1 Subsequences of a Sequence

Subsequence of a sequence:

• Given a sequence (x_n) , a subsequence (y_m) is formed by choosing an infinite collection of the entries of the original sequence in the order that these elements appear in the original sequence.

For example let us consider a sequence x such that $x : \mathbb{N} \to \mathbb{R}$,

now consider the subsequences of the above sequence x_1, x_2, \ldots, x_n , so a subsequence is a composite function $x \circ m : \mathbb{N} \to \mathbb{R}$ where $m : \mathbb{N} \to \mathbb{N}$ which is increasing and one to one, so $m_1 = 1, m_2 = 2, \ldots, m_n = n$.

the subsequence can be denoted as x(m(n)) or x_{m_n} .

Proposition 5:

• if (x_n) is a convergent sequence with limit l_x , then every subsequence (x_{n_k}) of (x_n) converges to l_x .

<u>Proof</u>: Suppose $x_n \to l_x$, then we want to prove that $x_{n_k} \to l_x$.

Notice that $n_k \ge k$ because n_k is strictly increasing sequence such that $n_1 < n_2 < n_3 < \ldots$, we are basically saying that the nth term of a subsequence must have a subscript greater than or equal to n.

Now consider $\epsilon > 0$ and we drop some N terms of the original sequence then whatever is left from the original sequence lies in the interal $(l_x - \epsilon, l_x + \epsilon)$ now instead of dropping those N terms from the original sequence we drop them from the subsequence then also the remaining terms will lie in $(l_x - \epsilon, l_x + \epsilon)$.

Proposition 6:

• Let (x_n) be a sequence in \mathbb{R} . We define

$$\lim \sup x_n = \lim_{N \to \infty} \sup \{x_n : n > N\}$$

and

$$\lim\inf x_n = \lim_{N \to \infty} \inf \left\{ x_n : n > N \right\}$$

Then, $\lim x_n$ exists if and only if $\lim \sup x_n = \lim \inf x_n$.

Suppose $y_m = \sup_{n>M} x_n$ and consider $x_n = (-1)^n$ then notice that

$$y_1 = 1$$

$$y_2 = 1$$

$$y_M = 1$$

and suppose $z_M = \inf_{n>M} x_n$ then notice that,

$$z_{M} = -1$$

or if we consider the sequence $x_n = -1, \frac{1}{2}, \frac{-1}{3}, \frac{1}{4}, \frac{-1}{5}, \dots$ then,

$$y_1 = \frac{1}{2}$$

$$y_2 = \frac{1}{4}$$

$$y_3 = \frac{1}{4}$$

$$y_M = \begin{cases} \frac{1}{m+2} & \text{if m is even} \\ \frac{1}{m+1} & \text{if m is odd} \end{cases}$$

Proposition 7:

• Every convergent real sequence is bounded.

Proof:

- Take any (x_n) with $x_n \to x$ for some real number x.
- Then there must exist a natural number M such that $|x_m x| < 1$, and hence $|x_m| < |x| + 1$, for all $m \ge M$.
- But then $|x_m| \leq \max\{|x|+1,|x_1|,\ldots,|x_M|\}$ for all $m \in \mathbb{N}$.
- Hence, (x_n) is bounded.

Note that if we have a sequence x_n such that $x_n \to 0$ and we have another bounded sequence y_n then, $x_n \times y_n$ will also be a convergent infact, $x_n \times y_n \to 0$ as well.

Monotonic sequence:

- A real sequence (x_n) is said to be increasing if $x_n \leq x_{n+1}$ for each $n \in \mathbb{N}$
- A real sequence (x_n) is said to be strictly increasing if $x_n < x_{n+1}$ for each $n \in \mathbb{N}$.
- It is said to be (strictly) decreasing if $(-x_n)$ is (strictly) increasing.

A real sequence which is either increasing or decreasing is referred to as a monotonic sequence

Proposition 8:

• Every increasing (decreasing) real sequence that is bounded from above (below) converges.

