dSm}{Sm}$ );

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$$w := \frac{((q S + a d - b) cm - c (q S - b + d)) \sigma - c^2 cm \tau (q S + a d - b)}{(c - cm) \sigma + c^2 cm \tau} \quad (15)$$

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> # Calcualte the fitness gradient
> dw1 := simplify(subs(cm = c, subs(S = eql, diff(w, cm))));

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$$dw1 := - \frac{d \sigma (-1 + a) (\tau c^2 - \sigma)}{c^5 \tau^2} \quad (16)$$

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> # Intuitively if R0_I > 1 & a < 1, then dw > 0 for all c
>
>
>
> # Special case - 3) R0_I, R0_D < 1
>
>
> # Trivial: cm does not feature in invasion fitness, so dw=0 for all c
>

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