physics on screen

xMCF 3.0 schema and documentation revision 1 (amendment)

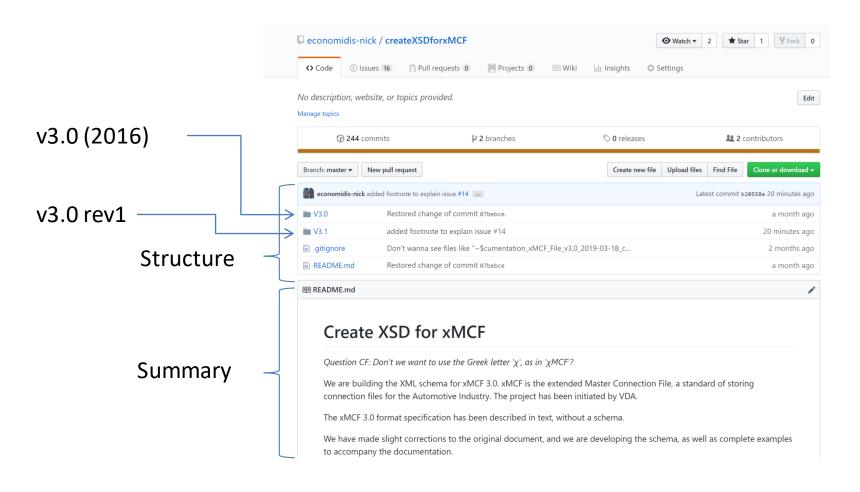
Nick Economidis, BETA-CAE Systems



How to access it on Github

Hosted page:

https://github.com/economidis-nick/createXSDforxMCF



Amendments since last meeting (29th May 2019):

<u>Chapter 5.2.1.1 Finite Element specific data < femdata > </u>

- Simplification of the way FE <entity> is defined
- xMCF schema is ready to bind to FATXML schema

Chapter 5.3.1.3 Special Topological Situations

- Clarification of grouping of joints in <connected_to>
- Introduction of <stacking> element
 - For self connecting joints
 - For keeping the order of connected parts

Chapter 7.5.1 Introduction (bolts & screws)

Re-stated the bolts-vs-screw definition (wiki)

Chapter 7.5.2 Contacts & Friction (for bolts & screws)

- Removed the competing definition
- Encouraged the use of definition of chapter 5.3.2.5



TO DOs:

Official location of xMCF v3.0r1 schema file

- Current location of xsd is:
 https://github.com/economidis-nick/createXSDforxMCF
- Passing ownership of the repository

Abaqus does not have PIDs



stay connected

















thank you!



For Dr. Zhang:

Output using both label & pid

```
<connected to>
         <assy index="1">
                  <part label="PART 01" pid="100">
                   <part label="PART_01" pid="101">
                  <part label="PART 01" pid="102">
         </assy>
</connected to>
<connected to>
         <assy index="1"> <!-- same part, but different contents -->
                  <part label="PART 01" pid="100">
                  <part label="PART_01" pid="101">
         </assy>
</connected to>
```



For Dr. Zhang:

Why /How to output p

- Current location of xsd is: https://github.com/economidis-nick/createXSDforxMCF
- Passing ownership of the repository

Abaqus does not have PIDs