CSE 220: Systems Fundamentals I Unit 1: **Introduction to Digital Systems**

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The Landscape of Computing

- Three broad classes of modern computing devices:
 - **Personal computers**: general-purpose, low-performing machines
 - **Servers and supercomputers**: more powerful machines usually built for a particular purpose
 - Modern supercomputers typically have 10,000+ processing units and terabytes of memory
 - **Embedded computers**: special-purpose computers that are embedded in a larger system, such as a car, TV, network router, etc.
- For which of these computing platforms will fault tolerance be the least? (i.e., for which computer type is a failure totally unacceptable?)

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But Wait, There's More!

- · Harder to categorize are devices like smart phones and tablets
 - Somewhere between a personal computer and an embedded system? Or a totally different category?
- Cloud computing systems also don't fit well into these categories
 - An evolution of server technology
 - SaaS: software as a service why buy an expensive server when you can rent one at a fraction of the price?

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Architecture vs. Organization

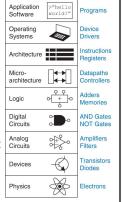
- The terms computer architecture and computer organization are often thrown about without clear explanation of what these terms mean
- **Computer architecture** refers to those aspects of the hardware that are visible to the programmer
 - e.g., instructions the computer is capable of executing, word size (native unit of data of CPU), data formats
- Computer organization (also called microarchitecture) refers to how the physical components of the machine interact to implement the architecture
 - A particular computer architecture could be implemented by several different microarchitectures

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Eight Great Ideas in Architecture

- 1. Design for Moore's Law
 - Moore's "Law" refers to the trend that circuit complexity/speed doubles every 18-24 months
 - Anticipate where technology will be when a system is completed, not when it is being designed
- 2. Use abstraction to simplify design
 - Abstraction refers to ignoring irrelevant details and focusing on higher-level design/implementation issues
 - Part of software development too



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Eight Great Ideas in Architecture

- 3. Make the common case fast
 - Enhance the performance of those operations which occur most frequently
- 4. Increase performance via parallelism
 - Perform operations in parallel (simultaneously) when possible
- 5. Increase performance via pipelining
 - A form of parallelism in which single instructions are broken into multiple stages and executed in parallel
- 6. Increase performance via prediction
 - The computer "guesses" which operation will be executed next and starts executing it early

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Eight Great Ideas in Architecture

- 7. Implement a hierarchy of memories
 - Fastest, smallest and expensive memory at the top; slowest, largest and cheapest at the bottom
- 8. Increase dependability via redundancy
 - Include redundant components that can take over when a failure occurs
 - Of particular importance in cloud computing systems and other server technologies

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2. Modularity

These modules have well-defined functions and interfaces

as a collection of collaborating modules

3. Regularity

1. Hierarchy

The Three Y's

 Modules can be reused many times in a single design, thereby reducing then umber of distinct components that must be designed

We will look at the design of a CPU from the bottom-up

 Note how well these concepts apply also to software design and implementation

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von Neumann Architecture

- The term **von Neumann architecture** refers to a particular computer hardware design model for a storedprogram digital computer (e.g., PCs)
- Separate central processing unit (CPU) and randomaccess memory (RAM)
- Both instructions and data stored in RAM
- Data to be processed is transferred from RAM to CPU, and results are transferred back to RAM
- Named for Hungarian-American mathematician John von Neumann, but others participated in the original design
- Most modern computers follow this basic design model, but are substantially more complex

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von Neumann Architecture

- CPU: performs the actual processing
 - control unit: performs instruction decoding and control
 - arithmetic/logic unit (ALU): performs basic arithmetical and logical operations
 - registers: small amount of memory used to hold addresses, instructions and data
- RAM: larger memory used to store both program instructions and data
- I/O devices permit data to enter/leave machine
 - We'll concern ourselves with **standard input**, **standard** output, standard error and also file I/O

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Stored-program Computer

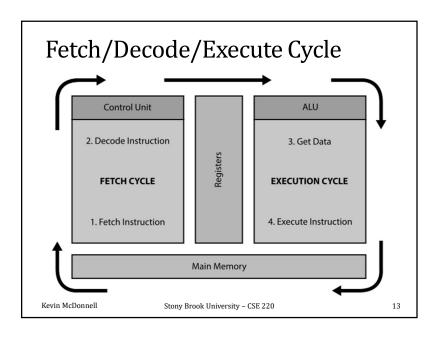
- In a stored-program computer, the program to be executed is stored in RAM along with the data to be processed
 - So please note: by saying "stored program" it does NOT mean we are storing the programs on a disk
- A program consists of binary **instructions** stored in RAM
- Each instruction or small piece of data in RAM has an associated **memory address** to indicate its location
- A program counter (or instruction pointer) register in the CPU stores the memory address of the next instruction to be executed
- Earlier computers were "hard-wired" to a particular program via switches, patch cables, etc.

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Fetch/Decode/Execute Cycle

- So what is a 3 GHz CPU doing 3 billion times per second?
- The basic cycle of operation of a von Neumann-style computer:
 - Fetch: the next instruction is retrieved from RAM
 - **Decode**: the instruction is examined to determine what the CPU should do:
 - **Opcode**: field that determines the type of instruction
 - **Operand(s)**: fields that determine the source and destination of data to be operated on
 - **Execute**: the operation specified by the instruction is performed, which may involve one or more memory references

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Instruction Set

- The **instruction set** of a computer is the repertoire of instructions that the CPU can perform
 - Determined by the computer architects/designers
 - "Hard-wired" as part of the computer design
 - · Different for each type of CPU
- What is an "instruction"?
- · Answer: it depends on the kind of CPU
- In **RISC** (reduced instruction set computer) CPUs, the instruction set is small and consists of simple instructions
- In **CISC** (complex instruction set computer) CPUs, the instruction set is larger and consists of instructions that vary in length and complexity

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Typical RISC Instructions

- In this course we will study the **MIPS** architecture (Microprocessor without Interlocked Pipeline Stages), which is of the RISC type. Instructions include:
 - · Load data from memory to CPU register
 - Copy ("Store") data from CPU register to memory
 - Add, subtract, multiply, divide, etc. data in CPU registers
 - AND, OR, XOR, NOT, etc. data in CPU registers
 - Shift and rotate data in CPU registers
 - Jump based on CPU state flags ("condition codes")
 - \boldsymbol{Call} a subroutine (function) and \boldsymbol{return} to caller

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Example

- A **high-level programming language** statement like X = A + B would be translated to assembly language instructions as follows:
 - LOAD A
- LOAD B
- ADD C, A, B
- STORE C, X
- Naturally, the real assembly instructions are a little more sophisticated than this (e.g., from what memory address are loading the data?), but the beauty of RISC machines is that the instructions are quite simple
- The assembly language instructions are then translated into machine language (1s and 0s) for execution by the CPU

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Course Roadmap

- Data representations: numbers, characters
- MIPS assembly programming: basics, conditionals, loops
- MIPS assembly programming: functions, 1D arrays
- Digital logic design: basic circuit design
- Digital logic design: computational units, timing
- Digital logic design: circuit simplification
- MIPS assembly programming: 2D arrays
- MIPS architecture: single-cycle data path
- MIPS assembly programming: recursive functions
- MIPS architecture: multi-cycle data path
- MIPS architecture: pipelined data path

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