Proof:

- Let (x_n) be an increasing sequence which is bounded from above, and let $S = \{x_1, x_2, \ldots\}$.
- Let $x = \sup S$. We claim that $x_n \to x$.
- To show this, pick an arbitrary $\epsilon > 0$.
- Since x is the least upper boundnof $S, x \epsilon$ cannot be an upper bound of S, so $x_M > x \epsilon$ for some $M \in \mathbb{N}$.
- Since (x_n) is increasing, we must then have $x \ge x_m \ge x_M > x \epsilon$, so $|x_m x| < \epsilon$, for all $m \ge M$.
- Hence $x_n \to x$.
- The proof of the second claim is analogous.

Proposition 9:

• Every real sequence has a monotonic subsequence.

Proof:

- Take any (x_n) and define $S_m = \{x_m, x_{m+1}, \ldots\}$ for each $m \in \mathbb{N}$.
- If there is no maximum element in S_1 , then it is easy to see that (x_n) has a monotonic subsequence.
- (Let $x_{n_1} = x_1$, let x_{n_2} be the first term in the sequence (x_2, x_3, \ldots) greater than x_1 , let x_{n_3} be the first term in the sequence $(x_{n_2+1}, x_{n_2+2}, \ldots)$ greater than x_{n_2} , and so on.)
- By the same logic, if, for any $m \in \mathbb{N}$, there is no maximum element in S_m , then we are done.
- Assume then $\max S_m$ exists for each $m \in \mathbb{N}$.
- Now define the subsequence (x_{n_k}) recursively as follows

$$x_{n_1} = \max S_1, x_{n_2} = \max S_{n_1+1}, x_{n_3} = \max S_{n_2+1}, \dots$$

• Clearly, (x_{n_k}) is decreasing.

To prove: Every sequence has a monotonic subsequence.

Consider a real sequence x_n and the set $S_m = \{x_m, x_{m+1}, \ldots\}$ basically we are dropping m-1 terms from the sequence and the rest are in the set S_M .

So $S_1 = \{x_1, x_2, \ldots\}$, then either the maximum (max) of the set S_1 exists ir it does not exist.

Now suppose the maximum of S_1 does not exist and then consider the subsequenc x_m such that

$$x_{m_1} = x_1$$

$$x_{m_2} = x_{\min\{k|x_k > x_{m_1}\}}$$

$$x_{m_3} = x_{\min\{k|x_k > x_{m_2}\}}$$

and so on is our monotonic sequence,

note that the $x_{\min\{k|x_k>x_{m_1}\}}$ and $x_{\min\{k|x_k>x_{m_2}\}}$ exist since the max S_1 does not exist.

Now suppose that $\max S_1 = x_{k_1}$ so the maximum exists then if we drop k_1 terms of the sequence then we are only left with the set S_{k+1} and now we again have only two possibilities either $\max S_{k+1}$ exist or it does not exist, if it does not exist then we can find a monotonic sequence in the manner discussed above and if it exist then suppose $x_{k_2} = \max S_{k+1}$ then again we have the same situation as above so either we have an increasing sequence S_n when the maximum does not exist or we have an decreasing sequence x_{k_m} both of which are monotonic sequences.

Proposition 10 (Bolzano Weierstrass Theorem):

• Every bounded real sequence has a convergent subsequence.

Proof:

• Putting the propositions 8 and 9 together, we get this result as an immediate corollary.

2 Metric Space:

- Let X be a nonempty set. A function $d: X \times X \to \mathbb{R}_+$ is a metric (distance function) if, for any a, b, and c in X, it satisfies the following three conditions:
 - 1. Properness: d(a, b) = 0 if and only if a = b,

- 2. Symmetry: d(a, b) = d(b, a), and
- 3. Triangle Inequality: $d(a,b) \le d(a,c) + d(c,b)$.

A nonempty set X equipped with a metric d constitutes a metric space (X,d).

let $X = \mathbb{R}$ then d(x, y) = |x - y| is a valid distance function.

let $X \subseteq \mathbb{R}^2$ then $d((x_1, y_1)(x_2, y_2)) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$ is the Euclidean distance and also a valid metric, also another example of a metric is the taxicab metric or the Manhattan distance, $d((x_1, y_1)(x_2, y_2)) = |x_1 - x_2| + |y_1 - y_2|$.

Another valid mertic example is, Let $X \subseteq \mathbb{R}^2$

$$d((x_1, y_1)(x_2, y_2)) = \max(|x_1 - x_2|, |y_1 - y_2|)$$

Another example the Discrete metric is defined as, $X \neq \phi$

$$d(a,b) = \begin{cases} 1 & \text{if } a \neq b \\ 0 & \text{if } a = b \end{cases}$$

Similarly the Euclidean metric for \mathbb{R}^n is defined as, $X = \mathbb{R}^n$

$$d((x_1, y_1)(x_2, y_2) \dots (x_n, y_n)) = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2 + \dots + (x_n - y_n)^2}$$

let (X,d) be a metric space, then for any $a \in X$, and any $\epsilon > 0$, ϵ -neighbourhood is defined as

$$\mathcal{N}_{\epsilon}(a) = \{ b \in X \mid d(b, a) < \epsilon \}$$

Examples;

- 1. $X = \mathbb{R}$ and d(x, y) = |x y| then $\mathcal{N}_{\frac{1}{2}}(0) = (\frac{-1}{2}, \frac{1}{2})$.
- 2. X = [0, 1] and d(x, y) = |x y| then $\mathcal{N}_{\frac{1}{2}}(0) = [0, \frac{1}{2})$.
- 3. $X = \mathbb{Z}$ and d(x, y) = |x y| then $\mathcal{N}_{\frac{1}{2}}(0) = \{0\}$.
- 4. $X = \mathbb{R}^2$ and

 $d((x_1, y_1)(x_2, y_2)) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$ then $\mathcal{N}_1(0, 0)$ will be an open circle at (0, 0) of radius 1 and similarly $\mathcal{N}_2(0, 0)$ will be an open circle at (0, 0) of radius 2. More generally if $r \leq s$ if $\mathcal{N}_r(a) \subset \mathcal{N}_s(a)$.

- 5. $X = \mathbb{R}$ and metric is the discrete metric then, $\mathcal{N}_2(0) = \mathbb{R}$ and $\mathcal{N}_3(0) = \mathbb{R}$ and note that $\mathcal{N}_3(0) \subset \mathcal{N}_2(0)$
- 6. $X = \mathbb{R}^2$ and

 $d((x_1, y_1)(x_2, y_2)) = |x_2 - x_1| + |y_2 - y_1|$ then $\mathcal{N}_1(0, 0)$ will be an open rhombus with the origin at (0, 0).

7. $X = \mathbb{R}^2$ and

 $d((x_1, y_1)(x_2, y_2)) = \max(|x_2 - x_1|, |y_2 - y_1|)$ then $\mathcal{N}_1(0, 0)$ will be an open square at the origin.

Let (X, d) be a metric space then $Y \subset X$ is said to be open in (X, d) if, $(\forall y \in Y)(\exists \epsilon > 0)(\mathcal{N}_{\epsilon}(y) \subset Y)$, where $\mathcal{N}_{\epsilon}(y) = \{x \in X \mid d(x, y) < \epsilon\}$

Examples;

- 1. $X = \mathbb{R}$ and d(x,y) = |x-y| then [0,1) is not open because $(-\epsilon,\epsilon) \not\subset [0,1) \forall \epsilon > 0$
- 2. $X = \mathbb{R}_+$ and d(x,y) = |x-y| then [0,1) is an open set because now 0 does not create a problem like before.

Let (X, d) be a metric space then $Z \subset X$ is said to be closed in (X, d) if, X/Z is open in (X, d) where $X/Z = \{x \in X \mid x \notin Z\}$

Examples;

1. $X = \mathbb{R}$ and d(x,y) = |x-y| then Z = [0,1) is not closed because it's complement $(-\infty,0) \cup [1,\infty)$ is not open.

(X,d) be a metric space then

 $Y \subset X$ is said to be bounded if

$$(\exists \in > 0, x \in X) (Y \subset N_{\epsilon}(x))$$